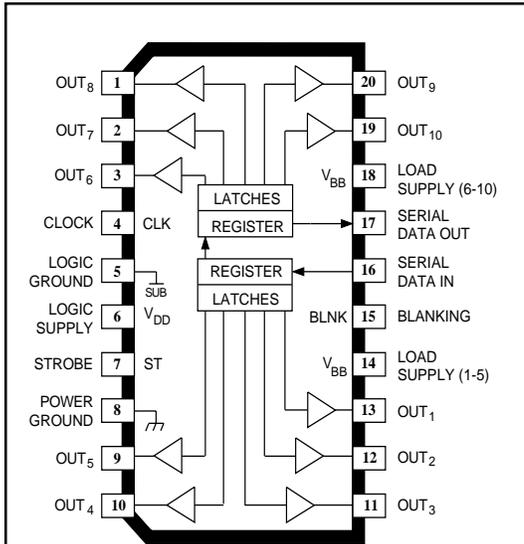


5910

HIGH-VOLTAGE BiMOS III 10-BIT SERIAL-INPUT, LATCHED DRIVERS



Dwg. PP-029-14

Note that the dual in-line package (designator 'A') and small-outline IC package (designator 'LW') are electrically identical and share a common terminal number assignment.

ABSOLUTE MAXIMUM RATINGS at $T_A = 25^\circ\text{C}$

| | |
|--|----------------------------|
| Logic Supply Voltage, V_{DD} | 15 V |
| Driver Supply Voltage, V_{BB} | |
| UCN5910A/LW | 150 V |
| Suffix "-2" | 140 V |
| Continuous Output Current Range, | |
| I_{OUT} | -30 mA to +40 mA |
| Input Voltage Range, | |
| V_{IN} | -0.3 V to $V_{DD} + 0.3$ V |
| Package Power Dissipation, P_D . See Graph | |
| Operating Temperature Range, | |
| T_A | -20°C to +85°C |
| Storage Temperature Range, | |
| T_S | -55°C to +150°C |

Caution: CMOS devices have input static protection but are susceptible to damage when exposed to extremely high static electrical charges.

The UCN5910x combines a 10-bit CMOS shift register and accompanying data latches, control circuitry, high-voltage bipolar sourcing outputs with DMOS active pull-downs. Designed primarily to drive ink-jet and piezoelectric printers, large flat-panel vacuum-fluorescent or ac plasma displays, the 140 V or 150 V and ± 50 mA output ratings also allow these devices to be used in many other peripheral power driver applications. The lower-cost (suffix "-2") devices are identical to the basic devices except for output voltage rating.

The CMOS shift register and latches allow direct interfacing with micro-processor-based systems. With a 5 V logic supply, serial-data input rates are typically over 5 MHz, with significantly higher speeds obtainable at 12 V. Use with TTL may require appropriate pull-up resistors to ensure an input logic high.

A CMOS serial data output enables cascade connections in applications requiring additional drive lines. Similar devices for up to 60-volt operation are available in 10, 12, 20, and 32-bit configurations.

The UCN5910A/LW output source drivers are npn Darlington transistors capable of sourcing at least 40 mA. The DMOS active pull-downs are capable of sinking at least 30 mA. For inter-digit blanking, all of the output drivers can be disabled and the DMOS sink drivers turned ON by the BLANKING input high.

The UCN5910A and UCN5910A-2 are furnished in a 20-pin dual in-line plastic package. The surface-mount UCN5910LW and UCN5910LW-2 are furnished in a wide-body, small-outline plastic package (SOIC) with gull-wing leads. Copper lead frames, reduced supply current requirements, and lower output saturation voltages allow all devices to be operated at ± 20 mA from all outputs (50% duty cycle), at ambient temperatures up to +30°C, or at ± 15 mA to +55°C.

