

16K

X25160

2K x 8 Bit

SPI Serial EEPROM With Block Lock™ Protection

FEATURES

- 2MHz clock rate
- SPI modes (0,0 & 1,1)
- 2K X 8 bits
 - 32-byte page mode
- Low power CMOS
 - <1µA standby current
 - <5mA active current
- 2.7V To 5.5V power supply
- Block lock protection
 - Protect 1/4, 1/2 or all of EEPROM array
- Built-in inadvertent write protection
 - Power-up/power-down protection circuitry
 - Write enable latch
 - Write protect pin
- Self-timed write cycle
 - 5ms write cycle time (typical)
- High reliability
 - Endurance: 1,000,000 cycles
 - Data retention: 100 years
 - ESD protection: 2000V on all pins
- 8-lead PDIP package
- 8-lead SOIC package

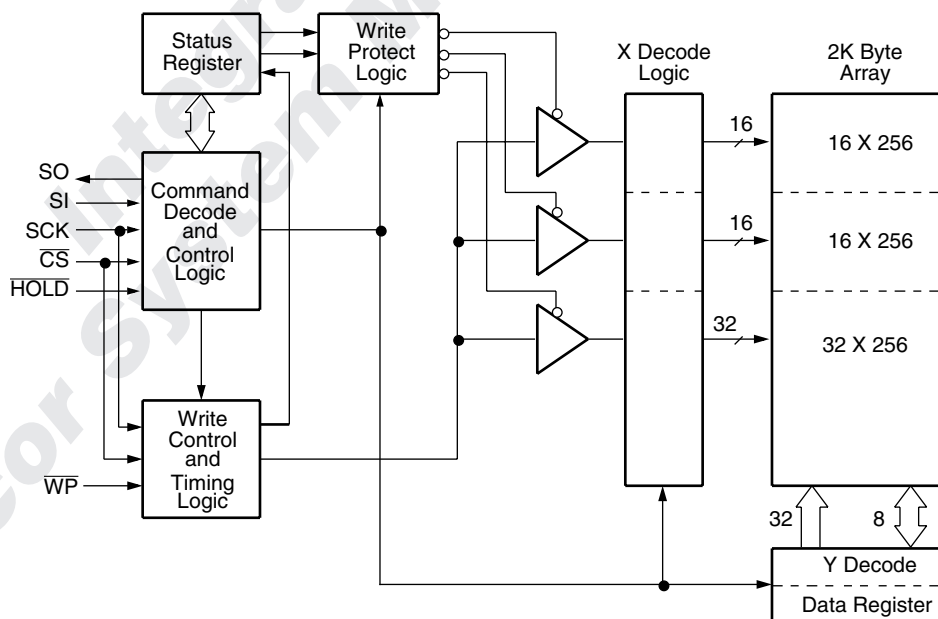
DESCRIPTION

The X25160 is a CMOS 16384-bit serial EEPROM, internally organized as 2K x 8. The X25160 features a Serial Peripheral Interface (SPI) and software protocol, allowing operation on a simple three-wire bus. The bus signals are a clock input (SCK) plus separate data in (SI) and data out (SO) lines. Access to the device is controlled through a chip select ($\overline{CS}$) input, allowing any number of devices to share the same bus.

The X25160 also features two additional inputs that provide the end user with added flexibility. By asserting the HOLD input, the X25160 will ignore transitions on its inputs, thus allowing the host to service higher priority interrupts. The WP input can be used as a hardware input to the X25160 disabling all write attempts to the status register, thus providing a mechanism for limiting end user capability of altering 0, 1/4, 1/2 or all of the memory.

The X25160 utilizes Xicor's proprietary Direct Write™ cell, providing a minimum endurance of 1,000,000 cycles and a minimum data retention of 100 years.

BLOCK DIAGRAM



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PIN DESCRIPTIONS

Serial Output (SO)

SO is a push/pull serial data output pin. During a read cycle, data is shifted out on this pin. Data is clocked out by the falling edge of the serial clock.

Serial Input (SI)

SI is the serial data input pin. All opcodes, byte addresses, and data to be written to the memory are input on this pin. Data is latched by the rising edge of the serial clock.

Serial Clock (SCK)

The Serial Clock controls the serial bus timing for data input and output. Opcodes, addresses, or data present on the SI pin are latched on the rising edge of the clock input, while data on the SO pin change after the falling edge of the clock input.

Chip Select ($\overline{CS}$)

It should be noted that after power-up, a HIGH to LOW transition on $\overline{CS}$ is required prior to the start of any operation.

When $\overline{CS}$ is HIGH, the X25160 is deselected, the SO output pin is at HIGH impedance and, unless an internal write operation is underway, the X25160 will be in the standby power mode. $\overline{CS}$ LOW enables the X25160, placing it in the active power mode.

Write Protect ($\overline{WP}$)

When $\overline{WP}$ is LOW and the nonvolatile bit WPEN is "1", nonvolatile writes to the X25160 status register are disabled, but the part otherwise functions normally. When $\overline{WP}$ is held HIGH, all functions, including nonvolatile writes operate normally. $\overline{WP}$ going LOW while $\overline{CS}$ is still LOW will interrupt a write to the X25160 status register. If the internal write cycle has already been initiated, $\overline{WP}$ going LOW will have no effect on a write.

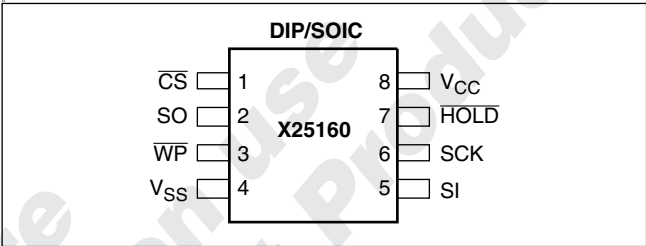
The $\overline{WP}$ pin function is blocked when the WPEN bit in the status register is "0". This allows the user to install the X25160 in a system with $\overline{WP}$ pin grounded, and still be able to write to the status register. The $\overline{WP}$ pin functions will be enabled when the WPEN bit is set "1".

Hold ($\overline{HOLD}$)

$\overline{HOLD}$ is used in conjunction with the $\overline{CS}$ pin to select the device. Once the part is selected and a serial sequence is underway, $\overline{HOLD}$ may be used to pause

the serial communication with the controller without resetting the serial sequence. To pause, $\overline{HOLD}$ must be brought LOW while SCK is LOW. To resume communication, $\overline{HOLD}$ is brought HIGH, again while SCK is LOW. If the pause feature is not used, $\overline{HOLD}$ should be held HIGH at all times.

