

CMOS 16-Bit Microcontrollers

TMP95PS54F

1. Outline and Features

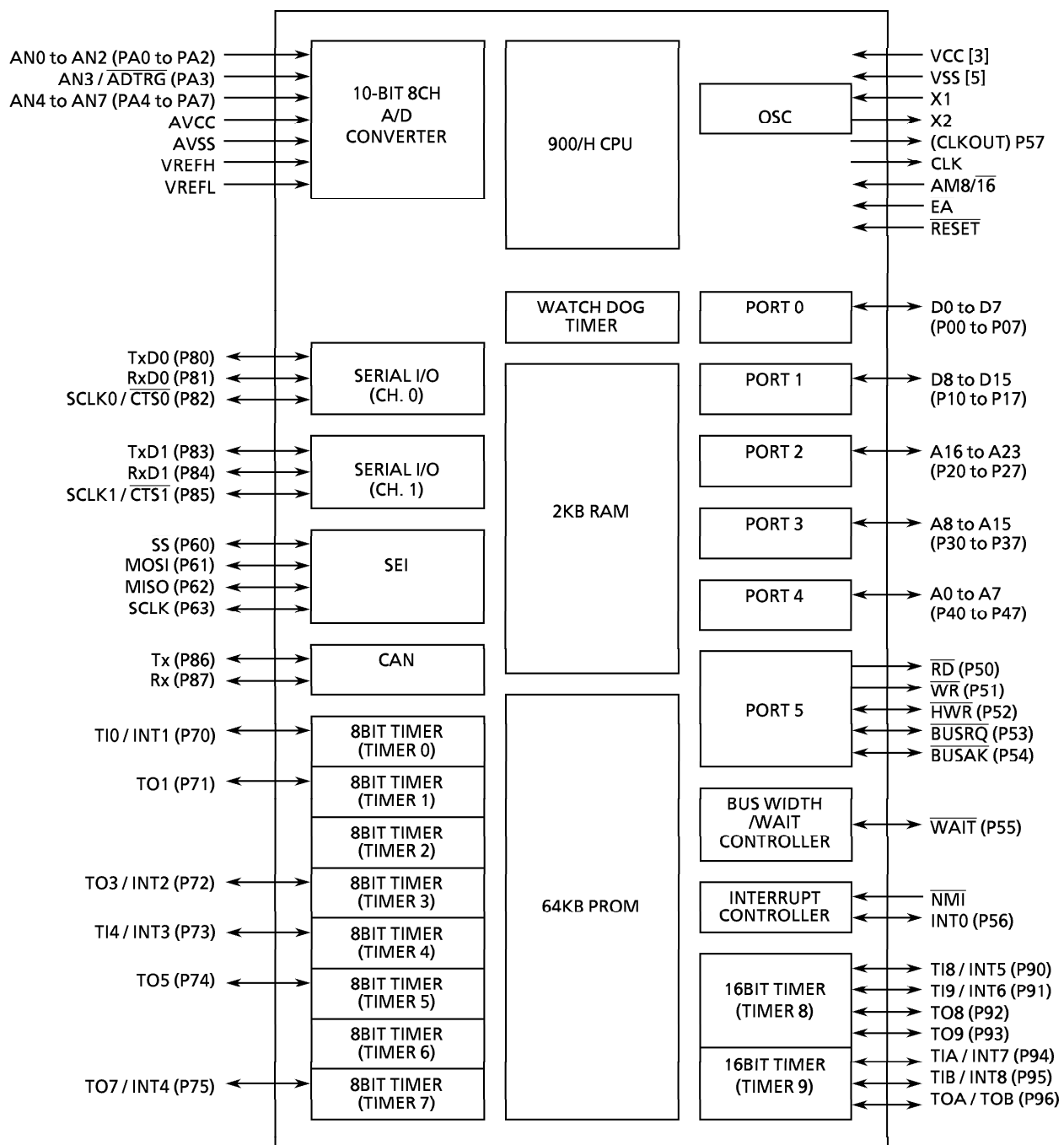
TMP95PS54 is an LSI for TMP95CS54 system evaluation. TMP95PS54 incorporates a 64 Kbyte one-time PROM. With an adapter socket, the user can write/verify data in the TMP95PS54's PROM using a general-purpose EPROM writer.

TMP95PS54 is pin-compatible with TMP95CS54, which incorporates a mask ROM. To achieve the same operations as TMP95CS54, write program data to the internal PROM.

Product Name	ROM	RAM	Package	Adapter Socket
TMP95PS54F	OTP 64 Kbyte	2 Kbyte	LQFP100-P-1414-0.50D	BM11129

980910EBP1

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Note: After reset, functions in parentheses () are selected for the shared pins.

Figure 1 TMP95PS54 Block Diagram

2. Pin Assignment and Pin Functions

This section shows the TMP95PS54F pin assignment, and the names and an outline of the functions of the input/output pins.

2.1 Pin Assignment Diagram

Figure 2.1 is a pin assignment diagram for TMP95PS54F.

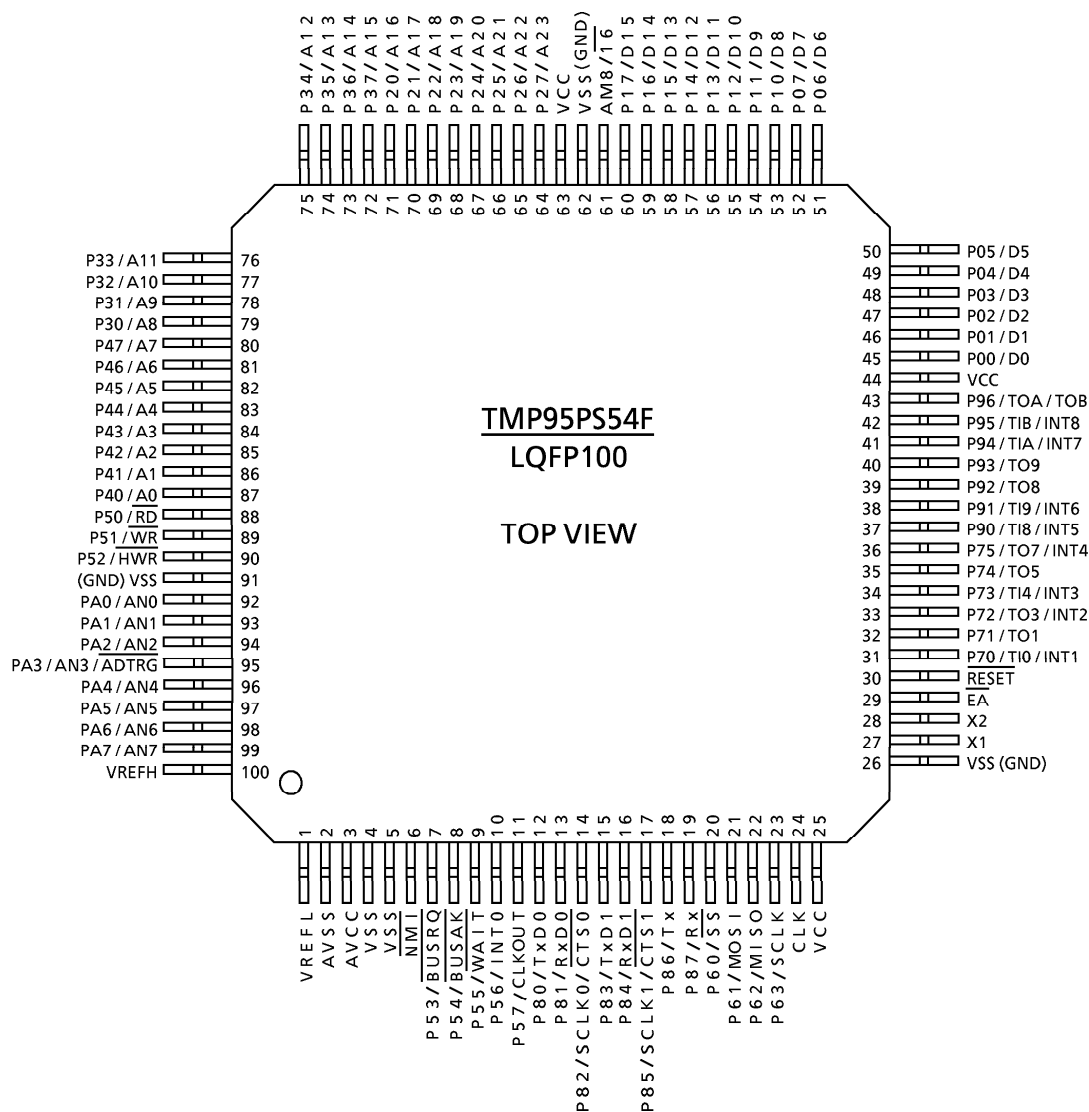


Figure 2.1 Pin Allocation Diagram (100-Pin LQFP)

2.2 Pin Names and Functions

TMP95PS54 has an MCU mode and a PROM mode.

