

Product Features:

Common Features:

- PI74FCT16240T, PI74FCT162240T, and PI74FCT162H240T are high-speed, low power devices with high current drive
- $V_{CC} = 5V \pm 10\%$
- Hysteresis on all inputs
- Packages available:
 - 48-pin 240 mil wide plastic TSSOP (A)
 - 48-pin 300 mil wide plastic SSOP (V)

PI74FCT16240T Features:

- High output drive: $I_{OH} = -32\text{ mA}$; $I_{OL} = 64\text{ mA}$
- Power off disable outputs permit "live insertion"
- Typical V_{OLP} (Output Ground Bounce) $< 1.0\text{ V}$ at $V_{CC} = 5\text{ V}$, $T_A = 25^\circ\text{C}$

PI74FCT162240T Features:

- Balanced output drivers: $\pm 24\text{ mA}$
- Reduced system switching noise
- Typical V_{OLP} (Output Ground Bounce) $< 0.6\text{ V}$ at $V_{CC} = 5\text{ V}$, $T_A = 25^\circ\text{C}$

PI74FCT162H240T Features:

- Bus Hold retains last active bus state during 3-state
- Eliminates the need for external pull-up resistors

Product Description:

Pericom Semiconductor's PI74FCT series of logic circuits are produced in the Company's advanced 0.6 micron CMOS technology, achieving industry leading speed grades.

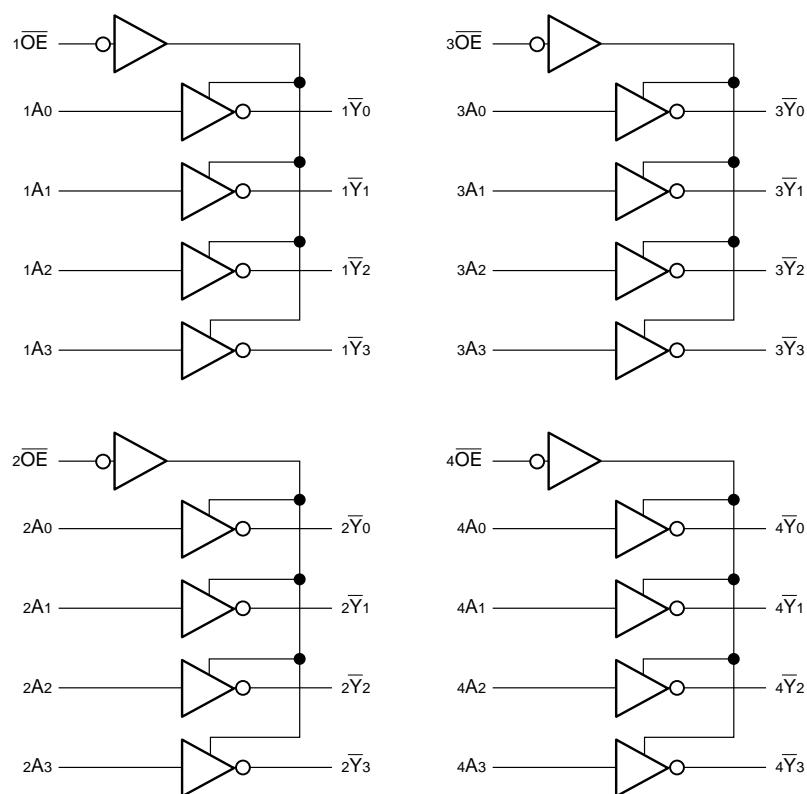
The PI74FCT16240T, PI74FCT162240T, and PI74FCT162H240T are inverting 16-bit buffer/line drivers designed for applications driving high capacitance loads and low impedance backplanes. These high-speed, low power devices offer bus/backplane interface capability and a flow-through organization for ease of board layout. These devices are designed with three-state controls to operate in a Quad-Nibble, Dual-Byte, or a single 16-bit word mode.

The PI74FCT16240T output buffers are designed with a Power-Off disable allowing "live insertion" of boards when used as backplane drivers.

The PI74FCT162240T has $\pm 24\text{ mA}$ balanced output drivers. It is designed with current limiting resistors at its outputs to control the output edge rate resulting in lower ground bounce and undershoot. This eliminates the need for external terminating resistors for most interface applications.

The PI74FCT162H240T has "Bus Hold" which retains the input's last state whenever the input goes to high-impedance preventing "floating" inputs and eliminating the need for pull-up/down resistors.