PIN CONFIGURATION



PIN NAMES

Symbol	Description
$\overline{CS}$	Chip Select Input
SO	Serial Output
SI	Serial Input
SCK	Serial Clock Input
$\overline{WP}$	Write Protect Input
V_{SS}	Ground
V_{CC}	Supply Voltage
$\overline{HOLD}$	Hold Input
NC	No Connect

PRINCIPLES OF OPERATION

The X25160 is a 2K x 8 EEPROM designed to interface directly with the synchronous serial peripheral interface (SPI) of many popular microcontroller families.

The X25160 contains an 8-bit instruction register. It is accessed via the SI input, with data being clocked in on the rising SCK. $\overline{CS}$ must be LOW and the $\overline{HOLD}$ and $\overline{WP}$ inputs must be HIGH during the entire operation. The $\overline{WP}$ input is "Don't Care" if WPEN is set "0".

Table 1 contains a list of the instructions and their opcodes. All instructions, addresses and data are transferred MSB first.

Data input is sampled on the first rising edge of SCK after $\overline{CS}$ goes LOW. SCK is static, allowing the user to stop the clock and then resume operations. If the clock line is shared with other peripheral devices on the SPI bus, the user can assert the $\overline{HOLD}$ input to place the

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X25160 into a “PAUSE” condition. After releasing HOLD, the X25160 will resume operation from the point when HOLD was first asserted.

Write Enable Latch

The X25160 contains a “write enable” latch. This latch must be SET before a write operation will be completed internally. The WREN instruction will set the latch and the WRDI instruction will reset the latch. This latch is automatically reset upon a power-up condition and after the completion of a byte, page, or status register write cycle.

Status Register

The RDSR instruction provides access to the status register. The status register may be read at any time, even during a write cycle. The status register is formatted as follows:

7	6	5	4	3	2	1	0
WPEN	X	X	X	BP1	BP0	WEL	WIP

WPEN, BP0 and BP1 are set by the WRSR instruction. WEL and WIP are read-only and automatically set by other operations.

The Write-In-Process (WIP) bit indicates whether the X25160 is busy with a write operation. When set to a “1”, a write is in progress, when set to a “0”, no write is in progress. During a write, all other bits are set to “1”.

The Write Enable Latch (WEL) bit indicates the status of the “write enable” latch. When set to a “1”, the latch is set, when set to a “0”, the latch is reset.

The Block Protect (BP0 and BP1) bits are nonvolatile and allow the user to select one of four levels of protection. The X25160 is divided into four 4096-bit segments. One, two, or all four of the segments may be protected. That is, the user may read the segments but will be unable to alter (write) data within the selected segments. The partitioning is controlled as illustrated below.

Status Register Bits		Array Addresses Protected
BP1	BP0	
0	0	None
0	1	\$0600–\$07FF
1	0	\$0400–\$07FF
1	1	\$0000–\$07FF

Table 1. Instruction Set

Instruction Name	Instruction Format*	Operation
WREN	0000 0110	Set the write enable latch (enable write operations)
WRDI	0000 0100	Reset the write enable latch (disable write operations)
RDSR	0000 0101	Read status register
WRSR	0000 0001	Write status register
READ	0000 0011	Read data from memory array beginning at selected address
WRITE	0000 0010	Write data to memory array beginning at selected address (1 to 32-bytes)

Note: *Instructions are shown MSB in leftmost position. Instructions are transferred MSB first.

Write-Protect Enable

The Write-Protect-Enable (WPEN) is available for the X25160 as a nonvolatile enable bit for the $\overline{WP}$ pin.

WPEN	WP	WEL	Protected Blocks	Unprotected Blocks	Status Register
0	X	0	Protected	Protected	Protected
0	X	1	Protected	Writable	Writable
1	Low	0	Protected	Protected	Protected
1	Low	1	Protected	Writable	Protected
X	High	0	Protected	Protected	Protected
X	High	1	Protected	Writable	Writable

The Write Protect ($\overline{WP}$) pin and the nonvolatile Write Protect Enable (WPEN) bit in the status register control the programmable hardware write protect feature. Hardware write protection is enabled when $\overline{WP}$ pin is LOW, and the WPEN bit is “1”. Hardware write protection is disabled when either the $\overline{WP}$ pin is HIGH or the WPEN bit is “0”. When the chip is hardware write protected, nonvolatile writes are disabled to the status register, including the block protect bits and the WPEN bit itself, as well as the block-protected sections in the memory array. Only the sections of the memory array that are not block-protected can be written.

Note: Since the WPEN bit is write protected, it cannot be changed back to a “0”, as long as the $\overline{WP}$ pin is held LOW.

Clock and Data Timing

Data input on the SI line is latched on the rising edge of SCK. Data is output on the SO line by the falling edge of SCK.

Read Sequence

When reading from the EEPROM memory array, $\overline{CS}$ is first pulled LOW to select the device. The 8-bit read instruction is transmitted to the X25160, followed by the 16-bit address, of which the last 11 are used. After the read opcode and address are sent, the data stored in the memory at the selected address is shifted out on the SO line. The data stored in memory at the next address can be read sequentially by continuing to provide clock pulses. The address is automatically incremented to the next higher address after each byte of data is shifted out. When the highest address is reached (\$07FF) the address counter rolls over to address \$0000 allowing the read cycle to be continued indefinitely. The read operation is terminated by taking $\overline{CS}$ HIGH. Refer to the read EEPROM array operation sequence illustrated in Figure 1.

To read the status register the $\overline{CS}$ line is first pulled LOW to select the device followed by the 8-bit RDSR instruction. After the RDSR opcode is sent, the contents of the status register are shifted out on the SO line. The read status register sequence is illustrated in Figure 2.

Write Sequence

Prior to any attempt to write data into the X25160, the “write enable” latch must first be set by issuing the WREN instruction (See Figure 3). $\overline{CS}$ is first taken LOW, then the WREN instruction is clocked into the X25160. After all

eight bits of the instruction are transmitted, $\overline{CS}$ must then be taken HIGH. If the user continues the write operation without taking $\overline{CS}$ HIGH (after issuing the WREN instruction), the write operation will be ignored.

To write data to the EEPROM memory array, the user issues the write instruction, followed by the address and then the data to be written. This is minimally a thirty-two clock operation. $\overline{CS}$ must go LOW and remain LOW for the duration of the operation. The host may continue to write up to 32-bytes of data to the X25160. The only restriction is the 32-bytes must reside on the same page. If the address counter reaches the end of the page and the clock continues, the counter will “roll over” to the first address of the page and overwrite any data that may have been written.