(1) Pin Names and Functions in MCU Mode

Table 2.2 (1) lists the names and functions of the input/output pins.

Table 2.2 Pin Names and Functions (1/4)

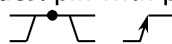
Pin Name	Number of Pins	Input/Output	Function
P00 to P07 / D0 to D7	8	Input/output	Port 0: I/O port. Input or output specifiable in units of bits
		Input/output	Data: Data bus 0 to 7
P10 to P17 / D8 to D15	8	Input/output	Port 1: I/O port. Input or output specifiable in units of bits
		Input/output	Data: Data bus 8 to 15
P20 to P27 / A16 to A23	8	Input/output	Port 2: I/O port. Input or output specifiable in units of bits
		Output	Address: Address bus 16 to 23
P30 to P37 / A8 to A15	8	Input/output	Port 3: I/O port. Input or output specifiable in units of bits
		Output	Address: Address bus 8 to 15
P40 to P47 / A0 to A7	8	Input/output	Port 4: I/O port. Input or output specifiable in units of bits
		Output	Address: Address bus 0 to 7
P50 / $\overline{\text{RD}}$	1	Output	Port 50: Output-only port
		Output	Read: Outputs strobe signal to read external memory (setting P5 <P50> = 0 and P5FC <P50F> = 1 outputs strobe signal at all read timings)
P51 / $\overline{\text{WR}}$	1	Output	Port 51: Output-only port.
		Output	Write: Outputs strobe signal to write data on pins D0 to D7
P52 / $\overline{\text{HWR}}$	1	Input/output	Port 52: I/O port (with built-in pull-up resistor)
		Output	Upper write: Outputs strobe signal to write data on pins D8 to D15
P53 / $\overline{\text{BUSRQ}}$	1	Input/output	Port 53: I/O port (with built-in pull-up resistor)
		Input	Bus request: Input pin to request external bus release
P54 / $\overline{\text{BUSAK}}$	1	Input/output	Port 54: I/O port (with built-in pull-up resistor)
		Output	Bus acknowledge: Output pin to acknowledge that CPU received $\overline{\text{BUSRQ}}$ and released external bus.
P55 / $\overline{\text{WAIT}}$	1	Input/output	Port 55: I/O port (with built-in pull up resistor)
		Input	Wait: Bus wait request pin for CPU (Effective when 1 WAIT + N mode, or 0 + N WAIT mode. Set using bus width/wait control register.)
P56 / INT0	1	Input/output	Port 56: I/O port (with built-in pull-up resistor)
		Input	Interrupt request pin 0: Interrupt request pin with programmable level/rising edge. 

Table 2.2 Pin Names and Functions (2/4)

Pin Name	Number of Pins	Input/Output	Function
P57 / CLKOUT	1	Output	Port 57: Output-only port (with built-in pull-up resistor)
		Output	CLKOUT output: Outputs external clock divided by 6. Pulled up during reset.
P60 / SS	1	Input/output	Port 60: I/O port
		Input	SEI slave select input
P61 / MOSI	1	Input/output	Port 61: I/O port
		Input/output	SEI master output, slave input
P62 / MISO	1	Input/output	Port 62: I/O port
		Input/output	SEI master input, slave output
P63 / SCLK	1	Input/output	Port 63: I/O port
		Input/output	SEI clock input/output
P70 / TI0 / INT1	1	Input/output	Port 70: I/O port
		Input	Timer input 0: Input pin for timer 0
		Input	Interrupt request pin 1: Rising-edge interrupt request pin 
P71 / TO1	1	Input/output	Port 71: I/O port.
		Output	Timer output 1: Output pin for timer 0 or 1
P72 / TO3 / INT2	1	Input/output	Port 72: I/O port
		Output	Timer output 3: Output pin for timer 2 or 3
		Input	Interrupt request pin 2: Rising-edge interrupt request pin 
P73 / TI4 / INT3	1	Input/output	Port 73: I/O port
		Input	Timer input 4: Input pin for timer 4
		Input	Interrupt request pin 3: Rising-edge interrupt request pin 
P74 / TO5	1	Input/output	Port 74: I/O port
		Output	Timer output 5: Output pin for timer 4 or 5
P75 / TO7 / INT4	1	Input/output	Port 75: I/O port
		Output	Timer output 7: Output pin for timer 6 or 7
		Input	Interrupt request pin 4: Rising-edge interrupt request pin 
P80 / TxD0	1	Input/output	Port 80: I/O port (with built-in pull-up resistor)
		Output	Serial transmission data 0
P81 / RxD0	1	Input/output	Port 81: I/O port (with built-in pull-up resistor)
		Input	Serial receive data 0
P82 / SCLK0 / $\overline{\text{CTS0}}$	1	Input/output	Port 82: I/O port (with built-in pull-up resistor)
		Input/output	Serial clock input/output 0
		Input	Serial data ready to send 0 (Clear-to-send)

Table 2.2 Pin Names and Functions (3/4)

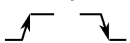
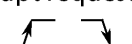
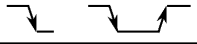
Pin Name	Number of Pins	Input/Output	Function
P83 / TxD1	1	Input/output	Port 83: I/O port (with built-in pull-up resistor)
		Output	Serial transmission data 1
P84 / RxD1	1	Input/output	Port 84: I/O port (with built-in pull-up resistor)
		Input	Serial receive data 1
P85 / SCLK1 / CTS1	1	Input/output	Port 85: I/O port (with built-in pull-up resistor)
		Input/output	Serial clock input/output 1
		Input	Serial data ready to send 1 (Clear-to-send)
P86 / Tx	1	Input/output	Port 86: I/O port (with built-in pull-up resistor)
		Output	CAN transmission data
P87 / Rx	1	Input/output	Port 87: I/O port (with built-in pull-up resistor)
		Input	CAN receive data
P90 / TI8 / INT5	1	Input/output	Port 90: I/O port
		Input	Timer input 8: Input pin for timer 8
		Input	Interrupt request pin 5: Interrupt request pin with programmable rising/falling edge 
P91 / TI9 / INT6	1	Input/output	Port 91: I/O port
		Input	Timer input 9: Input pin for timer 8
		Input	Interrupt request pin 6: Rising edge interrupt request pin 
P92 / TO8	1	Input/output	Port 92: I/O port
		Output	Timer output 8: Output pin for timer 8
P93 / TO9	1	Input/output	Port 93: I/O port
		Output	Timer output 9: Output pin for timer 8
P94 / TIA / INT7	1	Input/output	Port 94: I/O port
		Input	Timer input A: Input pin for timer 9
		Input	Interrupt request pin 7: Interrupt request pin with programmable rising/falling edge 
P95 / TIB / INT8	1	Input/output	Port 95: I/O port
		Input	Timer input B: Input pin for timer 9
		Input	Interrupt request pin 8: Rising edge interrupt request pin 
P96 / TOA / TOB	1	Input/output	Port 96: I/O port
		Output	Timer output A: Output pin for timer 9
		Output	Timer output B: Output pin for timer 9
PA0 to PA2 / AN0 to AN2	3	Input	Port A0 to A2: Input-only port
		Input	Analog input 0 to 2: A/D converter input pins
PA3 / AN3 / ADTRG	1	Input	Port A3: Input-only port
		Input	Analog input 3: A/D converter input pin
		Input	External start trigger

Table 2.2 Pin Names and Functions (4/4)

Pin Name	Number of Pins	Input/Output	Function
PA4 to PA7 / AN4 to AN7	4	Input	Port A4 to A7: Input-only port
		Input	Analog input 4 to 7: A/D converter input pins
$\overline{\text{NMI}}$	1	Input	Non-maskable interrupt request pin: Interrupt request pin with programmable falling edge or both falling and rising edge 
CLK	1	Output	Clock output: Outputs external clock divided by 4. Pulled up during reset.
$\overline{\text{EA}}$	1	Input	External access: Connect to VCC.
AM8 / $\overline{\text{T6}}$	1	Input	Address mode: External data bus width select pin Connect this pin to VCC. Data bus width at external access can be set by bus width / wait control register.
$\overline{\text{RESET}}$	1	Input	Reset: Initializes TMP95PS54 (with built-in pull-up resistor)
VREFH	1	Input	Reference voltage input pin for A/D converter (high)
VREFL	1	Input	Reference voltage input pin for A/D converter (low)
AVCC	1		Power supply pin for A/D converter: Connect to power supply
AVSS	1		GND pin for A/D converter: Connect to GND
X1 / X2	2	Input/output	Oscillator connecting pin
VCC	3		Power supply pin: Connect all VCC pins to power supply
VSS	5		GND pin: Connect all VSS pins to GND (0V)

Note: Software can be used to turn off the resistance of pull-up pins with resistors (except for the $\overline{\text{RESET}}$ pin).

