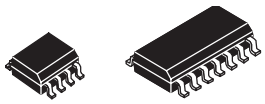


SLLS558A – DECEMBER 2002 – JUNE 2003

MULTIPOINT-LVDS LINE DRIVER AND RECEIVER

FEATURES

- **Low-Voltage Differential 30-Ω to 55-Ω Line Drivers and Receivers for Signaling Rates(1) Up to 200 Mbps**
- **Type-1 Receivers Incorporate 25 mV of Hysteresis**
- **Type-2 Receivers Provide an Offset (100 mV) Threshold to Detect Open-Circuit and Idle-Bus Conditions**
- **Meets or Exceeds the M-LVDS Standard TIA/EIA-899 for Multipoint Data Interchange**
- **Power Up/Down Glitch Free**
- **Controlled Driver Output Voltage Transition Times for Improved Signal Quality**
- **–1 V to 3.4 V Common-Mode Voltage Range Allows Data Transfer With 2 V of Ground Noise**
- **Bus Pins High Impedance When Disabled or $V_{CC} \leq 1.5$ V**
- **100-Mbps Devices Available (SN65MLVD200, 202, 204, 205)**

APPLICATIONS

- **Low-Power High-Speed Short-Reach Alternative to TIA/EIA-485**
- **Backplane or Cabled Multipoint Data and Clock Transmission**
- **Cellular Base Stations**
- **Central-Office Switches**
- **Network Switches and Routers**

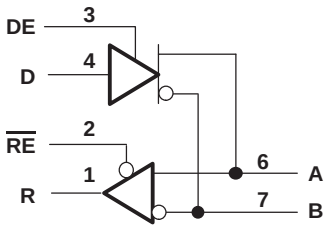
DESCRIPTION

The SN65MLVD201, 203, 206, and 207 are multipoint-low-voltage differential (M-LVDS) line drivers and receivers, which are optimized to operate at signaling rates up to 200 Mbps. All parts comply with the multipoint low-voltage differential signaling (M–LVDS) standard TIA/EIA-899. These circuits are similar to their TIA/EIA-644 standard compliant LVDS counterparts, with added features to address multipoint applications. The driver output has been designed to support multipoint buses presenting loads as low as 30 Ω, and incorporates controlled transition times to allow for stubs off of the backbone transmission line.

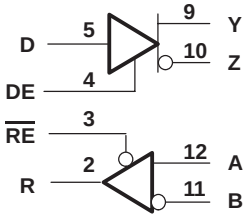
These devices have Type-1 and Type-2 receivers that detect the bus state with as little as 50 mV of differential input voltage over a common-mode voltage range of –1 V to 3.4 V. The Type-1 receivers exhibit 25 mV of differential input voltage hysteresis to prevent output oscillations with slowly changing signals or loss of input. Type-2 receivers include an offset threshold to provide a known output state under open-circuit, idle-bus, and other faults conditions. The devices are characterized for operation from –40°C to 85°C.

LOGIC DIAGRAM (POSITIVE LOGIC)

SN65MLVD201, SN65MLVD206



SN65MLVD203, SN65MLVD207



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.

(1) The signaling rate of a line, is the number of voltage transitions that are made per second expressed in the units bps (bits per second).

These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

ORDERING INFORMATION

PART NUMBER	FOOTPRINT	RECEIVER TYPE	PACKAGE MARKING
SN65MLVD201D	SN75176	Type 1	MF201
SM65MLVD203D	SN75ALS180	Type 1	MLVD203
SN65MLVD206D	SN75176	Type 2	MF206
SM65MLVD207D	SN75ALS180	Type 2	MLVD207

PACKAGE DISSIPATION RATINGS

PACKAGE	$T_A \le 25°C$ POWER RATING	DERATING FACTOR ABOVE $T_A = 25°C$	$T_A = 85°C$ POWER RATING
D(8)	725 mW	5.8 mW/°C	377 mW
D(14)	950 mW	7.6 mW/°C	494 mw

ABSOLUTE MAXIMUM RATINGS

over operating free-air temperature range unless otherwise noted(1)

			SN65MLVD201, 203, 206, AND 207
Supply voltage range(2), V_{CC}			–0.5 V to 4 V
Input voltage range	D, DE, $\overline{RE}$		–0.5 V to 4 V
	A, B (201, 206)		–1.8 V to 4 V
	A, B (203, 207)		–4 V to 6 V
Output voltage range	R		–0.3 V to 4 V
	Y, Z, A, or B		–1.8 V to 4 V
Electrostatic discharge	Human Body Model(3)	A, B, Y, and Z	±8 kV
		All pins	±2 kV
	Charged-Device Model(4)	All pins	±1500 V
Continuous power dissipation			See Dissipation Rating Table
Storage temperature range			–65°C to 150°C

(1) Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
(2) All voltage values, except differential I/O bus voltages, are with respect to network ground terminal.
(3) Tested in accordance with JEDEC Standard 22, Test Method A114–A.
(4) Tested in accordance with JEDEC Standard 22, Test Method C101.

RECOMMENDED OPERATING CONDITIONS

	MIN	NOM	MAX	UNIT
Supply voltage, V_{CC}	3	3.3	3.6	V
High-level input voltage, V_{IH}	2		V_{CC}	V
Low-level input voltage, V_{IL}	GND		0.8	V
Voltage at any bus terminal V_A, V_B, V_Y or V_Z	–1.4		3.8	V
Magnitude of differential input voltage, $\lvert V_{ID} \rvert$	0.05		V_{CC}	V
Operating free-air temperature, T_A	–40		85	°C

DEVICE ELECTRICAL CHARACTERISTICS

over recommended operating conditions unless otherwise noted

PARAMETER			TEST CONDITIONS	MIN	TYP(1)	MAX	UNIT
I_{CC}	Supply current	Driver only	$\overline{RE}$ and DE at V_{CC}, R_L = 50 Ω, All others open		13	22	mA
		Both enabled	$\overline{RE}$ at V_{CC}, DE at 0 V, R_L = No Load, All others open		1	4	
		Both enabled	$\overline{RE}$ at 0 V, DE at V_{CC}, R_L = 50 Ω, All others open		16	24	
		Receiver only	$\overline{RE}$ at 0 V, DE at 0 V, R_L = 50 Ω, All others open		4	13	

(1) All typical values are at 25°C and with a 3.3-V supply voltage.

DRIVER ELECTRICAL CHARACTERISTICS

over recommended operating conditions unless otherwise noted

PARAMETER		TEST CONDITIONS	MIN(1)	TYP(2)	MAX	UNIT
$\lvert V_{AB}\rvert$ or $\lvert V_{YZ}\rvert$	Differential output voltage magnitude	See Figure 2	480		650	mV
$\Delta\lvert V_{AB}\rvert$ or $\Delta\lvert V_{YZ}\rvert$	Change in differential output voltage magnitude between logic states	See Figure 2	–50		50	mV
$V_{OS(SS)}$	Steady-state common-mode output voltage	See Figure 3	0.8		1.2	V
$\Delta V_{OS(SS)}$	Change in steady-state common-mode output voltage between logic states	See Figure 3	–50		50	mV
$V_{OS(PP)}$	Peak-to-peak common-mode output voltage	See Figure 3			150	mV
$V_{Y(OC)}$ or $V_{A(OC)}$	Maximum steady-state open-circuit output voltage	See Figure 7	0		2.4	V
$V_{Z(OC)}$ or $V_{B(OC)}$	Maximum steady-state open-circuit output voltage	See Figure 7	0		2.4	V
$V_{P(H)}$	Voltage overshoot, low-to-high level output	See Figure 5			$1.2V_{SS}$	V
$V_{P(L)}$	Voltage overshoot, high-to-low level output	See Figure 5	$–0.2\ V_{SS}$			V
I_{IH}	High-level input current (D, DE)	V_{IH} = 2 V	0		10	µA
I_{IL}	Low-level input current (D, DE)	V_{IL} = 0.8 V	0		10	µA
$\lvert I_{OS}\rvert$	Differential short-circuit output current magnitude	See Figure 4			24	mA
I_{OZ}	High-impedance state output current (driver only)	–1.4 V ≤ V_Y or V_Z ≤ 3.8 V, Other output = 1.2 V	–15		10	µA
$I_{O(OFF)}$	Power-off output current	–1.4 V ≤ V_Y or V_Z ≤ 3.8 V, Other output = 1.2 V, 0 V ≤ V_{CC} ≤ 1.5 V	–10		10	µA
C_Y or C_Z	Output capacitance	V_I = 0.4 sin(30E6πt) + 0.5 V, (3) Other input at 1.2 V, driver disabled		3		pF
C_{YZ}	Differential output capacitance	V_{AB} = 0.4 sin(30E6πt) V, (3) Driver disabled			2.5	pF
$C_{Y/Z}$	Output capacitance balance, (C_Y/C_Z)		0.99		1.01	