FEATURES

- High-Speed Source Drivers
- 140 V (suffix "-2") or 150 V Minimum Output Breakdown
- Improved Replacements for TL4810B
- Low Output Saturation Voltages
- Low-Power CMOS Logic and Latches
- To 3.3 MHz Data Input Rate
- Active DMOS Pull-Downs

PRELIMINARY INFORMATION

(Subject to change without notice)

January 18, 2000

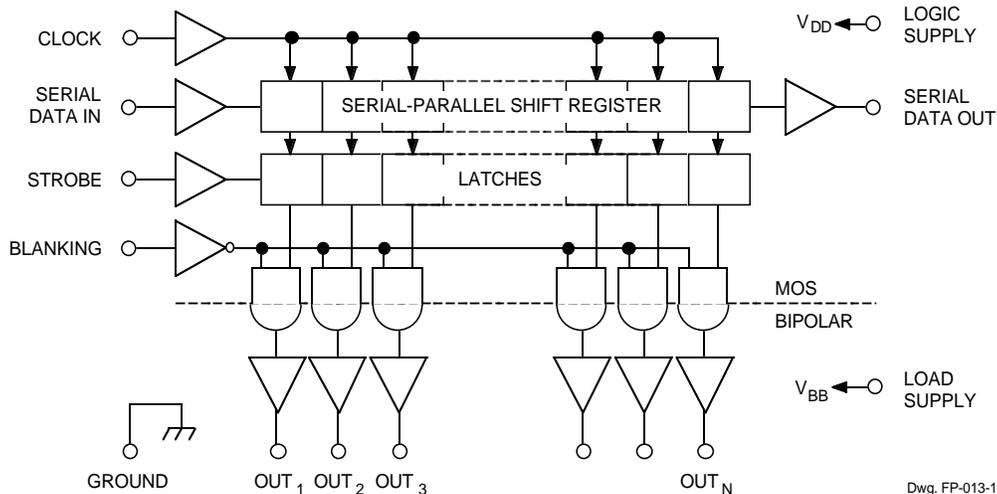
Always order by complete part number, e.g., **UCN5910A-2**.

