

TOSHIBA CMOS DIGITAL INTEGRATED CIRCUIT SILICON MONOLITHIC

TC74HC597AP, TC74HC597AF**8-BIT LATCH / SHIFT REGISTER**

The TC74HC597A is a high speed CMOS 8-BIT PARALLEL-IN / SERIAL-IN SERIAL-OUT LATCH / SHIFT REGISTER fabricated with silicon gate C2MOS technology.

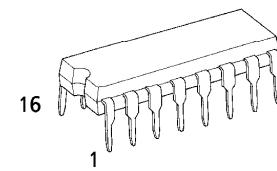
It achieves the high speed operation similar to equivalent LSTTL while maintaining the CMOS low power dissipation.

It consists of an 8-bit data register feeding an 8-bit shift register. The parallel data on the A~H inputs is stored in the input register on the positive going transition of RCK. When the SLOAD input is held low, the input register data is passed into the shift registers. When SLOAD input is held high, the serial data input (SI) is enabled and the eight flip-flops perform serial shifting on the positive transition of SCK. A direct clear input (SCLR) sets the 8-bit shift register to zero.

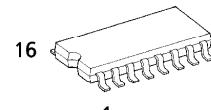
All inputs are equipped with protection circuits against static discharge or transient excess voltage.

FEATURES:

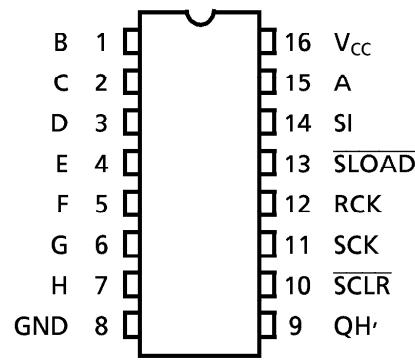
- High Speed..... $f_{MAX} = 60MHz$ (typ.) at $V_{CC} = 5V$
- Low Power Dissipation..... $I_{CC} = 4\mu A$ (Max.) at $T_a = 25^\circ C$
- High Noise Immunity..... $V_{NIH} = V_{NIL} = 28\% V_{CC}$
- Output Drive Capability.....10 LSTTL Loads
- Symmetrical Output Impedance..... $|I_{OH}| = I_{OL} = 4mA$ (Min.)
- Balanced Propagation Delays..... $t_{PLH} \approx t_{PHL}$
- Wide Operating Voltage Range..... V_{CC} (opr.) = $2V \sim 6V$
- Pin and Function Compatible with 74LS597



P (DIP16-P-300-2.54A)
Weight : 1.00g (Typ.)



F (SOP16-P-300-1.27)
Weight : 0.18g (Typ.)

PIN ASSIGNMENT

(TOP VIEW)