(1) The algebraic convention, in which the least positive (most negative) limit is designated as minimum is used in this data sheet.
(2) All typical values are at 25°C and with a 3.3-V supply voltage.
(3) HP4194A impedance analyzer (or equivalent)

RECEIVER ELECTRICAL CHARACTERISTICS

over recommended operating conditions unless otherwise noted(1)

PARAMETER			TEST CONDITIONS	MIN	TYP(1)	MAX	UNIT
V_{IT+}	Positive-going differential input voltage threshold	Type 1	See Figure 9 and Table 1 and Table 2			50	mV
		Type 2				150	
V_{IT-}	Negative-going differential input voltage threshold	Type 1		–50			mV
		Type 2		50			
V_{HYS}	Differential input voltage hysteresis, ($V_{IT+} - V_{IT}$)	Type 1			25		mV
		Type 2			0		
V_{OH}	High-level output voltage		I_{OH} = –8 mA	2.4			V
V_{OL}	Low-level output voltage		I_{OL} = 8 mA			0.4	V
I_{IH}	High-level input current ($\overline{RE}$)		V_{IH} = 2 V	–10		0	µA
I_{IL}	Low-level input current ($\overline{RE}$)		V_{IL} = 0.8 V	–10		0	µA
I_{OZ}	High-impedance output current		V_O = 0 V or 3.6 V	–10		15	µA
C_A or C_B	Input capacitance		V_I = 0.4 sin(30E6πt) + 0.5 V,(2) Other input at 1.2 V		3		pF
C_{AB}	Differential input capacitance		V_{AB} = 0.4 sin(30E6πt) V(2)			2.5	pF
$C_{A/B}$	Input capacitance balance, (C_A/C_B)			0.99		1.01	

(1) All typical values are at 25°C and with a 3.3-V supply voltage.
(2) HP4194A impedance analyzer (or equivalent)

BUS INPUT AND OUTPUT ELECTRICAL CHARACTERISTICS

over recommended operating conditions unless otherwise noted

PARAMETER		TEST CONDITIONS			MIN	TYP(1)	MAX	UNIT
I_A	Receiver or transceiver with driver disabled input current	V_A = 3.8 V,	V_B = 1.2 V,		0		32	µA
		V_A = 0 V or 2.4 V,	V_B = 1.2 V		–20		20	
		V_A = –1.4 V,	V_B = 1.2 V		–32		0	
I_B	Receiver or transceiver with driver disabled input current	V_B = 3.8 V,	V_A = 1.2 V		0		32	µA
		V_B = 0 V or 2.4 V,	V_A = 1.2 V		–20		20	
		V_B = –1.4 V,	V_A = 1.2 V		–32		0	
I_{AB}	Receiver or transceiver with driver disabled differential input current ($I_A - I_B$)	$V_A = V_B$,	–1.4 ≤ V_A ≤ 3.8 V		–4		4	µA
$I_{A(OFF)}$	Receiver or transceiver power-off input current	V_A = 3.8 V,	V_B = 1.2 V,	0 V ≤ V_{CC} ≤ 1.5 V	0		32	µA
		V_A = 0 V or 2.4 V,	V_B = 1.2 V,	0 V ≤ V_{CC} ≤ 1.5 V	–20		20	
		V_A = –1.4 V,	V_B= 1.2 V,	0 V ≤ V_{CC} ≤ 1.5 V	–32		0	
$I_{B(OFF)}$	Receiver or transceiver power-off input current	V_B = 3.8 V,	V_A = 1.2 V,	0 V ≤ V_{CC} ≤ 1.5 V	0		32	µA
		V_B = 0 V or 2.4 V,	V_A = 1.2 V,	0 V ≤ V_{CC} ≤ 1.5 V	–20		20	
		V_B = –1.4 V,	V_A = 1.2 V,	0 V ≤ V_{CC} ≤ 1.5 V	–32		0	
$I_{AB(OFF)}$	Receiver input or transceiver power-off differential input current ($I_A - I_B$)	$V_A = V_B$, 0 V ≤ V_{CC} ≤ 1.5 V, –1.4 ≤ V_A ≤ 3.8 V			–4		4	µA
C_A	Transceiver with driver disabled input capacitance	V_A = 0.4 sin (30E6πt) + 0.5V(2),	V_B =1.2 V			5		pF
C_B	Transceiver with driver disabled input capacitance	V_B = 0.4 sin (30E6πt) + 0.5V(2),	V_A =1.2 V			5		pF

(1) All typical values are at 25°C and with a 3.3-V supply voltage.
(2) HP4194A impedance analyzer (or equivalent)

BUS INPUT AND OUTPUT ELECTRICAL CHARACTERISTICS (continued)

PARAMETER		TEST CONDITIONS	MIN	TYP(1)	MAX	UNIT
C_{AB}	Transceiver with driver disabled differential input capacitance	V_{AB} = 0.4 sin (30E6πt)V (2)			3	pF
$C_{A/B}$	Transceiver with driver disabled input capacitance balance, (C_A/C_B)		0.99		1.01	

(1) All typical values are at 25°C and with a 3.3-V supply voltage.
(2) HP4194A impedance analyzer (or equivalent)

DRIVER SWITCHING CHARACTERISTICS

over recommended operating conditions unless otherwise noted

PARAMETER		TEST CONDITIONS	MIN	TYP(1)	MAX	UNIT
t_{pLH}	Propagation delay time, low-to-high-level output	See Figure 5	1	1.5	2.4	ns
t_{pHL}	Propagation delay time, high-to-low-level output		1	1.5	2.4	ns
t_r	Differential output signal rise time		1		1.6	ns
t_f	Differential output signal fall time		1		1.6	ns
$t_{sk(p)}$	Pulse skew ($\lvert t_{pHL} - t_{pLH} \rvert$)			0	100	ps
$t_{sk(pp)}$	Part-to-part skew				1	ns
$t_{jit(per)}$	Period jitter, rms (1 standard deviation) (2)	100 MHz clock input(3)		2	3	ps
$t_{jit(pp)}$	Peak-to-peak jitter(2)(5)	200 Mbps 2^{15}–1 PRBS input(4)		30	130	ps
t_{pHZ}	Disable time, high-level-to-high-impedance output	See Figure 6			7	ns
t_{pLZ}	Disable time, low-level-to-high–impedance output				7	ns
t_{pZH}	Enable time, high-impedance-to-high-level output				7	ns
t_{pZL}	Enable time, high-impedance-to-low-level output				7	ns

(1) All typical values are at 25°C and with a 3.3-V supply voltage.
(2) Jitter is ensured by design and characterization. Stimulus jitter has been subtracted from the numbers.
(3) $t_r = t_f$ = 0.5 ns (10% to 90%), measured over 30 k samples.
(4) $t_r = t_f$ = 0.5 ns (10% to 90%), measured over 100 k samples.
(5) Peak-to-peak jitter includes jitter due to pulse skew ($t_{sk(p)}$).

RECEIVER SWITCHING CHARACTERISTICS

over recommended operating conditions unless otherwise noted

PARAMETER			TEST CONDITIONS	MIN	TYP(1)	MAX	UNIT
t_{pLH}	Propagation delay time, low-to-high-level output		C_L = 15 pF, See Figure 10	2	4	6	ns
t_{pHL}	Propagation delay time, high-to-low-level output			2	4	6	ns
t_r	Output signal rise time			1		2.3	ns
t_f	Output signal fall time			1		2.3	ns
$t_{sk(p)}$	Pulse skew ($\lvert t_{pHL} - t_{pLH} \rvert$)	Type 1			100	300	ps
		Type 2			300	500	ps
$t_{sk(pp)}$	Part-to-part skew(2)					1	ns
$t_{jit(per)}$	Period jitter, rms (1 standard deviation) (3)		100 MHz clock input(4)		4	7	ps
$t_{jit(pp)}$	Peak-to-peak jitter(3)(6)	Type 1	200 Mbps 2^{15}–1 PRBS input(5)		300	700	ps
		Type 2			450	800	ps
t_{pHZ}	Disable time, high-level-to-high-impedance output		See Figure 11			10	ns
t_{pLZ}	Disable time, low-level-to-high-impedance output					10	ns
t_{pZH}	Enable time, high-impedance-to-high-level output					15	ns
t_{pZL}	Enable time, high-impedance-to-low-level output					15	ns

(1) All typical values are at 25°C and with a 3.3-V supply voltage.
(2) HP4194A impedance analyzer (or equivalent)
(3) Jitter is ensured by design and characterization. Stimulus jitter has been subtracted from the numbers.
(4) V_{ID} = 200 mV_{pp} (LVD201, 203), V_{ID} = 400 mV_{pp} (LVD206, 207), V_{cm} = 1 V, $t_r = t_f$ = 0.5 ns (10% to 90%), measured over 30 k samples.
(5) V_{ID} = 200 mV_{pp} (LVD201, 203), V_{ID} = 400 mV_{pp} (LVD206, 207), V_{cm} = 1 V, $t_r = t_f$ = 0.5 ns (10% to 90%), measured over 100 k samples.
(6) Peak-to-peak jitter includes jitter due to pulse skew ($t_{sk(p)}$).