For the write operation (byte or page write) to be completed, $\overline{CS}$ can only be brought HIGH after bit 0 of data byte N is clocked in. If it is brought HIGH at any other time the write operation will not be completed. Refer to Figures 4 and 5 for a detailed illustration of the write sequences and time frames in which $\overline{CS}$ going HIGH are valid.

To write to the status register, the WRSR instruction is followed by the data to be written. Data bits 0, 1, 4, 5 and 6 must be “0”. This sequence is shown in Figure 6.

While the write is in progress following a status register or EEPROM write sequence, the status register may be read to check the WIP bit. During this time the WIP bit will be HIGH.

Hold Operation

The $\overline{HOLD}$ input should be HIGH (at V_{IH}) under normal operation. If a data transfer is to be interrupted, $\overline{HOLD}$ can be pulled LOW to suspend the transfer until it can be resumed. The only restriction is the SCK input must be LOW when $\overline{HOLD}$ is first pulled LOW, and SCK must also be LOW when $\overline{HOLD}$ is released.

The $\overline{HOLD}$ input may be tied HIGH either directly to V_{CC} or tied to V_{CC} through a resistor.

Operational Notes

The X25160 powers-up in the following state:

- The device is in the LOW power standby state.
- A HIGH to LOW transition on $\overline{CS}$ is required to enter an active state and receive an instruction.
- SO pin is HIGH impedance.
- The “write enable” latch is reset.

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Data Protection

The following circuitry has been included to prevent inadvertent writes:

- The “write enable” latch is reset upon power-up.

- A WREN instruction must be issued to set the “write enable” latch.

- $\overline{CS}$ must come HIGH at the proper clock count in order to start a write cycle.

