

# ORCA® ORLI10G Field-Programmable System Chip 10 Gbits/s Transmit and Receive Line Interface

#### Introduction

Agere Systems Inc has developed a new ORCA Series 4 based FPSC, which combines a high-speed line interface with a flexible FPGA logic core. Built on the Series 4 reconfigurable embedded system-on-chips (SoC) architecture, the ORLI10G consists of an OIF standard (OIF 99.102.5) compliant XSBI 10 Gbits/s transmit and 10 Gbits/s receive line interface. Both transmit and receive interfaces consist of 16-bit LVDS data up to 667 Mbits/s, integrated transmit and receive programmable PLLs for data rate conversions between the lineside and system-side data rates, and a programmable logic interface at the system end for use with SONET/SDH, Ethernet, or OTN/digital wrapper with strong FEC system device data standards. In addition to the embedded functionality, the device will include up to 400k of usable FPGA gates. The line interface includes logic to divide the data rate down to 167 MHz or less (1/4 line rate) or 84 MHz or less (1/8 line rate) for transfer to the FPGA logic. The ORLI10G is designed to connect directly to Lucent's 10 Gbits/s TTRN0110G MUX and TRCV0110G deMUX on the line side as well as other industry-standard devices. The programmable logic interface on the system side allows for direct connection to a 10 Gbits/s Ethernet MAC, a 10 Gbits/s SONET/SDH framer/data engine, or a 10 Gbits/s digital wrapper/FEC framer/data engine.

For 10 Gbits/s Ethernet, the ORLI10G supports the physical coding sublayer (PCS), interfaces to the physical media attachment (PMA), and connects to the system interface (host or switch) for the proposed *IEEE*\* 802.3ae 10 Gbits/s serial LAN PHY.

The ORLI10G FPSC is a high-speed programmable device for 10 Gbits/s data solutions. It can be used as the interface between the line interface and the system interface in a variety of emerging networks, including

10 Gbits/s SONET/SDH (OC-192/STM-48), 10 Gbits/s optical transport networks (OTN) using digital wrapper and strong FEC, or 10 Gbits/s Ethernet. Other functions include use in Quad OC-48/STM-16 SONET/SDH systems, interfaces between Quad OC-48/STM-16 and OC-192/STM-64 components, and use as a generic data transfer mechanism between two devices at 10 Gbits/s rates. Data is received at the line interface and then sent to either a 4-bit or 8-bit serial-to-parallel converter. On the transmit interface, either a 4-bit or 8-bit parallel-to-serial converter is used. Thus, the data rate at the internal FPGA interface is either 1/4 or 1/8 the line rate.

The programmable PLLs on the ORLI10G provide for great flexibility in handling clock rate conversion due to differing amounts of overhead bits in various system data standards. For example, when used as a 10 Gbits/s Ethernet interface, the ORLI10G will automatically divide the line frequency of 645 MHz by 4 x 66/64 (receive side) to synchronize with the system frequency of 156 MHz. When the ORLI10G is used as an interface to a 10 Gbits/s digital wrapper/FEC framer/ data engine, these same PLLs can divide the strong FEC standard line frequency of 667 MHz by 4 x 15/14 (receive side) to provide the 156 MHz system clock frequency. The ORLI10G can also divide down the STS-192/STM-64 SONET/SDH data line rate of 622 MHz by 4 to synchronize with a 155 MHz system clock. The ORLI10G can also be configured to provide a 78 MHz system data rate.

\* IEEE is a registered trademark of The Institute of Electrical and Electronics Engineers, Inc.

Table 1. ORCA ORLI10G—Available FPGA Logic

Device	PFU Rows	PFU Columns	Total PFUs	User I/Os	LUTs	EBR Blocks	EBR Bits (k)	Usable Gates (k)
ORLI10G	36	36	1296	432	10368	12	111	380—800

<sup>†</sup>The embedded core and interface are not included in the above gate counts. The usable gate counts range from a logic-only gate count to a gate count assuming 20% of the PFUs/SLICs being used as RAMs. The logic-only gate count includes each PFU/SLIC (counted as 108 gates/PFU), including 12 gates per LUT/FF pair (eight per PFU), and 12 gates per SLIC/FF pair (one per PFU). Each of the four PIO groups are counted as 16 gates (three FFs, fast-capture latch, output logic, CLK, and I/O buffers). PFUs used as RAM are counted at four gates per bit, with each PFU capable of implementing a 32 x 4 RAM (or 512 gates) per PFU. Embedded block RAM (EBR) is counted as four gates per bit plus each block has an additional 25k gates. 7k gates are used for each PLL and 50k gates for the embedded system bus and microprocessor interface logic. Both the EBR and PLLs are conservatively utilized in the gate count calculations.

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#### **Embedded Function Features**

- Provides a 10 Gbits/s line interface-to-interface with various system standards such as OC-192/STM-64 SONET/SDH, Quad OC-48/STM-16 10 Gbits/s Ethernet, and 10 Gbits/s OTN (digital wrapper/strong FEC).
- Embedded PLLs with programmable M/N multiplication/division values provide for flexible data rate conversion between line side and system side.
- Line side provides for 16-bit LVDS data with multiple line frequencies supported up to 667 MHz.
- Line-side interface, including timing and jitter specifications, compliant to OIF 99.102.5 standard.
- Receive-side interface can be split into four separate asynchronous 2.5 Gbits/s interfaces (4-bit LVDS data interface for each) with a separate clock for each for transfer to the FPGA logic.
- Data and clock rates divided by 4 or 8 for use in FPGA logic.
- Direct interface to Lucent's 10 Gbits/s MUX (TTRN0110G) and deMUX (TRCV0110G).
- LVDS I/Os compliant with *EIA\**-644, support hot insertion. All embedded LVDS I/Os include both input and output on-board termination to allow high-speed operation.
- Low-power LVDS buffers.
- Built-in boundary scan (*IEEE* 1149.1 JTAG).

# **Intellectual Property Features**

Programmable logic provides a variety of yet-to-be standardized interface functions, including the following IP core functions:

- 10 Gbits/s Ethernet as defined by IEEE 802.3ae:
  - XGMII for interfacing to 10 Gbits/s Ethernet MACs.
     XGMII is a 156 MHz double data rate parallel short-reach (typically less than 2 inches) interconnect interface.
  - Elastic store buffers for clock domain transfer to/ from the XGMII interface.
  - X<sup>58</sup> + X<sup>19</sup> + X<sup>1</sup> scrambler/descrambler for 10 Gbits/s Ethernet.
  - 66-bit word aligner and 64b/66b receive path decoder, 64b/66b transmit path encoder, and 66b/ 64b transmit path conversion for Ethernet overhead bits.

- 10 Gbits/s media access controller (MAC) can be implemented in a separate FPGA, FPSC, or ASIC.
- POS-PHY4 interface for 10 Gbits/s SONET/SDH and OTN systems and some 10 Gbits/s Ethernet systems.
- Quad 2.5 Gbits/s SONET/SDH to 10 Gbits/s SONET/ SDH MUX/deMUX functions.

# **Programmable Features**

- High-performance programmable logic:
  - 0.13 μm 7-level metal technology.
  - Internal performance of >250 MHz.
  - 400k usable system gates.
  - Meets multiple I/O interface standards.
  - 1.5 V operation (30% less power than 1.8 V operation) translates to greater performance.
- Traditional I/O selections:
  - LVTTL and LVCMOS (3.3 V, 2.5 V, and 1.8 V) I/Os.
  - Per pin-selectable I/O clamping diodes provide 3.3 V PCI compliance.
  - Individually programmable drive capability:
     24 mA sink/12 mA source, 12 mA sink/6 mA source, or 6 mA sink/3 mA source.
  - Two slew rates supported (fast & slew-limited).
  - Fast-capture input latch and input flip-flop (FF) latch for reduced input setup time and zero hold time.
  - Fast open-drain drive capability.
  - Capability to register 3-state enable signal.
  - Off-chip clock drive capability.
  - Two input function generator in output path.
- New programmable high-speed I/O:
  - Single-ended: GTL, GTL+, PECL, SSTL3/2 (class I & II), HSTL (Class I, III, IV), ZBT, and DDR.
  - Double-ended: LVDS, bused-LVDS, LVPECL.
  - Customer defined: ability to substitute arbitrary standard-cell I/O to meet fast moving standards.
- New capability to (de)multiplex I/O signals:
  - New DDR on both input and output at rates up to 311 MHz (622 MHz effective rate).
  - New 2x and 4x downlink and uplink capability per I/O (i.e., 50 MHz internal to 200 MHz I/O).

<sup>\*</sup> EIA is a registered trademark of Electronic Industries Association.

### **Programmable Features** (continued)

- Enhanced twin-quad programmable function unit (PFU):
  - Eight 16-bit look-up tables (LUTs) per PFU.
  - Nine user registers per PFU, one following each LUT, and organized to allow two nibbles to act independently, plus one extra for arithmetic operations.
  - New register control in each PFU has two independent programmable clocks, clock enables, local set/reset, and data selects.
  - New LUT structure allows flexible combinations of LUT4, LUT5, new LUT6, 4 → 1 MUX, new 8 → 1 MUX, and ripple mode arithmetic functions in the same PFU.
  - 32 x 4 RAM per PFU, configurable as single- or dual-port. Create large, fast RAM/ROM blocks (128 x 8 in only eight PFUs) using the SLIC decoders as bank drivers.
  - Soft-wired LUTs (SWL) allow fast cascading of up to three levels of LUT logic in a single PFU through fast internal routing which reduces routing congestion and improves speed.
  - Flexible fast access to PFU inputs from routing.
  - Fast-carry logic and routing to all four adjacent PFUs for nibble-wide, byte-wide, or longer arithmetic functions, with the option to register the PFU carry-out.
- Abundant high-speed buffered and nonbuffered routing resources provide 2x average speed improvements over previous architectures.
- New cycle stealing capability allows a typical 15% to 40% internal speed improvement after final place and route. This feature also allows many I/O specifications to be met for setup/hold and clock-to-out times. It may also reduce ground bounce effects for output buses by allowing flexible delays in switching output buffers.
- Hierarchical routing optimized for both local and global routing with dedicated routing resources. This results in faster routing times with predictable and efficient performance.
- SLIC provides eight 3-statable buffers, up to a 10-bit decoder, and PAL\*-like and-or-invert (AOI) in each programmable logic cell.

- New 200 MHz embedded quad-port RAM blocks, two read ports, two write ports, and two sets of byte lane enables. Each embedded RAM block can be configured as:
  - One—512 x 18 (quad-port, two read/two write) with optional built-in arbitration.
  - One—256 x 36 (dual-port, one read/one write).
  - One—1k x 9 (dual-port, one read/one write).
  - Two—512 x 9 (dual-port, one read/one write for each).
  - Two RAMS with arbitrary number of words whose sum is 512 or less by 18 (dual-port, one read/one write).
  - Supports joining of RAM blocks.
  - Two 16 x 8-bit content addressable memory (CAM) support.
  - FIFO 512 x 18, 256 x 36, 1k x 9, or dual 512 x 9.
  - Constant multiply (8 x 16 or 16 x 8).
  - Dual variable multiply (8 x 8).
- Embedded 32-bit internal system bus plus 4-bit parity interconnects FPGA logic, microprocessor interface (MPI), embedded RAM blocks, and embedded standard-cell blocks with 100 MHz bus performance. Included are built-in system registers that act as the control and status center for the device.
- Built-in testability:
  - Full boundary scan (*IEEE* 1149.1 and draft 1149.2 JTAG).
  - Programming and readback through boundaryscan port compliant to *IEEE* Draft 1532:D1.7.
  - TS\_ALL testability function to 3-state all I/O pins.
  - New temperature-sensing diode.
- Improved built-in clock management with programmable phase-locked loops (PPLLs) provides optimum clock modification and conditioning for phase, frequency, and duty cycle from 20 MHz up to 420 MHz.

<sup>\*</sup> PAL is a trademark of Advanced Micro Devices, Inc.

# **Programmable Logic System Features**

- PCI local bus compliant for FPGA I/Os.
- Improved PowerPC\*860 and PowerPC II high-speed synchronous microprocessor interface can be used for configuration, readback, device control, and device status, as well as for a general-purpose interface to the FPGA logic, RAMs, and embedded standard-cell blocks. Glueless interface to synchronous PowerPC processors with user-configurable address space provided.
- New embedded AMBA<sup>†</sup> specification 2.0 AHB system bus (ARM <sup>†</sup> processor) facilitates communication among the microprocessor interface, configuration logic, embedded block RAM, FPGA logic, and embedded standard-cell blocks.
- New network PLLs meet ITU-T G.811 specifications and provide clock conditioning for DS-1/E-1 and STS-3/STM-1 applications.
- Flexible general-purpose PPLLs offer clock multiply (up to 8x), divide (down to 1/8x), phase shift, delay compensation, and duty-cycle adjustment combined.
- Variable-size bused readback of configuration data capability with the built-in microprocessor interface and system bus.