TRUTH TABLE

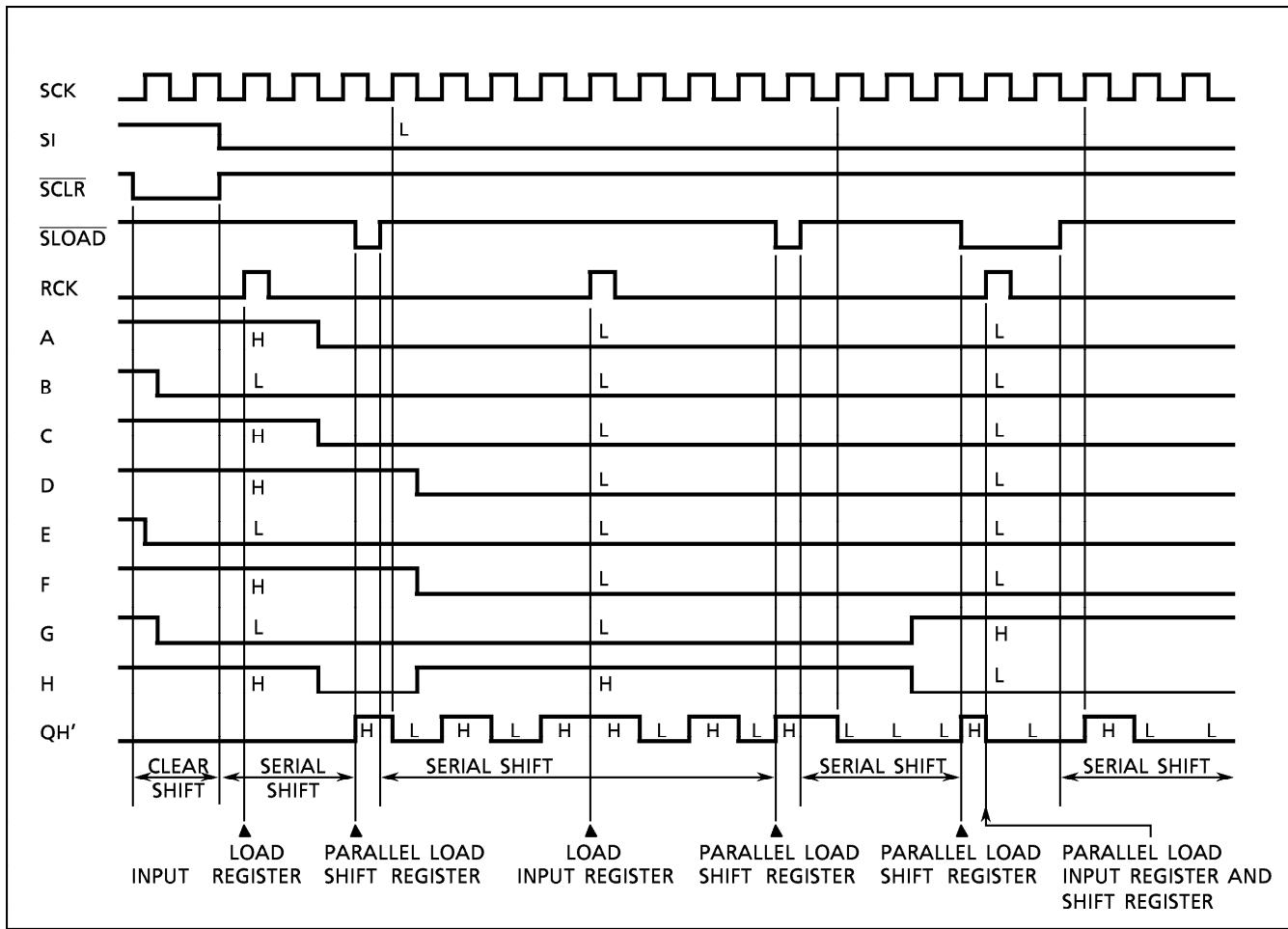
| INPUTS | | | | | FUNCTION |
|--------|-----|------|-------|-----|---|
| SI | SCK | SCLR | SLOAD | RCK | |
| X | X | L | H | X | S. R. is cleared to "L" |
| X | X | H | L | X | Input register data is stored into S. R. |
| L | ↑ | H | H | X | First stage of S. R. become "L". Other stages store the data of previous stage, respectively. |
| H | ↑ | H | H | X | First stage of S. R. become "H". Other stages store the data of previous stage, respectively. |
| X | ↖ | H | H | X | State of S. R. is not changed. |
| X | X | X | X | ↑ | Input data on A~H line is stored into input register. |
| X | X | X | X | ↖ | Storage register stage is not changed. |

X : Don't Care

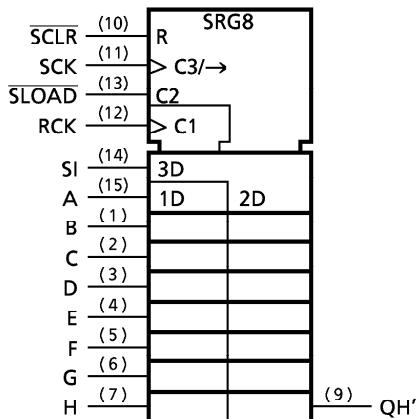
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TIMING CHART



