

128 Bit X24001 16 x 8 Bit

Identi[™]PROM

1

FEATURES

- 2.7V to 5.5V Power Supply
- 128 Bit Serial E2PROM
- Low Power CMOS
 - —Active Current Less Than 1mA
 - —Standby Current Less Than 50μA
- Internally Organized 16 x 8
- 2 Wire Serial Interface
- High Voltage Programmable Only
 - -V_{PGM}, 12V to 15V
- Push/Pull Output
- High Reliability
 - -Data Retention: 100 Years
- Available Packages
 - -8-Lead MSOP
 - -8-Lead PDIP
 - -8-Lead SOIC

DESCRIPTION

The X24001 is a CMOS 128 bit serial E^2PROM , internally organized as 16 x 8. The X24001 features a serial interface and software protocol allowing operation on a simple two wire bus.

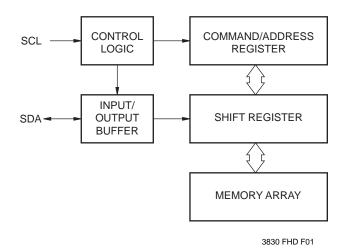
The X24001 is ideally suited for identification applications such as serial numbers or device revision numbers which need to be stored and retrieved electronically.

 V_{PGM} is used to enable writes to the device. This provides full protection of the data in the user's environment where V_{PGM} is not available.

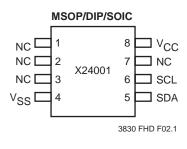
Xicor E²PROMs are designed and tested for applications requiring extended endurance. Inherent data retention is greater than 100 years.

The X24001 is fabricated with Xicor's Advanced CMOS Floating Gate technology.

FUNCTIONAL DIAGRAM



PIN CONFIGURATION



PIN DESCRIPTIONS

Serial Clock (SCL)

The SCL input is used to clock all data into and out of the device.

Serial Data (SDA)

SDA is a bidirectional pin used to transfer data into and out of the device. It is a push/pull output and does not require the use of a pull-up resistor. During the programming operation, SDA is an input.

PIN NAMES

Symbol	Description
NC	No Connect
V _{SS}	Ground
V _{CC}	Supply Voltage
SDA	Serial Data
SCL	Serial Clock

3830 PGM T01

DEVICE OPERATION

The X24001 supports a bidirectional bus oriented protocol. The protocol defines any device that sends data onto the bus as a transmitter and the receiving device as the receiver. The device controlling the transfer is a master and the device being controlled is the slave. The master will always initiate data transfers and provide the clock for both transmit and receive operations. Therefore, the X24001 will be considered a slave in all applications.

Clock and Data Conventions

Data states on the SDA line can change only during SCL LOW. SDA state changes during SCL HIGH are reserved for indicating start and stop conditions. Refer to Figures 1 and 2.

Start Condition

All commands are preceded by the start condition, which is a HIGH to LOW transition of SDA when SCL is HIGH. The X24001 continuously monitors the SDA and SCL lines for the start condition and will not respond to any command until this condition has been met.

A start may be issued to terminate the input of a control word or the input of data to be written. This will reset the device and leave it ready to begin a new read or write command. Because of the push/pull output, a start cannot be generated while the part is outputting data. Starts are also inhibited while a write is in progress.

Stop Condition

The stop condition is a LOW to HIGH transition of SDA when SCL is HIGH. The stop condition is used to reset the device during a command or data input sequence and will leave the device in the standby mode. As with starts, stops are inhibited when outputting data and while a write is in progress.

Figure 1. Data Validity

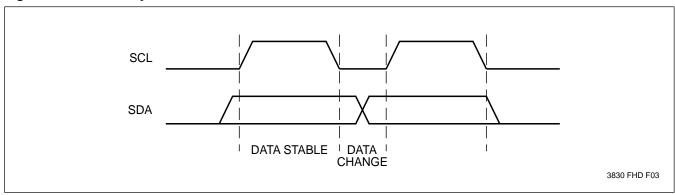
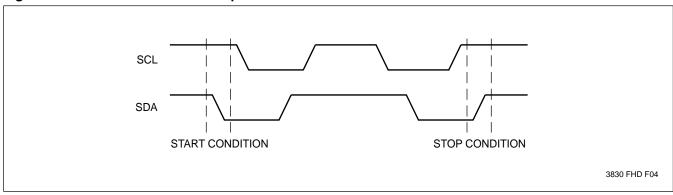


Figure 2. Definition of Start and Stop Conditions



Programming Operation

Programming of the X24001 is performed one byte at a time. After each byte is written, a delay equal to the write cycle time of 5ms must be observed before initiating the next write cycle.