- Internal, 3-state, and bidirectional buses with simple control provided by the SLIC.
- New clock routing structures for global and local clocking significantly increases speed and reduces skew (<200 ps for OR4E4).</li>
- New local clock routing structures allow creation of localized clock trees.
- Two new edge clock routing structures allow up to seven high-speed clocks on each edge of the device for improved setup/hold times on input pins and clock-to-out times on output pins (and both improvements for bidirectional pins).
- New double-data rate (DDR) and zero-bus turnaround (ZBT) memory interfaces support the latest high-speed memory interfaces.
- New 2x/4x uplink and downlink I/O capabilities interface high-speed external I/Os to reduced-speed internal logic.
- ORCA Foundry development system software. Supported by industry standard.
- CAE tools for design entry, synthesis, simulation, and timing analysis.
- Meets universal test and operations PHY interface for ATM (UTOPIA) Levels 1, 2, and 3 as well as POS-PHY3. Also meets proposed specifications for UTO-PIA Level 4 and POS-PHY4 for 10 Gbits/s interfaces.
- Meets POS-PHY3 (2.5 Gbits/s) and POS-PHY4 (10 Gbits/s) interface standards for packet-over-SONET as defined by the Saturn Group.

<sup>\*</sup> PowerPC is a registered trademark of International Business Machines, Inc.

<sup>†</sup> AMBA is a trademark and ARM is a registered trademark of Advanced RISC Machines Limited.

# **Description**

#### **FPSC Definition**

FPSCs, or field-programmable system chips, are devices that combine field-programmable logic with ASIC or mask-programmed logic on a single device. FPSCs provide the time to market and the flexibility of FPGAs, the design effort savings of using soft intellectual property (IP) cores, and the speed, design density, and economy of ASICs.

### **FPSC Overview**

Lucent's Series 4 FPSCs are created from Series 4 *ORCA* FPGAs. To create a Series 4 FPSC, several columns of programmable logic cells (see FPGA Logic Overview section for FPGA logic details) are added to an embedded logic core. Other than replacing some FPGA gates with ASIC gates, at greater than 10:1 efficiency, none of the FPGA functionality is changed—all of the Series 4 FPGA capability is retained: embedded block RAMs, MPI, PCMs, boundary scan, etc. The columns of programmable logic are replaced at the right of the device, allowing pins from the replaced columns to be used as I/O pins for the embedded core. The remainder of the device pins retain their FPGA functionality.

The embedded cores can take many forms and generally come from Lucent Technologies ASIC libraries. Other offerings allow customers to supply their own core functions for the creation of custom FPSCs.

## **FPSC Gate Counting**

The total gate count for an FPSC is the sum of its embedded core (standard-cell/ASIC gates) and its FPGA gates. Because FPGA gates are generally expressed as a usable range with a nominal value, the total FPSC gate count is sometimes expressed in the same manner. Standard-cell ASIC gates are, however, 10 to 25 times more silicon-area efficient than FPGA gates. Therefore, an FPSC with an embedded function is gate equivalent to an FPGA with a much larger gate count.

#### **FPGA/Embedded Core Interface**

The interface between the FPGA logic and the embedded core has been enhanced to allow for a greater number of interface signals than on previous FPSC architectures. Compared to bringing embedded core

signals off-chip, this on-chip interface is much faster and requires less power. All of the delays for the interface are precharacterized and accounted for in the ORCA Foundry Development System.

Series 4 based FPSCs expand this interface by providing a link between the embedded block and the multimaster 32-bit system bus in the FPGA logic. This system bus allows the core easy access to many of the FPGA logic functions including the embedded block RAMs and the microprocessor interface.

Clock spines also can pass across the FPGA/embedded core boundary. This allows for fast, low-skew clocking between the FPGA and the embedded core. Many of the special signals from the FPGA, such as DONE and global set/reset, are also available to the embedded core, making it possible to fully integrate the embedded core with the FPGA as a system.

For even greater system flexibility, FPGA configuration RAMs are available for use by the embedded core. This allows for user-programmable options in the embedded core, in turn allowing for greater flexibility. Multiple embedded core configurations may be designed into a single device with user-programmable control over which configurations are implemented, as well as the capability to change core functionality simply by reconfiguring the device.

# **ORCA** Foundry Development System

The *ORCA* Foundry development system is used to process a design from a netlist to a configured FPGA. This system is used to map a design onto the *ORCA* architecture and then place and route it using *ORCA* Foundry's timing-driven tools. The development system also includes interfaces to, and libraries for, other popular CAE tools for design entry, synthesis, simulation, and timing analysis.

The *ORCA* Foundry development system interfaces to front-end design entry tools and provides the tools to produce a configured FPGA. In the design flow, the user defines the functionality of the FPGA at two points in the design flow: design entry and the bitstream generation stage. Recent improvements in *ORCA* Foundry allow the user to provide timing requirement information through logical preferences only; thus, the designer is not required to have physical knowledge of the implementation.

# **Description** (continued)

Following design entry, the development system's map, place, and route tools translate the netlist into a routed FPGA. A floorplanner is available for layout feedback and control. A static timing analysis tool is provided to determine design speed, and a back-annotated netlist can be created to allow simulation and timing.

Timing and simulation output files from *ORCA* Foundry are also compatible with many third-party analysis tools. A bit stream generator is then used to generate the configuration data which is loaded into the FPGAs internal configuration RAM, embedded block RAM, and/or FPSC memory.

When using the bit stream generator, the user selects options that affect the functionality of the FPGA. Combined with the front-end tools, *ORCA* Foundry produces configuration data that implements the various logic and routing options discussed in this data sheet.

## **FPSC Design Kit**

Development is facilitated by an FPSC design kit which, together with *ORCA* Foundry and third-party synthesis and simulation engines, provides all software and documentation required to design and verify an FPSC implementation. Included in the kit are the FPSC configuration manager, *Synopsys Smart Model\**, and complete online documentation. The kit's software couples with *ORCA* Foundry, providing a seamless FPSC design environment. More information can be obtained by visiting the *ORCA* website or contacting a local sales office, both listed on the last page of this document.

### **FPGA Logic Overview**

The *ORCA* Series 4 architecture is a new generation of SRAM-based programmable devices from Lucent Technologies Microelectronics Group. It includes enhancements and innovations geared toward today's high-speed systems on a single chip. Designed with networking applications in mind, the Series 4 family incorporates system-level features that can further reduce logic requirements and increase system speed. *ORCA* Series 4 devices contain many new patented enhancements and are offered in a variety of packages and speed grades.

The hierarchical architecture of the logic, clocks, routing, RAM, and system-level blocks create a seamless merge of FPGA and ASIC designs. Modular hardware and software technologies enable system-on-chip integration with true plug-and-play design implementation.

The architecture consists of four basic elements: programmable logic cells (PLCs), programmable I/O cells (PIOs), embedded block RAMs (EBRs), and systemlevel features. These elements are interconnected with a rich routing fabric of both global and local wires. An array of PLCs are surrounded by common interface blocks which provide an abundant interface to the adjacent PLCs or system blocks. Routing congestion around these critical blocks is eliminated by the use of the same routing fabric implemented within the programmable logic core. Each PLC contains a PFU, SLIC, local routing resources, and configuration RAM. Most of the FPGA logic is performed in the PFU, but decoders, PAL-like functions, and 3-state buffering can be performed in the SLIC. The PIOs provide device inputs and outputs and can be used to register signals and to perform input demultiplexing, output multiplexing, uplink and downlink functions, and other functions on two output signals. Large blocks of 512 x 18 quadport RAM complement the existing distributed PFU memory. The RAM blocks can be used to implement RAM, ROM, FIFO, multiplier, and CAM. Some of the other system-level functions include the MPI, PLLs, and the embedded system bus (ESB).

### **PLC Logic**

Each PFU within a PLC contains eight 4-input (16-bit) LUTs, eight latches/FFs, and one additional flip-flop that may be used independently or with arithmetic functions.

The PFU is organized in a twin-quad fashion; two sets of four LUTs and FFs that can be controlled independently. Each PFU has two independent programmable clocks, clock enables, local set/reset, and data selects. LUTs may also be combined for use in arithmetic functions using fast-carry chain logic in either 4-bit or 8-bit modes. The carry-out of either mode may be registered in the ninth FF for pipelining. Each PFU may also be configured as a synchronous 32 x 4 single- or dual-port RAM or ROM. The FFs (or latches) may obtain input from LUT outputs or directly from invertible PFU inputs, or they can be tied high or tied low. The FFs also have programmable clock polarity, clock enables, and local set/reset.

<sup>\*</sup> Synopsys Smart Model is a registered trademark of Synopsys, Inc.

### **Description** (continued)

The SLIC is connected from PLC routing resources and from the outputs of the PFU. It contains eight 3-state, bidirectional buffers, and logic to perform up to a 10-bit AND function for decoding, or an AND-OR with optional INVERT to perform *PAL*-like functions. The 3-state drivers in the SLIC and their direct connections from the PFU outputs make fast, true, 3-state buses possible within the FPGA, reducing required routing and allowing for real-world system performance.

### Programmable I/O

The Series 4 PIO addresses the demand for the flexibility to select I/Os that meet system interface requirements. I/Os can be programmed in the same manner as in previous *ORCA* devices, with the additional new features which allow the user the flexibility to select new I/O types that support high-speed interfaces.

Each PIO contains four programmable I/O pads and is interfaced through a common interface block to the FPGA array. The PIO is split into two pairs of I/O pads with each pair having independent clock enables, local set/reset, and global set/reset. On the input side, each PIO contains a programmable latch/flip-flop which enables very fast latching of data from any pad. The combination provides for very low setup requirements and zero hold times for signals coming on-chip. It may also be used to demultiplex an input signal, such as a multiplexed address/data signal, and register the signals without explicitly building a demultiplexer with a PFU.

On the output side of each PIO, an output from the PLC array can be routed to each output flip-flop, and logic can be associated with each I/O pad. The output logic associated with each pad allows for multiplexing of output signals and other functions of two output signals.

The output FF, in combination with output signal multiplexing, is particularly useful for registering address signals to be multiplexed with data, allowing a full clock cycle for the data to propagate to the output. The output buffer signal can be inverted, and the 3-state control can be made active-high, active-low, or always enabled. In addition, this 3-state signal can be registered or nonregistered.

The Series 4 I/O logic has been enhanced to include modes for speed uplink and downlink capabilities. These modes are supported through shift register logic, which divides down incoming data rates or multiplies up outgoing data rates. This new logic block also supports high-speed DDR mode requirements where data is clocked into and out of the I/O buffers on both edges of the clock.

The new programmable I/O cell allows designers to select I/Os which meet many new communication standards permitting the device to hook up directly without any external interface translation. They support traditional FPGA standards as well as high-speed, single-ended, and differential-pair signaling (as shown in Table 1). Based on a programmable, bank-oriented I/O ring architecture, designs can be implemented using 3.3 V, 2.5 V, 1.8 V, and 1.5 V referenced output levels.

### Routing

The abundant routing resources of the Series 4 architecture are organized to route signals individually or as buses with related control signals. Both local and global signals utilize high-speed buffered and nonbuffered routes. One PLC segmented (x1), six PLC segmented (x6), and bused half chip (xHL) routes are patterned together to provide high connectivity with fast software routing times and high-speed system performance.

Eight fully distributed primary clocks are routed on a low-skew, high-speed distribution network and may be sourced from dedicated I/O pads, PLLs, or the PLC logic. Secondary and edge-clock routing is available for fast regional clock or control signal routing for both internal regions and on device edges. Secondary clock routing can be sourced from any I/O pin, PLLs, or the PLC logic.

The improved routing resources offer great flexibility in moving signals to and from the logic core. This flexibility translates into an improved capability to route designs at the required speeds when the I/O signals have been locked to specific pins.

# **System-Level Features**

The Series 4 also provides system-level functionality by means of its microprocessor interface, embedded system bus, quad-port embedded block RAMs, universal programmable phase-locked loops, and the addition of highly tuned networking specific phase-locked loops. These functional blocks allow for easy glueless system interfacing and the capability to adjust to varying conditions in today's high-speed networking systems.

### **Microprocessor Interface**

The MPI provides a glueless interface between the FPGA and *PowerPC* microprocessors. Programmable in 8-, 16-, and 32-bit interfaces with optional parity to the *Motorola\* PowerPC* 860 bus, it can be used for configuration and readback, as well as for FPGA control and monitoring of FPGA status. All MPI transactions utilize the Series 4 embedded system bus at 66 MHz performance.

A system-level microprocessor interface to the FPGA user-defined logic following configuration, through the system bus, including access to the embedded block RAM and general user-logic, is provided by the MPI. The MPI supports burst data read and write transfers, allowing short, uneven transmission of data through the interface by including data FIFOs. Transfer accesses can be single beat (1 x 4 bytes or less), 4-beat (4 x 4 bytes), 8-beat (8 x 2 bytes), or 16-beat (16 x 1 bytes).