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HIGH-VOLTAGE BiMOS III

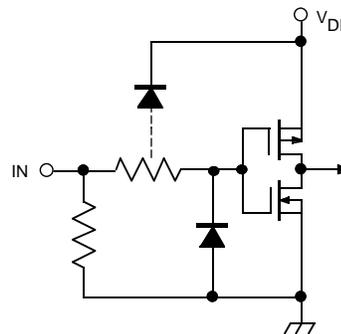
10-BIT SERIAL-INPUT, LATCHED DRIVERS

FUNCTIONAL BLOCK DIAGRAM

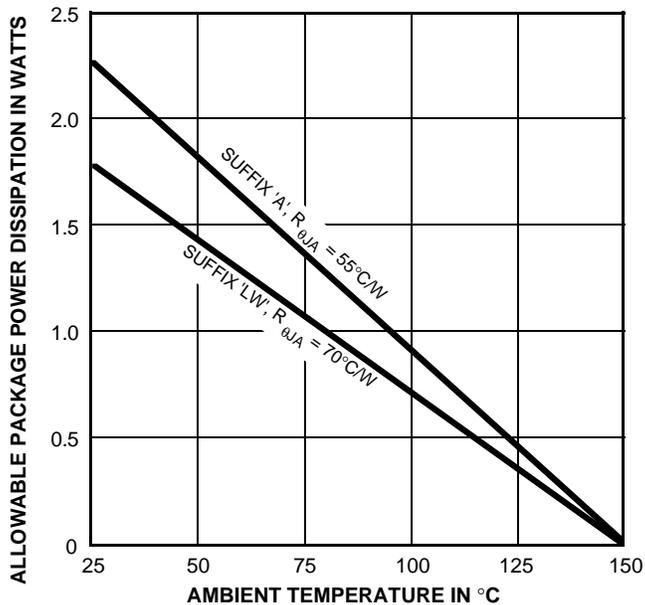


Dwg. FP-013-1

TYPICAL INPUT CIRCUIT

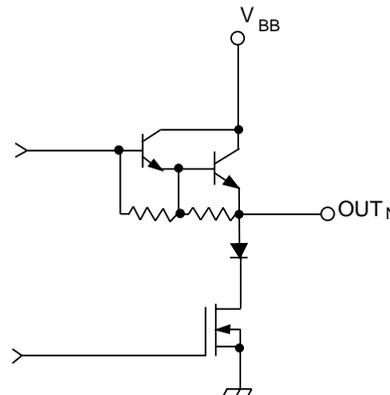


Dwg. EP-010-4A



Dwg. GS-004A

TYPICAL OUTPUT DRIVER



Dwg. No. A-14,219



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10-BIT SERIAL-INPUT,
LATCHED DRIVERS

ELECTRICAL CHARACTERISTICS at $T_A = +25^\circ\text{C}$, $V_{BB} = 150\text{ V}$ (basic devices) or 140 V (suffix “-2”) unless otherwise noted.

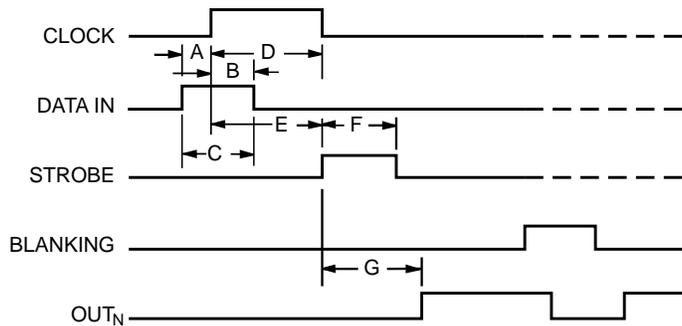
| Characteristic | Symbol | Test Conditions | Limits @ $V_{DD} = 5\text{ V}$ | | | Limits @ $V_{DD} = 12\text{ V}$ | | | Units |
|----------------------------|--------------|--|--------------------------------|------|------|---------------------------------|------|------|---------------|
| | | | Min. | Typ. | Max. | Min. | Typ. | Max. | |
| Output Leakage Current | I_{CEX} | $V_{OUT} = 0\text{ V}$, $T_A = +70^\circ\text{C}$ | – | -5.0 | -15 | – | -5.0 | -15 | μA |
| Output Voltage | $V_{OUT(1)}$ | Basic, $I_{OUT} = -40\text{ mA}$ | 145 | 148 | – | 145 | 148 | – | V |
| | | Suffix “-2”, $I_{OUT} = -40\text{ mA}$ | 135 | – | – | 135 | – | – | V |
| | $V_{OUT(0)}$ | $I_{OUT} = 5\text{ mA}$ | – | 2.5 | 3.2 | – | 2.0 | 3.2 | V |
| | | $I_{OUT} = 10\text{ mA}$ | – | 5.0 | – | – | – | – | V |
| | | $I_{OUT} = 30\text{ mA}$ | – | – | – | – | 12 | 25 | V |
| Output Pull-Down Current | $I_{OUT(0)}$ | $V_{OUT} = 5\text{ V}$ to V_{BB} | 10 | 14 | – | – | – | – | mA |
| | | $V_{OUT} = 20\text{ V}$ to V_{BB} | – | – | – | 25 | 40 | – | mA |
| Input Voltage | $V_{IN(1)}$ | | 3.5 | – | 5.3 | 10.5 | – | 12.3 | V |
| | $V_{IN(0)}$ | | -0.3 | – | +0.8 | -0.3 | – | +0.8 | V |
| Input Current | $I_{IN(1)}$ | $V_{IN} = V_{DD}$ | – | 0.05 | 0.5 | – | 0.05 | 1.0 | μA |
| | $I_{IN(0)}$ | $V_{IN} = 0.8\text{ V}$ | -0.3 | – | -0.8 | -0.3 | – | -0.8 | μA |
| Serial Data Output Voltage | $V_{OUT(1)}$ | $I_{OUT} = -200\text{ }\mu\text{A}$ | 4.5 | 5.0 | – | 11.7 | 12 | – | V |
| | $V_{OUT(0)}$ | $I_{OUT} = 200\text{ }\mu\text{A}$ | – | 200 | 250 | – | 200 | 250 | mV |
| Maximum Clock Frequency | f_{clk} | | 3.3 | 5.0 | – | 5.0 | – | – | MHz |
| Supply Current | $I_{DD(1)}$ | All Outputs High | – | 320 | 450 | – | 650 | 800 | μA |
| | $I_{DD(0)}$ | All Outputs Low | – | 320 | 450 | – | 650 | 800 | μA |
| | $I_{BB(1)}$ | Outputs High, No Load | – | 0.6 | 1.75 | – | 0.9 | 1.75 | mA |
| | $I_{BB(0)}$ | Outputs Low | – | 10 | 100 | – | 10 | 100 | μA |
| Blanking to Output Delay | t_{PHL} | $C_L = 30\text{ pF}$, 50% to 50% | – | 0.7 | 0.9 | – | 0.35 | 0.6 | μs |
| | t_{PLH} | $C_L = 30\text{ pF}$, 50% to 50% | – | 0.9 | 1.3 | – | 0.35 | 0.6 | μs |
| Output Fall Time | t_f | $C_L = 30\text{ pF}$, 90% to 10% | – | 1.3 | 1.5 | – | 0.6 | 0.7 | μs |
| Output Rise Time | t_r | $C_L = 30\text{ pF}$, 10% to 90% | – | 1.2 | 1.5 | – | 1.0 | 1.2 | μs |