The sequence of operations is: first raise the SCL pin to V_{PGM} and generate a HIGH to LOW transition of SDA (programming mode start). This is followed by eight bits of data containing the program command bits, four address bits and two don't care bits, immediately followed by the 8-bit data byte.

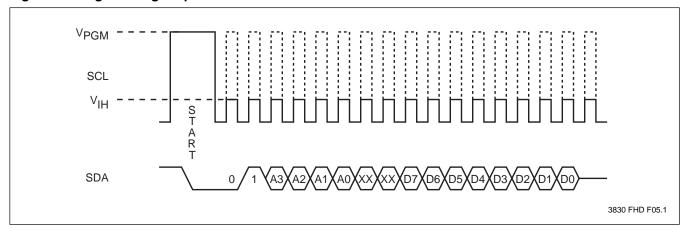
The timing of the operation conforms to the standard A.C. timing requirements and follows the sequence shown below. After generating the Programming Mode start condition the SCL HIGH level can be either V_{IH} or V_{PGM} .

Factory Programming Service

The X24001 can be programmed with customer specific data prior to shipment. The data programmed can be in two forms: static data pattern where there is no change in the data in a group of devices or sequential data, such as a base number incremented by one for each device tested and shipped.

Customers requiring one of these services should contact their local sales office for ordering procedures and service charges.

Figure 3. Programming Sequence



Read Operation

The byte read operation is initiated with a start condition. The start condition is followed by an eight-bit control byte which consists of a two-bit read command (1,0), four address bits, and two "don't care" bits. After receipt of the control byte, the X24001 will enter the read mode and transfer data into the shift register from the array. This data is shifted out of the device on the next eight SCL clocks. At the end of the read, all counters are reset

and the X24001 will enter the standby mode. As with a write, the read operation can be interrupted by a start or stop condition while the command or address is being clocked in. While clocking data out, starts or stops cannot be generated.

During the second don't care clock cycle, starts and stops are ignored. The master must free the bus prior to the end of this clock cycle to allow the X24001 to begin outputting data (Figures 4 and 5).

Figure 4. Read Sequence

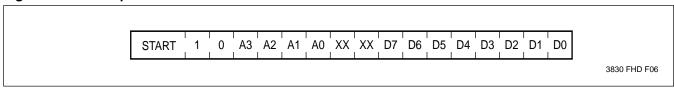
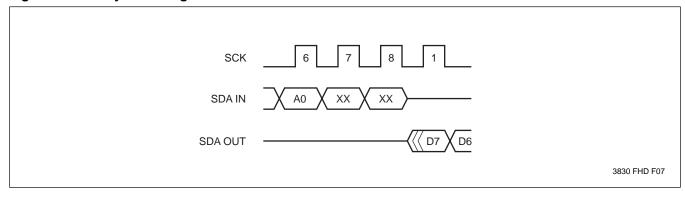
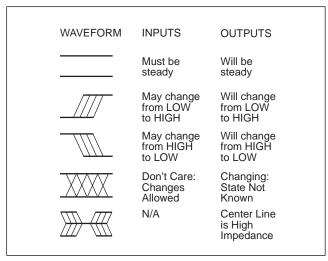


Figure 5. Read Cycle Timing



SYMBOL TABLE



ABSOLUTE MAXIMUM RATINGS*

Temperature under Bias	
X24001	65°C to +135°C
Storage Temperature	65°C to +150°C
Voltage on any Pin with	
Respect to V _{SS}	1V to +7V
Voltage on SCL with	
Respect to V _{SS}	1V to +17V
D.C. Output Current	5mA
Lead Temperature	
(Soldering, 10 seconds)	300°C

*COMMENT

Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and the functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

RECOMMENDED OPERATING CONDITIONS

Temperature	Min.	Max.
Commercial	0°C	+70°C
Industrial	–40°C	+85°C
Military	–55°C	+125°C

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Supply Voltage	Limits
X24001	5V ±10%
X24001-3	3V to 5.5V
X24001-2.7	2.7V to 5.5V

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D.C. OPERATING CHARACTERISTICS (Over recommended operating conditions unless otherwise specified.)