### System Bus

An on-chip, multimaster, 8-bit system bus with 1-bit parity facilitates communication among the MPI, configuration logic, FPGA control, and status registers, embedded block RAMs, as well as user logic. Utilizing the *AMBA* specification Rev 2.0 AHB protocol, the embedded system bus offers arbiter, decoder, master, and slave elements.

The system bus control registers can provide control to the FPGA such as signaling for reprogramming, reset functions, and PLL programming. Status registers monitor INIT, DONE, and system bus errors. An interrupt controller is integrated to provide up to eight possible interrupt resources. Bus clock generation can be sourced from the microprocessor interface clock, configuration clock (for slave configuration modes), internal oscillator, user clock from routing, or from the port clock (for JTAG configuration modes).

### **Phase-Locked Loops**

Up to eight PLLs are provided on each Series 4 device, with four PLLs generally provided for FPSCs. Programmable PLLs can be used to manipulate the frequency, phase, and duty cycle of a clock signal. Each PPLL is capable of manipulating and conditioning clocks from 20 MHz to 420 MHz. Frequencies can be adjusted from 1/8x to 8x, the input clock frequency. Each programmable PLL provides two outputs that have different multiplication factors but can have the same phase relationships. Duty cycles and phase delays can be adjusted in 12.5% of the clock period increments. An automatic input buffer delay compensation mode is available for phase delay. Each PPLL provides two outputs that can have programmable (12.5% steps) phase differences.

Additional highly tuned and characterized, dedicated phase-locked loops (DPLLs) are included to ease system designs. These DPLLs meet ITU-T G.811 primary-clocking specifications and enable system designers to very tightly target specified clock conditioning not traditionally available in the universal PPLLs. Initial DPLLs are targeted to low-speed networking DS1 and E1, and also high-speed SONET/SDH networking STS-3 and STM-1 systems.

#### **Embedded Block RAM**

New 512 x 18 quad-port RAM blocks are embedded in the FPGA core to significantly increase the amount of memory and complement the distributed PFU memories. The EBRs include two write ports, two read ports, and two byte lane enables which provide four-port operation. Optional arbitration between the two write ports is available, as well as direct connection to the high-speed system bus.

Additional logic has been incorporated to allow significant flexibility for FIFO, constant multiply, and two-variable multiply functions. The user can configure FIFO blocks with flexible depths of 512k, 256k, and 1k including asynchronous and synchronous modes and programmable status and error flags. Multiplier capabilities allow a multiple of an 8-bit number with a 16-bit fixed coefficient or vice versa (24-bit output), or a multiply of two 8-bit numbers (16-bit output). On-the-fly coefficient modifications are available through the second read/write port. Two 16 x 8-bit CAMs per embedded block can be implemented in single match, multiple match, and clear modes. The EBRs can also be preloaded at device configuration time.

<sup>\*</sup> Motorola is a registered trademark of Motorola, Inc.

### **System-Level Features** (continued)

### Configuration

The FPGAs functionality is determined by internal configuration RAM. The FPGAs internal initialization/configuration circuitry loads the configuration data at powerup or under system control. The configuration data can reside externally in an EEPROM or any other storage media. Serial EEPROMs provide a simple, low pin-count method for configuring FPGAs.

The RAM is loaded by using one of several configuration modes. Supporting the traditional master/slave serial, master/slave parallel, and asynchronous peripheral modes, the Series 4 also utilizes its microprocessor interface and embedded system bus to perform both programming and readback. Daisy chaining of multiple devices and partial reconfiguration are also permitted.

Other configuration options include the initialization of the embedded-block RAM memories and FPSC memory as well as system bus options and bit stream error checking. Programming and readback through the JTAG (IEEE 1149.2) port is also available meeting insystem programming (ISP) standards (IEEE 1532 Draft).

## **Additional Information**

Contact your local Lucent Technologies representative for additional information regarding the *ORCA* Series 4 FPGA devices, or visit our website at:

http://www.lucent.com/micro/netcom/orca

#### **ORLI10G Overview**

#### **Device Layout**

The ORLI10G FPSC provides a high-speed transmit and receive line interface combined with FPGA logic. The device is based on the 1.5 V OR4E4 FPGA. The ORLI10G consists of an embedded backplane transceiver core and a full OR4E4 36x36 FPGA array.

The ORLI10G is a line interface device that contains an FPGA base array, a 10 Gbits/s Line Interface block and programmable PLLs to do the overhead clock rate conversions on a single monolithic chip. The embedded portion includes:

Line Interface: This consists of a 16-bit LVDS receive data bus and a 16-bit LVDS transmit bus operating up to 667 Mbits/s per input/output pair. Each 4-bit LVDS I/O has a high-speed LVDS clock (operating up to 667 MHz) associated with it.

MUX/deMUX: This performs the MUXing and deMUXing between the high-speed line interface data operating at the line rate and system data operating at 1/4 or 1/8 the line rate.

On-board PLLs: This is used to align system-side data with the line-side data which is at a slightly higher data bandwidth than the system data because of the addition of overhead due to encoding.

Figure 1 shows the ORLI10G block diagram.

#### 10G Mode

The ORLI10G can operate in one of two data modes: 10G mode or Quad 2.5G mode.

In 10G (or single channel) mode, all 16 LVDS transmit data outputs are assumed to be one data bus with one LVDS clock provided off chip for the data. Likewise, all 16 LVDS receive data inputs are assumed to be one data bus with one LVDS input clock provided for the data.

#### **Transmit Path**

In 10G mode, the transmit data from the FPGA logic is passed to the embedded core as a single 128- or 64-bit bus. An off-chip transmit reference clock is divided down in the core by 8 (for 128-bit to 16-bit MUX) or by 4 (for 64-bit to 16-bit MUX). All four transmit clock outputs are therefore synchronized.

### **ORLI10G Overview** (continued)

#### **Receive Path**

The 16-bit receive data is deMUXed in the embedded core to a single 128-bit or 64-bit data bus and passed to the FPGA logic. The lowest-order LVDS input clock (rx\_clk\_in[0]) is used as the receive clock for all 16 data bits (the other three LVDS input clock pairs should be tied low). This clock is divided down in the core by 8 (for 16-bit to 128-bit deMUX) or by 4 (for 16-bit to 64-bit deMUX) and passed to the FPGA logic with the data.

The ORLI10G supports transmit and receive data rates up to 667 Mbits/s. Therefore, the total data rate for this mode is 667 Mbits/s x 16 or 10.672 Gbits/s.

#### 2.5G Mode

In 2.5G (or quad channel) mode, the 16 LVDS transmit data outputs are assumed to be four 4-bit data buses with four LVDS clocks provided off chip for each data bus. Likewise, the 16 LVDS receive data inputs are assumed to be four independent 4-bit data buses with four LVDS asynchronous input clocks provided for each data bus.

#### Transmit Path

In 2.5G mode, the transmit data from the FPGA logic is passed to the embedded core as four separate 32- or

16-bit buses. A separate clock for each of the four busses is also passed to the core. An off-chip transmit reference clock is divided down in the core by 8 (for each 32 to 8-bit MUX) or by 4 (for each 16 to 4 MUX). This divided down clock is used to resynchronize the output data and clocks. All four transmit clock outputs are therefore synchronized.

#### Receive Path

Each of the four 4-bit receive data buses are deMUXed in the embedded core to one of four independent 32- or 16-bit data buses and passed to the FPGA logic. The four receive clock inputs are divided down in the core by 8 (for each 4- to 32-bit deMUX) or by 4 (for each 4- to 16-bit deMUX) and each divided clock is passed to the FPGA logic with its associated data bus. All four data paths act as separate data interfaces that are asynchronous to each other.

The ORLI10G supports transmit and receive data rates up to 667 Mbits/s. Therefore, the total data rate each of the quad channels is thus 667 Mbits/s x 4 or 2.5 Gbits/s.

Figure 2 shows a representation of the 10G and 2.5G modes in both transmit and receive directions.

# **ORLI10G Overview** (continued)

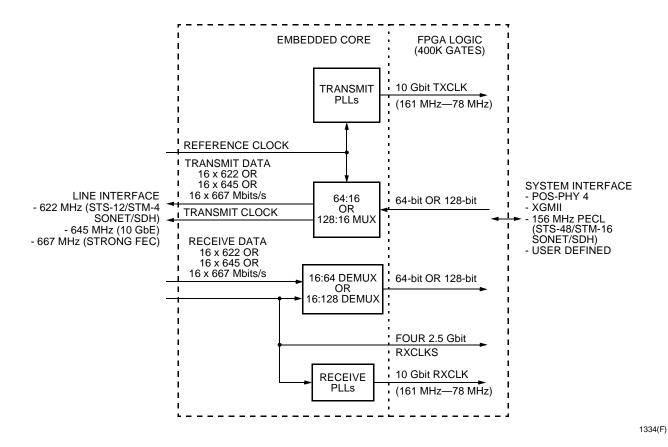


Figure 1. ORCA ORLI10G Block Diagram

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### **ORLI10G Overview** (continued)

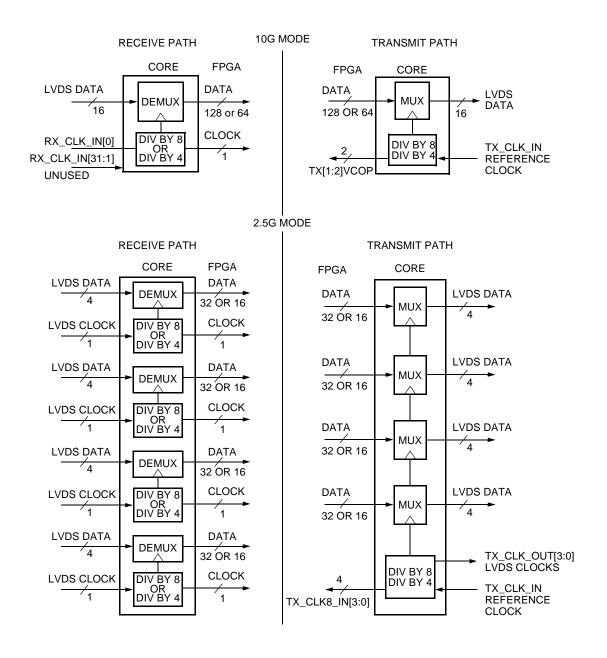


Figure 2. 10G (Single Channel) and 2.5G (Quad Channel) Modes

### ORLI10G Overview (continued)

#### **Receive Path**

In the receive path, the ORLI10G embedded core can be broken down into three sections: the high-speed line interface, the demultiplexer, and the receive-side onboard PLLs. Note that both transmit and receive PLLs are in addition to the four programmable PLLs (PPLLs) in the FPGA portion of the ORLI10G.

#### Line Interface

In the receive path, 16-bit data and associated clocks are inputs to the line interface. Typical data rates are expected to range from 622 Mbits/s to 667 Mbits/s for most applications. The 16-bit LVDS input data bus is actually composed of four 4-bit data busses with one clock for each four bit data bus. In the 10G mode, all four input clocks are tied together internal to the device and driven by the lowest-order input clock. In 2.5G mode, the four clocks may be asynchronous to each other. The ORLI10G uses LVDS (low voltage differential signaling) drivers/receivers which are intended to provide point-to-point connection between the ORLI10G and optical transceiver (MUX/deMUX) parts. The LVDS inputs are hot-swap compatible and can connect to other vendor's LVDS I/O buffers. The LVDS inputs are terminated with a 100  $\Omega$  resistor to improve performance.

#### **DeMUX**

The demultiplexer takes the high-speed line data and clocks and converts the data and clock to rates appropriate for transfer to the FPGA logic. The demultiplexer supports two modes of operation:

#### ■ Divide-by-8

10G (or single channel): The demultiplexer converts the incoming 16 bits of data at 622 Mbits/s to 667 Mbits/s to 128 bits at 78 Mbits/s to 83 Mbits/s. The incoming clocks are divided by 8.

2.5G (or quad channel): The demultiplexer converts the incoming four bits of data at 622 Mbits/s to 667 Mbits/s to 32 bits at 78 Mbits/s to 83 Mbits/s. The associated clock is also divided by 8. This is repeated four times with each 4-bit data/clock group assumed to be asynchronous to the others.

#### ■ Divide-by-4

10G (or single channel): The demultiplexer converts the incoming 16 bits of data at 622 Mbits/s to 667 Mbits/s to 64 bits at 156 Mbits/s to 166 Mbits/s. The incoming clocks are divided by 4.

2.5G (or quad channel): The demultiplexer converts the incoming four bits of data at 622 Mbits/s to 667 Mbits/s to 16 bits at 156 Mbits/s to 166 Mbits/s. The associated clock is also divided by 4. This is repeated four times with each 4-bit data/clock group assumed to be asynchronous to the others.