(2) PROM Mode Pin Functions and Pin Processing

Tables 2.2 (2) and (3) show the names and functions of the input/output pins, and the pin processing.

Table 2.2 (2) Pin Names and Functions

Pin Function Name	Number of Pins	Input/Output	Function	Pin Name (In MCU Mode)
A7 to A0	8	Input	Program memory address input	P20 to P27
A15 to A8	8			P17 to P10
A16	1			P34
D7 to D0	8	Input/output	Program memory data input/output	P07 to P00
$\overline{CE}$	1	Input	Chip enable input	P35
$\overline{OE}$	1	Input	Output control input	P37
$\overline{PGM}$	1	Input	Program control input	P36
VPP	1	Power supply	12.75 V / 5 V (program power supply)	$\overline{EA}$
VCC	4	Power supply	6.25 V / 5 V	VCC, AVCC
VSS	6	Power supply	0 V	VSS, AVSS

Table 2.2 (3) Pin Names and Pin Processing

Pin Name	Number of Pins	Input/Output	Pin Processing
P33	1	Input	Fixed to low level (SECURITY pin)
RESET	1	Input	Fixed to low level (set to PROM mode)
CLK	1	Input	
X1	1	Input	Connect oscillator and set to self-oscillation
X2	1	Output	
P32 to P30 P47 to P40 P56 to P52 P63 to P60 P75 to P70 P87 to P80 P96 to P90 PA7 to PA0 AM8/16 NMI	51	Input	Fixed to high level
P57, P51, P50	3	Output	Open
VREFH	1	Input	
VREFL	1		

3. Operation

The following describes the structure and operation of the TMP95PS54 hardware.

In TMP95PS54, the internal ROM of TMP95CS54 is replaced by an internal PROM. Otherwise, TMP95PS54 is structurally and operationally identical to TMP95CS54. Accordingly, for functions not described here, see the TMP95CS54 section of the manual. TMP95PS54 supports MCU operating mode and PROM operating mode.

3.1 MCU Mode

(1) Setting and function

Opening the CLK pin (setting to output) sets MCU mode.

In MCU mode, TMP95PS54 operates the same as TMP95CS54.

(2) Memory map

Figure 3.1 shows the memory map in MCU mode and the CPU access area in each addressing mode.

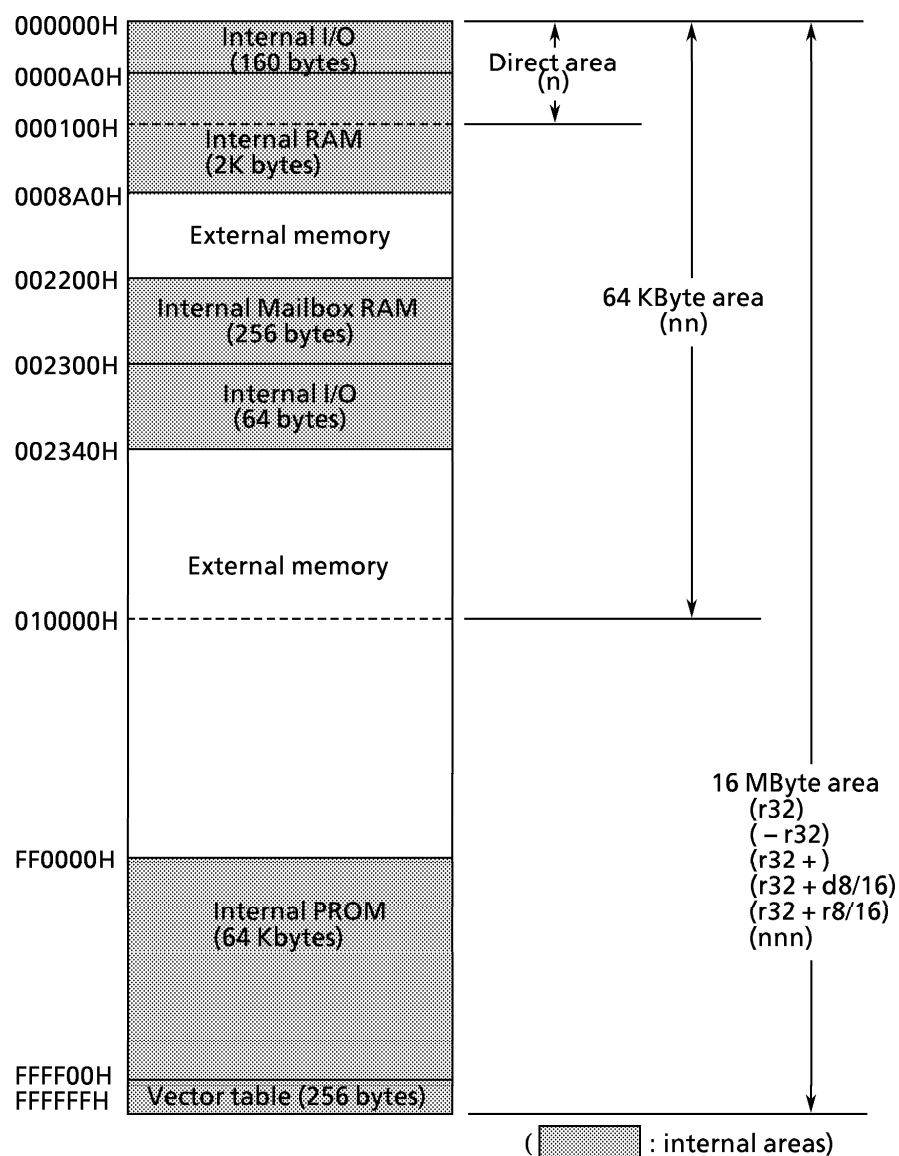


Figure 3.1 TMP95PS54 Memory Map

3.2 PROM Mode

(1) Setting and functions

To set PROM mode, set the $\overline{\text{RESET}}$ and CLK pins to low level.

After PROM mode is set, applying $V_{CC} = 6.25 \text{ V}$ and $V_{PP} = 12.75 \text{ V}$ enters program mode. PROM can be verified by setting $V_{CC} = V_{PP} = 5.0 \text{ V}$.

Programs can be written and verified using a general-purpose PROM writer and an adapter socket. Set the ROM type in the general-purpose PROM writer according to the following conditions. (Set the ROM type as equivalent to TC571000D).

- Size : 1 Mbit (128 K $\times$ 8 bit)
- V_{PP} : 12.75 V
- TPW : 0.1 ms
- Electric signature function : No

Figure 3.2 (1) shows the pin settings in PROM mode.

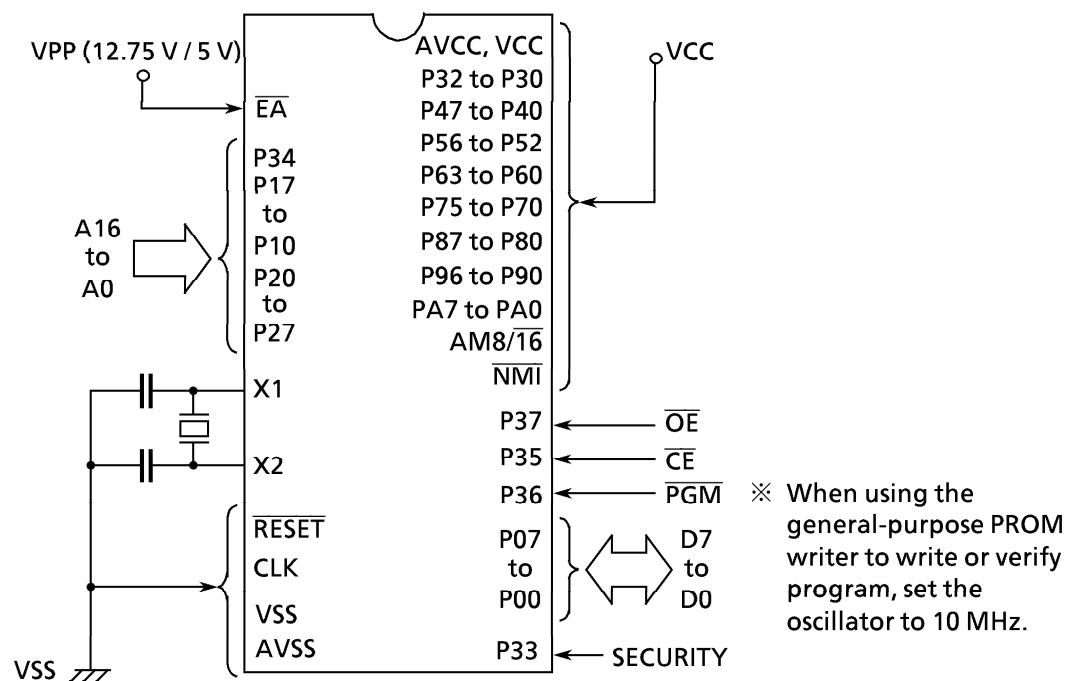


Figure 3.2 (1) PROM Mode Pin Settings

Electric Signature Cautions

TMP95PS54 does not support electric signature mode (hereafter called a signature). When a signature is used by a PROM writer, TMP95PS54 is damaged because 12 V ($\pm 0.5 \text{ V}$) is applied to address pin 9 (A9). Therefore, use with the signature mode set off.

