



June 1997-3

#### **FEATURES**

- Fully Integrated T1 Transceiver
- Low Power Consumption (normally 225mW)
- Recovered Data and Clock Outputs
- Driver Performance Monitor
- Internal Transmit LBO for Line Lengths Between 0 to 655 Feet
- Compliance with TR-TSY-000499, 43802 and 43801
  Input Jitter Tolerance Specifications

#### **APPLICATIONS**

- Interfacing T1 Network Equipment such as Multiplexers, Channel Banks and DSX-1 Switching Systems
- Interfacing Customer Premises Equipment such as CSUs, PBXs, T1 Measurement and Test Equipment

#### **GENERAL DESCRIPTION**

The XR-T5684 is a fully integrated PCM line transceiver intended for DSX-1 digital cross-connect applications. It combines both transmit and receive circuitry in a 28 pin PLCC or PDIP package. The receiver extracts data from AMI coded input signal, and outputs synchronized clock and unipolar RPOS and RNEG data by means of an external 8X or 16X oversampling clock. The oversampling clock is necessary only for applications where the clock recovery

feature is required. The transmitter of the device pre-shapes the transmit pulse internally, providing the appropriate pulse shape at the cross-connect for line lengths ranging from 0 to 655 feet. The XR-T5684 is manufactured using advanced CMOS technology and requires only a single +5V power supply.

#### **ORDERING INFORMATION**

Part No.	Package	Operating Temperature Range
XR-T5684IJ	28 Lead PLCC	-40 to + 85°C
XR-T5684IP	28 Lead 600 Mil PDIP	-40 to + 85°C





#### **BLOCK DIAGRAM**

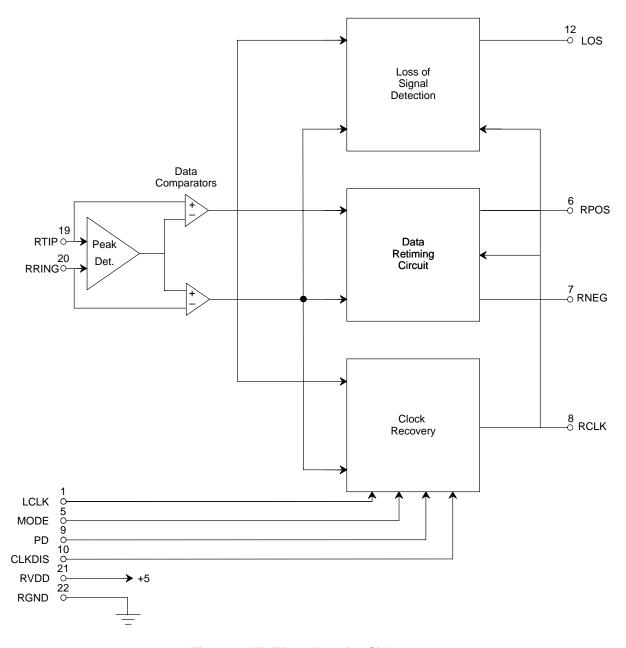


Figure 1. XR-T5684 Receive Side



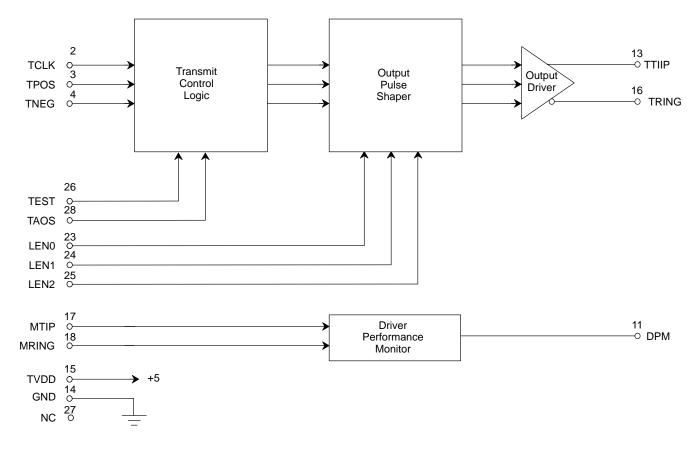
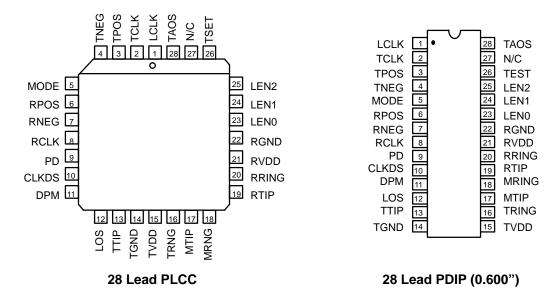