#### **Onboard Receive PLLs**

The function of the onboard PLLs is to align the system data with the line data which will be at a slightly higher rate owing to the addition of the overhead bits. There are two PLLs on the receive path. The input to the first PLL, RX1\_PLL (see Figure 3), is the divided down lowest-order clock from the demultiplexer. The RX1\_PLL generates a clock with a user-defined frequency ratio of M/N to the divided clock. This clock would generally be used to compensate for different data rates due to overhead bits. M and N can independently be set from 1 to 40.

The RX2\_PLL also takes its input from the divided down clock and is used to provide a balanced divided clock across the FPGA-embedded core interface.

Both PLLs have delay loops which compensate for routing delays to the embedded core/FPGA logic interface for minimum clock skew.

In addition, the user can specify an additional skew on each clock in increments of 1/8 the clock period.

The selection of the deMUX width (and corresponding clock division value), the RX1\_PLL M and N values, and the additional skew for RX1\_PLL and RX2\_PLL are specified by the user in a GUI interface provided in the ORLI10G design kit.

A detailed block diagram of the receive path in shown in Figure 3.

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### **ORLI10G Overview** (continued)

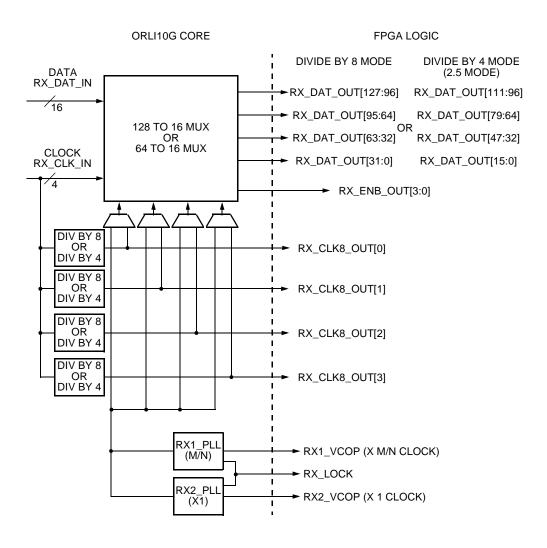


Figure 3. ORLI10G Embedded Core Receive Path Diagram

### **ORLI10G Overview** (continued)

#### **Transmit Path**

In the transmit path, the ORLI10G embedded core can be broken down into three sections: the multiplexer, the transmit side onboard PLLs, and the high-speed line interface. Note that both transmit and receive PLLs are in addition to the four programmable PLLs (PPLLs) in the FPGA portion of the ORLI10G.

#### MUX

The multiplexer takes data from the FPGA logic and multiplexes the data to rates for transfer by the high-speed line interface. The multiplexer supports two modes of operation:

#### ■ Multiplex-by-8

The multiplexer converts the incoming 128 bits of data at 78 Mbits/s to 83 Mbits/s to 16 bits at 622 Mbits/s to 667 Mbits/s. The incoming transmit reference clock is divided by 8.

#### ■ Multiplex-by-4

10G (or single channel): The multiplexer converts the incoming 64 bits of data at 156 Mbits/s to 166 Mbits/s to 16 bits at 622 Mbits to 667 Mbits/s. The transmit reference clock is divided by 4.

#### **Onboard Transmit PLLs**

The function of the onboard PLLs is to align the system data with the line data which will be at a slightly higher rate owing to the addition of the overhead bits. There are two PLLs on the transmit path. The input to the first PLL, TX1\_PLL (see Figure 4), is the divided down transmit reference clock from the multiplexer. The TX1\_PLL generates a clock with a user-defined frequency ratio of M/N to the divided clock. This clock would generally be used to compensate for different data rates due to overhead bits. M and N can independently be set from 1 to 40.

The TX2\_PLL also takes its input reference from the divided down reference clock and is used to provide a balanced divided clock across the FPGA-embedded core interface.

Both PLLs have delay loops which compensate for routing delays to the embedded core/FPGA logic interface for minimum clock skew.

In addition, the user can specify an additional skew on each clock in increments of 1/8 the clock period.

The selection of the MUX width (and corresponding clock division value), the TX1\_PLL M and N values, and the additional skew for TX1\_PLL and TX2\_PLL are specified by the user in a GUI interface provided in the ORLI10G deisng kit.

A detailed block diagram of the transmit path in shown in Figure 4.

#### **Line Interface**

In the transmit path, 16-bit data and associated clocks are outputs from the line interface. Typical data rates are expected to range from 622 Mbits/s to 667 Mbits/s for most applications. The 16-bit LVDS output data bus is actually composed of four 4-bit data buses with one clock for each 4-bit data bus. On the transmit side, these clocks will all be synchronized. The ORLI10G uses LVDS (low-voltage differential signaling) drivers/receivers which are intended to provide point-to-point connection between the ORLI10G and optical transceiver (MUX/deMUX) parts. The LVDS drivers are hot-swap compatible and can connect to other vendor's LVDS I/O buffers. The LVDS drivers are terminated with a 100  $\Omega$  resistor to improve performance.

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### **ORLI10G Overview** (continued)

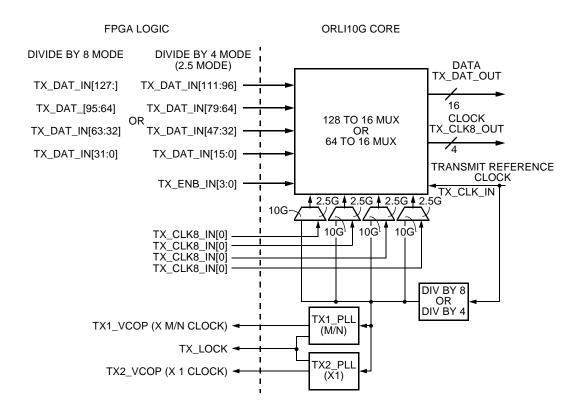


Figure 4. ORLI10G Embedded Core Transmit Path Diagram

# **ORLI10G Demultiplexer Detail**

The demultiplexer module converts the incoming 16 bits of data at 622 MHz/666 MHz into 128 bits of data at 78 MHz/83 MHz. It has been implemented in two stages: the first stage converts each incoming bit into a byte stream and the second stage bit interleaves these bytes into 128 bits depending upon the mode of operation. The low-speed clocks are generated by this block. These clocks are then driven back to this block from the low speed clock tree network. Functionally, the demultiplexer architecture consists of three blocks; the serial to parallel conversion, the counters, and the interleaving.

The first stage of the line interface module (demultiplexer) converts each incoming bit of data into a byte stream on a divided by 8 clock. The data is first registered on the rising edge of the clock input. The clock dividers also runs parallel to data shift (serial to parallel), on the rising edge of the input clock. An enable is created when a complete byte is taken in. This enable signal is used to register the serial-to-parallel converted data at the high-speed input clock. This ensures that the data can be safely transferred to the low-speed clock. This data is then transferred to the divided clock allowing a timing margin of approximately half the divided clock period.

The high-speed demultiplexer converts the incoming data as blocks of bytes. The byte boundaries of incoming data are unknown and are irrelevant to this module.

This data is then interleaved to the 128/32 bits of output data depending on the mode of operation (10G/2.5G). In 10G mode, the output data is assigned the retimed 128 bits of data from the first stage of line interface registered at the input clock [0]. In 2.5G mode, the output data is assigned four concatenated 32 bits of data from the first stage of line interface registered at input clocks [0 to 3]. The interleaving is done at bit level because the serial-to-parallel converter operates on bits of incoming data. In 10G mode, it is assumed that all the incoming 16 bits of data are synchronized to the input clock [0]. This block also generates the clock enables used by the output line interface (multiplexer) module for registering the data on the high-speed clock. These enables along with the enables from other clocks are selected through the high-speed clock MUX for the output line interface block.

Figure 5 shows the valid data output bits from the demultiplexer in each of the four modes (divide-by-8, 10G and 2.5G modes, and divide-by-4, 10G and 2.5G modes). Figure 6—Figure 9 show the demultiplexer input data and clock waveforms and output clock, enable, and data waveforms for all four modes.

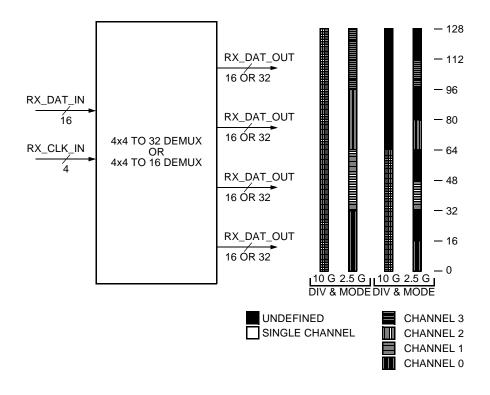


Figure 5. Demultiplexer Output Data Structure

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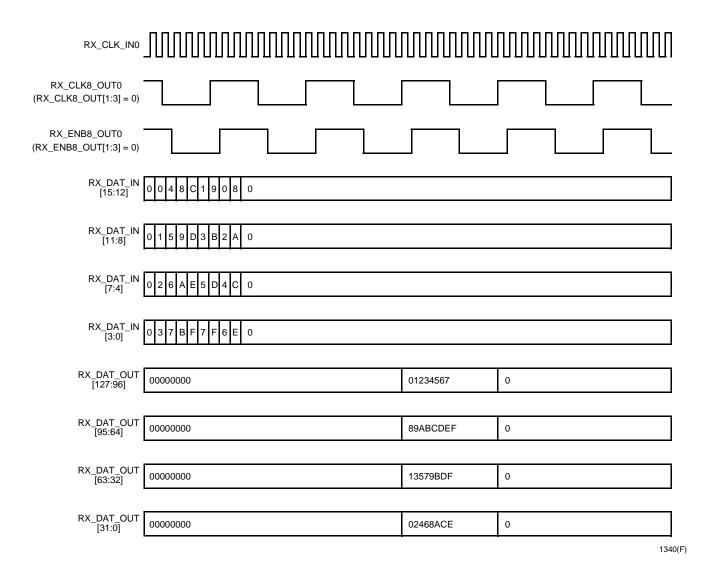


Figure 6. Demultiplexer Serial-to-Parallel Conversion—Divide by 8, 10G Mode

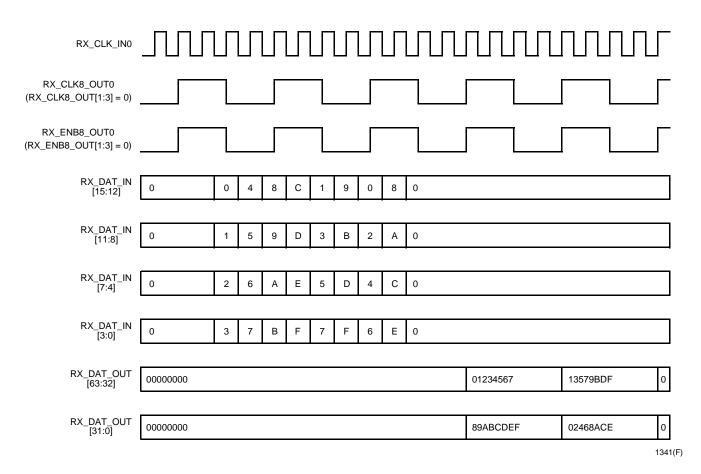


Figure 7. Demultiplexer Serial-to-Parallel Conversion—Divide by 4, 10G mode

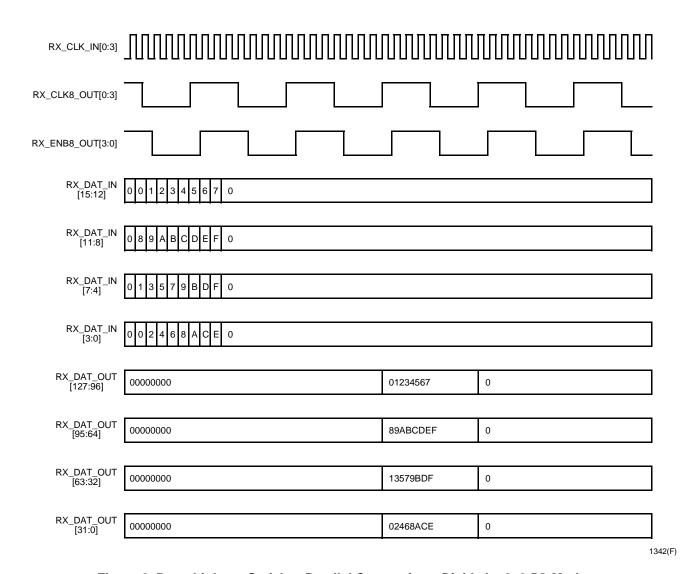


Figure 8. Demultiplexer Serial-to-Parallel Conversion—Divide by 8, 2.5G Mode

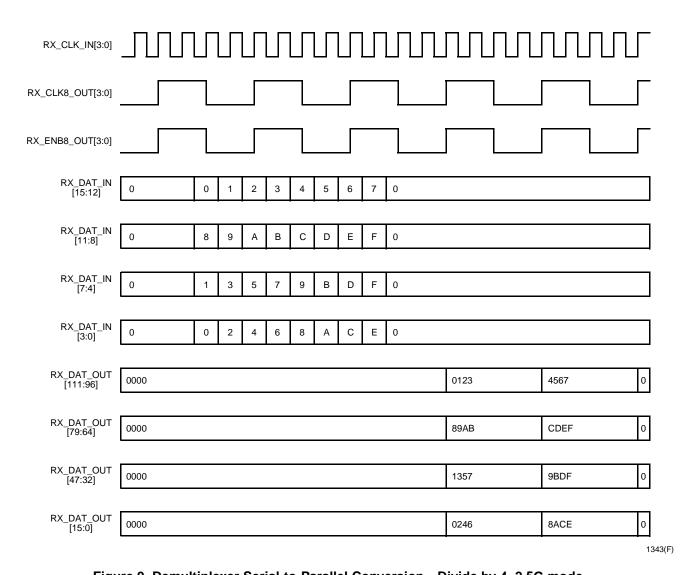


Figure 9. Demultiplexer Serial-to-Parallel Conversion—Divide by 4, 2.5G mode

# **ORLI10G Multiplexer Detail**

The multiplexer module converts the incoming 128 bits of data at 78 MHz/83 MHz or 64 bits of data at 156 MHz/166 MHz into 16 bits of data at 622 MHz/666 MHz. It has been implemented as two stages. The first stage deinterleaves each incoming byte into a different byte stream that can be serially output on the output data pins. The second stage outputs these bytes into 16 bits or four groups of 4 bits depending upon the mode of operation. Functionally, the multiplexer architecture consists of three blocks: the parallel-to-serial conversion, the counters, and the deinterleaving.