(2) Memory map

The internal PROM addresses in PROM mode are 00000H to 0FFFFH. These correspond to MCU mode addresses FF0000H to FFFFFFFH.

Figure 3.2 (2) shows a comparison of the MCU and PROM mode memory maps.

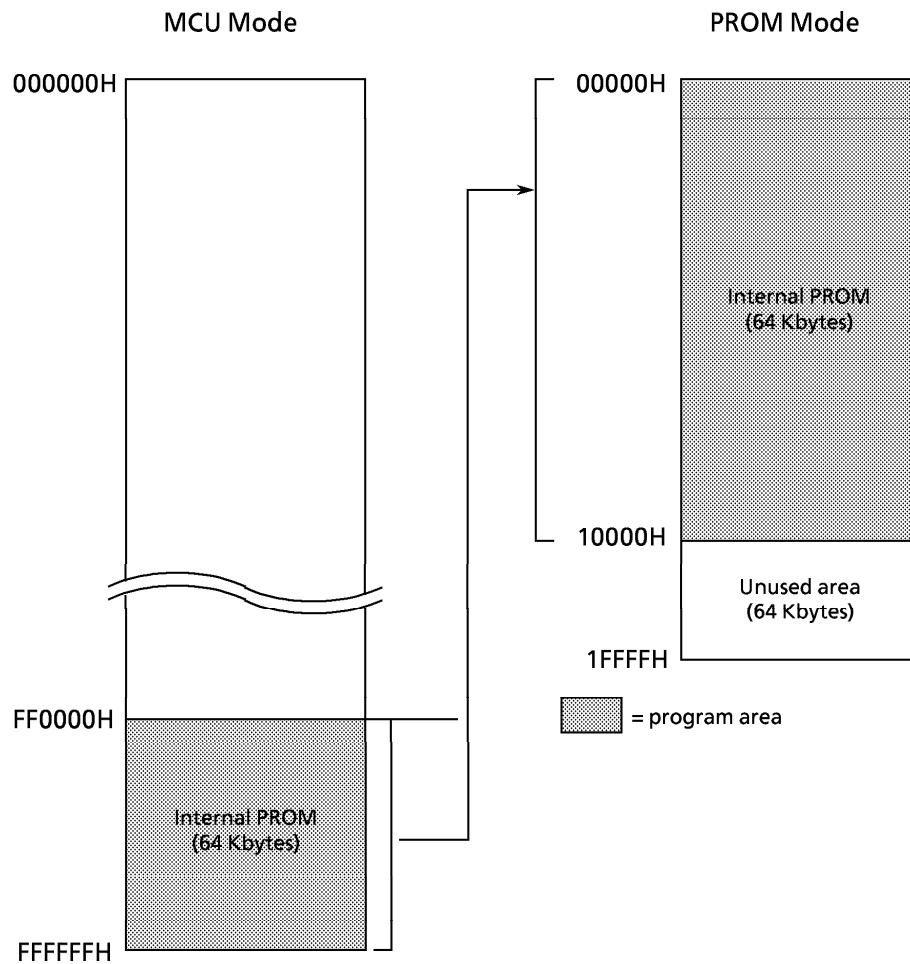


Figure 3.2 (2) Memory Map Comparison

(3) Program mode

When TMP95PS54 is delivered, all bits are set to 1 (erased). Accordingly, program operations write 0 to the necessary bits. To enable writing, apply $V_{PP}=12.75\text{ V}$, $\overline{OE}=V_{IH}$, $\overline{CE}=V_{IL}$.

The internal one-time PROM can be written to in any order, or may be written only at specified addresses.

(4) Adaptor socket (BM11129)

BM11129 is an adapter socket used to write data to the internal one-time PROM in TMP95PS54 using a general-purpose PROM writer.

(5) Settings for writing program using general-purpose PROM writer

Use a PROM writer equivalent to the TC571000D PROM writer.

1. Set BM11129 (hereafter called the adapter) switch (SW1) to the program side (NOR). (Note 1)
2. Set TMP95PS54F to the adapter socket. (Note 2)
3. Set the adapter socket to the PROM writer. (Note 2)
4. Set the PROM writer PROM type to TC571000D.
5. Set the PROM write start address to 0000H and the end address to FFFFH. (Note 3)
6. Write to the internal one-time PROM and verify according to the PROM writer operating procedure.

Note 1 : Writing data to the internal one-time PROM without setting the adapter switch (SW1) to the program side damages the device.

Note 2 : Adaptor socket pin 1 should be aligned with PROM writer socket pin 1.
Setting the two the wrong way round will damage the MCU or PROM writer.

Note 3 : If data are written to addresses exceeding end address FFFFH, the data may be written to the 0000H to FFFFH addresses and program content may be damaged.

(6) High-speed programming method

To enter program mode, apply $V_{PP} = 12.75\text{ V}$ of program voltage with $V_{CC} = 6.25\text{ V}$ and the $\overline{\text{RESET}}$ and CLK pins at low level input.

Input valid address and input data, and set $\overline{\text{CE}}$ to low level input. Data can be written by applying a 0.1ms program (single) pulse to the PGM input. Verify that data are written to each address. If data are not correctly written, again apply a 0.1ms program pulse, repeating this procedure (up to 25 times) until the data are correctly written. After that, write data in the same way, simply changing the addresses and the input data. When all writing is complete, set $V_{CC} = V_{PP} = 5\text{ V}$ and verify all addresses.

Figure 3.2 (3) shows a writing flow chart.

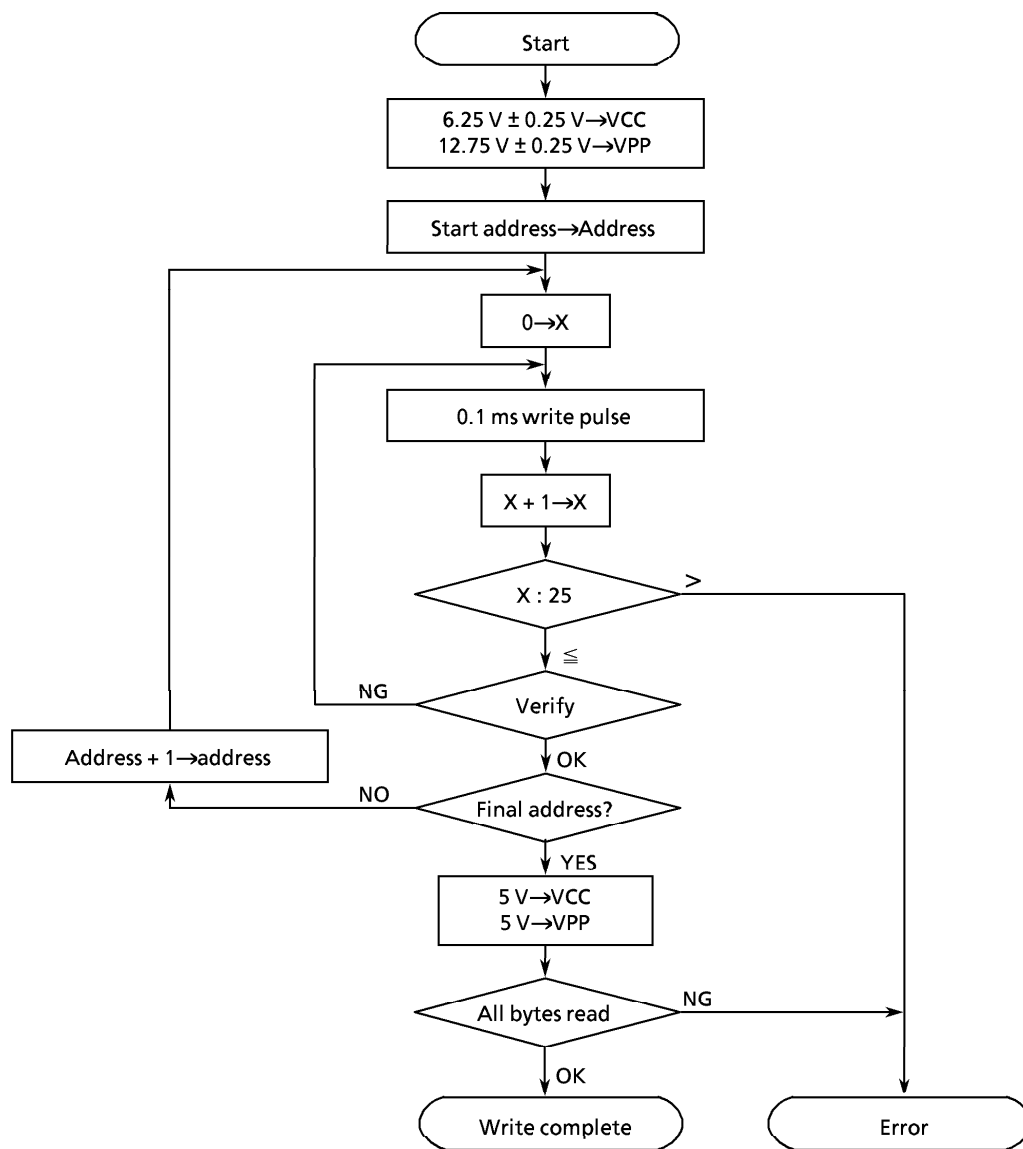


Figure 3.2 (3) Writing Flow Chart (High-Speed Programming Method)

(7) SECURITY bit

The TMP95PS54 PROM cell contains a built-in security bit (one bit). Writing 0 to this security bit prevents the internal PROM data from being read in PROM mode.