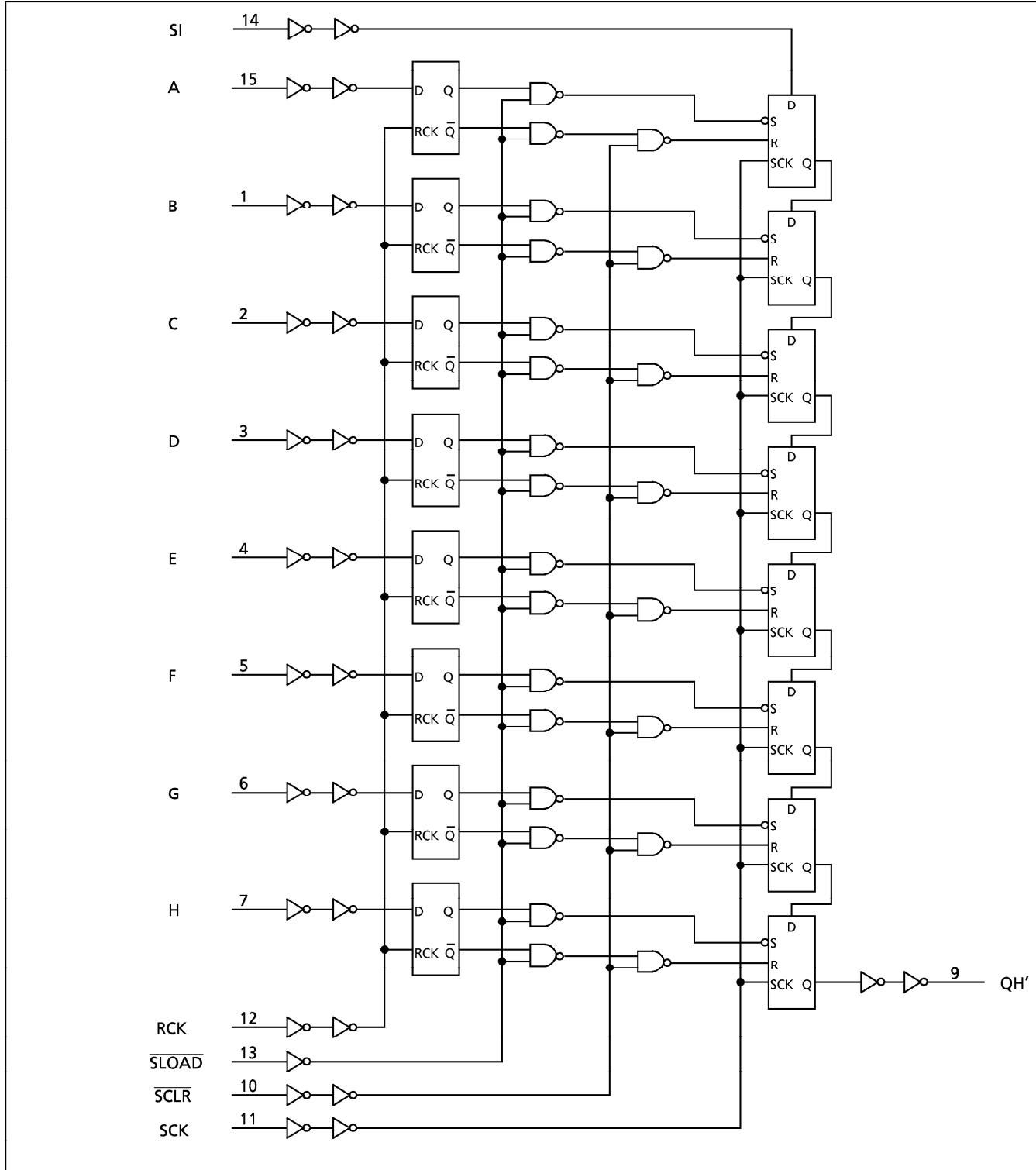
IEC LOGIC SYMBOL



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SYSTEM DIAGRAM



ABSOLUTE MAXIMUM RATINGS

| PARAMETER | SYMBOL | VALUE | UNIT |
|-----------------------------|-----------|------------------------|------|
| Supply Voltage Range | V_{CC} | -0.5~7.0 | V |
| DC Input Voltage | V_{IN} | -0.5~ V_{CC} + 0.5 | V |
| DC Output Voltage | V_{OUT} | -0.5~ V_{CC} + 0.5 | V |
| Input Diode Current | I_{IK} | ± 20 | mA |
| Output Diode Current | I_{OK} | ± 20 | mA |
| DC Output Current | I_{OUT} | ± 25 | mA |
| DC V_{CC} /Ground Current | I_{CC} | ± 50 | mA |
| Power Dissipation | P_D | 500 (DIP)* / 180 (SOP) | mW |
| Storage Temperature | T_{stg} | -65~150 | °C |

*500mW in the range of $T_a = -40^{\circ}\text{C} \sim 65^{\circ}\text{C}$. From $T_a = 65^{\circ}\text{C}$ to 85°C a derating factor of $-10\text{mW}/^{\circ}\text{C}$ should be applied up to 300mW.