Figure 2. XR-T5684 Transmit Side



#### **PIN CONFIGURATION**



#### **PIN DESCRIPTION**

Pin #	Symbol	Туре	Description
1	LCLK	I	Oversampling Clock. 8X or 16X input clock for receive clock recovery circuit. 8X=12.352MHz±200ppm with pin 9 set to low. 16X=24.704MHz ±200ppm with pin 9 set to high.
2	TCLK	1	Transmit Clock. T1=1.544MHz±50ppm.
3	TPOS	ı	<b>Transmit Positive Data</b> . A positive NRZ data on this pin causes a positive pulse to be transmitted on TTIP. TPOS is sampled on the falling edge of TCLK.
4	TNEG	ı	<b>Transmit Negative Data</b> . A positive NRZ data on this pin causes a negative pulse to be transmitted on TRING. TNEG is sampled on the falling edge of TCLK.
5	MODE	I	Receive Output Data Select. With this pin set to high, the extracted data at RPOS and RNEG are re-timed using the recovered clock RCLK. With this pin set to low, the received data have no relation to RCLK and are typically stretched by 80nS before being sent to the output. This pin is pulled down internally.
6	RPOS	0	<b>Receive Positive Data Output</b> . A positive pulse on this pin corresponds to a positive pulse on RTIP.
7	RNEG	0	<b>Receive Negative Data Output</b> . A positive pulse on this pin corresponds to a positive pulse on RRING.
8	RCLK	0	Receive Clock Output. Recovered clock using oversampling clock applied to pin 1. See MODE select of pin 5 and PD of pin 9.
9	PD	I	<b>Programmable Divider</b> . The state of this pin determines the oversampling clock applied to pin 1. When LCLK=16X1.544MHz, set PD to high. When LCLK=8X1.544MHz, set PD to low. This pin is pulled down internally.
10	CLKDS	ı	<b>Clock Disable</b> . With this pin set to high, the recovered clock at pin 8 is disabled. This function is provided for applications where upon input data loss, the output clock can be inhibited by connecting LOS to CLKDS externally. This pin is pulled down internally.
11	DPM	0	<b>Driver Performance Monitor</b> . Used as an early warning signal on non-functioning T1 links. If no signal is present on MTIP and MRING for 63 clock cycles. DPM goes high until a next pulse is detected.



### PIN DESCRIPTION (CONT'D)

Pin #	Symbol	Туре	Description
12	LOS	0	<b>Loss of Signal.</b> This pin goes high either when the input signal at RTIP and RRING drops to below 0.4V peak or after 175 zeros are detected. The 175 zeros detection is active only when LCLK is applied.
13	TTIP	0	<b>Transmit Positive Data.</b> Transmit AMI signal is driven to the line via a step-up transformer from this pin.
14	TGND		Transmitter Supply Ground. This pin can be connected to RGND externally.
15	TVDD	0	5 V ±5% Transmitter Supply.
16	TRING	0	<b>Transmit Negative Data.</b> Transmit AMI signal is driven to the line via a step-up transformer from this pin.
17	MTIP	I	<b>Driver Performance Monitor Input.</b> This pin is normally connected to TTIP for monitoring the driver's activity. It is pulled high internally.
18	MRING	I	<b>Driver Performance Monitor Input.</b> This pin is normally connected to TRING for monitoring the driver's activity. It is pulled high internally.
19	RTIP	l ı	Receive Tip Input. The AMI receive signal is input to this pin via a centre-tapped transformer.
20	RRING	l ı	Receive Ring Input. The AMI receive signal is input to this pin via a centre-tapped transformer.
21	RVDD		5 V ±5% Receive Supply. This pin can be connected to TVDD externally.
22	RGND		Receive Supply Ground. This pin is also connected to the substrate of the device.
23	LEN0	ı	Pulse Shaper Select Pin. Least significant bit.
24	LEN1	ı	Pulse Shaper Select Pin. Second significant bit.
25	LEN2	ı	Pulse Shaper Select Pin. Most significant bit.
26	TEST	ı	Factory Test Pin. This pin must be grounded for normal operation.
27	N/C		No Connection Pin. This pin can be grounded or left floating.
28	TAOS	I	<b>Transmit All Ones Select.</b> Setting TAOS high causes continuous AMI ones to be transmitted to the line at the frequency set by TCLK.