PARAMETER MEASUREMENT INFORMATION

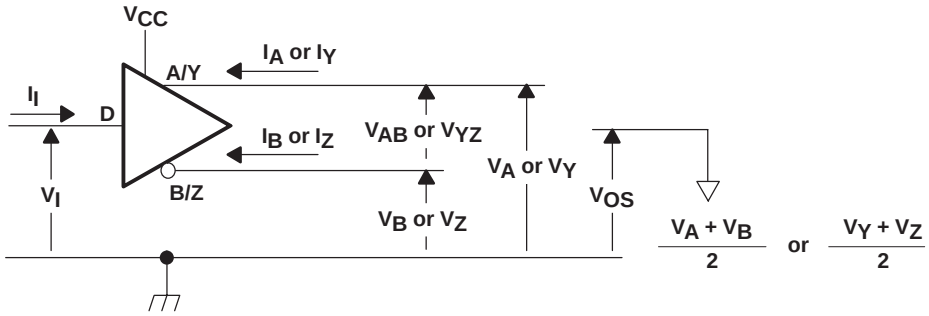
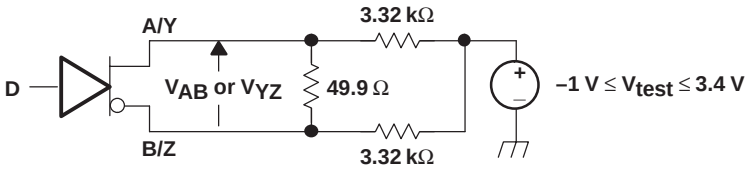
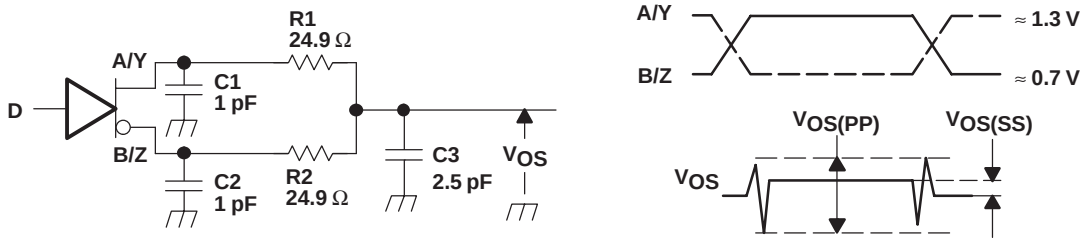


Figure 1. Driver Voltage and Current Definitions



NOTE: All resistors are 1% tolerance.

Figure 2. Differential Output Voltage Test Circuit



NOTES:A. All input pulses are supplied by a generator having the following characteristics: t_r or t_f ≤ 1 ns, pulse frequency = 500 kHz, duty cycle = 50 ± 5%.

B. C1, C2 and C3 include instrumentation and fixture capacitance within 2 cm of the D.U.T. and are ±20%.

C. R1 and R2 are metal film, surface mount, ±1%, and located within 2 cm of the D.U.T.

D. The measurement of $V_{OS(PP)}$ is made on test equipment with a –3 dB bandwidth of at least 1 GHz.

Figure 3. Test Circuit and Definitions for the Driver Common-Mode Output Voltage

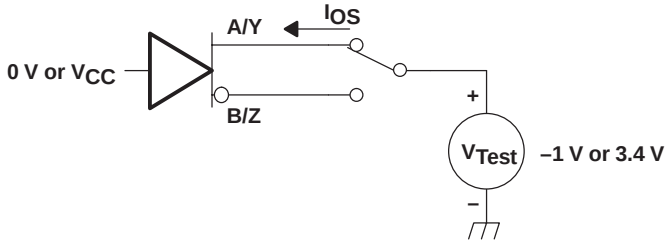
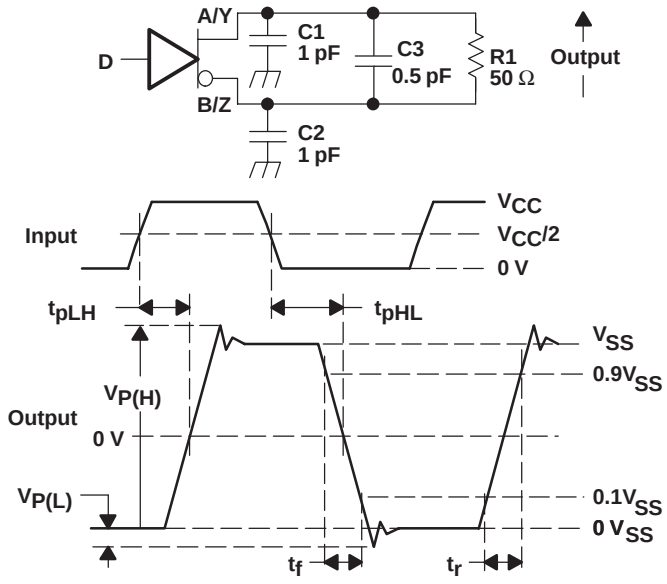
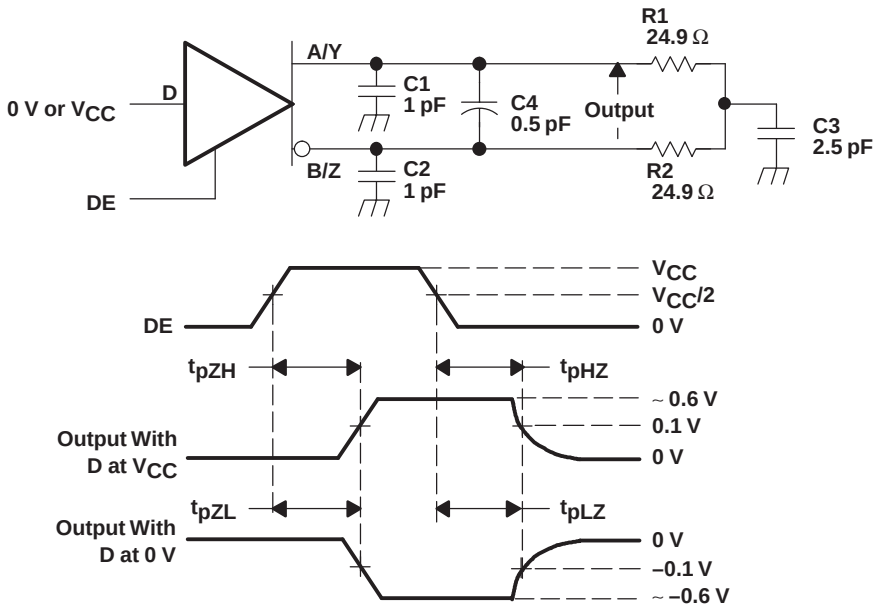


Figure 4. Driver Short-Circuit Test Circuit



NOTES:A. All input pulses are supplied by a generator having the following characteristics: t_r or $t_f \leq 1$ ns, frequency = 500 kHz, duty cycle = 50 ± 5%.
B. C1, C2, and C3 include instrumentation and fixture capacitance within 2 cm of the D.U.T. and are ±20%.
C. R1 is a metal film, surface mount, and 1% tolerance and located within 2 cm of the D.U.T.
D. The measurement is made on test equipment with a –3 dB bandwidth of at least 1 GHz.

Figure 5. Driver Test Circuit, Timing, and Voltage Definitions for the Differential Output Signal



NOTES:A. All input pulses are supplied by a generator having the following characteristics: t_r or $t_f \leq 1$ ns, frequency = 500 kHz, duty cycle = 50 ± 5%.
B. C1, C2, C3, and C4 includes instrumentation and fixture capacitance within 2 cm of the D.U.T. and are ±20%.
C. R1 and R2 are metal film, surface mount, and 1% tolerance and located within 2 cm of the D.U.T.
D. The measurement is made on test equipment with a –3 dB bandwidth of at least 1 GHz.