		Limits			
Symbol	Parameter	Min. Max.		Units	Test Conditions
I _{CC1}	V _{CC} Supply Current Read		1	mA	SCL = $V_{CC} \times 0.1/V_{CC} \times 0.9$ Levels @ 1MHz, SDA = Open
I _{SB1}	V _{CC} Standby Current		100	μΑ	$SCL = SDA = V_{CC}$ $V_{CC} = 5V \pm 10\%$
I _{SB2}	V _{CC} Standby Current		50	μΑ	$SCL = SDA = V_{CC}$ $V_{CC} = 3V$
ILI	Input Leakage Current		10	μΑ	$V_{IN} = V_{SS}$ to V_{CC}
I _{LO}	Output Leakage Current		10	μΑ	$V_{OUT} = V_{SS}$ to V_{CC}
V _{IL} (1)	Input LOW Voltage	-1.0	V _{CC} x 0.3	V	
V _{IH} (1)	Input HIGH Voltage	V _{CC} x 0.7	$V_{CC} + 0.5$	V	
V _{OL}	Output LOW Voltage		0.4	V	I _{OL} = 2.1mA
V _{OH}	Output HIGH Voltage	$V_{CC} - 0.8$		V	I _{OH} = 1mA
V_{PGM}	Program Enable Voltage	12	15	V	

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CAPACITANCE $T_A = +25^{\circ}C$, f = 1MHz, $V_{CC} = 5V$

Symbol Parameter		Max.	Units	Test Conditions
C _{I/O} (2)	Input/Output Capacitance (SDA)	8	pF	V _{I/O} = 0V
C _{IN} (2)	Input Capacitance (SCL)	6	pF	V _{IN} = 0V

3830 PGM T05.1

Notes: (1) V_{IL} min. and V_{IH} max. are for reference only and are not tested.

(2) This parameter is periodically sampled and not 100% tested.

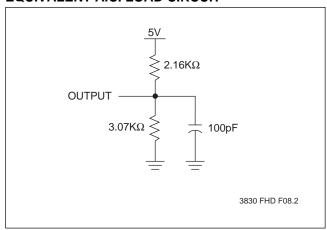
X24001

POWER-UP TIMING

Symbol	Parameter	Max.	Units
t _{PUR} (3)	Power-up to Read Operation	2	ms
t _{PUW} (3)	Power-up to Write Operation	5	ms

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EQUIVALENT A.C. LOAD CIRCUIT



A.C. CONDITIONS OF TEST

Input Pulse Levels	V _{CC} x 0.1 to V _{CC} x 0.9
Input Rise and Fall Times	10ns
Input and Output Timing Levels	V _{CC} x 0.5

3830 PGM T07.1

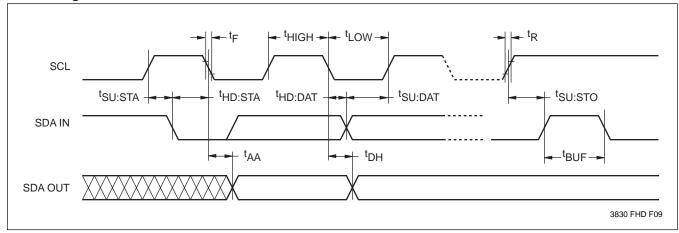
$\textbf{A.C. CHARACTERISTICS} \ (Over the \ recommended \ operating \ conditions \ unless \ otherwise \ specified.)$