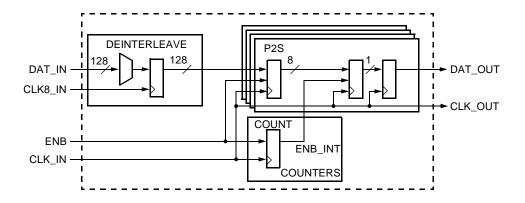
For 2.5G divide-by-8 mode, the first stage of the line interface module deinterleaves each incoming byte of data into a different byte stream on the 78 MHz/83 MHz clock. This data is first registered on the rising edge of the 622 MHz/666 MHz clock input. The data is registered at a time when it is safe to do so; in this case, it is nearer to the falling edge of the 78 MHz/83 MHz clock. The enable inputs are used to transfer data from the low-speed clock to the high-speed clock as well as synchronizing the counters of parallel-to-serial conversion which are running at the high-speed clock. The block diagram is shown in Figure 10.

For 2.5G divide-by-4 mode, the first stage of the line interface module deinterleaves each incoming byte of data into a different byte stream on the 156 MHz/166 MHz clock. This data is first registered on the rising edge of the 622 MHz/666 MHz clock input. The data is registered at a time when it is safe to do so; in this case, it is nearer to the falling edge of the 156 MHz/166 MHz clock. The enable inputs are used to transfer data from the low-speed clock to the high-speed clock as well as synchronizing the counters of parallel-to-serial conversion which are running at the high-speed clock. The block diagram is also shown in Figure 10.

In 2.5G modes, the enable inputs are assumed to be four clock cycles wide and are shortened internally. They have to be synchronous to their corresponding clock. In single channel operation, the four groups of 4 bits must have relationship to the slice zero clock. In single-channel mode, all the enable inputs are to be identical (generated from the slice zero clock).

In 10G mode the enable signal in generated internally from the transmit reference clock.

Figure 11 shows the valid data input bits to the multiplexer in each of the four modes (divide-by-8, 10G and 2.5G modes, and divide-by-4, 10G and 2.5G modes). Figure 12—Figure 15 show the multiplexer input transmit reference clock, data, enable, and clock waveforms and output clock and data waveforms for all four modes.



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Figure 10. Multiplexer Interface

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# **ORLI10G Multiplexer Detail** (continued)

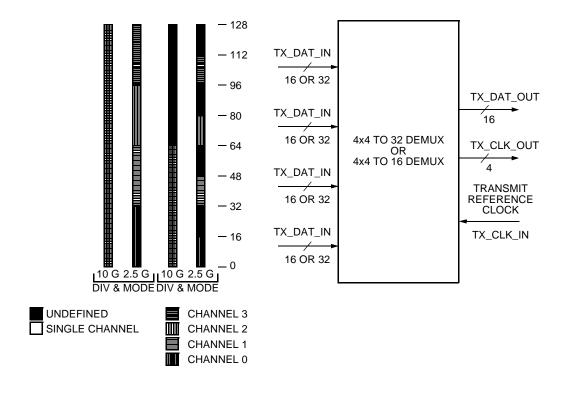


Figure 11. Multiplexer Input Data Structure

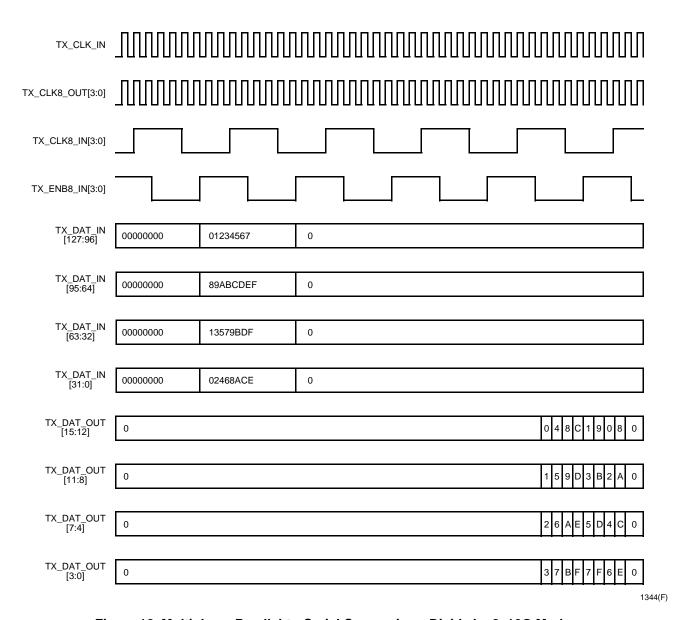


Figure 12. Multiplexer Parallel-to-Serial Conversion—Divide by 8, 10G Mode

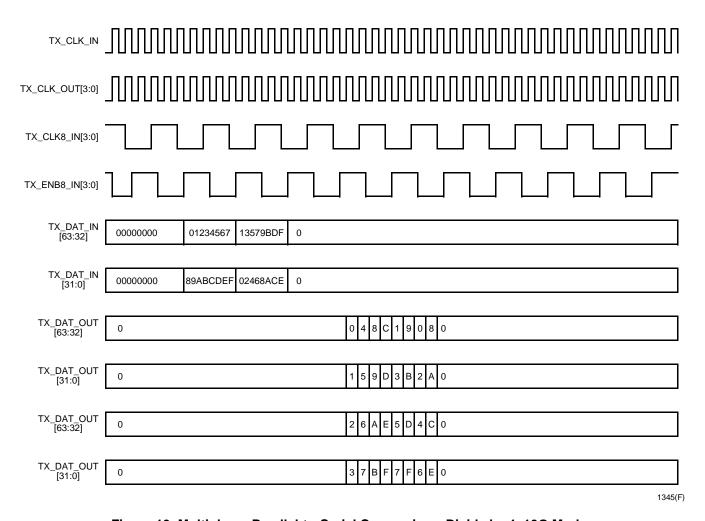


Figure 13. Multiplexer Parallel-to-Serial Conversion—Divide by 4, 10G Mode

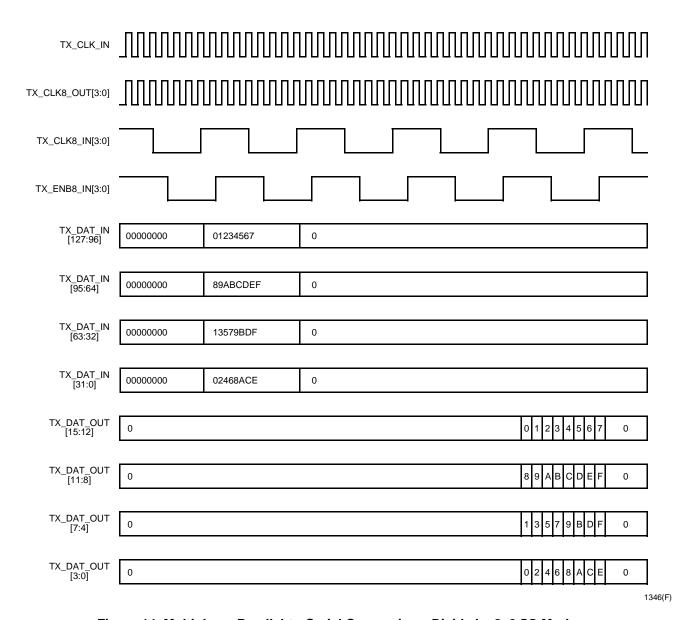


Figure 14. Multiplexer Parallel-to-Serial Conversion—Divide by 8, 2.5G Mode

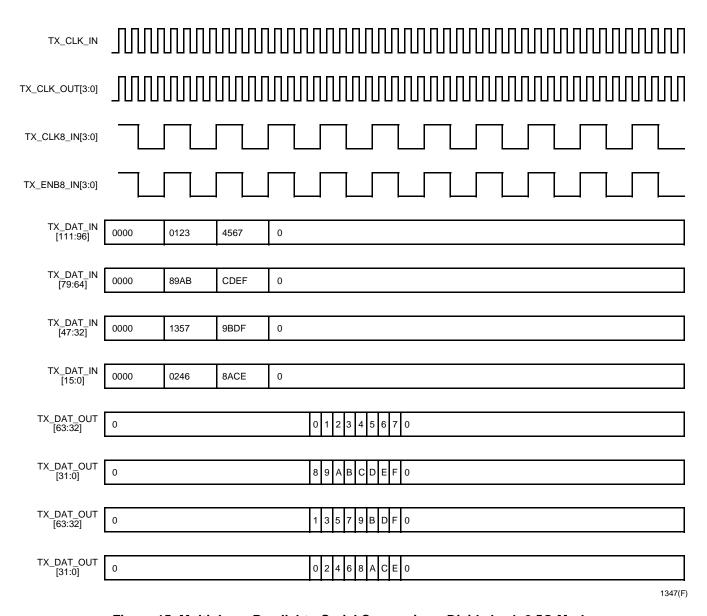


Figure 15. Multiplexer Parallel-to-Serial Conversion—Divide by 4, 2.5G Mode

#### ORLI10G Embedded PLLs

The ORLI10G embedded (transmit and receive) PLLs are based on the 4E series FPGA high-speed programmable PLL. The 4E PLL consists of a phase/frequency detector (PFD), a charge pump/filter, a multitap voltage controlled oscillator (VCO), a duty cycle synthesis circuitry, a power regulator, two programmable dividers, phase shift selector multiplexers, a lock signal generator, and a current DAC. A block diagram of the programmable PLL is shown in Figure 16. The receive path RX1\_PLL and transmit path TX1\_PLL, which can be programmed to create a N/M frequency clock, are based on this design.

The receive path RX2\_PLL and transmit path TX2\_PLL create a X1 clock. This is essentially the same PLL without the M and N divider.

The clock feedback loops for each PLL have been routed in the core so as to compensate for the routing delays to the FPGA logic interface. In this way, the clock skew at the embedded core/FPGA logic boundary is zero for the receive and transmit PLLs.

All PLLs include a phase shift selector which allows phase shift adjustments of each clock in increments of 1/8 the period of the clock.

All functions of the embedded core PLLs are user controlled through a GUI provided with the ORLI10G Design Kit software.