Logic Block Diagram

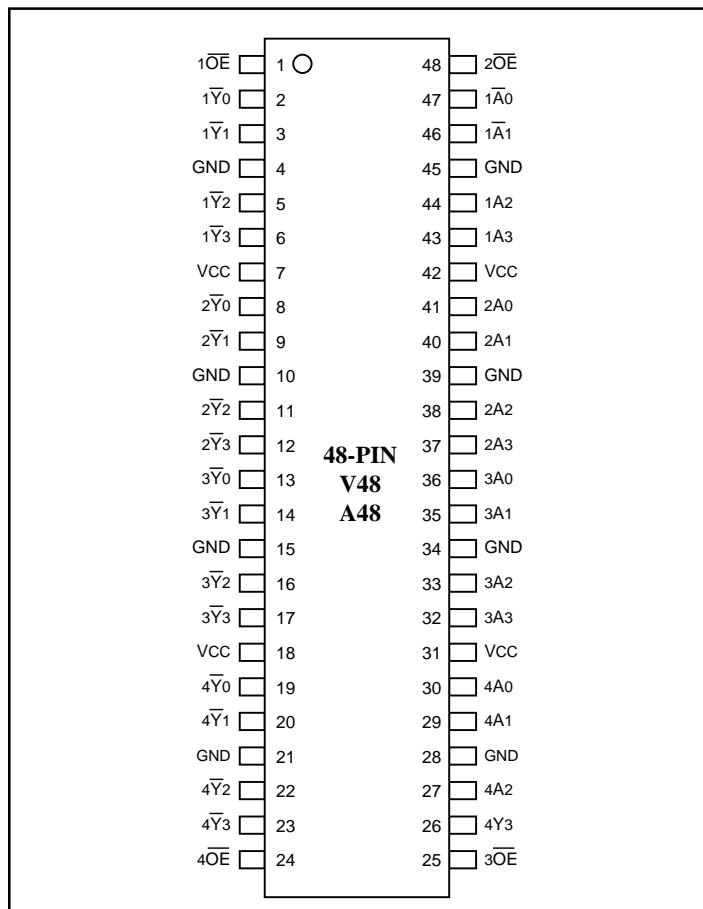


Product Pin Description

Pin Name	Description
xOE	3-State Output Enable Inputs (Active LOW)
xAx	Inputs ⁽¹⁾
x̄Yx	3-State Outputs
GND	Ground
VCC	Power

Note: 1. For the PI74FCT162H240T, these pins have "Bus Hold." All other pins are standard, outputs, or I/Os.

Product Pin Configuration



Truth Table

Inputs ⁽¹⁾		Outputs ⁽¹⁾
x̄OE	xAx	x̄Yx
L	L	H
L	H	L
H	X	Z

Note: 1. H = High Voltage Level
X = Don't Care
L = Low Voltage Level
Z = High Impedance

Maximum Ratings

(Above which the useful life may be impaired. For user guidelines, not tested.)

Storage Temperature	-65°C to +150°C
Ambient Temperature with Power Applied	-40°C to +85°C
Supply Voltage to Ground Potential (Inputs & Vcc Only)	-0.5V to +7.0V
Supply Voltage to Ground Potential (Outputs & D/O Only)	-0.5V to +7.0V
DC Input Voltage	-0.5V to +7.0V
DC Output Current	120mA
Power Dissipation	1.0W

Note:

Stresses greater than those listed under MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

DC Electrical Characteristics (Over the Operating Range, TA = -40°C to +85°C, VCC = 5.0V ± 10%)

Parameters	Description	Test Conditions ⁽¹⁾		Min.	Typ ⁽²⁾	Max.	Units
V _{IH}	Input HIGH Voltage	Guaranteed Logic HIGH Level		2.0			V
V _{IL}	Input LOW Voltage	Guaranteed Logic LOW Level				0.8	V
I _{IH}	Input HIGH Current	Standard Input, V _{CC} = Max.	V _{IN} = V _{CC}			1	µA
I _{IH}	Input HIGH Current	Standard I/O, V _{CC} = Max.	V _{IN} = V _{CC}			1	µA
I _{IH}	Input HIGH Current	Bus Hold Input ⁽⁴⁾ , V _{CC} = Max.	V _{IN} = V _{CC}			±100	µA
I _{IH}	Input HIGH Current	Bus Hold I/O ⁽⁴⁾ , V _{CC} = Max.	V _{IN} = V _{CC}			±100	µA
I _{IL}	Input LOW Current	Standard Input, V _{CC} = Min.	V _{IN} = GND			-1	µA
I _{IL}	Input LOW Current	Standard I/O, V _{CC} = Min.	V _{IN} = GND			-1	µA
I _{IL}	Input LOW Current	Bus Hold Input ⁽⁴⁾ , V _{CC} = Min.	V _{IN} = GND			±100	µA
I _{IL}	Input LOW Current	Bus Hold I/O ⁽⁴⁾ , V _{CC} = Min.	V _{IN} = GND			±100	µA
I _{BHH}	Bus Hold	Bus Hold Input ⁽⁴⁾ , V _{CC} = Min.	V _{IN} = 2.0V	-50			µA
I _{BHL}	Sustain Current		V _{IN} = 0.8V	+50			
I _{OZH⁽⁵⁾}	High Impedance	V _{CC} = Max.	V _{OUT} = 2.7V			1	µA
I _{OZL⁽⁵⁾}	Output Current	V _{CC} = Max.	V _{OUT} = 0.5V			-1	µA
V _{IK}	Clamp Diode Voltage	V _{CC} = Min., I _{IN} = -18 mA			-0.7	-1.2	V
I _{os}	Short Circuit Current	V _{CC} = Max. ⁽³⁾ , V _{OUT} = GND		-80	-140	-200	mA
I _o	Output Drive Current	V _{CC} = Max. ⁽³⁾ , V _{OUT} = 2.5V		-50		-180	mA
V _H	Input Hysteresis				100		mV