Figure 6. Driver Enable and Disable Time Circuit and Definitions

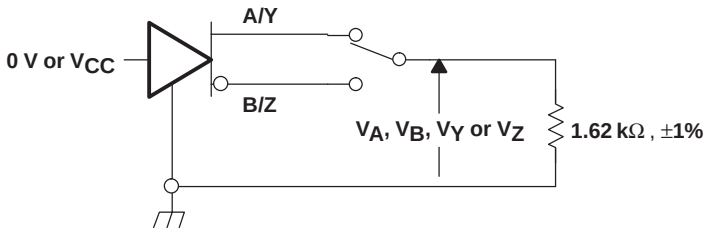
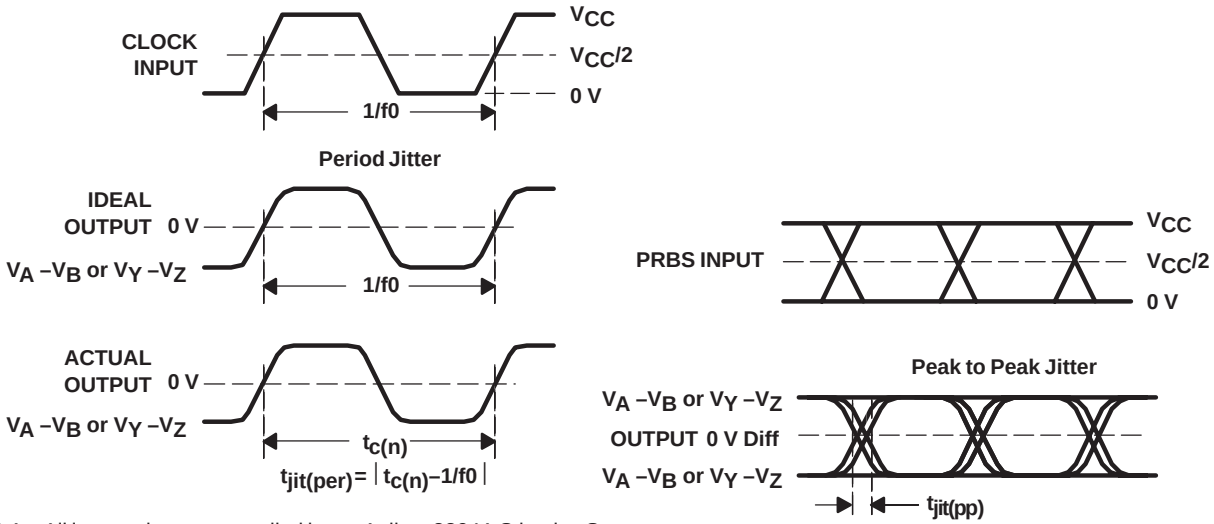


Figure 7. Maximum Steady State Output Voltage



NOTES:A. All input pulses are supplied by an Agilent 8304A Stimulus System.
B. The measurement is made on a TEK TDS6604 running TDSJIT3 application software
C. Period jitter is measured using a 100 MHz 50 ±1% duty cycle clock input.
D. Peak-to-peak jitter is measured using a 200Mbps 2^{15}–1 PRBS input.

Figure 8. Driver Jitter Measurement Waveforms

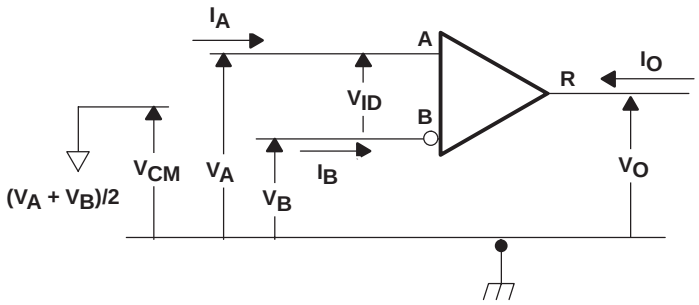


Figure 9. Receiver Voltage and Current Definitions

Table 1. Type-1 Receiver Input Threshold Test Voltages

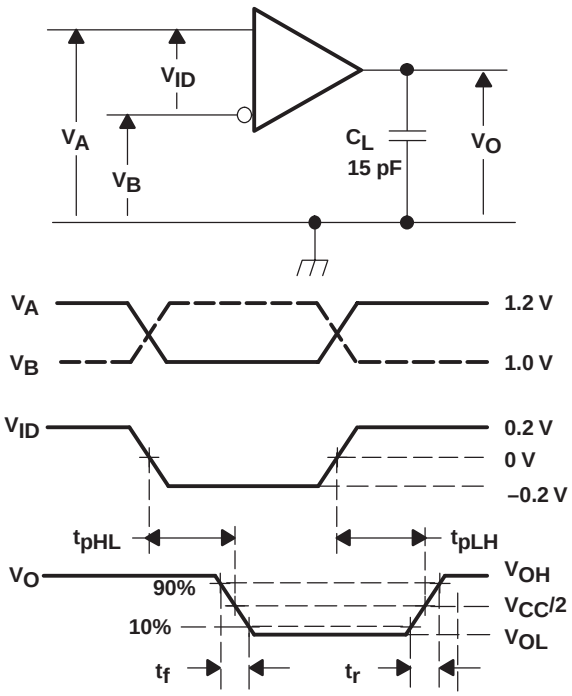
APPLIED VOLTAGES		RESULTING DIFFERENTIAL INPUT VOLTAGE	RESULTING COMMON–MODE INPUT VOLTAGE	RECEIVER OUTPUT
V_{IA}	V_{IB}	V_{ID}	V_{IC}	
2.400	0.000	2.400	1.200	H
0.000	2.400	–2.400	1.200	L
3.800	3.750	0.050	3.775	H
3.750	3.800	–0.050	3.775	L
–1.350	–1.400	0.050	–1.375	H
–1.400	–1.350	–0.050	–1.375	L

NOTE: H= high level, L = low level, output state assumes receiver is enabled ($\overline{RE}$ = L)

Table 2. Type-2 Receiver Input Threshold Test Voltages

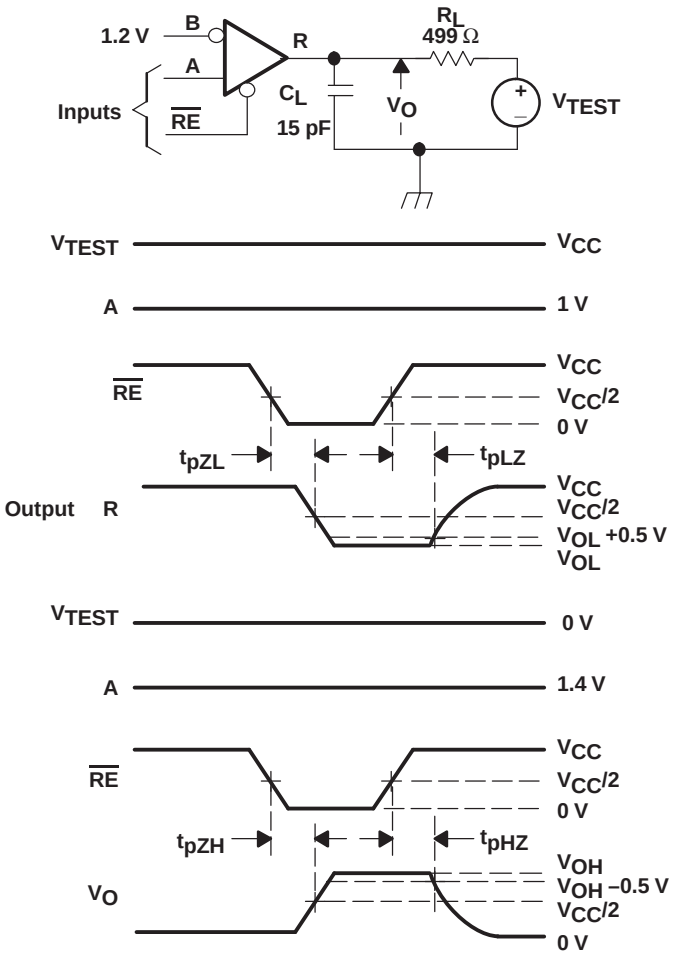
APPLIED VOLTAGES		RESULTING DIFFERENTIAL INPUT VOLTAGE	RESULTING COMMON–MODE INPUT VOLTAGE	RECEIVER OUTPUT
V_{IA}	V_{IB}	V_{ID}	V_{IC}	
2.400	0.000	2.400	1.200	H
0.000	2.400	–2.400	1.200	L
3.800	3.650	0.150	3.725	H
3.800	3.750	0.050	3.775	L
–1.250	–1.400	0.150	–1.325	H
–1.350	–1.400	0.050	–1.375	L

NOTE: H= high level, L = low level, output state assumes receiver is enabled ($\overline{RE}$ = L)



NOTES:A. All input pulses are supplied by a generator having the following characteristics: t_r or $t_f \le 1$ ns, frequency = 50 MHz, duty cycle = 50 ± 5%. C_L is a combination of a 20%-tolerance, low-loss ceramic, surface-mount capacitor and fixture capacitance within 2 cm of the D.U.T.
B. The measurement is made on test equipment with a –3 dB bandwidth of at least 1 GHz.