Figure 1. Read EEPROM Array Operation Sequence

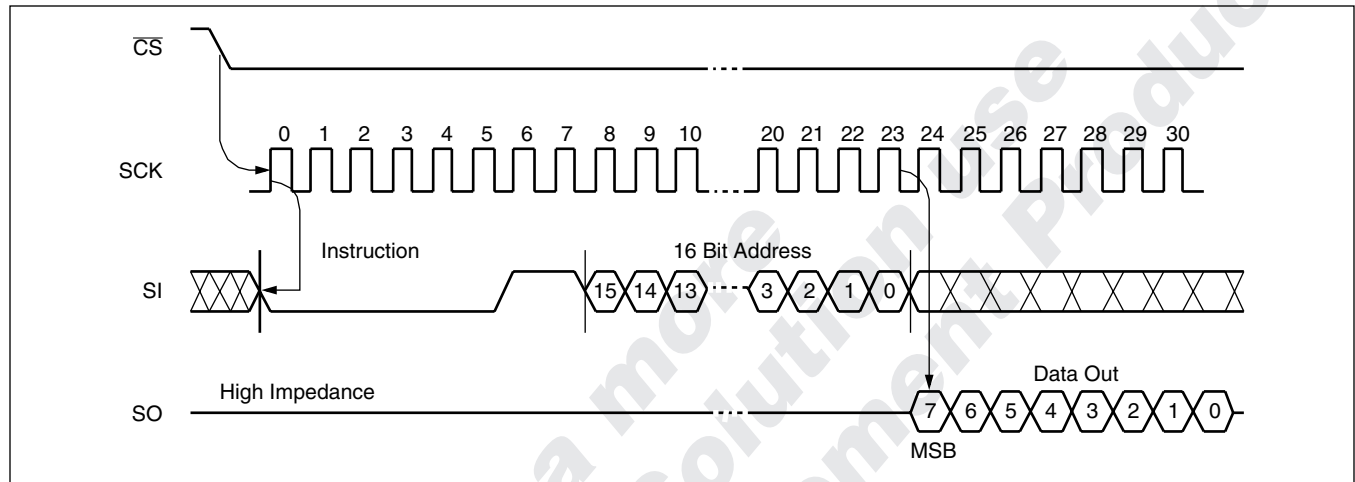


Figure 2. Read Status Register Operation Sequence

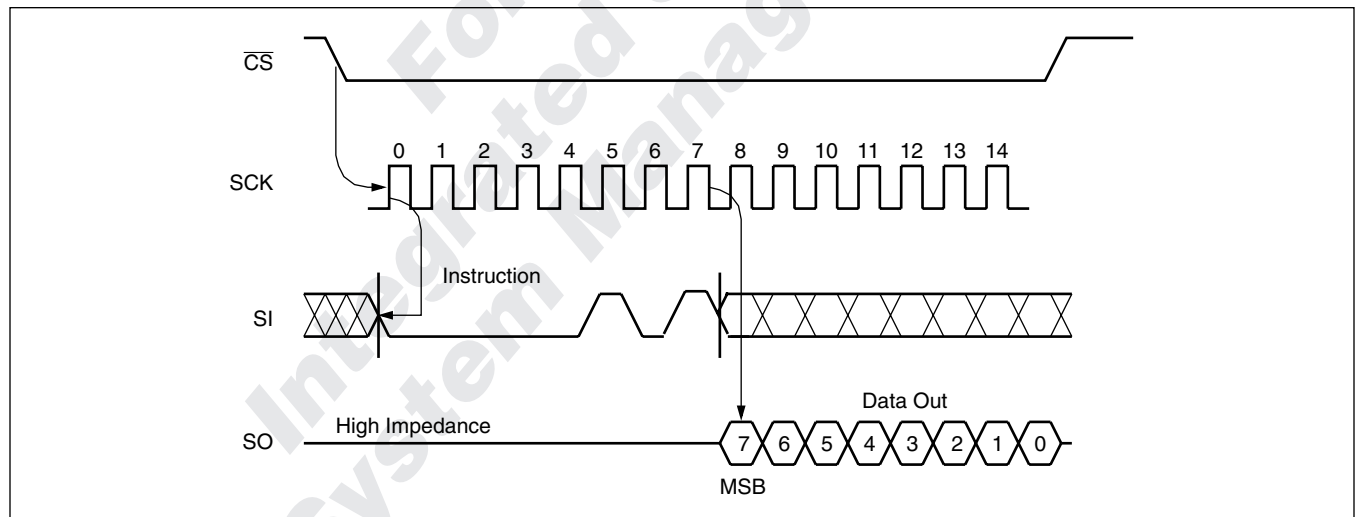


Figure 3. Write Enable Latch Sequence

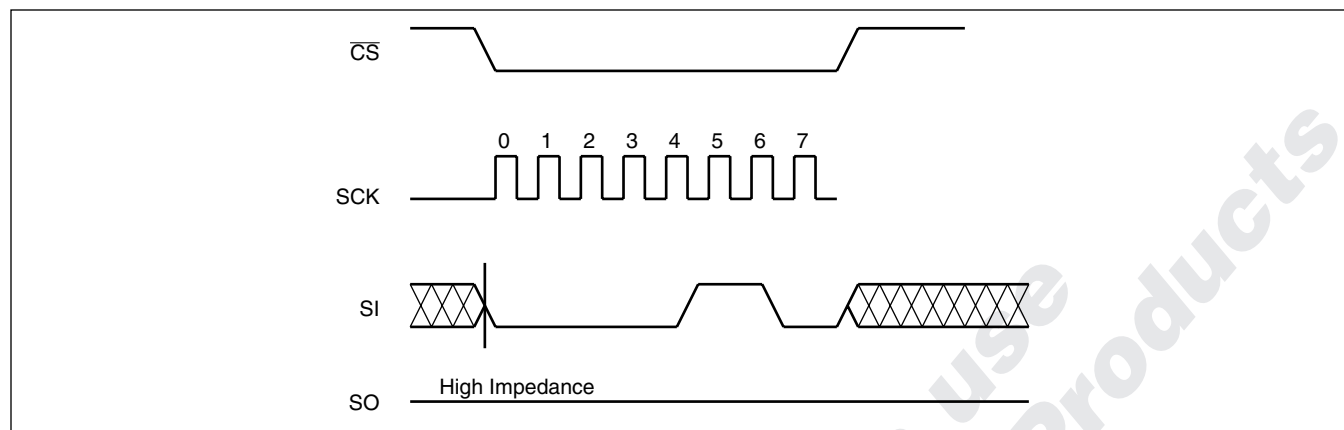


Figure 4. Byte Write Operation Sequence

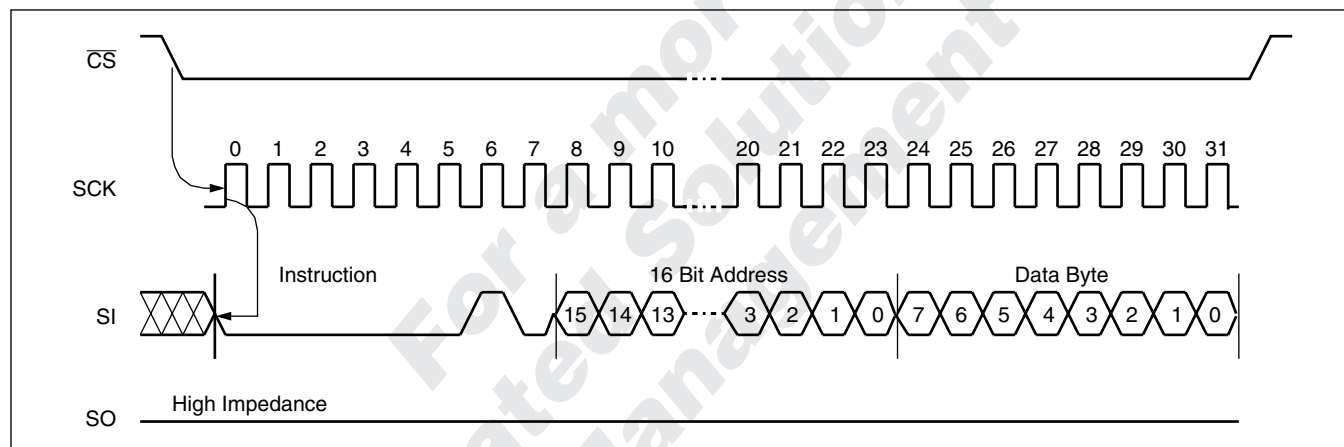


Figure 5. Page Write Operation Sequence

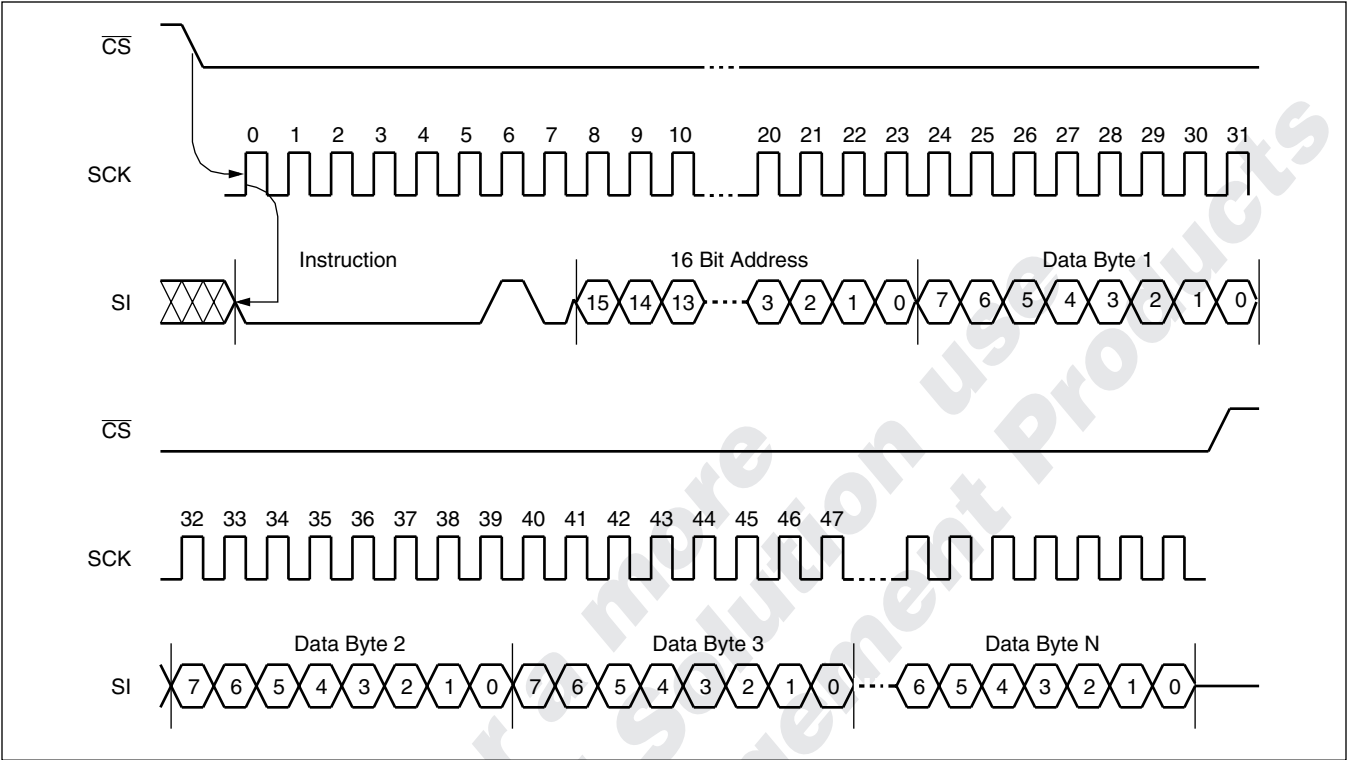
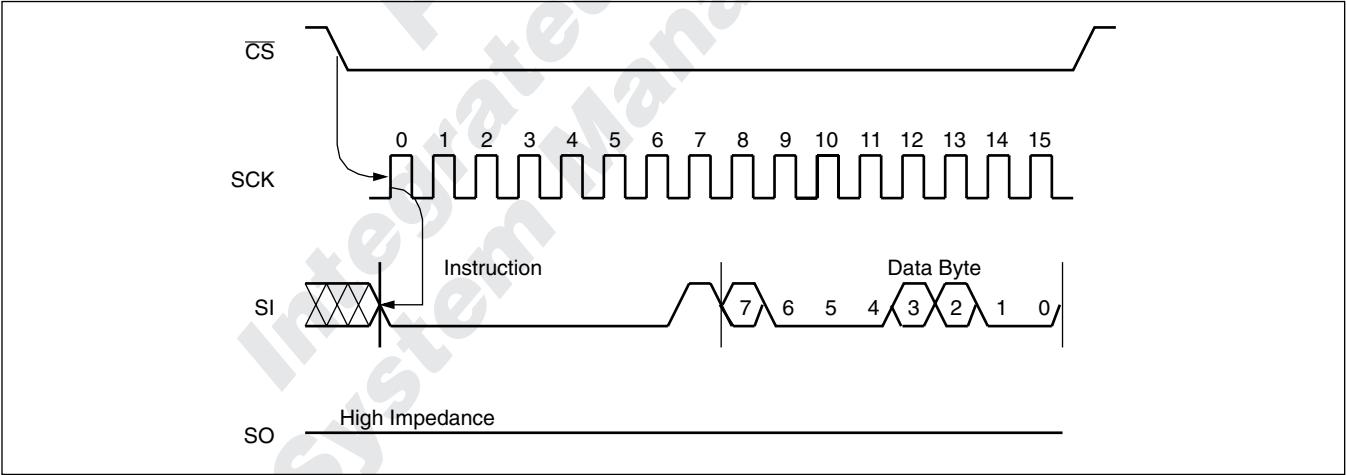


Figure 6. Write Status Register Operation Sequence



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ABSOLUTE MAXIMUM RATINGS

Temperature under bias-65°C to +135°C
Storage temperature-65°C to +150°C
Voltage on any pin with respect to V_{SS}-1V to +7V
D.C. output current 5mA
Lead temperature (soldering, 10 seconds).....300°C

COMMENT

Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only; functional operation of the device (at these or any other conditions above those listed in the operational sections of this specification) is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

RECOMMENDED OPERATING CONDITIONS

Temperature	Min.	Max.
Commercial	0°C	+70°C
Industrial	-40°C	+85°C

Supply Voltage	Limits
X25160-2.7	2.7V to 5.5V

D.C. OPERATING CHARACTERISTICS (Over the recommended operating conditions unless otherwise specified.)

Symbol	Parameter	Limits		Unit	Test Conditions