RECOMMENDED OPERATING CONDITIONS

| PARAMETER | SYMBOL | VALUE | UNIT |
|--------------------------|------------|--|------|
| Supply Voltage | V_{CC} | 2~6 | V |
| Input Voltage | V_{IN} | 0~ V_{CC} | V |
| Output Voltage | V_{OUT} | 0~ V_{CC} | V |
| Operating Temperature | T_{opr} | -40~85 | °C |
| Input Rise and Fall Time | t_r, t_f | 0~ 1000 ($V_{CC} = 2.0\text{V}$) 0~ 500 ($V_{CC} = 4.5\text{V}$) 0~ 400 ($V_{CC} = 6.0\text{V}$) | ns |

DC ELECTRICAL CHARACTERISTICS

| PARAMETER | SYMBOL | TEST CONDITION | V_{CC} (V) | Ta = 25°C | | | Ta = -40~85°C | | UNIT |
|-----------------------------|----------|-------------------------------|--|----------------------|-------------------|----------------------|----------------------|----------------------|---------------|
| | | | | MIN. | TYP. | MAX. | MIN. | MAX. | |
| High - Level Input Voltage | V_{IH} | | 2.0 4.5 6.0 | 1.50 3.15 4.20 | — — — | — — — | 1.50 3.15 4.20 | — — — | V |
| Low - Level Input Voltage | V_{IL} | | 2.0 4.5 6.0 | — — — | — — — | 0.50 1.35 1.80 | — — — | 0.50 1.35 1.80 | V |
| High - Level Output Voltage | V_{OH} | $V_{IN} = V_{IH}$ or V_{IL} | $I_{OH} = -20\mu\text{A}$ | 2.0 4.5 6.0 | 1.9 4.4 5.9 | 2.0 4.5 6.0 | — — — | 1.9 4.4 5.9 | V |
| | | | $I_{OH} = -4\text{ mA}$ $I_{OH} = -5.2\text{ mA}$ | 4.5 6.0 | 4.18 5.68 | 4.31 5.80 | — — | 4.13 5.63 | |
| Low - Level Output Voltage | V_{OL} | $V_{IN} = V_{IH}$ or V_{IL} | $I_{OL} = 20\mu\text{A}$ | 2.0 4.5 6.0 | 0.0 0.0 0.0 | 0.1 0.1 0.1 | — — — | 0.1 0.1 0.1 | V |
| | | | $I_{OL} = 4\text{ mA}$ $I_{OL} = 5.2\text{ mA}$ | 4.5 6.0 | 0.17 0.18 | 0.26 0.26 | — — | 0.33 0.33 | |
| Input Leakage Current | I_{IN} | $V_{IN} = V_{CC}$ or GND | 6.0 | — | — | ± 0.1 | — | ± 1.0 | μA |
| Quiescent Supply Current | I_{CC} | $V_{IN} = V_{CC}$ or GND | 6.0 | — | — | 4.0 | — | 40.0 | |

TIMING REQUIREMENTS (Input $t_r = t_f = 6\text{ns}$)