Negative current is defined as coming out of (sourcing) the specified device terminal.

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HIGH-VOLTAGE BiMOS III

10-BIT SERIAL-INPUT, LATCHED DRIVERS



Dwg. No. A-12,649A

TIMING CONDITIONS

($T_A = +25^\circ\text{C}$, $V_{DD} = 12\text{ V}$, Logic Levels are V_{DD} and Ground)

- A. Minimum Data Active Time Before Clock Pulse
(Data Set-Up Time) **75 ns**
- B. Minimum Data Active Time After Clock Pulse
(Data Hold Time) **75 ns**
- C. Minimum Data Pulse Width **150 ns**
- D. Minimum Clock Pulse Width **100 ns**
- E. Minimum Time Between Clock Activation and Strobe **300 ns**
- F. Minimum Strobe Pulse Width **100 ns**
- G. Typical Time Between Strobe Activation and
Output Transition **750 ns**

Serial Data present at the input is transferred to the shift register on the logic "0" to logic "1" transition of the CLOCK input pulse. On succeeding CLOCK pulses, the registers shift data information towards the SERIAL DATA OUTPUT. The SERIAL DATA must appear at the input prior to the rising edge of the CLOCK input waveform.

Information present at any register is transferred to the respective latch when the STROBE is high (serial-to-parallel conversion). The latches will continue to accept new data as long as the STROBE is held high. Applications where the latches are bypassed (STROBE tied high) will require that the BLANKING input be high during serial data entry.

When the BLANKING input is high, the output source drivers are disabled (OFF); the DMOS sink drivers are ON. The information stored in the latches is not affected by the BLANKING input. With the BLANKING input low, the outputs are controlled by the state of their respective latches.