Read & Write Cycle Limits

Symbol	Parameter	Min.	Max.	Units	
f _{SCL} SCL Clock Frequency		0	1	MHz	
t _{AA}	SCL LOW to SDA Data Out Valid		350	ns	
t _{BUF}	Time the Bus Must Be Free Before a New Transmission Can Start	500		ns	
t _{HD:STA}	Start Condition Hold Time	250		ns	
t _{LOW}	Clock LOW Period	500		ns	
t _{HIGH}	Clock HIGH Period	500		ns	
t _{SU:STA}	Start Condition Setup Time	250		ns	
t _{HD:DAT}	Data In Hold Time	0		μs	
t _{SU:DAT}	Data in Setup Time	250		ns	
t _R	SDA and SCL Rise Time		1	μs	
t _F	SDA and SCL Fall Time		300	ns	
t _{SU:STO}	Stop Condition Setup Time	250		ns	
t _{DH}	Data Out Hold Time	50		ns	

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Bus Timing

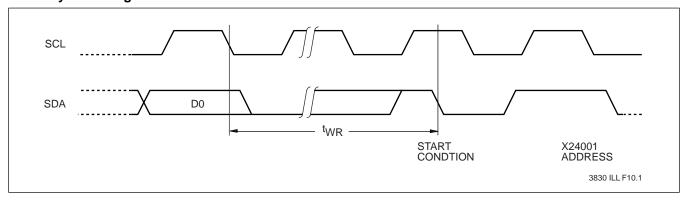


WRITE CYCLE LIMITS

Symbol	Symbol Parameter		Max.	Units	
t _{WR} (4)	Write Cycle Time		5	ms	

3830 PGM T09

Write Cycle Timing

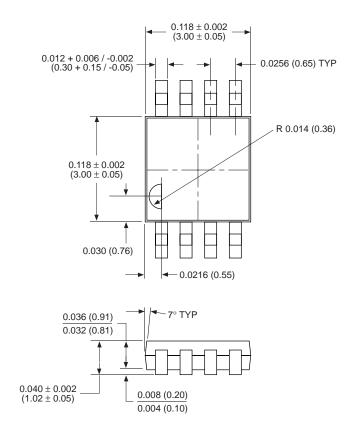


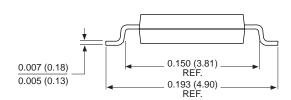
Note: (3) t_{PUR} and t_{PUW} are the delays required from the time V_{CC} is stable until the specified operation can be initiated. These parameters are periodically sampled and not 100% tested.

(4) The write cycle time is the time from the initiation of a write sequence to the end of the internal erase/program cycle. During the write cycle, the X24001 bus interface circuits are disabled, SDA is high impedance, and the device does not respond to start conditions.

PACKAGING INFORMATION

8-LEAD MINIATURE SMALL OUTLINE GULL WING PACKAGE TYPE M





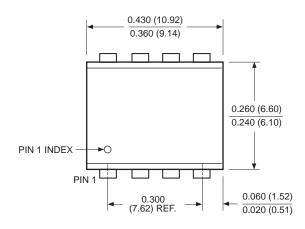
NOTE:

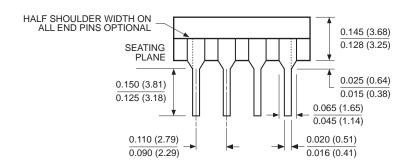
1. ALL DIMENSIONS IN INCHES AND (MILLIMETERS)

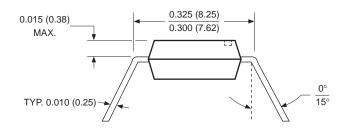
3926 ILL F49

PACKAGING INFORMATION

8-LEAD PLASTIC DUAL IN-LINE PACKAGE TYPE P





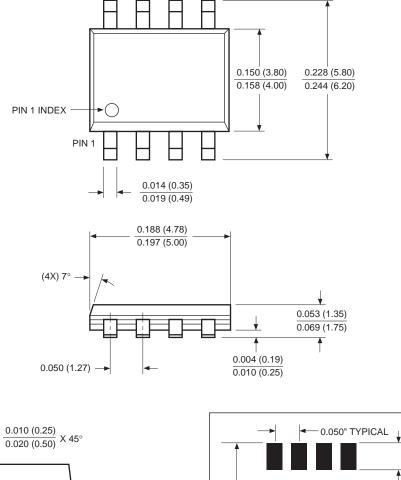


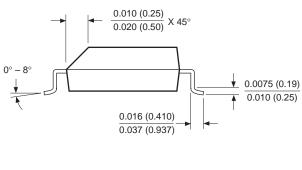
NOTE:

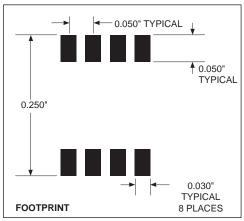
- 1. ALL DIMENSIONS IN INCHES (IN PARENTHESES IN MILLIMETERS)
- 2. PACKAGE DIMENSIONS EXCLUDE MOLDING FLASH

PACKAGING INFORMATION

8-LEAD PLASTIC SMALL OUTLINE GULL WING PACKAGE TYPE S



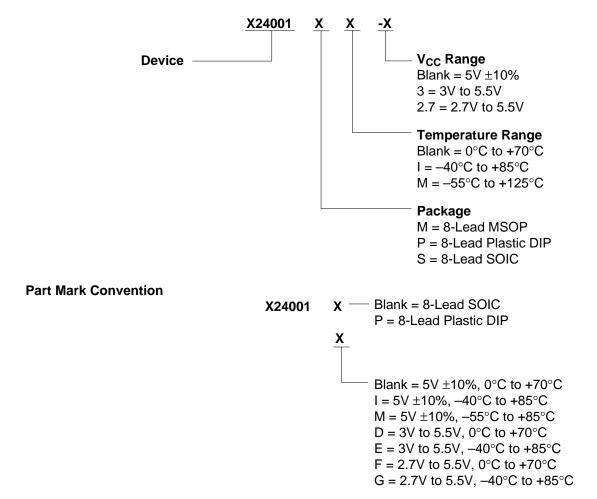




NOTE: ALL DIMENSIONS IN INCHES (IN PARENTHESES IN MILLIMETERS)

3926 FHD F22.1

ORDERING INFORMATION



LIMITED WARRANTY

Devices sold by Xicor, Inc. are covered by the warranty and patent indemnification provisions appearing in its Terms of Sale only. Xicor, Inc. makes no warranty, express, statutory, implied, or by description regarding the information set forth herein or regarding the freedom of the described devices from patent infringement. Xicor, Inc. makes no warranty of merchantability or fitness tor any purpose. Xicor, Inc. reserves the right to discontinue production and change specifications and prices at any time and without notice.

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US. PATENTS

Xicor products are covered by one or more of the following U.S. Patents: 4,263,664; 4,274,012; 4,300,212; 4,314,265; 4,326,134; 4,393,481; 4,404,475; 4,450,402; 4,486,769; 4,488,060; 4,520,461; 4,533,846; 4,599,706; 4,617,652; 4,668,932; 4,752,912; 4,829,482; 4,874,967; 4,883,976. Foreign patents and additional patents pending.

LIFE RELATED POLICY

In situations where semiconductor component failure may endanger life, system designers using this product should design the system with appropriate error detection and correction, redundancy and back-up features to prevent such an occurrence.

Xicor's products are not authorized for use as critical components in life support devices or systems.

- 1. Life support devices or systems are devices or systems which, (a) are intended for surgical implant into the body, or (b) support or sustain life, and whose failure to perform, when properly used in accordance with instructions for use provided in the labeling, can be reasonably expected to result in a significant injury to the user.
- 2. A critical component is any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its satety or effectiveness.

X24001

X2	4001 PROGRAMMING ORDER INFORMATION	AUTHORIZATION Programming Information Supplied By				
Cu	stomer Name:					
Ad	dress:					
		Print or Type Clearly Full Name				
Со	mplete Device Part Number:					
	Static Pattern Fill in matrix A below	Title				
	Incrementing Pattern Indicate in Matix A any static pattern and indicate in Matrix B beginning sequence value to be incremented.	Signature	Date			
	Totally Random Pattern					

Matrix A

Address		Data Pattern MSB First						
Addiess	7	6	5	4	3	2	1	0
0								
1								
2								
3								
4								
5								
6								
7								
8								
9								
Α								
В								
С								
D								
Е								
F								

Matrix B

IIIX D								
Address	Data Pattern MSB First							
	7	6	5	4	3	2	1	0
0								
1								
2								
3								
4								
5								
6								
7								
8								
9								
Α								
В								
С								
D								
Е								
F								