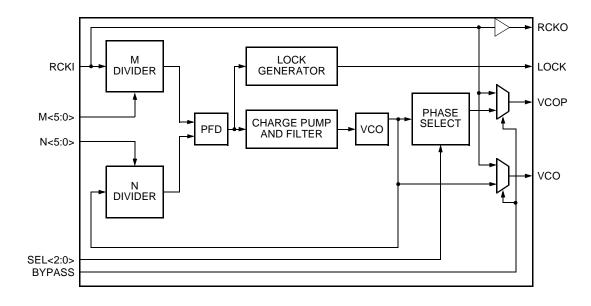


Figure 16. ORLI10G Programmable PLL Block Diagram

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# **ORLI10G Embedded Programmable PLLs Specifications**

**Table 2. Programmable PLL Specifications** 

Parameters	Min	Nom	Max	Unit
V <sub>DD</sub> 1.5	1.425	1.5	1.575	V
VDD 3.3	3.0	3.3	3.6	V
Operating Temperature	-40	25	125	°C
Input Clock Voltage	1.425	1.5	1.575	V
Output Clock Voltage	1.425	1.5	1.575	V
Input Clock Frequency	60	_	667	MHz
Output Clock Frequency	60	_	667	MHz
Output Duty Cycle	45	50	55	%
dc On Power Consumption	_	50	_	mW
Total On Current (dc)	_	14.0	_	mA
Total Off Current (dc)	_	30.0	_	pА
Cycle to Cycle Jitter(p-p)	_	< 0.02	_	Ulpp
Lock Time	_	< 50	_	μs
Frequency Multiplication		1—40X		_
Frequency Division	1—40X			_
Phase Shift Between VCOP and VCO	0, 45, 90,	degree		

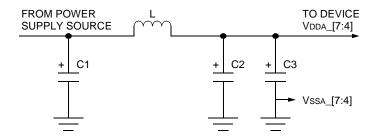
# LI Circuit Specifications

## **Power Supply Decoupling LC Circuit**

The 622 MHz—667 MHz LI macro contains both analog and digital circuitry. The data recovery function, for example, is implemented as primarily a digital function, but it relies on a conventional analog phase-locked loop to provide its 622 MHz—667 MHz reference frequency. The internal analog phase-locked loop contains a voltage-controlled oscillator. This circuit will be sensitive to digital noise generated from the rapid switching transients associated with internal logic gates and parasitic inductive elements. Generated noise that contains frequency components beyond the bandwidth of the internal phase-locked loop (about 3 MHz) will not be attenuated by the phase-locked loop and will impact bit error rate directly. Thus, separate power supply pins are provided for these critical analog circuit elements.

Additional power supply filtering in the form of a LC pi filter section will be used between the power supply source and these device pins as shown in Figure 17. The corner frequency of the LC filter is chosen based on the power supply switching frequency, which is between 100 kHz and 300 kHz in most applications.

Capacitors C1 and C2 are large electrolytic capacitors to provide the basic cutoff frequency of the LC filter. For example, the cutoff frequency of the combination of these elements might fall between 5 kHz and 50 kHz. Capacitor C3 is a smaller ceramic capacitor designed to provide a low-impedance path for a wide range of high-frequency signals at the analog power supply pins of the device. The physical location of capacitor C3 must be as close to the device lead as possible. Multiple instances of capacitors C3 can be used if necessary. The recommended filter for the HSI macro is shown below: L =  $4.7 \mu$ H, RL =  $1 \Omega$ , C1 =  $0.01 \mu$ F, C2 =  $0.01 \mu$ F, C3 =  $4.7 \mu$ F.



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Figure 17. Sample Power Supply Filter Network for Analog LI Power Supply Pins

# XGMII ORCA 4E Receive Analysis

#### XGMII Considerations

The stringent 10 Gbit media independent interface specifications from the *IEEE* 802.3ae standards are met in the FPGA side of the ORLI10G device. Figure 18 and Table 3 show a simplified block diagram for this interface and the receive voltage levels for the HSTL inputs to the ORLI10G device.

The ORLI10G device meets the 480 ps input setup time and 480 ps input hold time requirements for the XGMII receiver inputs into the FPGA side of the FPSC with the embedded IO DDR cells and the embedded PLLs on the FPGA side of the FPSC. The PLLs are not used on input due to this being a forward clocked interface. The ORLI10G meets the clock-to-out specification on the XGMII DDR outputs by using the output shift register to produce a nonduty cycle dependent output. The output clock is then centered around this data eye using internal PLLs.

There are two considerations to note about the pinout location of the XGMII input clocks.

- The XGMII input clocks must be located at the C pad of the programmable I/O Cells (PICs). In the pinout tables, the pads are labelled on a pin-by-pin basis. For example, a pin whose pad is referenced as PL1C can be used as an XGMII input clock, but pins referenced as PL1A, PL1B, or PL1D cannot be used as an XGMII input clock.
- The XGMII input data pins can be no further then six PICs away from the XGMII input clock pin. This means that in the 416 PBGA package, the clock needs to be driven on two pins to be able to clock in the 32-bit XGMII input data bus.

The only considerations to note about the XGMII output transmit clock is that it needs to be phase-locked with an embedded PLL in the FPGA side of the FPSC.

Due to the strict pinout locations mentioned above, when implementing a XGMII interface, the microprocessor interface (MPI) will not be available in the 416 PBGA and 680 PBGA packages.

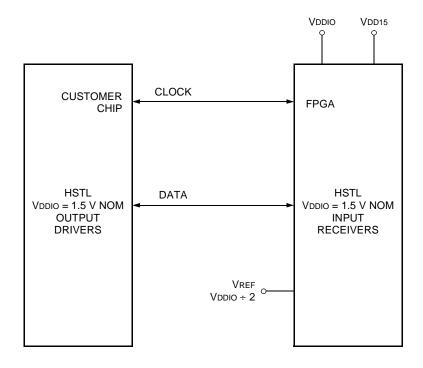


Figure 18. Simplified XGMII Block Diagram

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# XGMII ORCA 4E Receive Analysis (continued)

Table 3. Assumed Inputs to FPGA

Inputs	Low	Nom	High
VDDIO	1.4 V	1.5 V	1.6 V
VIH (min level)	0.88 V	0.95 V	1.10 V
VREF	0.68 V	0.75 V	0.90 V
VIL (max level)	0.48 V	0.55 V	0.70 V

# **Absolute Maximum Ratings**

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only. Functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of this data sheet. Exposure to absolute maximum ratings for extended periods can adversely affect device reliability.

The *ORCA* Series 4 FPSCs include circuitry designed to protect the chips from damaging substrate injection currents and to prevent accumulations of static charge. Nevertheless, conventional precautions should be observed during storage, handling, and use to avoid exposure to excessive electrical stress.

**Table 4. Absolute Maximum Ratings** 

Parameter	Symbol	Min	Max	Unit
Storage Temperature	Tstg	<del>-</del> 65	150	°C
Power Supply Voltage with Respect to	VDD3	_	≤4.2	V
Ground	VDD15	_	2	V
Input Signal with Respect to Ground	_	Vss - 0.3	VDDIO + 0.3	V
Signal Applied to High-impedance Output	_	Vss - 0.3	VDDIO + 0.3	V
Maximum Package Body Temperature	_	_	220	°C

# **Recommended Operating Conditions**

**Table 5. Recommended Operating Conditions** 

Parameter	Symbol	Min	Max	Unit
Power Supply Voltage with Respect to	VDD3	2.7	3.6	V
Ground	VDD15	1.4	1.6	V
Input Voltages	VIN	Vss - 0.3	VDDIO + 0.3	V
Junction Temperature	TJ	-40	125	°C

# **Embedded Core LVDS I/O**

Table 6. Driver dc Data\*

Parameter	Symbol	Test Conditions	Min	Тур	Max	Unit
Output Voltage High, Voa or Vob	Voн	RLOAD = $100 \Omega \pm 1\%$	_	_	1.475 <sup>†</sup>	V
Output Voltage Low, Voa or Vob	Vol	RLOAD = $100 \Omega \pm 1\%$	0.925 <sup>†</sup>	_	_	V
Output Differential Voltage	Vod	RLOAD = $100 \Omega \pm 1\%$	0.25	_	0.45 <sup>†</sup>	V
Output Offset Voltage	Vos	RLOAD = $100 \Omega \pm 1\%$	1.125*	_	1.275 <sup>†</sup>	V
Output Impedance, Differential	R₀	Vcм = 1.0 V and 1.4 V	80	100	120	Ω
Ro Mismatch Between A and B	ΔRo	Vcм= 1.0 V and 1.4 V	_	_	10	%
Change in Differential Voltage between Complementary States	Δ VOD	RLOAD = $100 \Omega \pm 1\%$	_	_	25	mV
Change in Output Offset Voltage Between Complementary States	Δ Vos	RLOAD = $100 \Omega \pm 1\%$	_	_	25	mV
Output Current	ISA, ISB	Driver shorted to GND	_	_	24	mA
Output Current	ISAB	Drivers shorted together	_	_	12	mΑ
Power-off Output Leakage	Ixa ,  Ixb	VDD = 0 V VPAD, VPADN = 0 V—2.5 V			10	mA

<sup>\*</sup> VDD33 = 3.1 V—3.5 V, VDD15 = 1.4 V—1.6 V, -40 °C, and slow-fast process.

Table 7. Driver ac Data\*

Parameter	Symbol	Test Conditions	Min	Max	Unit
Vod Fall Time, 80% to 20%	tF	$Z_L = 100 \Omega \pm 1\%$ CPAD = 3.0 pF, CPAD = 3.0 pF	100	210	ps
Vod Rise Time, 20% to 80%	<b>t</b> R	$Z_L = 100 \Omega \pm 1\%$ CPAD = 3.0 pF, CPAD = 3.0 pF	100	210	ps
Differential Skew  tPHLA - tPLHB  or  tPHLB - tPLHA	tskew1	Any differential pair on package at 50% point of the transition		50	ps
Channel-to-channel Skew  tpDIFFm - tpDIFFn ,	tskew2	Any two signals on package at 0 V differential			ps
Propagation Delay Time	tplh tphl	$Z_L = 100 \Omega \pm 1\%$ CPAD = 3.0 pF, CPADN = 3.0 pF	0.54 0.55	1.10 1.09	ns ns

<sup>\*</sup> VDD33 = 3.1 V—3.5 V, VDD15 = 1.4 V—1.6 V, -40 °C, and slow-fast process.

**Table 8. Driver Power Consumption\*** 

Parameter	Symbol	Test Conditions	Min	Max	Unit
Driver dc Power	PDdc	$Z_L = 100 \Omega \pm 1\%$	_	26.0	mW
Driver ac Power	PDac	$Z_L = 100 \ \Omega \pm 1\%$	_	64	μW/MHz
		CPAD = $3.0 \text{ pF}$ , CPADN = $3.0 \text{ pF}$			

<sup>\*</sup> VDD33 = 3.1 V-3.5 V, VDD15 = 1.4 V-1.6 V, -40 °C, and slow-fast process.

<sup>†</sup>External reference, REF10 = 1.0 V  $\pm$  3%, REF14 = 1.4 V  $\pm$  3%.

### Embedded Core LVDS I/O (continued)

### **LVDS Receiver Buffer Requirements**

Table 9. Receiver ac Data\*

Parameter	Symbol	Test Conditions	Min	Max	Unit
Pulse-width Distortion	tpwd	VIDTH = 100 mV, 311 MHz	_	160	ps
Propagation Delay Time	tPLH	$C_{L} = 0.5  pF$	0.60	1.42	ns
	tPHL		0.60	1.47	ns
With Common-mode Variation (0 V to 2.4 V)	∆ tPD	CL = 0.5 pF	_	50	ps
Output Rise Time, 20% to 80%	tR	CL = 0.5 pF	150	350	ps
Output Fall Time, 80% to 20%	tF	CL = 0.5 pF	150	350	ps

<sup>\*</sup> VDD = 3.1 V—3.5 V, 0 °C—125 °C, slow-fast process.

Table 10. Receiver Power Consumption\*

Parameter	Symbol	Test Conditions	Min	Max	Unit
Receiver dc Power	PRdc	dc	_	20.4	mW
Receiver ac Power	PRac	ac CL = 1.5 pF	_	4.5	μW/ MHz

<sup>\*</sup> VDD = 3.1 V—3.5 V, 0 °C—125 °C, slow-fast process.

Table 11. Receiver dc Data\*

Parameter	Symbol	Test Conditions	Min	Тур	Max	Unit
Input Voltage Range, VIA or VIB	Vı	VGPD   < 925 mV dc - 1 MHz	0.0	1.2	2.4	V
Input Differential Threshold	VIDTH	VGPD  < 925 mV 400 MHz	-100		100	mV
Input Differential Hysteresis	VHYST	(+VIDTHH) — (–VIDTHL)	_	_	†	mV
Receiver Differential Input Impedance	Rin	With build-in termination, center-tapped	80	100	120	Ω

 $<sup>^{\</sup>star}$  VDD = 3.1 V—3.5 V, 0 °C—125 °C, slow-fast process.

**Table 12. LVDS Operating Parameters** 

Parameter	Test Conditions	Min	Normal	Max	Unit
Transmit Termination Resistor	_	80	100	120	Ω
Receiver Termination Resistor	_	80	100	120	Ω
Temperature Range	_	-40	_	125	°C
Power Supply VDD33	_	3.1	_	3.5	V
Power Supply VDD15	_	1.4	_	1.6	V
Power Supply Vss	_	_	0		V

Note: Under worst-case operating condition, the LVDS driver will withstand a disabled or unpowered receiver for an unlimited period of time without being damaged. Similarly, when outputs are short-circuited to each other or to ground, the LVDS will not suffer permanent damage. The LVDS driver supports hot-insertion. Under a well-controlled environment, the LVDS I/O can drive backplane as well as cable.