TRUTH TABLE

| Serial Data Input | Clock Input | Shift Register Contents | | | | | | Serial Data Output | Strobe Input | Latch Contents | | | | | | Blanking | Output Contents | | | | | |
|-------------------|-------------|-------------------------|----------------|----------------|-----|------------------|------------------|--------------------|--------------|----------------|----------------|----------------|-----|------------------|----------------|----------|-----------------|----------------|----------------|-----|------------------|----------------|
| | | I ₁ | I ₂ | I ₃ | ... | I _{N-1} | I _N | | | I ₁ | I ₂ | I ₃ | ... | I _{N-1} | I _N | | I ₁ | I ₂ | I ₃ | ... | I _{N-1} | I _N |
| H | ┌ | H | R ₁ | R ₂ | ... | R _{N-2} | R _{N-1} | R _{N-1} | | | | | | | | | | | | | | |
| L | ┐ | L | R ₁ | R ₂ | ... | R _{N-2} | R _{N-1} | R _{N-1} | | | | | | | | | | | | | | |
| X | └ | R ₁ | R ₂ | R ₃ | ... | R _{N-1} | R _N | R _N | | | | | | | | | | | | | | |
| | | X | X | X | ... | X | X | X | L | R ₁ | R ₂ | R ₃ | ... | R _{N-1} | R _N | | | | | | | |
| | | P ₁ | P ₂ | P ₃ | ... | P _{N-1} | P _N | P _N | H | P ₁ | P ₂ | P ₃ | ... | P _{N-1} | P _N | L | | | | | | |
| | | | | | | | | | | X | X | X | ... | X | X | H | L | L | L | ... | L | L |

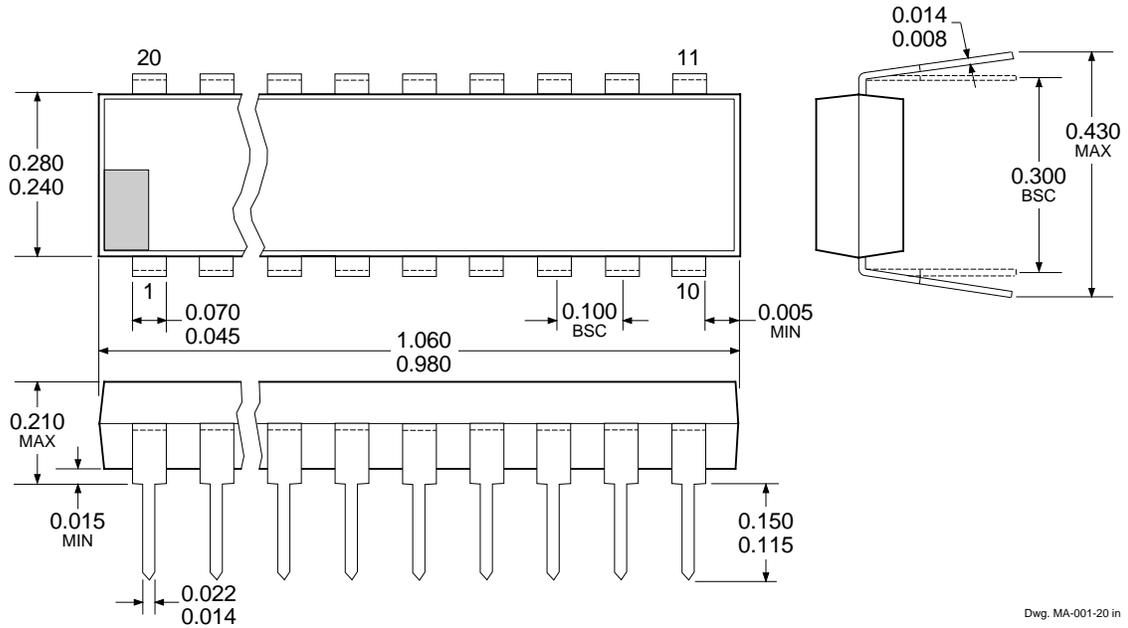
L = Low Logic Level H = High Logic Level X = Irrelevant P = Present State R = Previous State