		Min.	Max.		
I_{CC}	V_{CC} supply current (active)		5	mA	$SCK = V_{CC} \times 0.1/V_{CC} \times 0.9$ @ 2MHz, $SO = \text{Open}$, $\overline{CS} = V_{SS}$
I_{SB}	V_{CC} supply current (standby)		1	μA	$\overline{CS} = V_{CC}$, $V_{IN} = V_{SS}$ or V_{CC}
I_{LI}	Input leakage current		10	μA	$V_{IN} = V_{SS}$ to V_{CC}
I_{LO}	Output leakage current		10	μA	$V_{OUT} = V_{SS}$ to V_{CC}
$V_{IL(1)}$	Input LOW voltage	-1	$V_{CC} \times 0.3$	V	
$V_{IH(1)}$	Input HIGH voltage	$V_{CC} \times 0.7$	$V_{CC} + 0.5$	V	
V_{OL1}	Output LOW voltage		0.4	V	$V_{CC} = 5V$, $I_{OL} = 3mA$
V_{OH1}	Output HIGH voltage	$V_{CC} - 0.8$		V	$V_{CC} = 5V$, $I_{OL} = -1.6mA$
V_{OL2}	Output LOW voltage		0.4	V	$V_{CC} = 3V$, $I_{OL} = 1.5mA$
V_{OH2}	Output HIGH voltage	$V_{CC} - 0.3$		V	$V_{CC} = 3V$, $I_{OH} = -0.4mA$

POWER-UP TIMING

Symbol	Parameter	Min.	Max.	Unit
$t_{PUR}^{(3)}$	Power-up to read operation		1	ms
$t_{PUW}^{(3)}$	Power-up to write operation		5	ms

CAPACITANCE $T_A = +25^\circ C$, $f = 1MHz$, $V_{CC} = 5V$

Symbol	Test	Max.	Unit	Conditions
$C_{OUT}^{(2)}$	Output capacitance (SO)	8	pF	$V_{OUT} = 0V$
$C_{IN}^{(2)}$	Input capacitance (SCK, SI, $\overline{CS}$, $\overline{WP}$, HOLD)	6	pF	$V_{IN} = 0V$

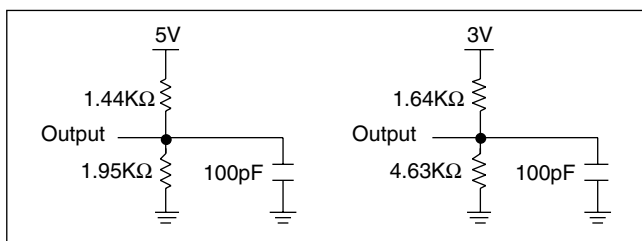
Notes: (1) V_{IL} min. and V_{IH} max. are for reference only and are not tested.