#### **ELECTRICAL CHARACTERISTICS**

Test Conditions: TA = -40 to + 85  $^{\circ}$ C, RV<sub>DD</sub> and TV<sub>DD</sub> = 5V  $\pm$  5%, RGND and TGND = 0V.

Symbol	Parameter	Min.	Тур.	Max.	Unit	Conditions		
DC ELECTR	DC ELECTRICAL CHARACTERISTICS							
Recommended Operating Conditions								
V <sub>DD</sub> /TV <sub>DD</sub>	DC Supply Voltage	4.75	5	5.25	V			
PD	Total Power Disapation			400	mW	100% ones density & max. line length @ 5.25V and with 16X oversampling clock running.		
PD	Normal Power Dissipation		225		mW	50% ones density & 300 feet line length @5.0V and with over-sampling clock disabled.		
Inputs								
V <sub>IH</sub>	High Level Input <sup>1</sup>	2.0			V			
$V_{IL}$	Low Level Input <sup>1</sup>			0.8	V			
I <sub>IL</sub>	Input Leakage Current			±10	μΑ	Pins = TCLK, TPOS, TNEG, LEN0/1/2.		
Outputs								
V <sub>OH</sub>	High Level Output <sup>2</sup>	2.4			V			
$V_{OL}$	Low Level Output <sup>2</sup>			0.4	V			
Analog Spec	ifications							
VPA	AMI Output Pulse Amplitudes	2.4	3.0	3.6	V	Measured at DSX-1 using a 1:1.36 step up transformer with all line length select as shown in <i>Table 1</i> .		
TXJA	Jitter added by the transmitter							
	10Hz - 40KHz <sup>3</sup>		0.025		UI			
	Broad Band <sup>3</sup>		0.05		UI			
RXS	Receiver Sensitivity Below DSX(0dB=2.4V)	6			dB			
RLOS	Receiver Loss of Signal Threshold		0.4		V			
	Number of Consecutive Zeros before LOS	160	175	190				
RTH	Receiver Data Slicing Threshold		70		% of peak			
AC CHARAC	TERISTICS							
TCLKf	Clock Frequency		1.544		MHz			
	TCLK Clock Duty Cycle	40	50	60	%			
LCLKf	Frequency 8X		12.352		MHz			
LCLKf	16X		24.704		MHz			
	LCLK Clock Tolerance			$\pm$ 200	ppm			
	LCLK Clock Duty Cycle	35	50	65	%			

- <sup>1</sup> All input pins except RTIP, RRING, MTIP and MRING.
- All output pins except TTIP and TRING.
  Input clock to TCLK is jitter free.
  Pin 5 Set to low.





### **ELECTRICAL CHARACTERISTICS (CONT'D)**

Test Conditions: TA = -40 to + 85  $^{\circ}$ C, RV<sub>DD</sub> and TV<sub>DD</sub> = 5V  $\pm$  5%, RGND and TGND = 0V.

Symbol	Parameter	Min.	Тур.	Max.	Unit	Conditions
tsu	TPOS/TNEG to TCLK Setup Time	25			ns	
tho	TCLK to TPOS/TNEG Hold Time	25			ns	
tdr	RTIP/RRING Rising to RPOS/ RNEG Rising <sup>4</sup>	15	30	120	ns	
tdf	RTIP/RRING Falling to RPOS/ RNEG Falling <sup>4</sup>	60	120	250	ns	
	RCLK Duty Cycle		50		%	
tsu	RPOS/RNEG to RCLK Falling Setup Time		300		ns	
tho	RCLK Falling to RPOS/RNEG Hold Time		324		ns	

#### Notes

#### **ABSOLUTE MAXIMUM RATINGS**

Supply Voltage (continuous) .....-0.5V, +7V Supply Current (continuous) ..... 20mA to -20mA Storage Temperature .....-65°C to + 150°C



<sup>&</sup>lt;sup>1</sup> All input pins except RTIP, RRING, MTIP and MRING.