Figure 10. Receiver Timing Test Circuit and Waveforms



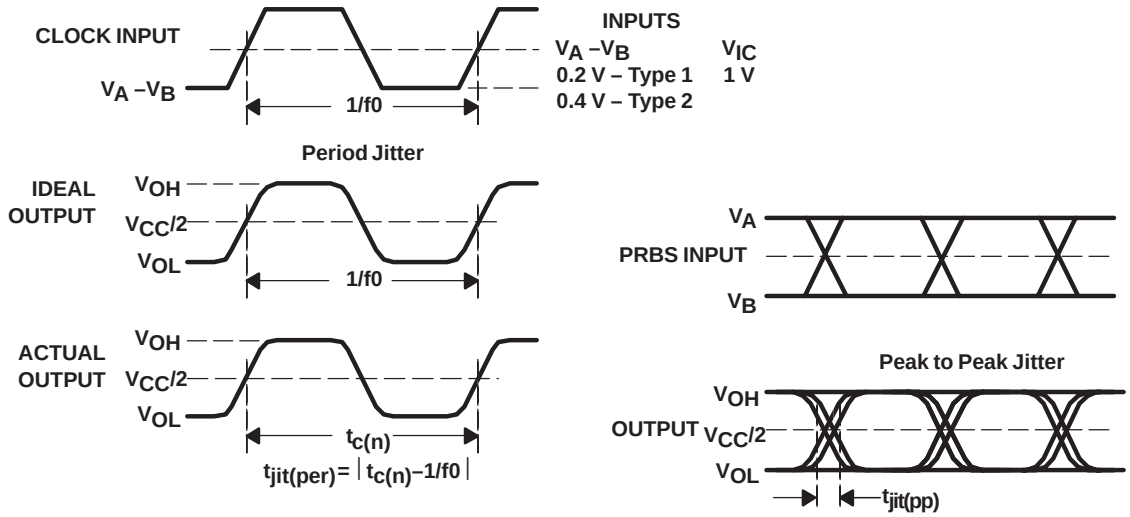
NOTES:A. All input pulses are supplied by a generator having the following characteristics: t_r or $t_f \leq 1$ ns, frequency = 500 kHz, duty cycle = 50 ± 5%.

B. R_L is 1% tolerance, metal film, surface mount, and located within 2 cm of the D.U.T.

C. R_L is 1% tolerance, metal film, surface mount, and located within 2 cm of the D.U.T.

D. C_L is the instrumentation and fixture capacitance within 2 cm of the DUT and ±20%.

Figure 11. Receiver Enable/Disable Time Test Circuit and Waveforms

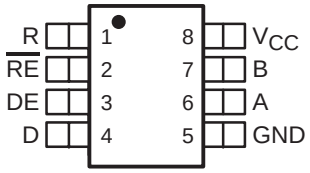


NOTES:A. All input pulses are supplied by an Agilent 8304A Stimulus System.
B. The measurement is made on a TEK TDS6604 running TDSJIT3 application software
C. Period jitter is measured using a 100 MHz 50 ±1% duty cycle clock input.
D. Peak-to-peak jitter is measured using a 200 Mbps 2^{15}–1 PRBS input.

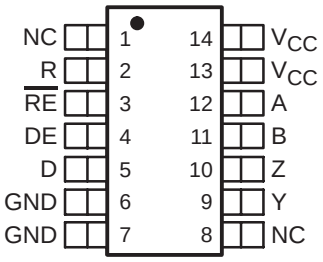
Figure 12. Receiver Jitter Measurement Waveforms

PIN ASSIGNMENTS

SN65MLVD201D (Marked as MF201)
SN65MLVD206D (Marked as MF206)
(TOP VIEW)



SN65MLVD203D (Marked as MLVD203)
SN65MLVD207D (Marked as MLVD207)
(TOP VIEW)



NC – No internal connection

DEVICE FUNCTION TABLE

TYPE-1 RECEIVER (201, 203)

INPUTS		OUTPUT
$V_{ID} = V_A - V_B$	$\overline{RE}$	R
$V_{ID} \geq 50$ mV	L	H
-50 mV $< V_{ID} < 50$ mV	L	?
$V_{ID} \leq -50$ mV	L	L
X	H	Z
X	Open	Z
Open Circuit	L	?

TYPE-2 RECEIVER (206, 207)

INPUTS		OUTPUT
$V_{ID} = V_A - V_B$	$\overline{RE}$	R
$V_{ID} \geq 150$ mV	L	H
50 mV $< V_{ID} < 150$ mV	L	?
$V_{ID} \leq 50$ mV	L	L
X	H	Z
X	Open	Z
Open Circuit	L	L

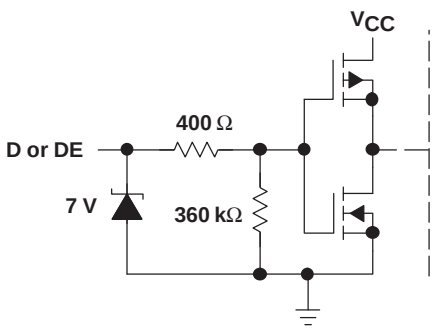
DRIVER

INPUT	ENABLE	OUTPUTS	
D	DE	A OR Y	B OR Z
L	H	L	H
H	H	H	L
OPEN	H	L	H
X	OPEN	Z	Z
X	L	Z	Z

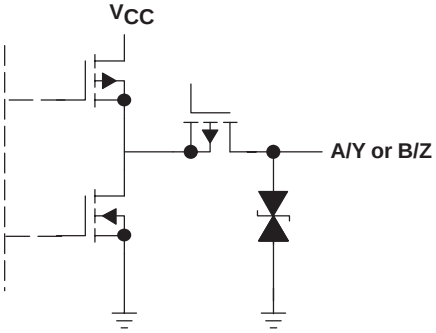
H = high level, L = low level, Z = high impedance, X = Don't care, ? = indeterminate