(2) This parameter is periodically sampled and not 100% tested.

(3) t_{PUR} and t_{PUW} are the delays required from the time V_{CC} is stable until the specified operation can be initiated. These parameters are periodically sampled and not 100% tested.

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EQUIVALENT A.C. LOAD CIRCUIT



A.C. TEST CONDITIONS

Input pulse levels	$V_{CC} \times 0.1$ to $V_{CC} \times 0.9$
Input rise and fall times	10ns
Input and output timing level	$V_{CC} \times 0.5$

A.C. CHARACTERISTICS (Over recommended operating conditions, unless otherwise specified)

Data Input Timing

Symbol	Parameter	Min.	Max.	Unit
f_{SCK}	Clock frequency	0	2	MHz
t_{CYC}	Cycle time	500		ns
t_{LEAD}	$\overline{CS}$ lead time	250		ns
t_{LAG}	$\overline{CS}$ lag time	250		ns
t_{WH}	Clock HIGH time	200		ns
t_{WL}	Clock LOW time	200		ns
t_{SU}	Data setup time	50		ns
t_H	Data hold time	50		ns
$t_{RI}^{(4)}$	Data in rise time		2	μs
$t_{FI}^{(4)}$	Data in fall time		2	μs
t_{HD}	$\overline{HOLD}$ setup time	100		ns
t_{CD}	$\overline{HOLD}$ hold time	100		ns
t_{CS}	$\overline{CS}$ deselect time	2.0		μs
$t_{WC}^{(5)}$	Write cycle time		10	ms

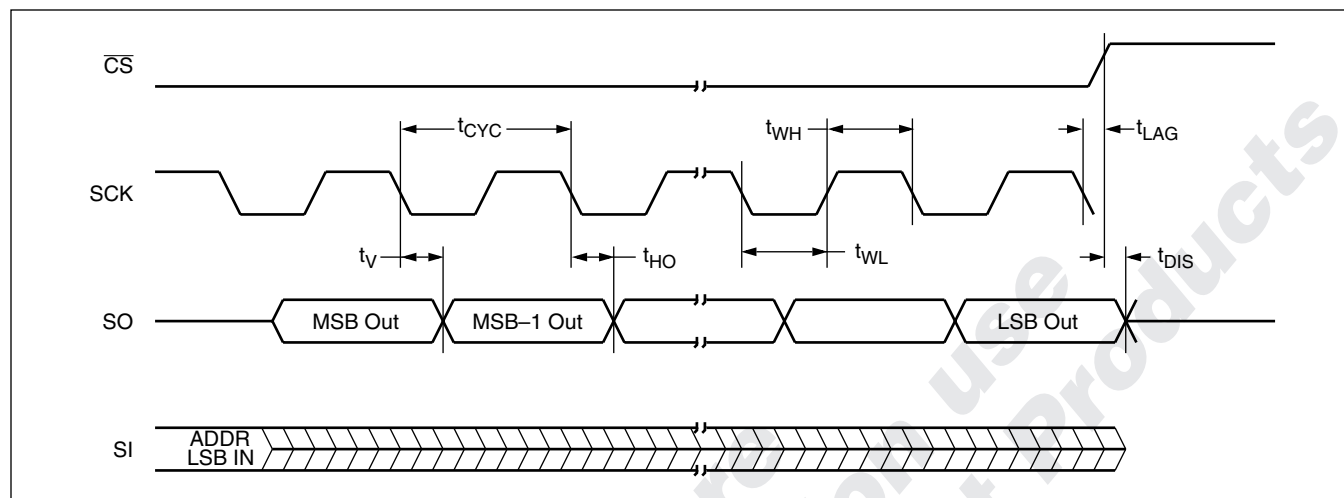
Data Output Timing

Symbol	Parameter	Min.	Max.	Unit
f_{SCK}	Clock frequency	0	2	MHz
t_{DIS}	Output disable time		250	ns
t_V	Output valid from clock LOW		200	ns
t_{HO}	Output hold time	0		ns
$t_{RO}^{(4)}$	Output rise time		100	ns
$t_{FO}^{(4)}$	Output fall time		100	ns
$t_{LZ}^{(4)}$	$\overline{HOLD}$ HIGH to output in low Z	100		ns
$t_{HZ}^{(4)}$	$\overline{HOLD}$ LOW to output in high Z	100		ns

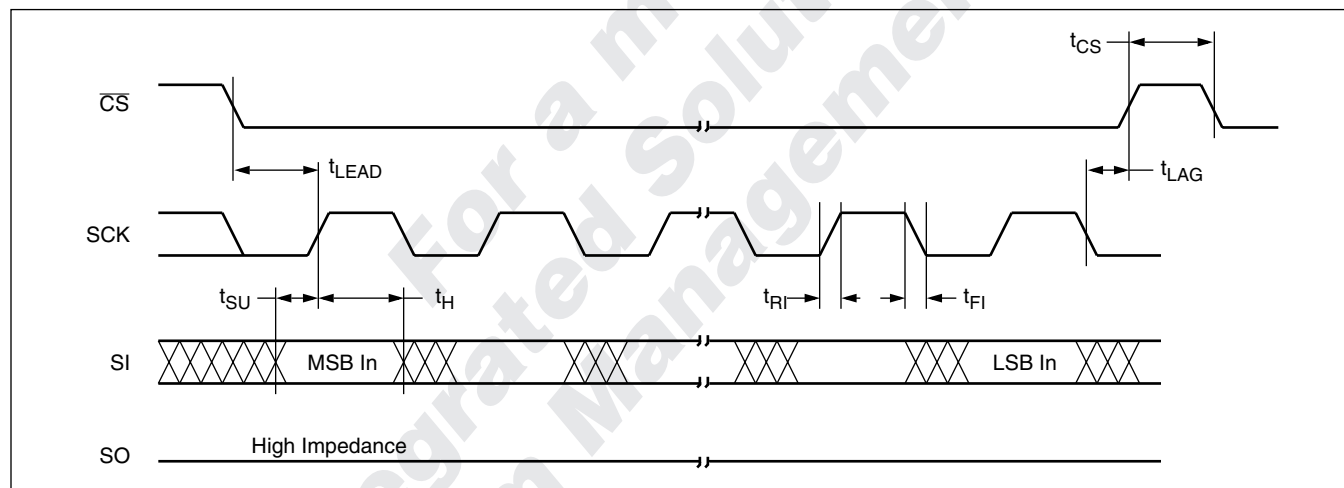
Notes: (4) This parameter is periodically sampled and not 100% tested.