Programming security bit

In PROM mode, set the security pin (P33) to 1 and write FEH to address 00000H. Set the PROM write start address to 00000H, the end address to 00000H, and the data on address 00000H to FEH. Then write FEH to address 00000H according to the PROM writer operating procedure. This sets the internal PROM security bit.

(8) Cautions

1. When turning the V_{PP} power supply (12.75 V) off and on, the V_{CC} must be on .
2. Do not plug in or unplug the device with the V_{PP} power on.
3. When executing the program, the voltage applied to the VPP pin should not exceed the maximum rating (14 V).

4. Electrical Characteristics

4.1 Absolute Maximum Ratings

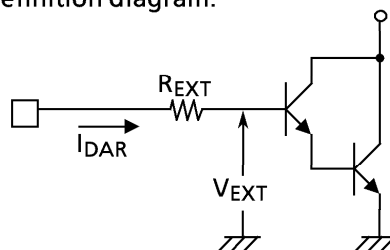
Symbol	Parameter	Rating		Unit
V_{CC}	Power Supply Voltage	– 0.5 to + 6.5		V
V_{IN}	Input Voltage	except for $\overline{EA}$ pin	– 0.5 to $V_{CC} + 0.5$	V
		$\overline{EA}$ pin	– 0.5 to 14.0	
ΣI_{OL}	Output current (total)	+ 120		mA
ΣI_{OH}	Output current (total)	– 120		mA
P_D	Power Dissipation ($T_a = + 85^\circ\text{C}$)	600		mW
T_{SOLDER}	Soldering Temperature (10 s)	+ 260		$^\circ\text{C}$
T_{STG}	Storage Temperature	– 65 to + 150		$^\circ\text{C}$
T_{OPR}	Operating Temperature	– 40 to + 85		$^\circ\text{C}$

Note : The absolute maximum ratings are rated values which must not be exceeded during operation, even for an instant. Any one of the ratings must not be exceeded. If any absolute maximum rating is exceeded, a device may break down or its performance may be degraded, causing it to catch fire or explode resulting in injury to the user. Thus, when designing products which include this device, ensure that no absolute maximum rating value will ever be exceeded.

4.2 DC Electrical Characteristics

 $V_{CC} = 4.7 \text{ to } 5.3\text{V}$, $T_a = -40 \text{ to } +85\text{ }^{\circ}\text{C}$ ($f_c = 8 \text{ to } 24 \text{ MHz}$)
(Typical values are for $T_a = +25\text{ }^{\circ}\text{C}$, $V_{CC} = +5\text{V}$.)

Parameter	Symbol	Test Condition	Min	Max	Unit
Input Low Voltage (D0 to 15)	V_{IL}		-0.3	0.8	V
Port 2 to A	V_{IL1}		-0.3	$0.3 V_{CC}$	V
(except P56, P70, P72, P73, P75)					
RESET, NMI, INT0 to 4	V_{IL2}		-0.3	$0.25 V_{CC}$	V
EA, AM8/16	V_{IL3}		-0.3	0.3	V
X1	V_{IL4}		-0.3	$0.2 V_{CC}$	V
Input High Voltage (D0 to 15)	V_{IH}		2.2	$V_{CC} + 0.3$	V
Port 2 to A	V_{IH1}		$0.7 V_{CC}$	$V_{CC} + 0.3$	V
(except P56, P70, P72, P73, P75)					
RESET, NMI, INT0 to 4	V_{IH2}		$0.75 V_{CC}$	$V_{CC} + 0.3$	V
EA, AM8/16	V_{IH3}		$V_{CC} - 0.3$	$V_{CC} + 0.3$	V
X1	V_{IH4}		$0.8 V_{CC}$	$V_{CC} + 0.3$	V
Output Low Voltage	V_{OL}	$I_{OL} = 1.6 \text{ mA}$		0.45	V
Output High Voltage	V_{OH}	$I_{OH} = -400 \text{ } \mu\text{A}$	2.4		V
	V_{OH1}	$I_{OH} = -100 \text{ } \mu\text{A}$	$0.75 V_{CC}$		V
	V_{OH2}	$I_{OH} = -20 \text{ } \mu\text{A}$	$0.9 V_{CC}$		V
Darlington Drive Current (8 Output Pins max.)	I_{DAR}	$V_{EXT} = 1.5 \text{ V}$ $R_{EXT} = 1.1 \text{ k}\Omega$	-1.0	-3.5	mA
Input Leakage Current	I_{LI}	$0.0 \leq V_{in} \leq V_{CC}$	0.02 (Typ)	± 5	μA
Output Leakage Current	I_{LO}	$0.2 \leq V_{in} \leq V_{CC} - 0.2$	0.05 (Typ)	± 10	μA
Operating Current (NORMAL)	I_{CC}	$f_c = 24 \text{ MHz}$	69 (Typ)	85	mA
RUN			35 (Typ)	50	mA
IDLE2			27 (Typ)	40	mA
IDLE1			5 (Typ)	10	mA
STOP ($T_a = -40 \text{ to } +85\text{ }^{\circ}\text{C}$)		$0.2 \leq V_{in} \leq V_{CC} - 0.2$	0.5 (Typ)	100	μA
($T_a = -20 \text{ to } +70\text{ }^{\circ}\text{C}$)				50	
($T_a = 0 \text{ to } +50\text{ }^{\circ}\text{C}$)				10	
Power Down Voltage (@STOP, RAM Back up)	V_{STOP}	$V_{IL2} = 0.2 V_{CC}$, $V_{IH2} = 0.8 V_{CC}$	2.0	6.0	V
Pull Up Registance	R_{RP}		45	160	$\text{k}\Omega$
Pin Capacitance	C_{IO}	$f_c = 1 \text{ MHz}$		10	pF
Schmitt Width	V_{TH}		0.4	1.0 (Typ)	V
RESET, NMI, INT0 to 4					

Note : I_{DAR} guarantees up to eight pins from any output port.Refer: I_{DAR} definition diagram.

