

# UTCAN6651 LINEAR INTEGRATED CIRCUIT

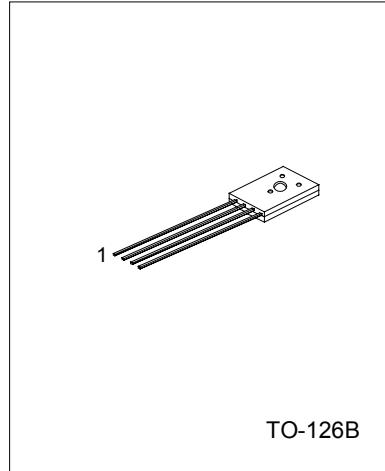
## MOTOR SPEED CONTROL CIRCUIT

### DESCRIPTION

The UTC AN6651 is a monolithic integrated circuit designed for the rotating control of a compact DC motor which is used for a tape recorder, recorder player etc.

### FEATURES

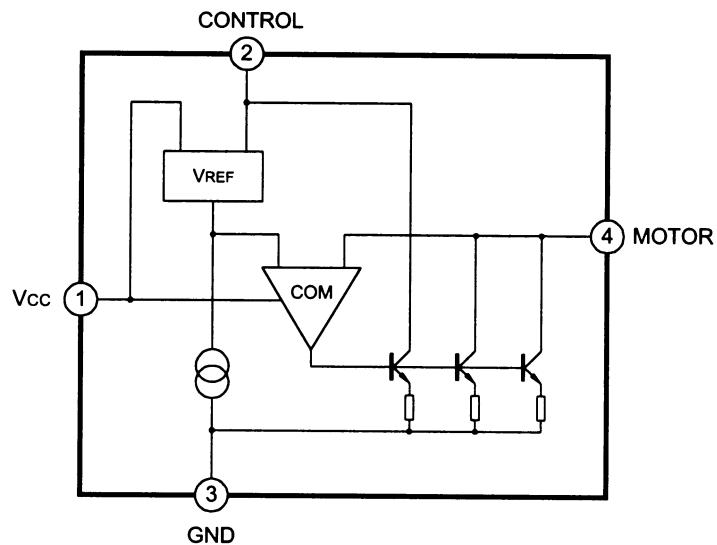
- \*Wide operating supply voltage:  $V_{CC}=3.5V \sim 14.4V$
- \*Small four-lead plastic packer for compact motor.
- \*Few external components
- \*Stable low reference voltage (1.0V, typical)
- \*Wide motor speed setting
- \*Reverse voltage protection circuit built-in



TO-126B

1: V<sub>CC</sub> 2: CONTROL 3: GND 4: MOTOR

### BLOCK DIAGRAM



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## ABSOLUTE MAXIMUM RATINGS ( $T_a=25^\circ\text{C}$ )

PARAMETER	SYMBOL	VALUE	UNIT
Supply Voltage	$V_{CC}$	14.4	V
Supply Current (note 1)	$I_{CC}$	2000	mA
Power Dissipation ( $T_a=25^\circ\text{C}$ ) (note 2)	$P_D$	1300	mW
Operating Temperature	$T_{OPR}$	-20 to +75	$^\circ\text{C}$
Storage Temperature	$T_{STG}$	-40 to +150	$^\circ\text{C}$
Terminal Voltage	$V_{n-3}$ (n=1,2,4)	-0.5 to +14.4	V
Terminal Current	$I_1$	150	mA
Terminal Current	$I_2$	100	mA
Terminal Current (note 1)	$I_3$	-2000 (MIN.)	mA
Terminal Current (note 1)	$I_4$	1750	mA

Note 1:  $t \leq 5$  sec

Note 2:  $T_a=25^\circ\text{C}$ , with a 10 x 10 mm bakelite PCB (3.5 $\mu\text{m}$  Cu leaf)

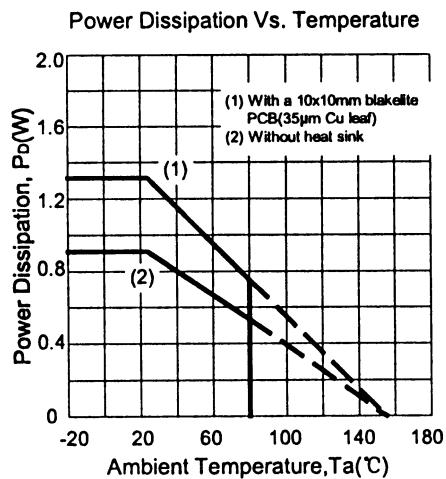
## ELECTRICAL CHARACTERISTICS ( $T_a=25^\circ\text{C}$ , unless otherwise specified)

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Reference Voltage	$V_{ref}$	$V_{CC}=6\text{V}$ , $R_a=1\text{k}\Omega$	0.85	1.00	1.15	V
Base Current	$I_{bias}$	$V_{CC}=6\text{V}$		0.8	1.8	mA
Current Proportional Constant	K	$V_{CC}=6\text{V}$ , $\Delta I_4=40\text{mA}$	35	40	45	
Saturation Voltage	$V_{SAT}$	$V_{CC}=4.2\text{V}$ , $R_a=5.0\Omega$		1.15	2.0	V
Voltage Characteristics 1	$\frac{\Delta V_{REF}}{V_{REF}}$ $\Delta V_{CC}$	$V_{CC}=3.5\text{V} \sim 14\text{V}$ $R_a=1\text{k}\Omega$		-0.1		%/V
Voltage Characteristics 2	$\frac{\Delta K}{K}$ $\Delta V_{CC}$	$V_{CC}=3.5\text{V} \sim 14\text{V}$ $\Delta I_4=40\text{mA}$		0.2		%/V
Current Characteristics 1	$\frac{\Delta V_{REF}}{V_{REF}}$ $\Delta I_4$	$I_4=50\text{mA} \sim 200\text{mA}$		-0.02		%/mA
Current Characteristics 2	$\frac{\Delta K}{K}$ $\Delta I_4$	$I_4=50\text{mA} \sim 200\text{mA}$		-0.01		%/mA
Temperature Characteristics 1	$\frac{\Delta V_{REF}}{V_{REF}}$ $\Delta T_a$	$T_a=-20 \sim +75^\circ\text{C}$ $V_{CC}=6\text{V}$ $R_a=1\text{k}\Omega$		0.01		%/ $^\circ\text{C}$

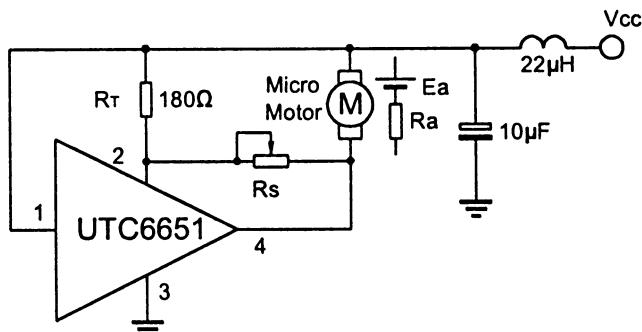
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PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Temperature Characteristics 2	$\frac{\Delta K}{K}$ $\Delta T_a$	$T_a = -20 \sim +75^\circ C$ $\Delta I_4 = 40mA$		0.01		%/ $^\circ C$

## CHARACTERISTICS CURVE



## APPLICATION CIRCUIT



Motor Constant:

Ka-- Electromotive force constant=1.1mV/rpm

Ra-- Internal Resistor=5Ω

Kτ=Torque Constant=100g.cm/A