(5) t_{WC} is the time from the rising edge of $\overline{CS}$ after a valid write sequence has been sent to the end of the self-timed internal nonvolatile write cycle.

Serial Output Timing

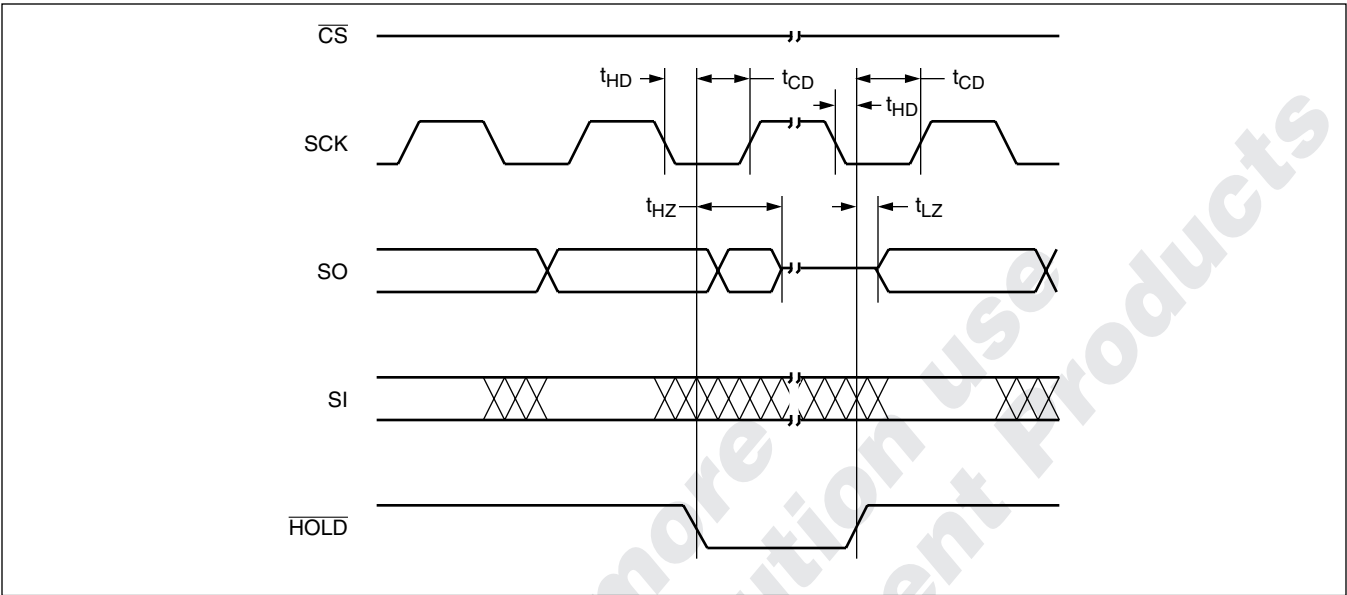


Serial Input Timing



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Hold Timing

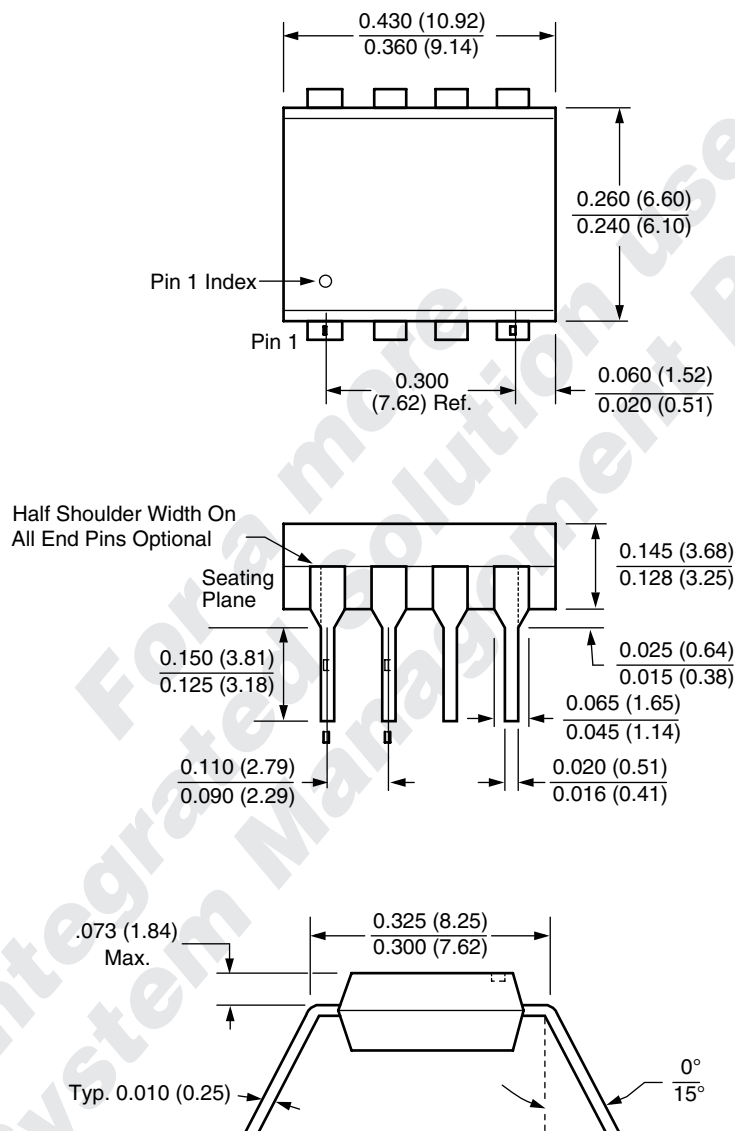


SYMBOL TABLE

WAVEFORM	INPUTS	OUTPUTS
	Must be steady	Will be steady
	May change from LOW to HIGH	Will change from LOW to HIGH
	May change from HIGH to LOW	Will change from HIGH to LOW
	Don't Care: Changes Allowed	Changing: State Not Known
	N/A	Center Line is High Impedance