4.3 AC Electrical Characteristics

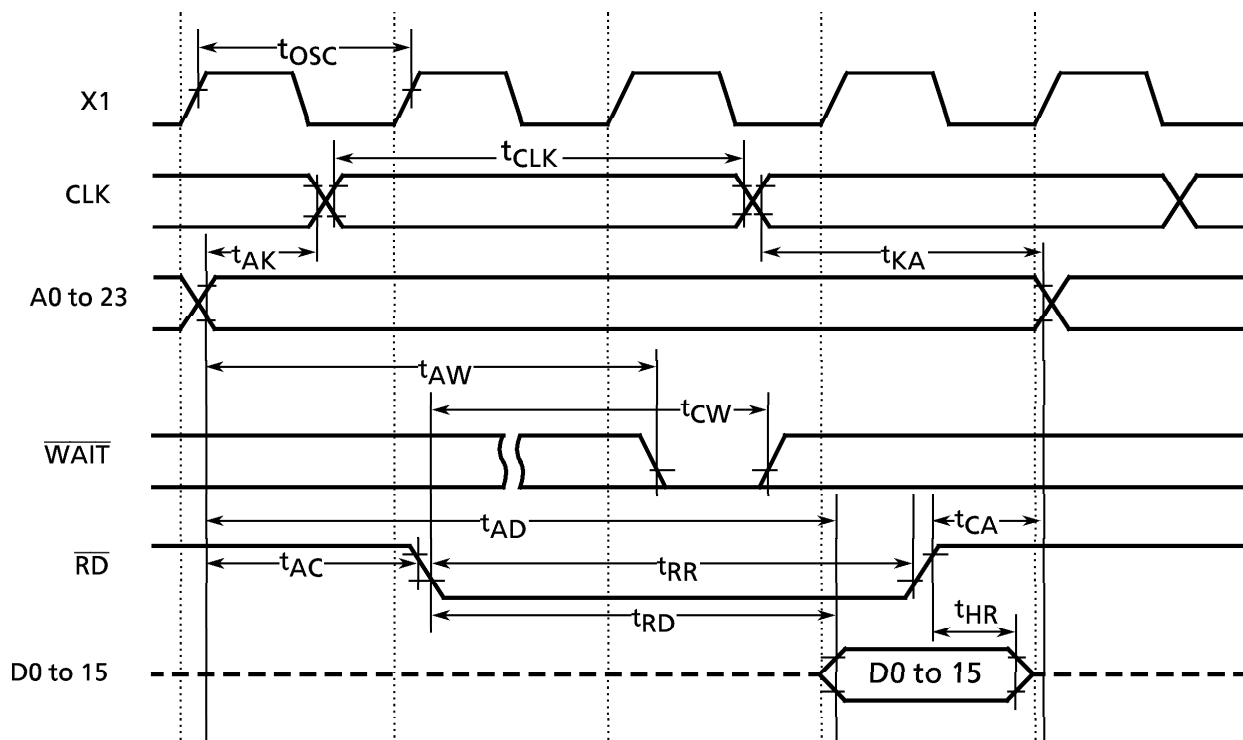
 $V_{CC} = 4.7 \text{ to } 5.3\text{V}$, $T_a = -40 \text{ to } +85^\circ\text{C}$
(f_c = 8 MHz to 24 MHz)

No.	Parameter	Symbol	Variable		24 MHz		Unit
			Min	Max	Min	Max	
1	Oscillation cycle (= x)	t _{OSC}	42	125	42		ns
2	Clock pulse width	t _{CLK}	2.0x – 40		44		ns
3	A0 to 23 valid → Clock hold	t _{AK}	0.5x – 20		1		ns
4	Clock valid → A0 to 23 hold	t _{KA}	1.5x – 60		3		ns
5	A0 to 23 valid → $\overline{\text{RD}}/\overline{\text{WR}}$ fall	t _{AC}	1.0x – 20		22		ns
6	$\overline{\text{RD}}/\overline{\text{WR}}$ rise → A0 to 23 hold	t _{CA}	0.5x – 20		1		ns
7	A0 to 23 valid → D0 to 15 input	t _{AD}		3.5x – 40		107	ns
8	$\overline{\text{RD}}$ fall → D0 to 15 input	t _{RD}		2.5x – 45		60	ns
9	$\overline{\text{RD}}$ low pulse width	t _{RR}	2.5x – 40		65		ns
10	$\overline{\text{RD}}$ rise → D0 to 15 hold	t _{HR}	0		0		ns
11	$\overline{\text{WR}}$ low pulse width	t _{WW}	2.5x – 40		65		ns
12	D0 to 15 valid → $\overline{\text{WR}}$ rise	t _{DW}	2.0x – 40		44		ns
13	$\overline{\text{WR}}$ rise → D0 to 15 hold	t _{WD}	0.5x – 10		11		ns
14	A0 to 23 valid → $\overline{\text{WAIT}}$ input ^(1 WAIT + n mode)	t _{AW}		3.5x – 90		57	ns
	A0 to 23 valid → $\overline{\text{WAIT}}$ input ^(0 + η WAIT mode)	t _{AW}		1.5x – 40		23	ns
15	$\overline{\text{RD}}/\overline{\text{WR}}$ fall → $\overline{\text{WAIT}}$ hold ^(1 WAIT + n mode)	t _{CW}	2.5x + 0		105		ns
	$\overline{\text{RD}}/\overline{\text{WR}}$ fall → $\overline{\text{WAIT}}$ hold ^(0 + η WAIT mode)	t _{CW}	0.5x + 0		21		ns
16	$\overline{\text{WR}}$ rise → PORT valid	t _{CP}		200		200	ns

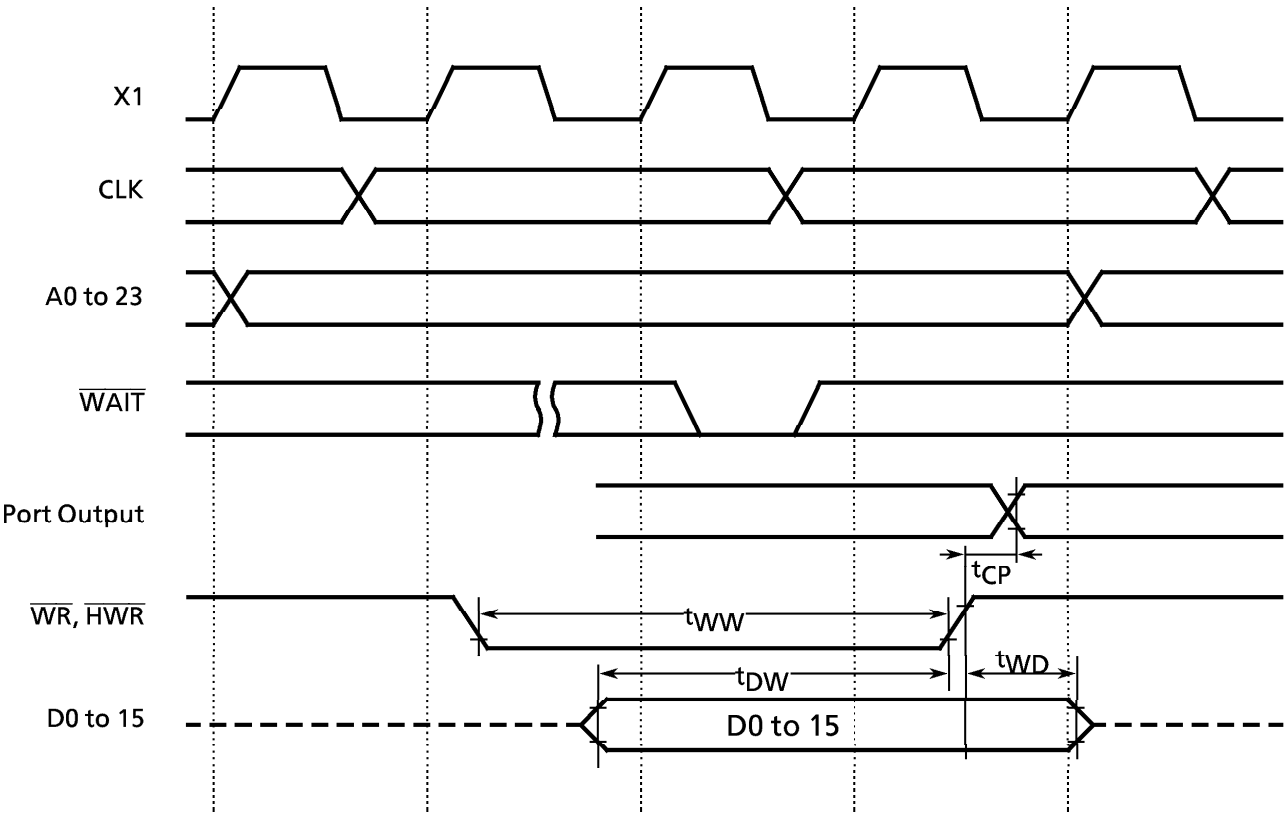
AC measuring conditions

- Output level : High 2.2 V/Low 0.8 V , CL = 50 pF
- Input level : High 2.4 V / Low 0.45 V (D0 to D15)
High 0.8 V_{CC} / Low 0.2 V_{CC} (except for D0 to D15)

(1) Read cycle



(2) Write cycle



4.4 Serial Channel Timing

(1) I/O interface mode

① SCLK input mode

$V_{CC} = 4.7$ to 5.3 V, $T_a = -40$ to $+85^\circ\text{C}$ ($f_c = 8$ to 24 MHz)