<sup>&</sup>lt;sup>2</sup> All output pins except TTIP and TRING. <sup>3</sup> Input clock to TCLK is jitter free.

<sup>&</sup>lt;sup>4</sup> Pin 5 Set to low.



#### SYSTEM DESCRIPTION

The device consists of receiver and transmitter circuitry with separate power supplies to reduce crosstalk between the two sections.

#### **RECEIVER**

The receiver is sensitive to the entire cable length from the cross-connect and requires no external equalization networks. The receive AMI input signal is applied to RTIP and RRING through a center-grounded transformer. The positive pulse is input to RTIP and the negative pulse is input to RRING.

Comparators are used to slice the data on RTIP and RRING. The slicing level of the comparators are dynamically set at around 70% of peak level of the input signal to ensure optimum signal-to-noise ratio. With Mode Select (pin 5) set to low, the clock recovery feature is bypassed and the output data from the comparators are typically stretched by 80nS before output to RPOS and RNEG respectively.

A positive data at RPOS corresponds to a positive pulse received at RTIP and a positive data at RNEG corresponds to a positive pulse received at RRING.

With Mode Select (pin 5) set to high and an oversampling clock applied to pin 1, the recovered data can be synchronized with RCLK at pin 8. The clock recovery circuit extracts the timing contents from the incoming data transitions by means of an 8X or 16X divider. If there is no data on the input, the divider operates in its free running mode, generating a equal mark-and-space ratio output clock. This free running mode will be interrupted if a positive pulse is detected; the resultant mark-and-space ratio of the output clock is then determined by the position of the occurrence of the positive data relative to its free running position. See timing diagram in *Figure 3* and *Figure 4*.

In all cases, the output data RPOS and RNEG remains stable on the falling edge of RCLK so as to be sampled correctly. The input jitter tolerance with an 8X oversampling clock is shown in *Figure 6* and that with a 16X oversampling clock is shown in *Figure 5*.

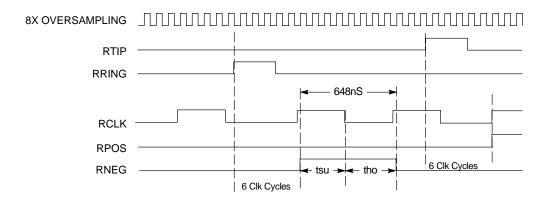


Figure 3. Receiver Clock and Data Switching Characteristics

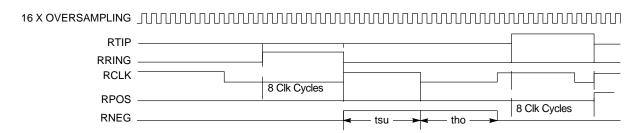


Figure 4. Typical Receive Timing Diagram Using 8X Oversampling Clock.





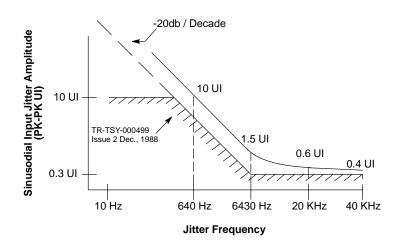


Figure 5. Typical Receive Timing Diagram Using 16X Oversampling Clock

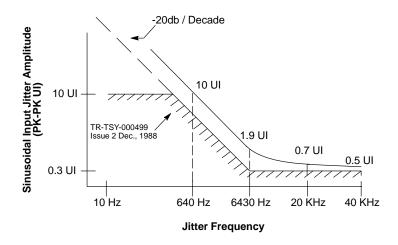


Figure 6. XR-T5684 Input Jitter Tolerance Using 8X Oversampling Clock



Another function of the receiver is the signal quality monitor that reports loss of signal when the input level on RTIP and RRING falls below 0.4V or upon detection of  $175\pm15$  consecutive zeros in the incoming data stream. The zero detection circuit is active only when LCLK clock is applied. In both cases, the receiver reports loss of signal by setting LOS high, and at the same time, RPOS and RNEG are forced to low. Under the loss of signal conditions, the receiver will continue to recover data and will return to its normal operation if a valid data is detected on RTIP and RRING.