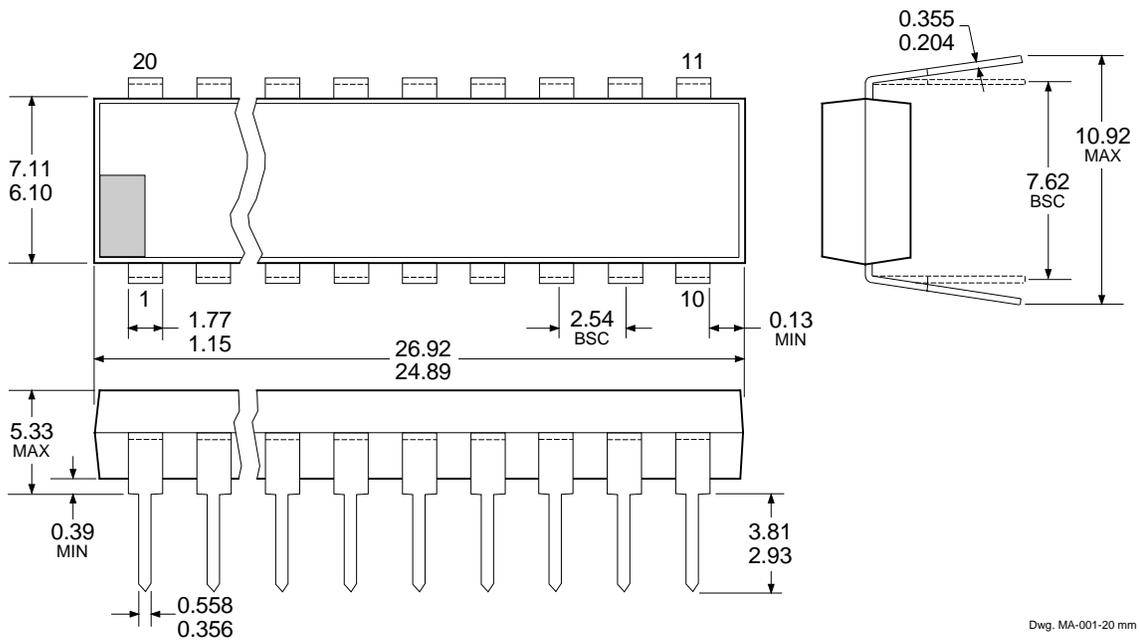
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HIGH-VOLTAGE BiMOS III
10-BIT SERIAL-INPUT,
LATCHED DRIVERS

UCN5910A & UCN5910A-2

Dimensions in Inches
 (controlling dimensions)



Dimensions in Millimeters
 (for reference only)

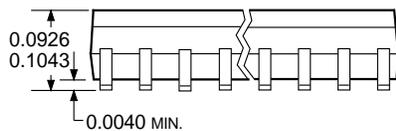
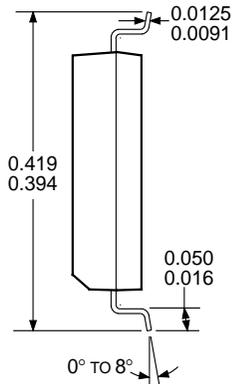
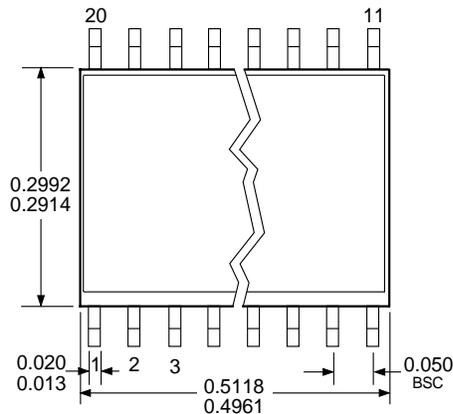


- NOTES: 1. Exact body and lead configuration at vendor's option within limits shown.
 2. Lead spacing tolerance is non-cumulative.
 3. Lead thickness is measured at seating plane or below.