Notes:

1. For Max. or Min. conditions, use appropriate value specified under Electrical Characteristics for the applicable device type.
2. Typical values are at V_{CC} = 5.0V, +25°C ambient and maximum loading.
3. Not more than one output should be shorted at one time. Duration of the test should not exceed one second.
4. Pins with Bus Hold are identified in the pin description.
5. This specification does not apply to bi-directional functionalities with Bus Hold.

PI74FCT16240T Output Drive Characteristics (Over the Operating Range)

Parameters	Description	Test Conditions ⁽¹⁾	Min.	Typ ⁽²⁾	Max.	Units	
VOH	Output HIGH Voltage	VCC=Min., VIN=VIH or VIL	IOH=-3.0 mA	2.5	3.5	V	
			IOH=-15.0 mA	2.4	3.5		
			IOH=-32.0 mA	2.0	3.0		
VOL	Output LOW Voltage	VCC=Min., VIN=VIL or VIH	IOL=64 mA	—	0.2	0.55	V
IOFF	Power Down Disable	VCC=0V, VIN or VOUT≤4.5V	—	—	±100	μA	

PI74FCT162240T/162H240T Output Drive Characteristics (Over the Operating Range)

Parameters	Description	Test Conditions ⁽¹⁾	Min.	Typ ⁽²⁾	Max.	Units	
VOH	Output HIGH Voltage	VCC=Min., VIN=VIH or VIL	IOH=-24.0 mA	2.4	3.3	V	
VOL	Output LOW Voltage	VCC=Min., VIN=VIL or VIH	IOL=24 mA	—	0.3	0.55	V
IODL	Output LOW Current	VCC=5V, VIN=VIH or VIL, VOUT=1.5V ⁽³⁾	—	60	115	150	mA
IODH	Output HIGH Current	VCC=5V, VIN=VIL or VIH, VOUT=1.5V ⁽³⁾	—	-60	-115	-150	mA

Capacitance (TA=25°C, f=1 MHz)

Parameters ⁽⁴⁾	Description	Test Conditions	Typ	Max.	Units
CIN	Input Capacitance	VIN=0V	4.5	6	pF
COUT	Output Capacitance	VOUT=0V	5.5	8	pF

Notes:

1. For Max. or Min. conditions, use appropriate value specified under Electrical Characteristics for the applicable device type.
2. Typical values are at Vcc = 5.0V, +25°C ambient and maximum loading.
3. Not more than one output should be shorted at one time. Duration of the test should not exceed one second.
4. This parameter is determined by device characterization but is not production tested.

Power Supply Characteristics

Parameters	Description	Test Conditions ⁽¹⁾		Min.	Typ ⁽²⁾	Max.	Units
Icc	Quiescent Power Supply Current	Vcc = Max.	Vin = GND or Vcc		0.1	500	µA
ΔIcc	Supply Current per Input @ TTL HIGH	Vcc = Max.	Vin = 3.4 V ⁽³⁾		0.5	1.5	mA
ICCD	Supply Current per Input per MHz ⁽⁴⁾	Vcc = Max., Outputs Open xOE = GND One Bit Toggling 50% Duty Cycle	Vin = Vcc Vin = GND		60	100	µA/MHz
Ic	Total Power Supply Current ⁽⁶⁾	Vcc = Max., Outputs Open f _t = 10 MHz 50% Duty Cycle xOE = GND One Bit Toggling	Vin = Vcc Vin = GND		0.6	1.5 ⁽⁵⁾	mA
			Vin = 3.4 V Vin = GND		0.9	2.3 ⁽⁵⁾	
		Vcc = Max., Outputs Open f _t = 2.5 MHz 50% Duty Cycle xOE = GND 16 Bits Toggling	Vin = Vcc Vin = GND		2.4	4.5 ⁽⁵⁾	
			Vin = 3.4 V Vin = GND		6.4	16.5 ⁽⁵⁾	

Notes:

1. For Max. or Min. conditions, use appropriate value specified under Electrical Characteristics for the applicable device.
2. Typical values are at Vcc = 5.0 V, +25°C ambient.
3. Per TTL driven input (Vin = 3.4 V); all other inputs at Vcc or GND.
4. This parameter is not directly testable, but is derived for use in Total Power Supply Calculations.
5. Values for these conditions are examples of the Icc formula. These limits are guaranteed but not tested.
6. Ic = I_{QUIESCENT} + I_{INPUTS} + I_{DYNAMIC}

$$Ic = Icc + \Delta Icc D_{HNT} + ICCD (f_{CP}/2 + f_i N_i)$$

Icc = Quiescent Current

ΔIcc = Power Supply Current for a TTL High Input (Vin = 3.4 V)

D_H = Duty Cycle for TTL Inputs High

N_t = Number of TTL Inputs at D_H

ICCD = Dynamic Current Caused by an Input Transition Pair (HLH or LHL)

f_{CP} = Clock Frequency for Register Devices (Zero for Non-Register Devices)

f_i = Input Frequency

N_i = Number of Inputs at f_i

All currents are in millamps and all frequencies are in megahertz.

PI74FCT16240T Switching Characteristics over Operating Range

Parameters	Description	Conditions ⁽¹⁾	16240T		16240AT		16240CT		16240DT		16240ET		Unit	
			Com.		Com.		Com.		Com.		Com.			
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max		
tPLH tPHL	PropagationDelay xAx to x \bar{Y} x	CL=50 pF RL=500Ω	1.5	8.0	1.5	4.8	1.5	4.3	1.5	3.6	1.5	3.2	ns	
tPZH tPZL	OutputEnableTime x $\bar{O}\bar{E}$ to xAx or x \bar{Y} x		1.5	10.0	1.5	6.2	1.5	5.8	1.5	4.8	1.5	4.4	ns	
tPHZ tPLZ	OutputDisableTime ⁽³⁾ x $\bar{O}\bar{E}$ to xAx or x \bar{Y} x		1.5	9.5	1.5	5.6	1.5	5.2	1.5	4.0	1.5	4.0	ns	
tsk(o)	OutputSkew ⁽⁴⁾		—	0.5	—	0.5	—	0.5	—	0.5	—	0.5	ns	

PI74FCT162240T Switching Characteristics over Operating Range

Parameters	Description	Conditions ⁽¹⁾	162240T		162240AT		162240CT		162240DT		162240ET		Unit	
			Com.		Com.		Com.		Com.		Com.			
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max		
tPLH tPHL	PropagationDelay xAx to x \bar{Y} x	CL=50 pF RL=500Ω	1.5	8.0	1.5	4.8	1.5	4.3	1.5	3.6	1.5	3.2	ns	
tPZH tPZL	OutputEnableTime x $\bar{O}\bar{E}$ to xAx or x \bar{Y} x		1.5	10.0	1.5	6.2	1.5	5.8	1.5	4.8	1.5	4.4	ns	
tPHZ tPLZ	OutputDisableTime ⁽³⁾ x $\bar{O}\bar{E}$ to xAx or x \bar{Y} x		1.5	9.5	1.5	5.6	1.5	5.2	1.5	4.0	1.5	4.0	ns	
tsk(o)	OutputSkew ⁽⁴⁾		—	0.5	—	0.5	—	0.5	—	0.5	—	0.5	ns	

PI74FCT162H240T Switching Characteristics over Operating Range

Parameters	Description	Conditions ⁽¹⁾	162H240T		162H240AT		162H240CT		162H240DT		162H240ET		Unit	
			Com.		Com.		Com.		Com.		Com.			
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max		
tPLH tPHL	PropagationDelay xAx to x \bar{Y} x	CL=50 pF RL=500Ω	1.5	8.0	1.5	4.8	1.5	4.3	1.5	3.6	1.5	3.2	ns	
tPZH tPZL	OutputEnableTime x $\bar{O}\bar{E}$ to xAx or x \bar{Y} x		1.5	10.0	1.5	6.2	1.5	5.8	1.5	4.8	1.5	4.4	ns	
tPHZ tPLZ	OutputDisableTime ⁽³⁾ x $\bar{O}\bar{E}$ to xAx or x \bar{Y} x		1.5	9.5	1.5	5.6	1.5	5.2	1.5	4.0	1.5	4.0	ns	
tsk(o)	OutputSkew ⁽⁴⁾		—	0.5	—	0.5	—	0.5	—	0.5	—	0.5	ns	

Notes:

1. See test circuit and wave forms.
2. Minimum limits are guaranteed but not tested on Propagation Delays.
3. This parameter is guaranteed but not production tested.
4. Skew between any two outputs, of the same package, switch in the same direction.
This parameter is guaranteed by design.

Pericom Semiconductor Corporation

2380 Bering Drive • San Jose, CA 95131 • 1-800-435-2336 • Fax (408) 435-1100 • <http://www.pericom.com>