#### **TRANSMITTER**

The transmitter is designed to take dual rail NRZ data, plus a synchronized input clock and produces a bipolar signal with the appropriate shape for transmission to the line.

After sampling by the falling edge of TCLK, TPOS and TNEG data are processed by a digital to analog converter together with a slew-control circuit to generate output pulses at TTIP and TRING with the appropriate amplitude and shape to meet the cross-connect template specified in CB 119. A typical output pulse is shown in *Figure 7*. In order to meet the amplitude requirement with a single +5V supply, the transmit signal is driven to the line differentially via a 1:1.36 step-up transformer.

Pulse shaping is selectable through input control pins LEN2, LEN1 and LEN0 for line lengths ranging from 0 to 655 feet of ABAM cable as illustrated in *Table 1*.

LEN2	LEN1	LEN0	Line Length Selected (ft.)
0	1	1	0 - 133
1	0	0	133 - 266
1	0	1	266 - 399
1	1	0	399 - 533
1	1	1	533 - 655

Table 1. ABAM or ALVYN Cable Type Line Length Selection

The transmitter can be set to transmit a continuous AMI encoded all ones signal to the line by forcing TAOS high. In this mode, input data TPOS and TNEG are ignored and the frequency of the transmitted signal is determined by TCLK.

With TTIP connected to MTIP and TRING connected to MRING, the driver monitor can detect a non-functional T1 transmitter by monitoring the activity at its input. If no signal is presented on MTIP and MRING for 63 TCLK clock cycles, DPM goes high until the next AMI signal is detected.