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10-BIT SERIAL-INPUT,
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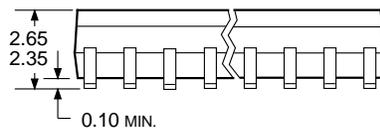
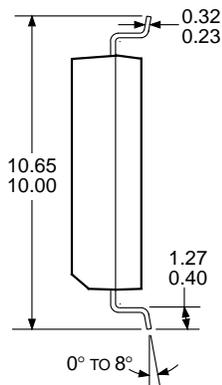
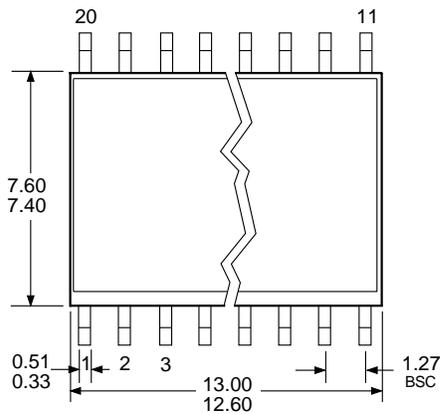
UCN5910LW & UCN5910LW-2

Dimensions in Inches
 (for reference only)



Dwg. MA-008-20 in

Dimensions in Millimeters
 (controlling dimensions)



Dwg. MA-008-20 mm

- NOTES: 1. Exact body and lead configuration at vendor's option within limits shown.
 2. Lead spacing tolerance is non-cumulative.



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HIGH-VOLTAGE BiMOS III
10-BIT SERIAL-INPUT,
LATCHED DRIVERS

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5910
HIGH-VOLTAGE BiMOS III
10-BIT SERIAL-INPUT,
LATCHED DRIVERS

***BiMOS II (Series 5800), BiMOS III (Series 5900),
 & DABiC IV (Series 6800) INTELLIGENT POWER
 INTERFACE DRIVERS***

| Function | Output Ratings* | | Part Number† |
|--|-----------------|-------|--------------------|
| SERIAL-INPUT LATCHED DRIVERS | | | |
| 8-Bit (saturated drivers) | -120 mA | 50 V‡ | 5895 |
| 8-Bit | 350 mA | 50 V | 5821 |
| 8-Bit | 350 mA | 80 V | 5822 |
| 8-Bit | 350 mA | 50 V‡ | 5841 |
| 8-Bit | 350 mA | 80 V‡ | 5842 |
| 8-Bit (constant-current LED driver) | 75 mA | 17 V | 6275 |
| 9-Bit | 1.6 A | 50 V | 5829 |
| 10-Bit (active pull-downs) | -25 mA | 60 V | 5810-F and 6809/10 |
| 10-Bit (active pull-downs) | -40 mA | 140 V | 5910-2 |
| 10-Bit (active pull-downs) | -40 mA | 150 V | 5910 |
| 12-Bit (active pull-downs) | -25 mA | 60 V | 5811 and 6811 |
| 16-Bit (constant-current LED driver) | 75 mA | 17 V | 6276 |
| 20-Bit (active pull-downs) | -25 mA | 60 V | 5812-F and 6812 |
| 32-Bit (active pull-downs) | -25 mA | 60 V | 5818-F and 6818 |
| 32-Bit | 100 mA | 30 V | 5833 |
| 32-Bit (saturated drivers) | 100 mA | 40 V | 5832 |
| PARALLEL-INPUT LATCHED DRIVERS | | | |
| 4-Bit | 350 mA | 50 V‡ | 5800 |
| 8-Bit | -25 mA | 60 V | 5815 |
| 8-Bit | 350 mA | 50 V‡ | 5801 |
| SPECIAL-PURPOSE DEVICES | | | |
| Unipolar Stepper Motor Translator/Driver | 1.25 A | 50 V‡ | 5804 |
| Addressable 28-Line Decoder/Driver | 450 mA | 30 V | 6817 |

* Current is maximum specified test condition, voltage is maximum rating. See specification for sustaining voltage limits. Negative current is defined as coming out of (sourcing) the output.

† Complete part number includes additional characters to indicate operating temperature range and package style.

‡ Internal transient-suppression diodes included for inductive-load protection.

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