EQUIVALENT INPUT AND OUTPUT SCHEMATIC DIAGRAMS

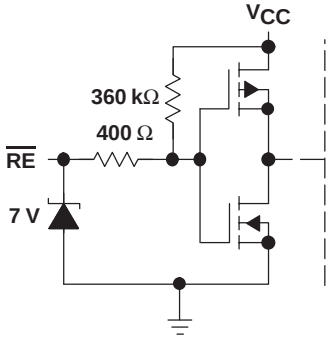
DRIVER INPUT AND DRIVER ENABLE



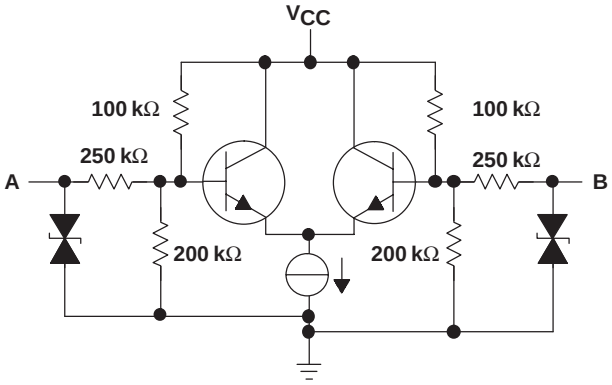
DRIVER OUTPUT



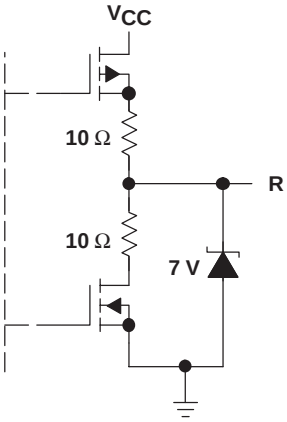
RECEIVER ENABLE



RECEIVER INPUT



RECEIVER OUTPUT



TYPICAL CHARACTERISTICS

SUPPLY CURRENT vs FREQUENCY

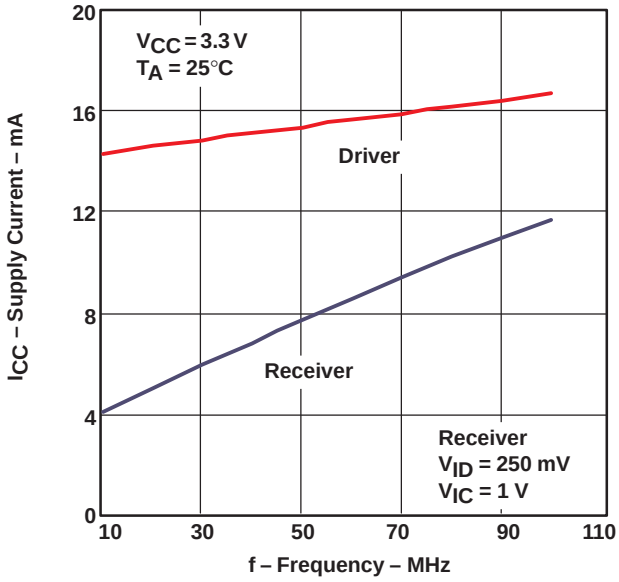


Figure 13

SUPPLY CURRENT vs FREE-AIR TEMPERATURE

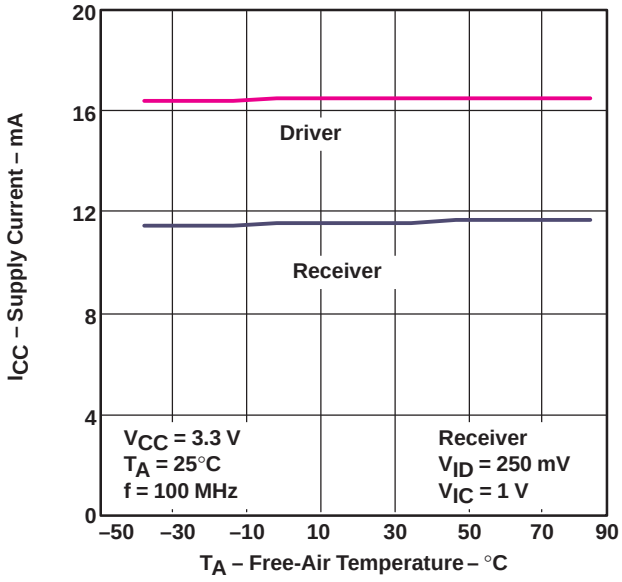


Figure 14

RECEIVER LOW-LEVEL OUTPUT CURRENT vs LOW-LEVEL OUTPUT VOLTAGE

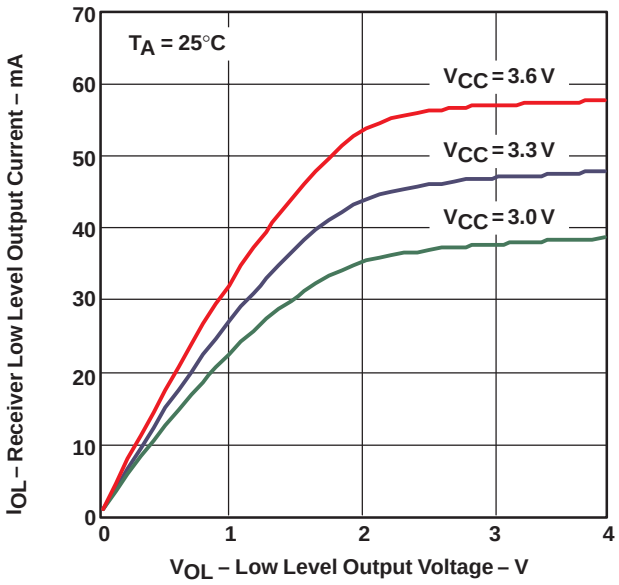


Figure 15

RECEIVER HIGH-LEVEL OUTPUT CURRENT vs HIGH-LEVEL OUTPUT VOLTAGE

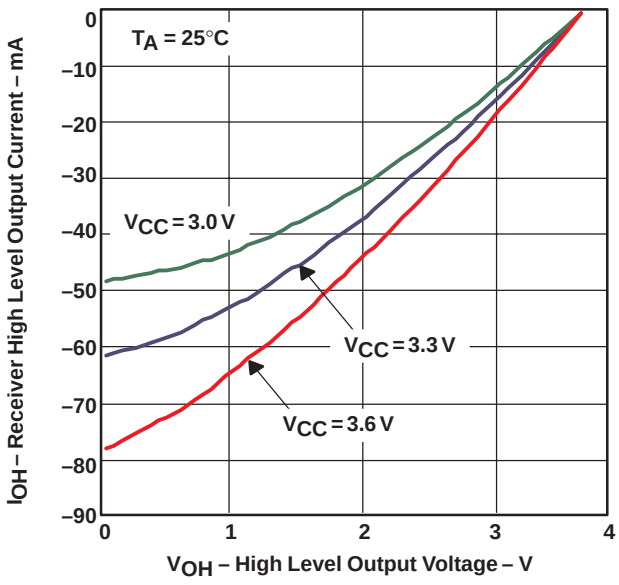


Figure 16

DIFFERENTIAL OUTPUT VOLTAGE
vs
OUTPUT CURRENT

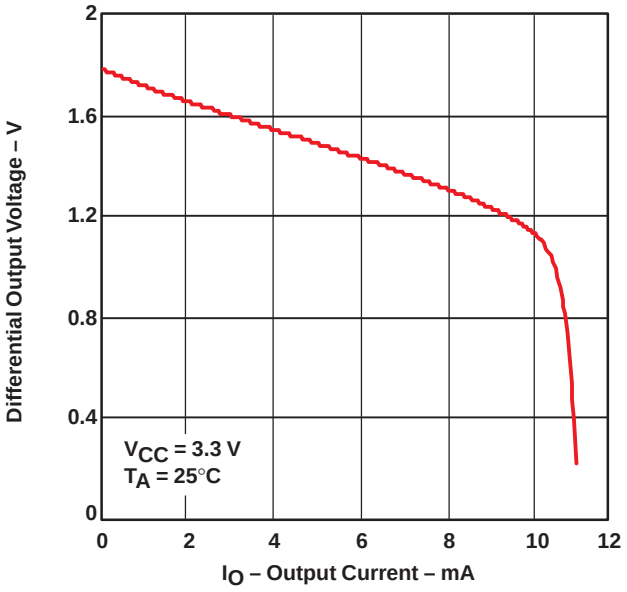


Figure 17

DRIVER PROPAGATION DELAY
vs
FREE-AIR TEMPERATURE