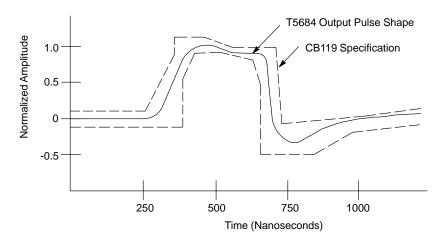


Figure 7. Receiver Clock and Data Switching Characteristics



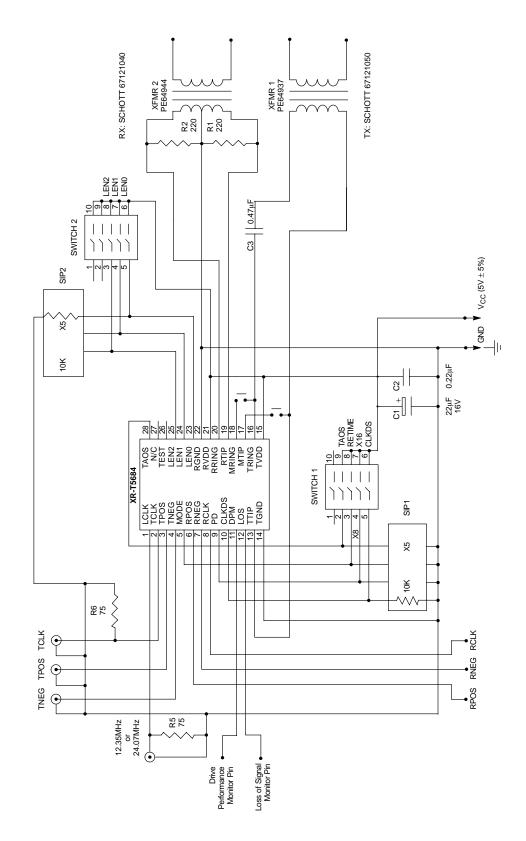


Figure 1. Application Schematic Diagram

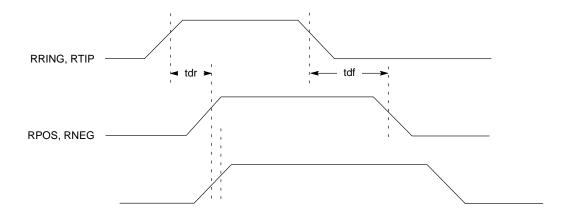


Figure 2. Receiver Clock and Data Switching Characteristics

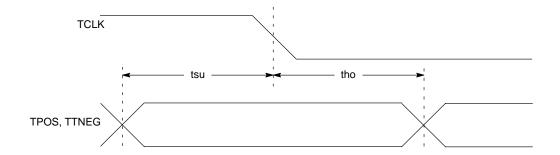
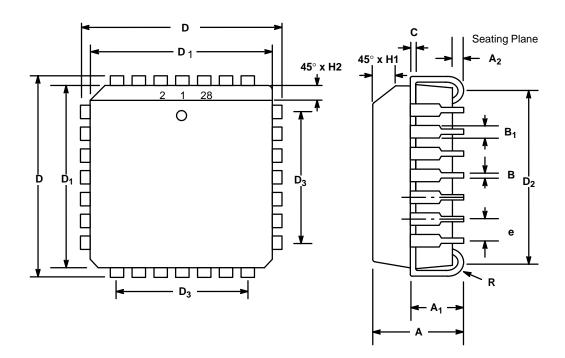


Figure 3. Receiver Clock and Data Switching Characteristics



## 28 LEAD PLASTIC LEADED CHIP CARRIER (PLCC)

Rev. 1.00



	INC	CHES	MILLI	MILLIMETERS		
SYMBOL	MIN	MAX	MIN	MAX		
Α	0.165	0.180	4.19	4.57		
A <sub>1</sub>	0.090	0.120	2.29	3.05		
A <sub>2</sub>	0.020	—.	0.51			
В	0.013	0.021	0.33	0.53		
B <sub>1</sub>	0.026	0.032	0.66	0.81		
С	0.008	0.013	0.19	0.32		
D	0.485	0.495	12.32	12.57		
D <sub>1</sub>	0.450	0.456	11.43	11.58		
D <sub>2</sub>	0.390	0.430	9.91	10.92		
D <sub>3</sub>	0.3	00 typ.	7.6	2 typ.		
е	0.0	50 BSC	1.2	7 BSC		
H1	0.042	0.056	1.07	1.42		
H2	0.042	0.048	1.07	1.22		
R	0.025	0.045	0.64	1.14		

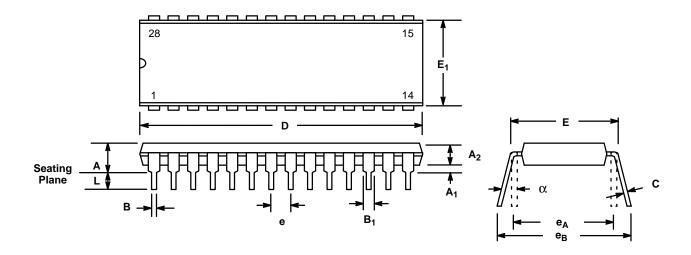
Note: The control dimension is the inch column





# 28 LEAD PLASTIC DUAL-IN-LINE (600 MIL PDIP)

Rev. 1.00



	INC	HES	MILLIN	METERS
SYMBOL	MIN	MAX	MIN	MAX
Α	0.160	0.250	4.06	6.35
A <sub>1</sub>	0.015	0.070	0.38	1.78
A <sub>2</sub>	0.125	0.195	3.18	4.95
В	0.014	0.024	0.36	0.56
B <sub>1</sub>	0.030	0.070	0.76	1.78
С	0.008	0.014	0.20	0.38
D	1.380	1.565	35.05	39.75
Е	0.600	0.625	15.24	15.88
E <sub>1</sub>	0.485	0.580	12.32	14.73
е	0.10	0 BSC	2.5	4 BSC
e <sub>A</sub>	0.60	00 BSC	15.2	24 BSC
e <sub>B</sub>	0.600	0.700	15.24	17.78
L	0.115	0.200	2.92	5.08
α	0°	15°	0°	15°

Note: The control dimension is the inch column





### **Notes**





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