<sup>†</sup>External reference, REF10 = 1.0 V  $\pm$  3%, REF14 = 1.4 V  $\pm$  3%.

### **Timing Characteristics**

### Receive/Transmit Input Data/Sync Interface

#### Receive (Line)/Transmit (System) STS-48/STS-192 (2.5G/10G) Data Inputs

Figure 19 illustrates the timing for the receive (line) and transmit (system) STS-48/STS-192 data stream. Both the clock and data pins are low-voltage differential signal (LVDS) input buffers. The expected clock rate is 622.08 MHz/666.51428 MHz and the receive/transmit data is clocked on the rising edge of the clock. In 2.5G (divide-by-8) mode, each of the four channels uses one set of RX\_CLK\_IN\_n and 4 RX\_DAT\_IN\_n data pins. In 10G (divide-by-4) mode, only RX\_CLK\_IN\_0 and TX\_CLK\_IN is used, along with theRX\_DAT\_IN\_[15:0] pins.

Both the clock and frame sync are low-voltage differential signal (LVDS) input buffers. The expected clock is 622.08 MHz—666.51 MHz. It is recommended that the Rx clock be inverted by crossing the LVDS pin pair, that is, connect the N to the P and the P to the N. This is because the embedded LI requires the Rx data to be centered on the Rx clock. The timing values for the diagram are given in Table 13.

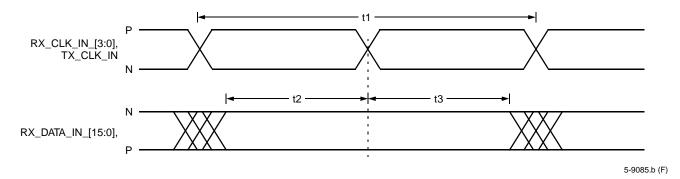


Figure 19. Receive/Transmit Data Timing

Table 13. Receive (Line)/Transmit (System) Data Timing

Symbol	Parameter	Min	Тур	Max	Unit
t1	Clock Period	_	1608/1500	_	ps
t2	Data Setup Time Required	300	_	_	ps
t3	Data Hold Time Required	300			ps

### Timing Characteristics (continued)

### Transmit (Line)/Receive (System) STS-48/STS-192 (2.5G/10G) Data Outputs

Figure 20 illustrates the timing for the transmit (line)/receive (system) STS-48/STS-192 data stream. Both the clock and data pins are driven with low-voltage differential signal buffers. The expected clock rate is 622.08 MHz/666.51428 MHz and the receive/transmit data is clocked out on the rising edge of the clock. In 2.5G mode, each of the four channes uses one set of TX\_CLK\_OUT\_n with four TX\_DAT\_OUT\_n data pins. In 10G mode, only TX\_CLK\_OUT[0] is used with the 16 TX\_DAT\_OUT pins. The timing values for the diagram are given in Table 14.

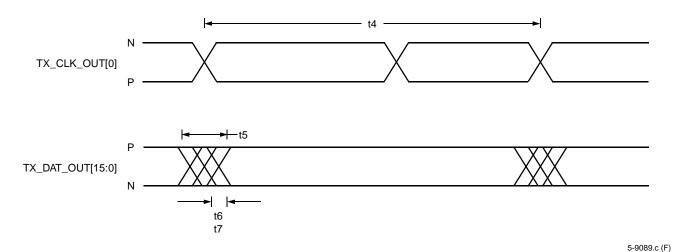


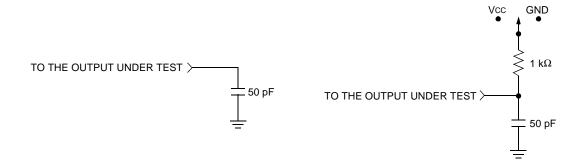
Figure 20. Transmit (Line)/Receive (System) Data Timing

Table 14. Transmit (Line)/Receive (System) Data Output Timing

Symbol	Parameter	Min	Тур	Max	Unit
t4	Clock Period	_	1608/1500	_	ps
_	Duty Cycle <sup>1</sup>	45	50	55	%
t5	Data Delay from Clock Edge	-220	_	220	ps
t6	Data Rise Time: 20%—80%	100	_	200	ps
t7	Data Fall Time: 80%—20%	100	_	200	ps
	Clock In to Clock Out		_	4500	ps

<sup>1.</sup> This requirement is for all sources of the output clocks (e.g., RCLKSI, etc.).

### Input/Output Buffer Measurement Conditions (On-LVDS Buffer)



#### A. Load Used to Measure Propagation Delay

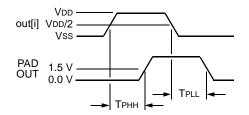
#### B. Load Used to Measure Rising/Falling Edges

Note: Switch to VDD for TPLZ/TPZL; switch to GND for TPHZ/TPZH.

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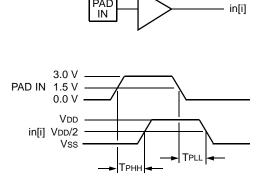
Figure 21. ac Test Loads





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Figure 22. Output Buffer Delays



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Figure 23. Input Buffer Delays

#### **LVDS Buffer Characteristics**

#### **Termination Resistor**

The LVDS drivers and receivers operate on a 100  $\Omega$  differential impedance, as shown below. External resistors are not required. The differential driver and receiver buffers include termination resistors inside the device package as shown in Figure 24 below.

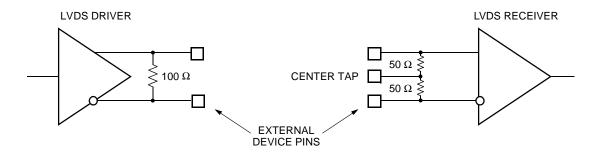


Figure 24. LVDS Driver and Receiver and Associated Internal Components

#### LVDS Driver Buffer Capabilities

Under worst-case operating condition, the LVDS driver must withstand a disabled or unpowered receiver for an unlimited period of time without being damaged. Similarly, when its outputs are short-circuited to each other or to ground, the LVDS driver will not suffer permanent damage. Figure 25 illustrates the terms associated with LVDS driver and receiver pairs.

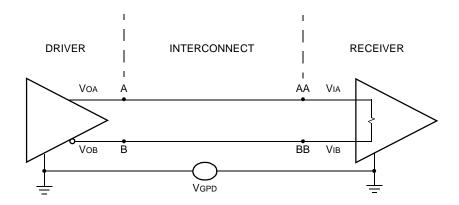
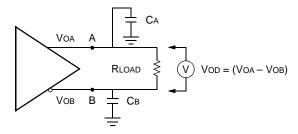


Figure 25. LVDS Driver and Receiver



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Figure 26. LVDS Driver

### **Pin Information**

This section describes the pins and signals that perform FPGA-related functions. During configuration, the user-programmable I/Os are 3-stated and pulled-up with an internal resistor. If any FPGA function pin is not used (or not bonded to package pin), it is also 3-stated and pulled-up after configuration.

**Table 15. FPGA Common-Function Pin Description** 

Symbol	I/O	Description
<b>Dedicated Pins</b>		
VDD33	_	3 V positive power supply.
V <sub>DD</sub> 15	_	1.5 V positive power supply for internal logic.
VDDIO	_	Positive power supply used by I/O banks.
GND	_	Ground supply.
PTEMP	I	Temperature-sensing diode pin. Dedicated input.
RESET	I	During configuration, RESET forces the restart of configuration and a pull-up is enabled. After configuration, RESET can be used as a general FPGA input or as a direct input, which causes all PLC latches/FFs to be asynchronously set/reset.
CCLK	- 0	In the master and asynchronous peripheral modes, CCLK is an output which strobes configuration data in. In the slave or readback after configuration, CCLK is input synchronous with the data on DIN or D[7:0]. CCLK is an output for daisy-chain operation when the lead device is in master, peripheral, or system bus modes.
DONE	Ι	As an input, a low level on DONE delays FPGA start-up after configuration.*
	0	As an active-high, open-drain output, a high level on this signal indicates that configuration is complete. DONE has an optional pull-up resistor.
PRGM	I	PRGM is an active-low input that forces the restart of configuration and resets the boundary-scan circuitry. This pin always has an active pull-up.
RD_CFG	I	This pin must be held high during device initialization until the INIT pin goes high. This pin always has an active pull-up.
		During configuration, RD_CFG is an active-low input that activates the TS_ALL function and 3-states all of the I/O.
		After configuration, RD_CFG can be selected (via a bit stream option) to activate the TS_ALL function as described above, or, if readback is enabled via a bit stream option, a high-to-low transition on RD_CFG will initiate readback of the configuration data, including PFU output states, starting with frame address 0.
RD_DATA/TDO	0	RD_DATA/TDO is a dual-function pin. If used for readback, RD_DATA provides configuration data out. If used in boundary-scan, TDO is test data out.
CFG_IRQ/MPI_IRQ	0	During JTAG, slave, master, and asynchronous peripheral configuration assertion on this CFG_IRQ (active-low) indicates an error or errors for block RAM or FPSC initialization. MPI active-low interrupt request output.

<sup>\*</sup> The FPGA States of Operation section contains more information on how to control these signals during start-up. The timing of DONE release is controlled by one set of bit stream options, and the timing of the simultaneous release of all other configuration pins (and the activation of all user I/Os) is controlled by a second set of options.

Table 15. FPGA Common-Function Pin Description (continued)

Special Burness B		
Special-Ful pose F	Pins	(Can also be used as a general I/O.)
M[3:0]	I	During powerup and initialization, M0—M3 are used to select the configuration mode with their values latched on the rising edge of INIT. During configuration, a pull-up is enabled.
	I/O	After configuration, these pins are user-programmable I/O.*
PLL_CK[0:1,6:7]	I/O	Dedicated PCM clock pins. These pins are a user-programmable I/O pins if not used by PLLs.
P[TBLR]CLK[1:0] [TC]	I/O	Pins dedicated for the primary clock. Input pins on the middle of each side with differential pairing. They may be used as general I/O pins if not needed for clocking purposes.
TDI, TCK, TMS	I	If boundary-scan is used, these pins are test data in, test clock, and test mode select inputs. If boundary-scan is not selected, all boundary-scan functions are inhibited once configuration is complete. Even if boundary-scan is not used, either TCK or TMS must be held at logic 1 during configuration. Each pin has a pull-up enabled during configuration.
	I/O	After configuration, these pins are user-programmable I/O.*
RDY/BUSY/RCLK	0	During configuration in peripheral mode, RDY/RCLK indicates another byte can be written to the FPGA. If a read operation is done when the device is selected, the same status is also available on D7 in asynchronous peripheral mode.
		After configuration, if the MPI is not used, this pin is a user-programmable I/O pin.*
	I/O	During the master parallel configuration mode, RCLK is a read output signal to an external memory. This output is not normally used.
HDC	0	High during configuration is output high until configuration is complete. It is used as a control output, indicating that configuration is not complete.
	I/O	After configuration, this pin is a user-programmable I/O pin.*
LDC	0	Low during configuration is output low until configuration is complete. It is used as a control output, indicating that configuration is not complete.
	I/O	After configuration, this pin is a user-programmable I/O pin.*
ĪNIT	I/O	INIT is a bidirectional signal before and during configuration. During configuration, a pull-up is enabled, but an external pull-up resistor is recommended. As an active-low, open-drain output, INIT is held low during power stabilization and internal clearing of memory. As an active-low input, INIT holds the FPGA in the wait-state before the start of configuration. After configuration, this pin is a user-programmable I/O pin.*
CS0, CS1	I	CS0 and CS1 are used in the asynchronous peripheral, slave parallel, and microprocessor configuration modes. The FPGA is selected when CS0 is low and CS1 is high. During configuration, a pull-up is enabled.
	I/O	After configuration, these pins are user-programmable I/O pins.*
RD/MPI_STRB	I	RD is used in the asynchronous peripheral configuration mode. A low on RD changes D7 into a status output. As a status indication, a high indicates ready, and a low indicates busy. WR and RD should not be used simultaneously. If they are, the write strobe overrides. This pin is also used as the MPI data transfer strobe.
	I/O	After configuration, if the MPI is not used, this pin is a user-programmable I/O pin.*

<sup>\*</sup> The FPGA States of Operation section contains more information on how to control these signals during start-up. The timing of DONE release is controlled by one set of bit stream options, and the timing of the simultaneous release of all other configuration pins (and the activation of all user I/Os) is controlled by a second set of options.