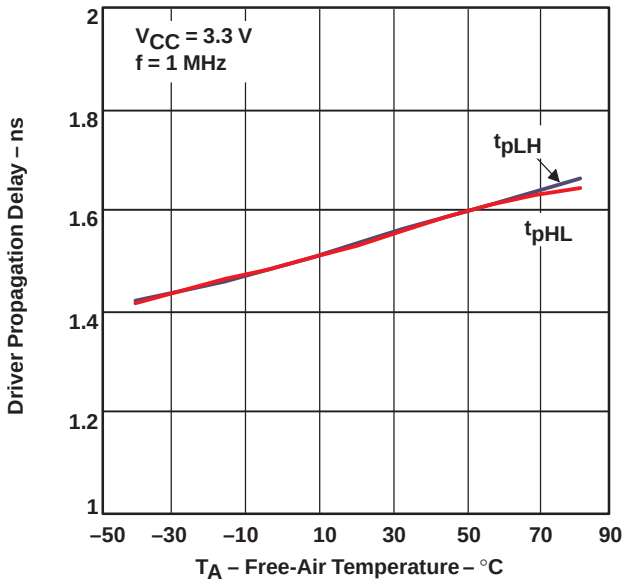


Figure 18

RECEIVER PROPAGATION DELAY
vs
FREE-AIR TEMPERATURE

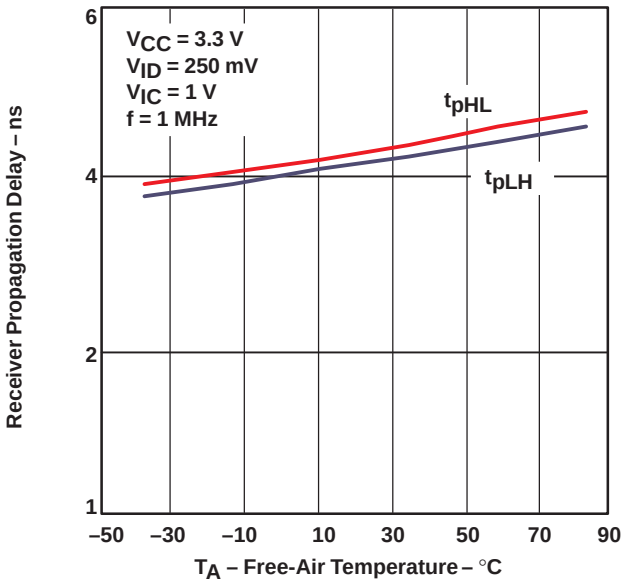


Figure 19

ADDED DRIVER CYCLE-TO-CYCLE JITTER (PEAK)
vs
FREQUENCY

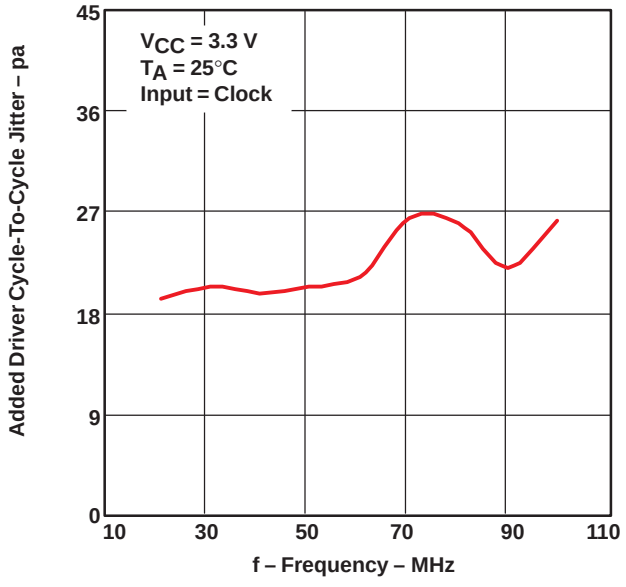


Figure 20

ADDED DRIVER PEAK-TO-PEAK JITTER
vs
DATA RATE

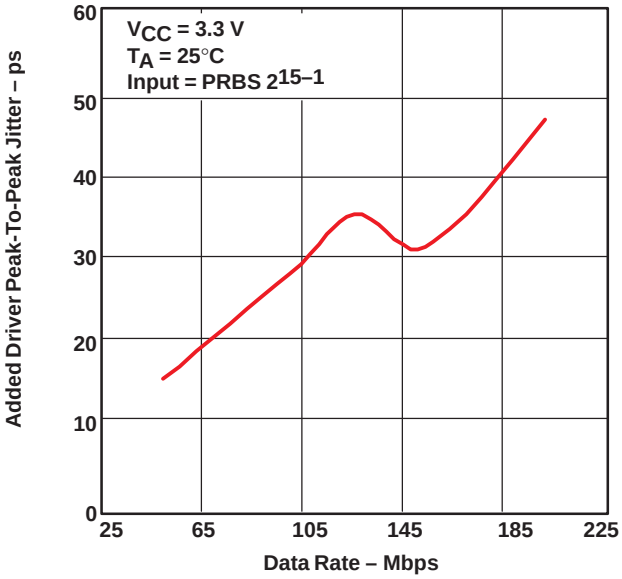


Figure 21

ADDED DRIVER PEAK-TO-PEAK JITTER
vs
FREE-AIR TEMPERATURE

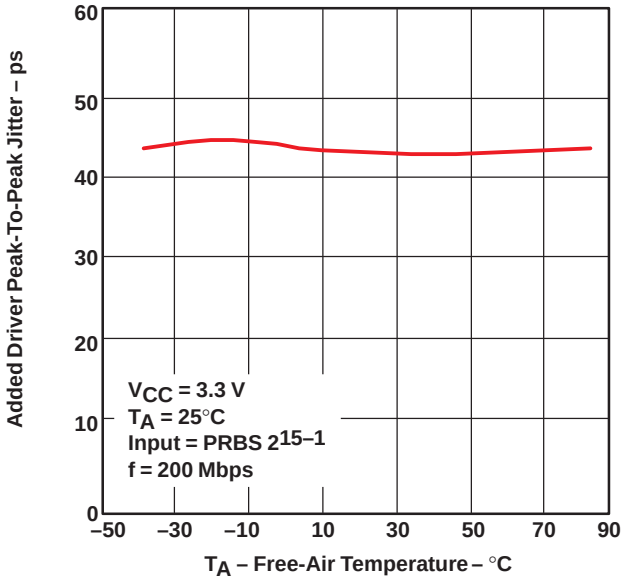


Figure 22

ADDED RECEIVER CYCLE-TO-CYCLE JITTER
vs
FREQUENCY

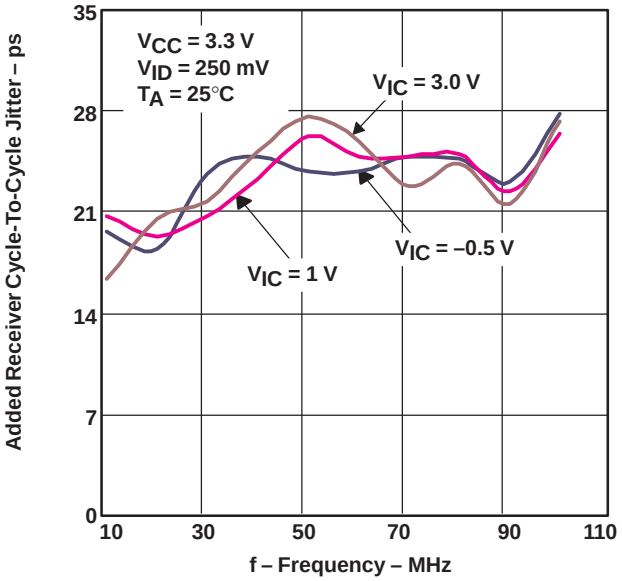


Figure 23

ADDED RECEIVER PEAK-TO-PEAK JITTER
vs
FREE-AIR TEMPERATURE

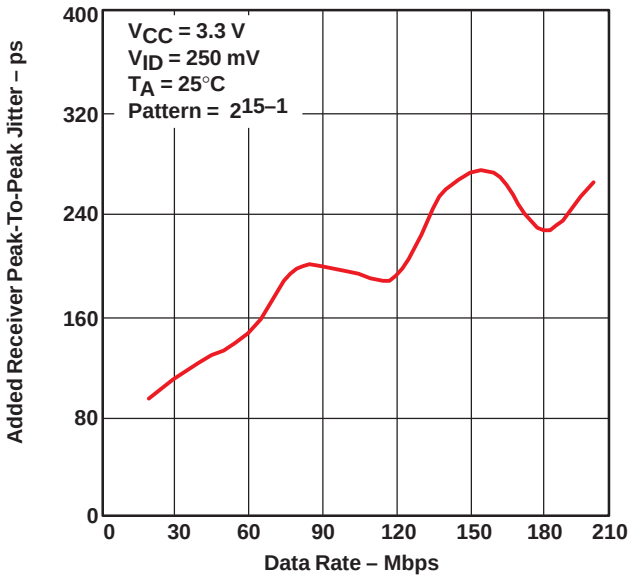


Figure 24

ADDED RECEIVER PEAK-TO–PEAK JITTER vs FREE-AIR TEMPERATURE

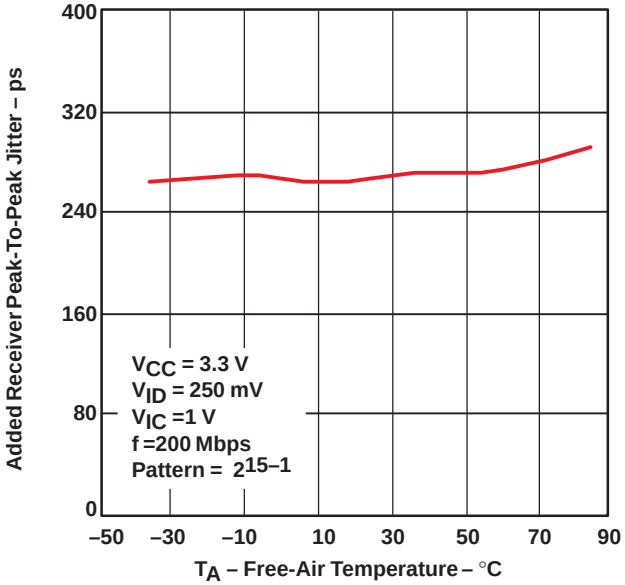
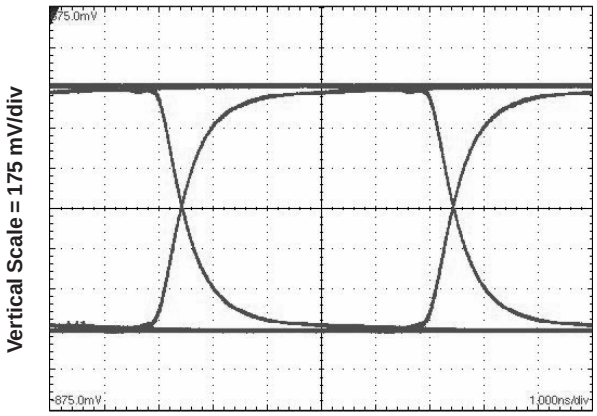