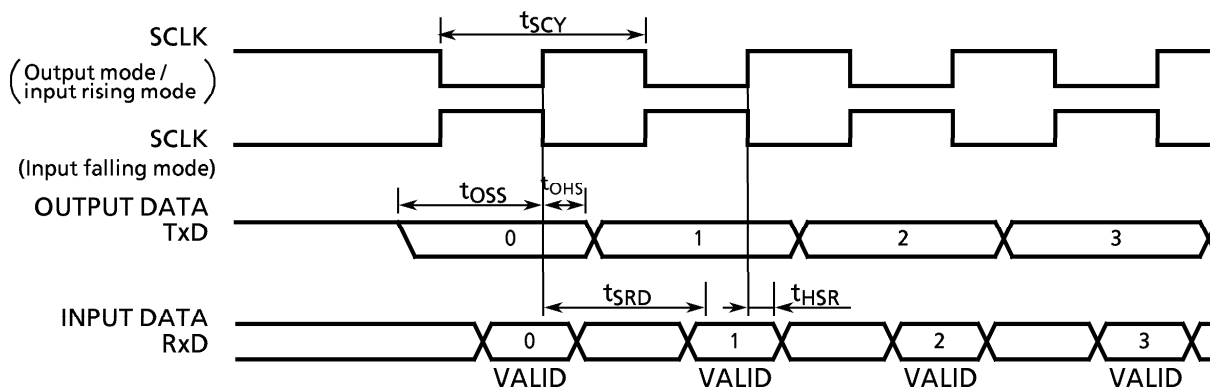
Parameter	Symbol	Variable		24 MHz		Unit
		Min	Max	Min	Max	
SCLK cycle	t_{SCY}	16x		0.667		μs
Output Data → SCLK rise/fall*	t_{OSS}	$t_{SCY}/2 - 5x - 50$		75		ns
SCLK rise/fall* → Output Data hold	t_{OHS}	$5x - 100$		108		ns
SCLK rise/fall* → input data hold	t_{HSR}	0		0		ns
SCLK rise/fall* → valid data input	t_{SRD}		$t_{SCY} - 5x - 100$		358	ns

*) SCLK rise/fall: In SCLK rising edge mode, SCLK rising edge timing; in SCLK falling edge mode, SCLK falling edge timing

② SCLK output mode

$V_{CC} = 4.7$ to 5.3 V, $T_a = -40$ to $+85^\circ\text{C}$ ($f_c = 8$ to 24 MHz)

Parameter	Symbol	Variable		24 MHz		Unit
		Min	Max	Min	Max	
SCLK cycle (programmable)	t_{SCY}	16x	8192x	0.667	341.3	μs
Output Data → SCLK rising edge	t_{OSS}	$t_{SCY} - 2x - 150$		433		ns
SCLK rising edge → Output Data hold	t_{OHS}	$2x - 80$		3		ns
SCLK rising edge → Input Data hold	t_{HSR}	0		0		ns
SCLK rising edge → valid data input	t_{SRD}		$t_{SCY} - 2x - 150$		433	ns



(2) UART mode (SCLK0 to 1 External Input)

$V_{CC} = 4.7$ to 5.3 V, $T_a = -40$ to $+85^\circ\text{C}$ ($f_c = 8$ to 24 MHz)

Parameter	Symbol	Variable		24 MHz		Unit
		Min	Max	Min	Max	
SCLK cycle	t_{SCY}	$4x + 20$		187		ns
Low-level SCLK pulse width	t_{SCYL}	$2x + 5$		88		ns
High-level SCLK pulse width	t_{SCYH}	$2x + 5$		88		ns

4.5 A/D Conversion Characteristics

$V_{CC} = 4.7 \text{ to } 5.3 \text{ V}$, $T_a = -40 \text{ to } +85^\circ\text{C}$ ($f_c = 8 \text{ to } 24 \text{ MHz}$)

Parameter		Symbol	Test Conditions	Min	Typ	Max	Unit
A/D analog reference supply voltage (+)		V_{REFH}		$V_{CC} - 0.2$		V_{CC}	V
A/D analog reference supply voltage (-)		V_{REFL}		V_{SS}		$V_{SS} + 0.2$	
Analog reference voltage		AV_{CC}		$V_{CC} - 0.2$		V_{CC}	
Analog reference voltage		AV_{SS}		V_{SS}		$V_{SS} + 0.2$	
Analog input voltage		V_{AIN}		V_{REFL}		V_{REFH}	
Analog reference voltage supply current	$<V_{REFON}> = 1$	I_{REF}	$V_{CC} = 4.7 \text{ to } 5.3 \text{ V}$			3.7	mA
	$<V_{REFON}> = 0$		$V_{CC} = 4.7 \text{ to } 5.3 \text{ V}$		0.02	5.0	μA
Total tolerance (excludes quantization error)		E_T	$V_{CC} = 4.7 \text{ to } 5.3 \text{ V}$		± 1	± 3	LSB

Note 1: $1\text{LSB} = (V_{REFH} - V_{REFL}) / 2^{10} [\text{V}]$

Note 2: Power supply current ICC from the VCC pin includes the power supply current from the AVCC pin.

4.6 Event Counter (External Input Clocks : TI0, TI4, TI8, TI9, TIA, TIB)

$V_{CC} = 4.7 \text{ to } 5.3 \text{ V}$, $T_a = -40 \text{ to } +85^\circ\text{C}$ ($f_c = 8 \text{ to } 24 \text{ MHz}$)

Parameter	Symbol	Variable		24 MHz		Unit
		Min	Max	Min	Max	
External input clock cycle	t_{VCK}	$8x + 100$		433		ns
External low-level input clock pulse width	t_{VCKL}	$4x + 40$		207		ns
External high-level input clock pulse width	t_{VCKH}	$4x + 40$		207		ns

4.7 Interrupt Operation

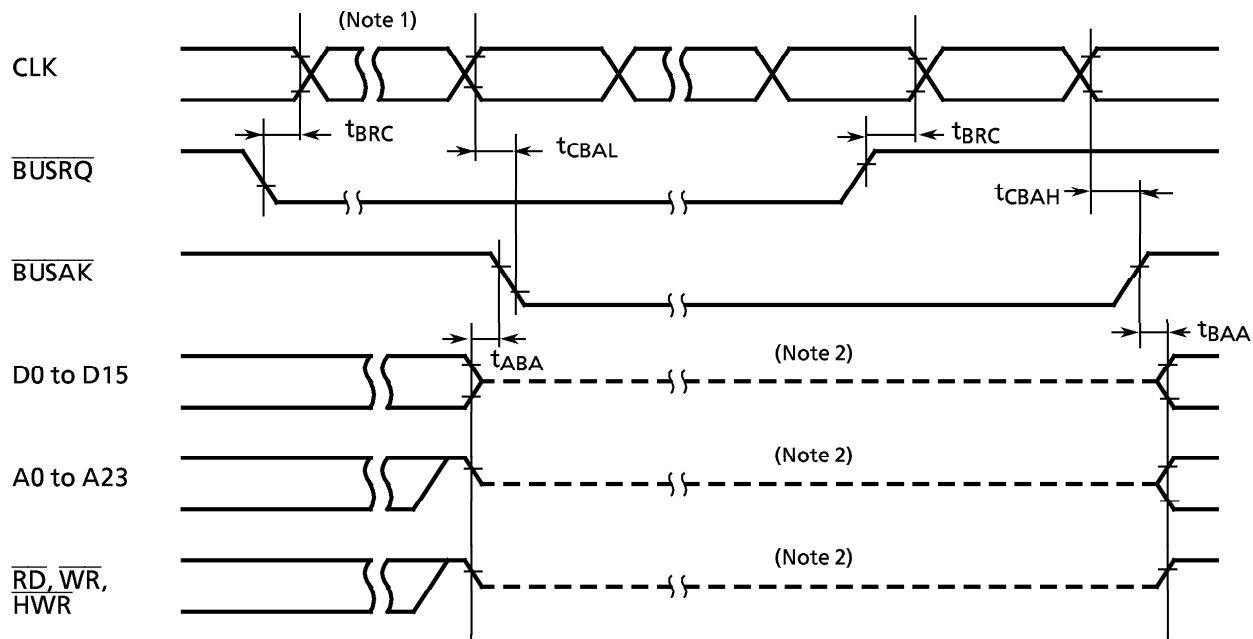
$V_{CC} = 4.7 \text{ to } 5.3 \text{ V}$, $T_a = -40 \text{ to } +85^\circ\text{C}$ ($f_c = 8 \text{ to } 24 \text{ MHz}$)

Parameter	Symbol	Variable		24 MHz		Unit
		Min	Max	Min	Max	
NMI, INT0 to 4 low-level pulse width	t_{INTAL}	$4x$		167		ns
NMI, INT0 to 4 high-level pulse width	t_{INTAH}	$4x$		167		ns
INT5 to INT8 low-level pulse width	t_{INTBL}	$8x + 100$		433		ns
INT5 to INT8 high-level pulse width	t_{INTBH}	$8x + 100$		433		ns

4.8 Bus Request/Bus Acknowledge Timing

$V_{CC} = 4.7 \text{ to } 5.3 \text{ V}$, $T_a = -40 \text{ to } +85^\circ\text{C}$ ($f_c = 8 \text{ to } 24 \text{ MHz}$)

Parameter	Symbol	Variable		24 MHz		Unit
		Min	Max	Min	Max	
BUSRQ setup time for CLK	t_{BRC}	120		120		ns
CLK→BUSAK fall	t_{CBAL}		$2.0x + 120$		203	ns
CLK→BUSAK rise	t_{CBAH}		$0.5x + 40$		61	ns
Time from output buffer off until BUSAK falling edge	t_{ABA}	0	80	0	80	ns
Time from BUSAK rising edge until output buffer on	t_{BAA}	0	80	0	80	ns



Note 1: When $\overline{\text{BUSRQ}}$ goes to low level to request bus release, if the current bus cycle is yet complete due to a wait, the bus is not released until the wait completes.