PACKAGING INFORMATION

8-Lead Plastic Dual In-Line Package Type P

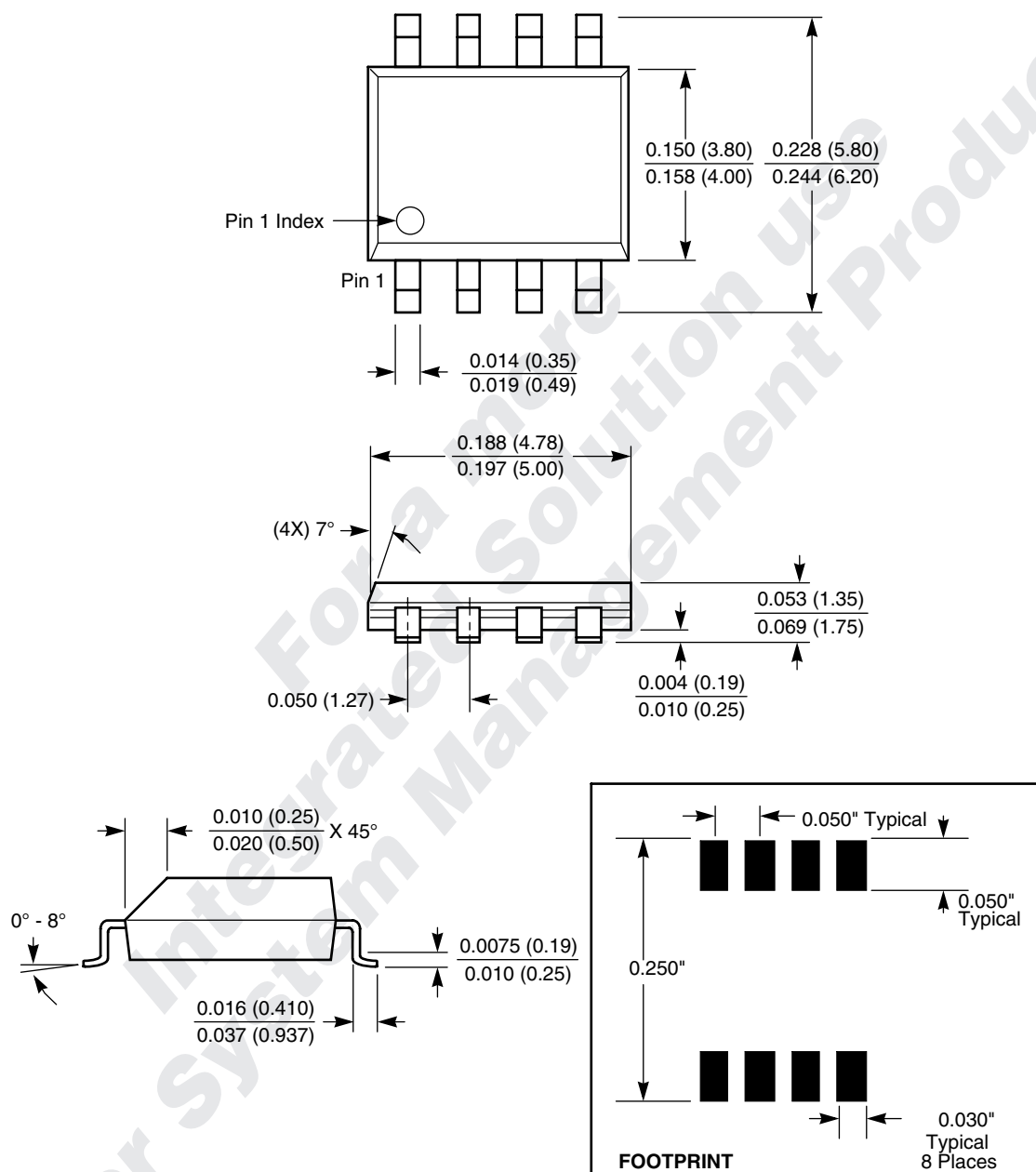


NOTE:

1. ALL DIMENSIONS IN INCHES (IN PARENTHESES IN MILLIMETERS)
2. PACKAGE DIMENSIONS EXCLUDE MOLDING FLASH

PACKAGING INFORMATION

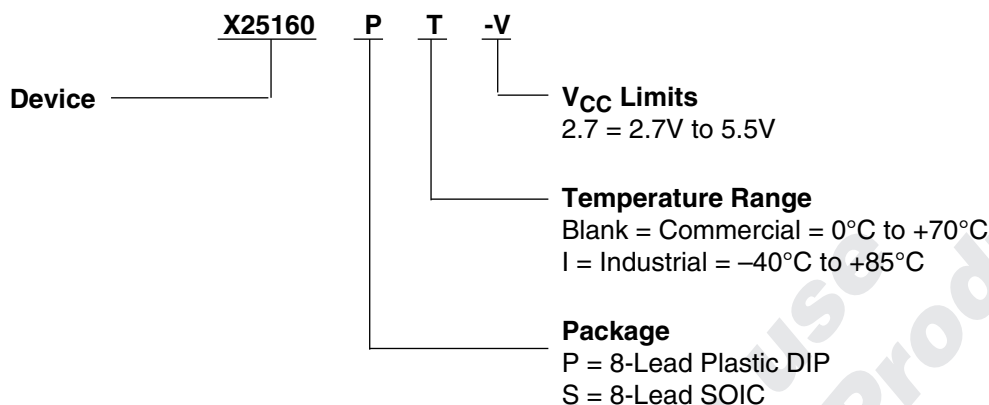
8-Lead Plastic Small Outline Gull Wing Package Type S



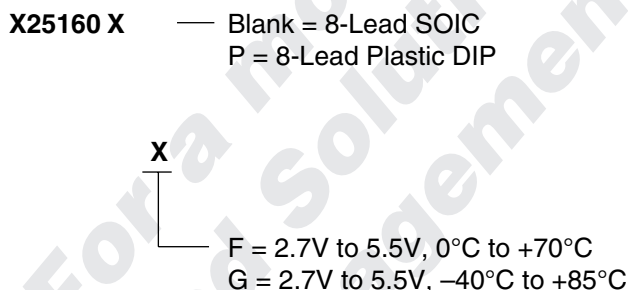
NOTE: ALL DIMENSIONS IN INCHES (IN PARENTHESES IN MILLIMETERS)

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Ordering Information



Part Mark Convention



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LIFE RELATED POLICY

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Xicor's products are not authorized for use in critical components in life support devices or systems.

1. Life support devices or systems are devices or systems which, (a) are intended for surgical implant into the body, or (b) support or sustain life, and whose failure to perform, when properly used in accordance with instructions for use provided in the labeling, can be reasonably expected to result in a significant injury to the user.
2. A critical component is any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.