| PARAMETER | SYMBOL | TEST CONDITION | V_{CC} (V) | $T_a = 25^\circ\text{C}$ | | $T_a = -40\sim85^\circ\text{C}$ | UNIT |
|---------------------------------------|--------------------------|----------------|--------------|--------------------------|-------|---------------------------------|------|
| | | | TYP. | LIMIT | LIMIT | | |
| Minimum Pulse Width (SCK, RCK) | $t_{W(H)}$ $t_{W(L)}$ | | 2.0 | — | 75 | 95 | ns |
| | | | 4.5 | — | 15 | 19 | |
| | | | 6.0 | — | 13 | 16 | |
| Minimum Pulse Width (SCLR) | $t_{W(L)}$ | | 2.0 | — | 75 | 95 | ns |
| | | | 4.5 | — | 15 | 19 | |
| | | | 6.0 | — | 13 | 16 | |
| Minimum Pulse Width (SLOAD) | $t_{W(L)}$ | | 2.0 | — | 75 | 95 | ns |
| | | | 4.5 | — | 15 | 19 | |
| | | | 6.0 | — | 13 | 16 | |
| Minimum Set-up Time (RCK—SLOAD) | t_s | | 2.0 | — | 100 | 125 | ns |
| | | | 4.5 | — | 20 | 25 | |
| | | | 6.0 | — | 17 | 21 | |
| Minimum Set-up Time (SI—SCK) | t_s | | 2.0 | — | 75 | 95 | ns |
| | | | 4.5 | — | 15 | 19 | |
| | | | 6.0 | — | 13 | 16 | |
| Minimum Set-up Time (PI—RCK) | t_s | | 2.0 | — | 75 | 95 | ns |
| | | | 4.5 | — | 15 | 19 | |
| | | | 6.0 | — | 13 | 16 | |
| Minimum Hold Time | t_h | | 2.0 | — | 0 | 0 | ns |
| | | | 4.5 | — | 0 | 0 | |
| | | | 6.0 | — | 0 | 0 | |
| Minimum Removal Time (SCLR, SLOAD) | t_{rem} | | 2.0 | — | 75 | 95 | ns |
| | | | 4.5 | — | 15 | 19 | |
| | | | 6.0 | — | 13 | 16 | |
| Clock Frequency | f | | 2.0 | — | 6 | 5 | MHz |
| | | | 4.5 | — | 30 | 24 | |
| | | | 6.0 | — | 35 | 28 | |

AC ELECTRICAL CHARACTERISTICS ($C_L = 15\text{pF}$, $V_{CC} = 5\text{V}$, $T_a = 25^\circ\text{C}$, Input $t_r = t_f = 6\text{ns}$)

| PARAMETER | SYMBOL | TEST CONDITION | MIN. | TYP. | MAX. | UNIT | |
|---------------------------------------|------------------------|--|------|------|------|------|--|
| Output Transition Time | t_{TLH} t_{THL} | | — | 5 | 8 | ns | |
| | | | | | | | |
| Propagation Delay Time (SCK—QH') | t_{PLH} t_{PHL} | | — | 16 | 25 | | |
| | | | | | | | |
| Propagation Delay Time (SCLR—QH') | t_{PLH} t_{PHL} | | — | 20 | 32 | ns | |
| | | | | | | | |
| Propagation Delay Time (SLOAD—QH') | t_{PLH} t_{PHL} | | — | 18 | 30 | | |
| | | | | | | | |
| Propagation Delay Time (RCK—QH') | t_{PLH} t_{PHL} | $\overline{\text{SLOAD}} = \text{"L"}$ | — | 25 | 37 | ns | |
| | | | | | | | |
| Maximum Clock Frequency | f_{MAX} | | 30 | 59 | — | MHz | |

AC ELECTRICAL CHARACTERISTICS ($C_L = 50\text{pF}$, Input $t_r = t_f = 6\text{ns}$)