Figure 25

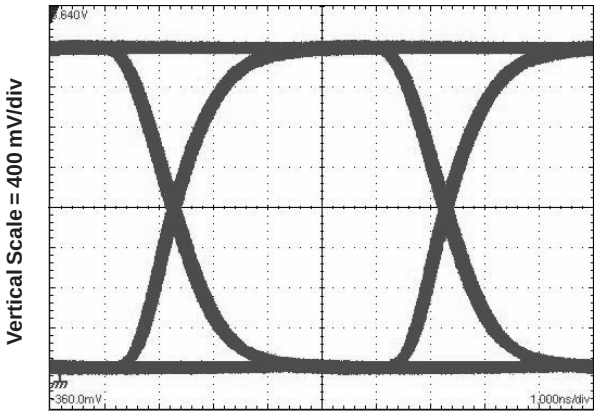
SN65MLVD201 DRIVER OUTPUT EYE PATTERN
200 Mbps, $2^{15}-1$ PRBS, R_L = 50 Ω



Horizontal Scale = 1 ns/div

Figure 26

SN65MLVD201 RECEIVER OUTPUT EYE PATTERN
200 Mbps, $2^{15}-1$ PRBS, C_L = 15 pF



Horizontal Scale = 1 ns/div

Figure 27

APPLICATION INFORMATION

COMPARISON OF MLVD TO TIA/EIA-485

Receiver Input Threshold (Failsafe)

The MLVD standard defines a type 1 and type 2 receiver. Type 1 receivers include no provisions for failsafe and have their differential input voltage thresholds near zero volts. Type 2 receivers have their differential input voltage thresholds offset from zero volts to detect the absence of a voltage difference. The impact to receiver output by the offset input can be seen in Table 3 and Figure 28.

Table 3. Receiver Input Voltage Threshold Requirements

RECEIVER TYPE	OUTPUT LOW	OUTPUT HIGH
Type 1	$-2.4\ V \le V_{ID} \le -0.05\ V$	$0.05\ V \le V_{ID} \le 2.4\ V$
Type 2	$-2.4\ V \le V_{ID} \le 0.05\ V$	$0.15\ V \le V_{ID} \le 2.4\ V$

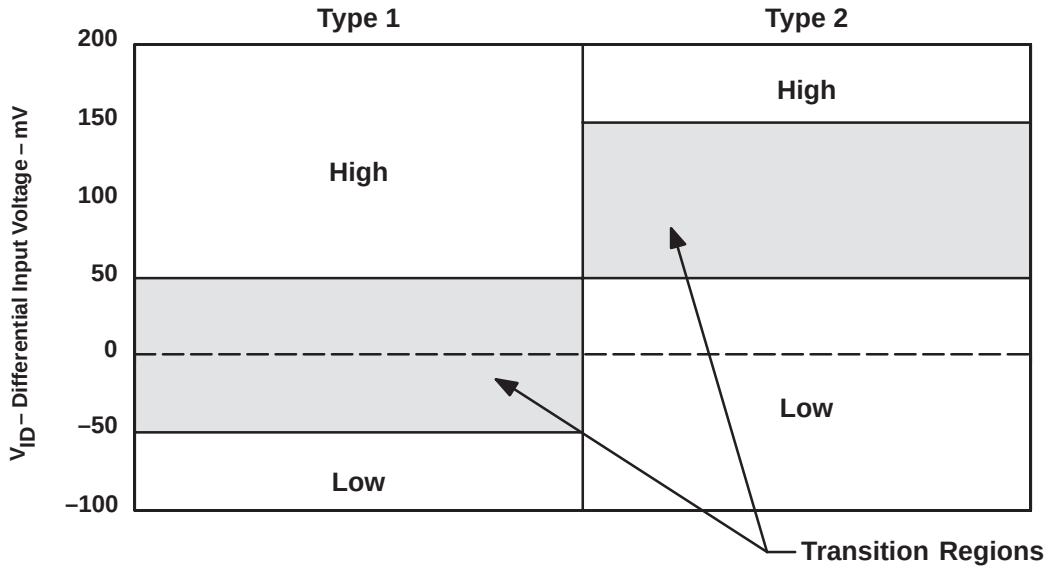


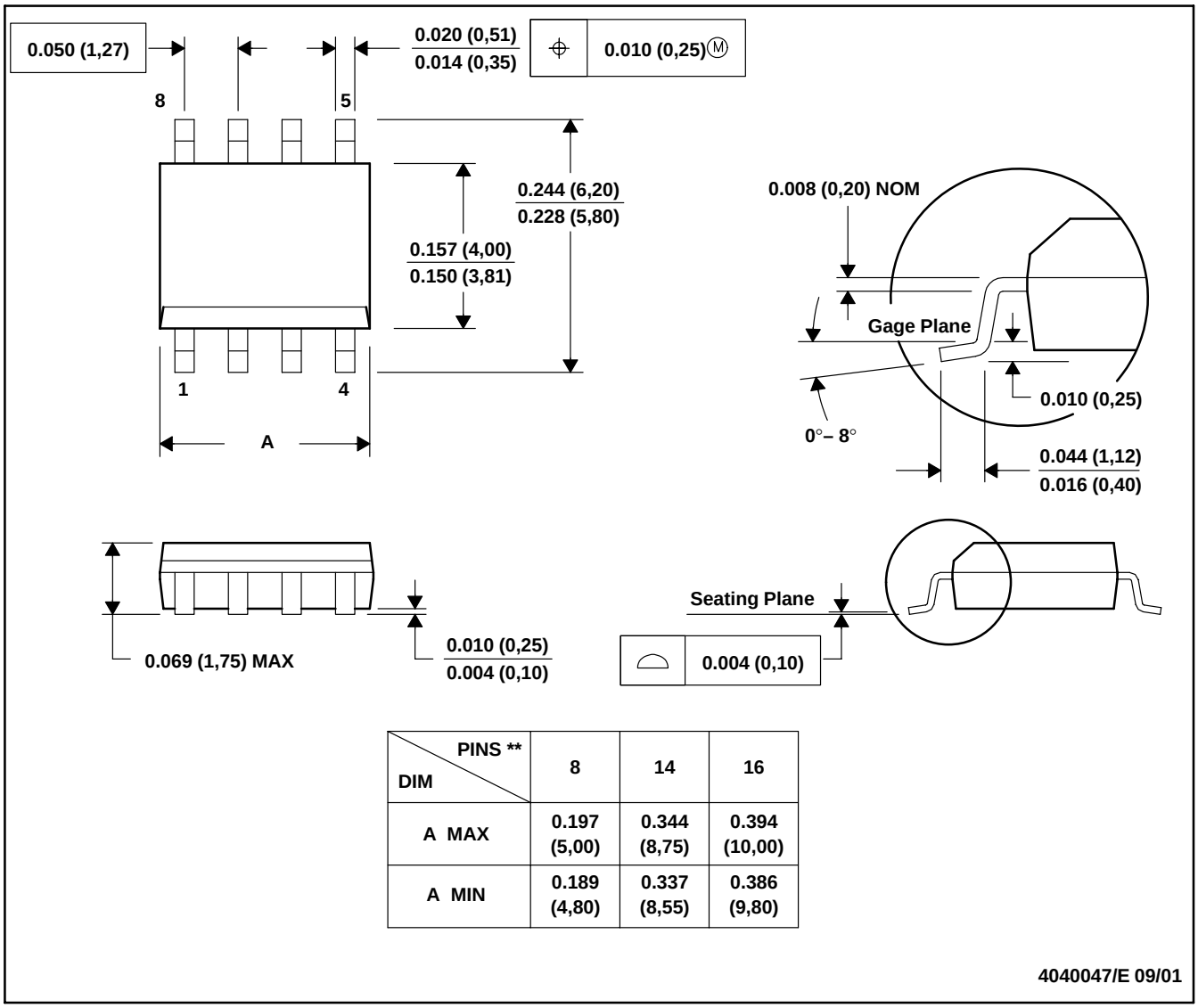
Figure 28. Expanded Graph of Receiver Differential Input Voltage Showing Transition Region

MSOI002B – JANUARY 1995 – REVISED SEPTEMBER 2001

D (R-PDSO-G**)

PLASTIC SMALL-OUTLINE PACKAGE

8 PINS SHOWN



DIM \ PINS **	8	14	16
A MAX	0.197 (5,00)	0.344 (8,75)	0.394 (10,00)
A MIN	0.189 (4,80)	0.337 (8,55)	0.386 (9,80)

4040047/E 09/01

NOTES: A. All linear dimensions are in inches (millimeters).
B. This drawing is subject to change without notice.
C. Body dimensions do not include mold flash or protrusion, not to exceed 0.006 (0,15).
D. Falls within JEDEC MS-012

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