Note 2: The dotted line indicates only that the output buffer is off, not that the signal is at middle level. Immediately after bus release, the signal level prior to the bus release is held dynamically by the external load capacitance. Therefore, designs should allow for the fact that when using an external resistor or similar to fix the signal level while the bus is released, after bus release a delay occurs before the signal goes to its fixed level (due to the CR time constant). The internal programmable pull-up resistor continues to function in accordance with the internal signal level.

4.9 Read Operations in PROM Mode

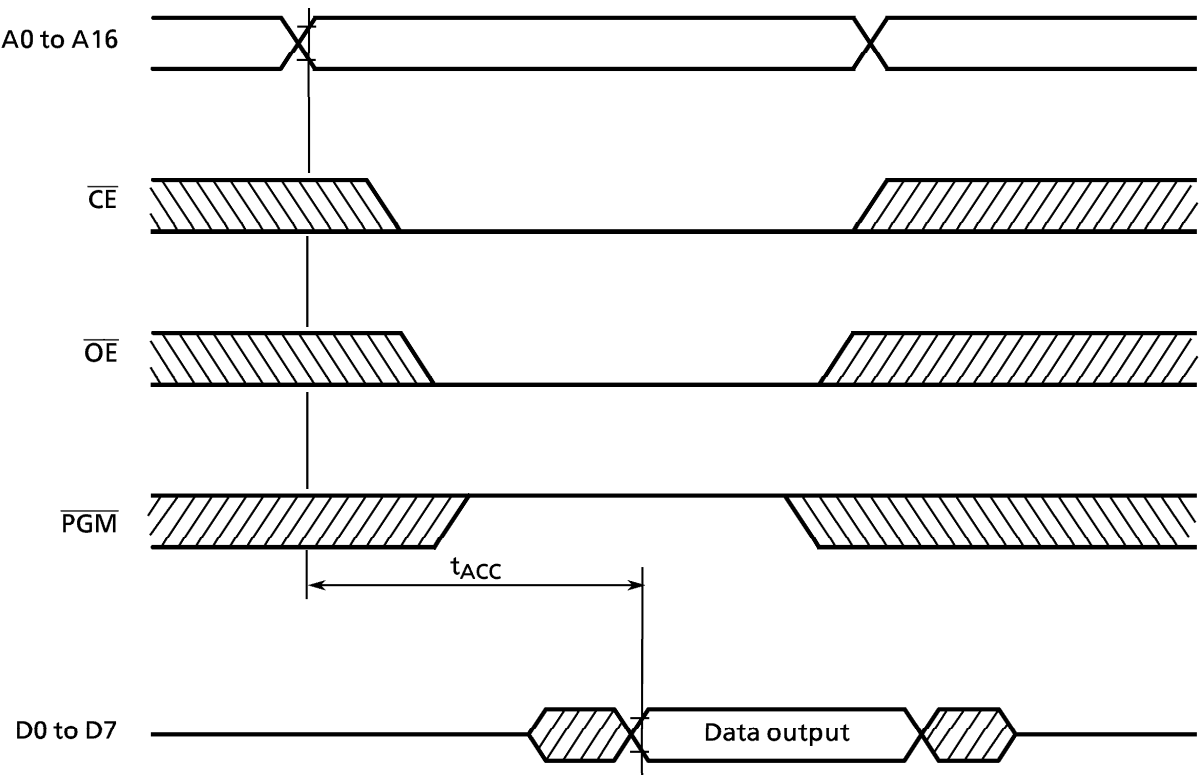
DC / AC Electrical Specifications

Ta = 25 ± 5°C, Vcc = 5 V ± 10 %

Parameter	Symbol	Test Condition	Min	Max	Unit
Vpp Read Voltage	Vpp		4.5	5.5	V
Input High Voltage (A0 to A16, $\overline{CE}$, $\overline{OE}$, PGM)	V _{IH}		2.2	V _{CC} + 0.3	V
Input Low Voltage (A0 to A16, $\overline{CE}$, $\overline{OE}$, PGM)	V _{IL}		− 0.3	0.8	V
Address to Output Delay	t _{ACC}	C _L = 50 pF	−	2.25TCYC + α	ns

TCYC = 400 ns (10 MHz Clock)

α = 200 ns

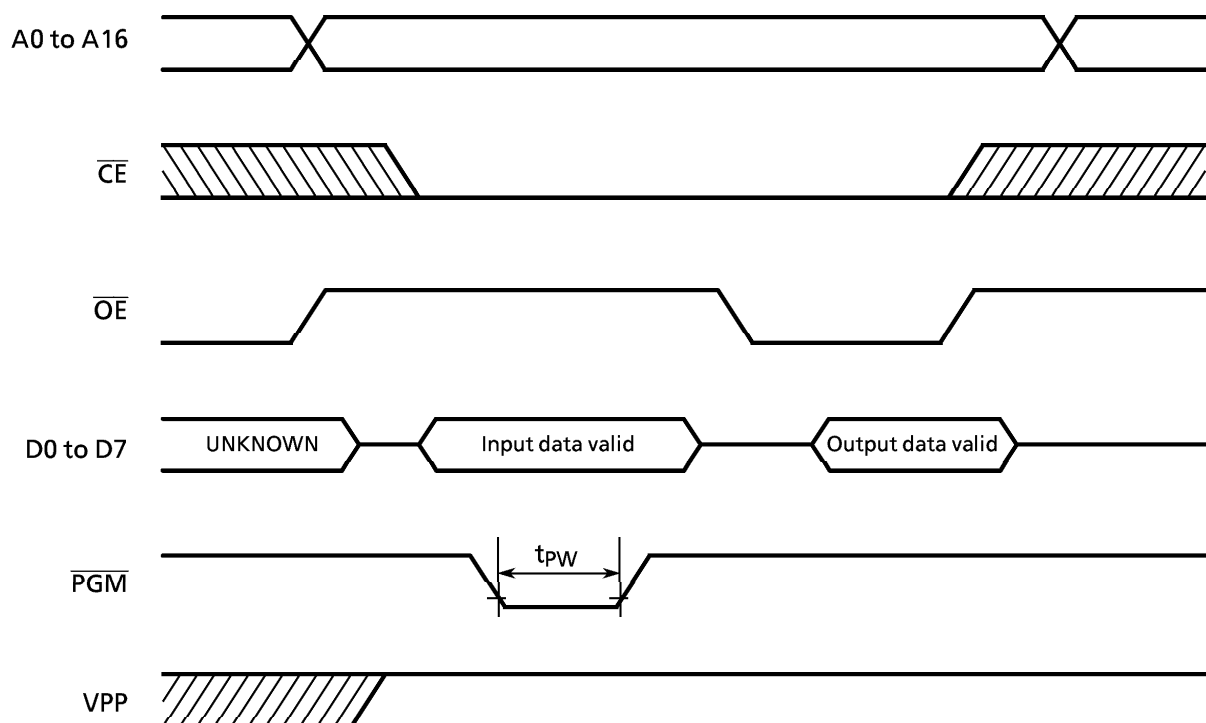


4.10 Program Operations in PROM Mode

DC / AC Electrical Specifications

 $T_a = 25 \pm 5^\circ\text{C}$, $V_{CC} = 6.25\text{ V} \pm 0.25\text{ V}$

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Programing Supply Voltage	V_{PP}		12.50	12.75	13.00	V
Input High Voltage (D0 to D7, A0 to A16, $\overline{CE}$, $\overline{OE}$, $\overline{PGM}$)	V_{IH}		2.6		$V_{CC} + 0.3$	V
Input Low Voltage (D0 to D7, A0 to A16, $\overline{CE}$, $\overline{OE}$, $\overline{PGM}$)	V_{IL}		-0.3		0.8	V
V_{CC} Supply Current	I_{CC}	$f_c = 10\text{ MHz}$	-		50	mA
V_{PP} Supply Current	I_{PP}	$V_{PP} = 13.00\text{ V}$	-		50	mA
$\overline{PGM}$ Program Pulse Width	t_{PW}	$C_L = 50\text{ pF}$	0.095	0.1	0.105	ms



Note 1: When turning the V_{PP} (12.75 V) power supply off and on, ensure that V_{CC} is on.

Note 2: Do not plug in or unplug the device when the V_{PP} power (12.75 V) is on.
(This can damage the device.)

Note 3: The V_{PP} pin maximum rating is 14V. When the program is executed, the voltage applied, including overshoot, should not exceed 14V.