| PARAMETER | SYMBOL | TEST CONDITION | $V_{CC}(\text{V})$ | Ta = 25°C | | | Ta = -40~85°C | | UNIT |
|---------------------------------------|-------------|----------------|--------------------|-----------|------|------|---------------|------|------|
| | | | | MIN. | TYP. | MAX. | MIN. | MAX. | |
| Output Transition Time | t_{TLH} | | 2.0 | — | 32 | 75 | — | 95 | ns |
| | t_{THL} | | 4.5 | — | 8 | 15 | — | 19 | |
| | | | 6.0 | — | 7 | 13 | — | 16 | |
| Propagation Delay Time (SCK-QH') | t_{PLH} | | 2.0 | — | 78 | 145 | — | 180 | |
| | t_{PHL} | | 4.5 | — | 20 | 29 | — | 36 | |
| | | | 6.0 | — | 16 | 25 | — | 31 | |
| Propagation Delay Time (SCLR-QH') | t_{PHL} | | 2.0 | — | 90 | 175 | — | 220 | |
| | | | 4.5 | — | 24 | 35 | — | 44 | |
| | | | 6.0 | — | 20 | 30 | — | 37 | |
| Propagation Delay Time (SLOAD-QH') | t_{PLH} | | 2.0 | — | 80 | 175 | — | 220 | |
| | t_{PHL} | | 4.5 | — | 22 | 35 | — | 44 | |
| | | | 6.0 | — | 18 | 30 | — | 37 | |
| Propagation Delay Time (RCK-QH') | t_{PLH} | SLOAD = "L" | 2.0 | — | 112 | 210 | — | 265 | |
| | t_{PHL} | | 4.5 | — | 30 | 42 | — | 53 | |
| | | | 6.0 | — | 24 | 36 | — | 45 | |
| Maximum Clock Frequency | f_{MAX} | | 2.0 | 6 | 12 | — | 5 | — | MHz |
| Input Capacitance | C_{IN} | | 4.5 | 30 | 48 | — | 24 | — | |
| Power Dissipation Capacitance | $C_{PD}(1)$ | | 6.0 | 35 | 50 | — | 28 | — | pF |

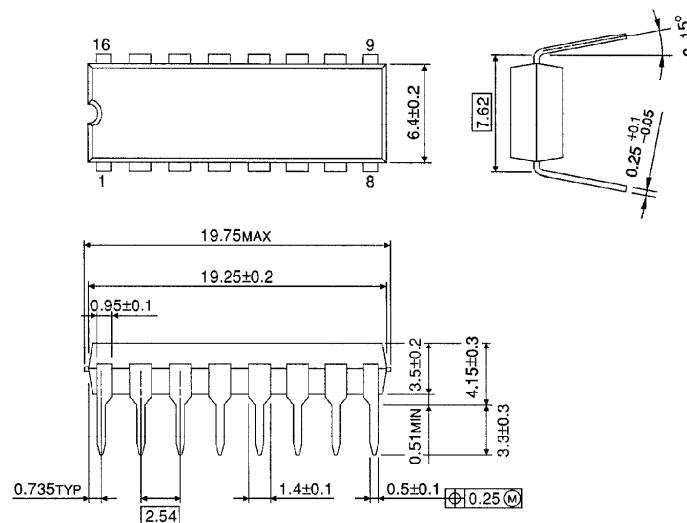
Note (1) C_{PD} is defined as the value of the internal equivalent capacitance which is calculated from the operating current consumption without load.

Average operating current can be obtained by the equation :

$$I_{CC(\text{opr})} = C_{PD} \cdot V_{CC} \cdot f_{IN} + I_{CC}$$

DIP 16PIN OUTLINE DRAWING (DIP16-P-300-2.54A)

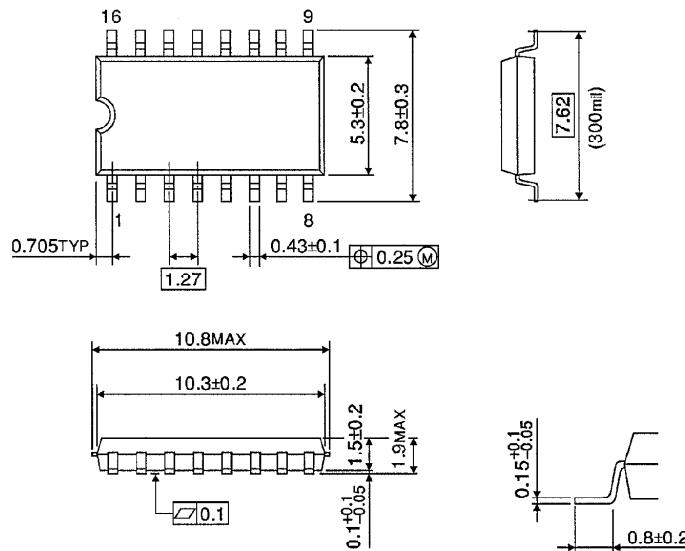
Unit in mm



Weight : 1.00g (Typ.)

SOP 16PIN (200mil BODY) OUTLINE DRAWING (SOP16-P-300-1.27)

Unit in mm



Weight : 0.18g (Typ.)