Table 15. FPGA Common-Function Pin Description (continued)

Symbol	I/O	Description
A[17:0]	I	During MPI mode, the A[17:0] are used as the address bus driven by the <i>PowerPC</i> bus master utilizing the least significant bits of the <i>PowerPC</i> 32-bit address.
	0	During master parallel configuration mode, A[17:0] address the configuration EPROM. In MPI mode, many of the A[n] pins have alternate uses as described below. See the special function blocks section for more MPI information. During configuration, if not in master parallel or an MPI configuration mode, these pins are 3-stated with a pull-up enabled.
MPI_BURST		A[21] is used as the MPI_BURST. It is driven low to indicate a burst transfer is in progress. Driven high indicates that the current transfer is not a burst.
MPI_BDIP		A[20] is used as the MPI_BDIP. It is driven by the <i>PowerPC</i> processor assertion of this pin indicates that the second beat in front of the current one is requested by the master. Negated before the burst transfer ends to abort the burst data phase.
MPI_TSZ[1:0]		A[19:18] are used as the MPI_TSZ[1:0] signals and are driven by the bus master to indicate the data transfer size for the transaction. Set 01 for byte, 10 for half-word, and 00 for word. During master parallel mode A[21:0], address the configuration EPROMs up to 4 Mbytes.
A[21:0]		If not used for MPI, these pins are user-programmable I/O pins.*
MPI_ACK	0	In <i>PowerPC</i> mode MPI operation, this is driven low indicating the MPI received the data on the write cycle or returned data on a read cycle.
MPI_CLK	_	This is the <i>PowerPC</i> synchronous, positive-edge bus clock used for the MPI interface. It can be a source of the clock for the embedded system bus. If MPI is used, this can be the <i>AMBA</i> bus clock.
MPI_TEA	0	A low on the MPI transfer error acknowledge indicates that the MPI detects a bus error on the internal system bus for the current transaction.
MPI_RTRY	0	This pin requests the MPC860 to relinquish the bus and retry the cycle.
D[31:0]	I/O	Selectable data bus width from 8-, 16-, 32-bit. Driven by the bus master in a write transaction. Driven by MPI in a read transaction.
	-	D[7:0] receive configuration data during master parallel, peripheral, and slave parallel configuration modes and each pin has a pull-up enabled. During serial configuration modes, D0 is the DIN input.
		D[7:3] output internal status for asynchronous peripheral mode when RD is low.
		After configuration, the pins are user-programmable I/O pins.*
DP[3:0]	I/O	D[23:16], and DP[3] for D[32:24].
		After configuration, this pin is a user-programmable I/O pin.*
DIN	_	During slave serial or master serial configuration modes, DIN accepts serial configuration data synchronous with CCLK. During parallel configuration modes, DIN is the D0 input. During configuration, a pull-up is enabled.
	I/O	After configuration, this pin is a user-programmable I/O pin.*
DOUT	0	During configuration, DOUT is the serial data output that can drive the DIN of daisy-chained slave devices. Data out on DOUT changes on the rising edge of CCLK.
	I/O	After configuration, DOUT is a user-programmable I/O pin.*

<sup>\*</sup> The FPGA States of Operation section contains more information on how to control these signals during start-up. The timing of DONE release is controlled by one set of bit stream options, and the timing of the simultaneous release of all other configuration pins (and the activation of all user I/Os) is controlled by a second set of options.

This table describes the I/O signal ports on the embedded core portion of the device.

**Table 16. FPSC Function Pin Description** 

Symbol	I/O	Description
Control and Global Pins		
PLL_BYPASS	l	3.3 V Active-high. Enables the bypass mode for both receive and both transmit PLLs.
PWRDN	I	3.3 V Active-high. Power down all LVDS links and both receive and both transmit PLLs.
RESET_RX	I	3.3 V Active-high. Resets the receive PLLs and the demultiplexer block.
RESET_TX	I	3.3 V Active-high. Resets the transmit PLLs and the multiplexer block.
Receive I/O Pins		
RX_DAT_IN_N<15:0>	I	LVDS data input for receive side.
RX_DAT_IN_P<15:0>	I	LVDS data input for receive side.
RX_CLK_IN_N<3:0>	I	LVDS clock inputs for receive side.
RX_CLK_IN_P<3:0>	I	LVDS clock inputs for receive side.
Transmit I/O Pins		
TX_DAT_OUT_N<15:0>	0	LVDS data outputs on transmit side.
TX_DAT_OUT_N<15:0>	0	LVDS data outputs on transmit side.
TX_CLK_OUT_N<3:0>	0	LVDS clock outputs on transmit side.
TX_CLK_OUT_N<3:0>	0	LVDS clock outputs on transmit side.
TX_CLK_IN_N	I	LVDS transmit reference clock input.
TX_CLK_IN_P	I	LVDS transmit reference clock input.
LVDS Input Reference P	ins	
LV_REF10	_	LVDS reference voltage: 1.0 V ± 3%
LV_REF14	_	LVDS reference voltage: 1.4 V ± 3%
LV_RESHI	_	LVDS resistor high pin (use 100 Ω to LV_RESLO pin).
LV_RESLO	_	LVDS resistor low pin (use 100 $\Omega$ to LV_RESHI pin).
LVCTAP_[6:1]	_	LVDS input centertap (use 0.01 μF to GND).

In Table 17, an input refers to a signal flowing into the FGPA logic (out of the embedded core) and an output refers to a signal flowing out of the FPGA logic (into the embedded core).

Table 17. Embedded Core/FPGA Interface Signal Description

Pin Name	I/O	Description
Receive Signals		
RX_DAT_OUT<127:0>	0	Data from demultiplexer on receive side.
RX_CLK8_OUT<3:0>	0	Divided down clocks on receive side.
RX_ENB8_OUT<3:0>	0	Data enables on receive side.
RX1_VCOP	0	RX1_PLL output clock on receive side (M/N clock).
RX2_VCOP	0	RX1_PLL output clock on receive side (x1 clock).
RX_LOCK	0	Lock signal for RX1_PLL and RX2_PLL.
Transmit Signals		
TX_DAT_IN<127:0>	I	Data to multiplexer on transmit side.
TX_CLK8_IN<3:0>	I	Clocks to multiplexer on transmit side.
TX_ENB_IN	I	Data enables on transmit side.
TX1_VCOP	0	TX1_PLL output clock on transmit side (M/N clock).
TX2_VCOP	0	TX1_PLL output clock on transmit side (x1 clock).
TX_LOCK	0	Lock signal for TX1_PLL and TX2_PLL.
Vss_A<7:4>	_	Analog ground for the embedded line interface PLLs.
VDD33_A<7:4>	_	Analog power supply for the embedded line interface PLLs.

### **Package Pinouts**

Table 15 provides the number of user programmable I/Os available for each available package.

Table 19 provides the package pin and pin function for the ORLI10G FPSC and packages. The bond pad name is identified in the PIO nomeclature used in the *ORCA* Foundry design editor. The bank column provides information as to which output voltage level bank the given pin is in. The group column provides information as to the group of pins the given pin is in. This is used to show which VREF pin is used to provide the reference voltage for single-ended limited-swing I/Os. If none of these buffer types (such as SSTL, GTL, HSTL) are used in a given group, then the VREF pin is available as an I/O pin.

When the number of FPGA bond pads exceeds the number of package pins, bond pads are unused. When the number of package pins exceeds the number of bond pads, package pins are left unconnected (no connects). When a package pin is to be left as a no connect for a specific die, it is indicated as a note in the device column for the FPGA. The tables provide no information on unused pads.

Table 18. ORCA Programmable I/Os Summary

Device	416 PBGAM1	680 PBGAM1
user programmable I/O	192	316
Available programmable differential pairs	184	272
FPGA configuration pins	7	7
FPGA dedicated function pins	2	2
Core function pins	86	86
VDD15	28	84
Vdd33_A	4	4
VDDIO	21	44
Vss	48	95
Vss_A	4	4
LVCTAP For dedicated differential channels	6	6
Core LV_REF pins	4	4
Total Package pins	416	680

It is very important to note the pinout limitations for 10 Gbits/s Ethernet applications. Specifically, the very stringent timing requirements of the XGMII specification coupled with the I/O availability and locations in the 416-pin PBGA requires that the XGMII output pins be located on three sides of the device. This may cause issues with routing the XGMII bus at a board level as the XGMII specification for routing this bus on a board is only 2 in.

In addition, the built-in microprocessor interface (MPI) cannot be fully utilized in the 416-pin PBGA and the 680-pin PBGA packages because the implementation of the XGMII interface limits the number of available address and data pins.

As shown in the Pair columns in Table 19, differential pairs and physical locations are numbered within each bank (e.g., L19C\_A0 is the nineteenth pair in an associated bank). A C indicates complementary differential whereas a T indicates true differential. An \_A0 indicates the physical location of adjacent balls in either the horizontal or vertical direction. Other physical indicators are as follows:

- \_A1 indicates one ball between pairs.
- \_A2 indicates two balls between pairs.
- \_D0 indicates balls are diagonally adjacent.
- \_D1 indicates balls are diagonally adjacent separated by one physical ball.

VREF pins, shown in the Pin Description column in Table 19, are associated to the bank and group (e.g., VREF\_TL\_01 is the VREF for group one of the top left (TL) bank).

**Table 19. PBGA Pinout Table** 

416 BGA Ball	680 BGA Ball	V <sub>DDIO</sub> Bank	V <sub>REF</sub> Group	ORLI10G Pin Description	416 BGA Pair	680 BGA Pair
D4	E5	_		VDD33	_	_
D3	E4	_		PRD_DATA/TDO	_	_
A1	PLANE	_		VDD15	_	_
C1	C1	_		PRESET	_	_
E4	D1	_		PRD_CFG	_	_
F4	E2	_		PPRGRM	_	_
D2	F4	VDDIO0_TL	7	PL2D/PLL_CK0C	L14C_D0	L21C_A0
E3	F3	VDDIO0_TL	7	PL2C/PLL_CK0T	L14T_D0	L21T_A0
NC	G5	VDDIO0_TL	7	PL3D	_	L22C_A0
D1	F5	VDDIO0_TL	7	PL3C/VREF_TL_07	_	L22T_A0
E2	G4	VDDIO0_TL	7	PL4D/D5	L15C_D0	L23C_D1
F3	F2	VDDIO0_TL	7	PL4C/D6	L15T_D0	L23T_D1
NC	H5	VDDIO0_TL	8	PL4B	_	L24C_D1
NC	G3	VDDIO0_TL	8	PL4A/VREF_TL_08	_	L24T_D1
E1	F1	VDDIO0_TL	8	PL5D/HDC	L16C_D0	L25C_A0
F2	G2	VDDIO0_TL	8	PL5C/LDC	L16T_D0	L25T_A0
NC	H4	VDDIO0_TL	8	PL5B	_	L26C_A0
NC	J5	VDDIO0_TL	8	PL5A	_	L26T_A0
G4	Н3	VDDIO0_TL	9	PL6D	L17C_A0	L27C_D1
H4	G1	VDDIO0_TL	9	PL6C/D7	L17T_A0	L27T_D1
F1	J4	VDDIO0_TL	9	PL7D/VREF_TL_09	L18C_D0	L28C_D1
G2	H2	VDDIO0_TL	9	PL7C/A17	L18T_D0	L28T_D1
H2	K5	VDDIO0_TL	9	PL8D/CS0	L19C_A0	L29C_D1
H3	J3	VDDIO0_TL	9	PL8C/CS1	L19T_A0	L29T_D1
G1	H1	VDDIO0_TL	1	PL9D	L20C_A0	L30C_A0
H1	J2	VDDIO0_TL	1	PL9C	L20T_A0	L30T_A0
NC	K4	VDDIO0_TL	1	PL9A	_	_
J4	L5	VDDIO0_TL	1	PL10D/INIT	L21C_A0	L31C_D1
K4	K3	VDDIO0_TL	1	PL10C/DOUT	L21T_A0	L31T_D1
A26	PLANE	_		VDD15	_	_
J3	J1	VDDIO0_TL	1	PL11D/VREF_TL_10	L22C_A0	L32C_A0
J2	K2	VDDIO0_TL	1	PL11C/A16	L22T_A0	L32T_A0
NC	K1	VDDIO0_TL	1	PL11A	_	_
J1	M5	VDDIO7_CL	1	PL12D/A15	L1C_D0	L1C_A0
K2	L4	VDDIO7_CL	1	PL12C/A14	L1T_D0	L1T_A0
NC	M4	VDDIO7_CL	1	PL12B		L2C_A0
NC	N5	VDDIO7_CL	1	PL12A	_	L2T_A0
K3	L3	VDDIO7_CL	1	PL13D/VREF_CL_01	L2C_A0	L3C_A0
L3	L2	VDDIO7_CL	1	PL13C/D4	L2T_A0	L3T_A0

Table 19. PBGA Pinout Table (continued)

416 BGA Ball	680 BGA Ball	V <sub>DDIO</sub> Bank	V <sub>REF</sub> Group	ORLI10G Pin Description	416 BGA Pair	680 BGA Pair
NC	N4	VDDIO7_CL	2	PL13B		L4C_A0
NC	P5	VDDIO7_CL	2	PL13A	_	L4T_A0
L4	M2	VDDIO7_CL	2	PL14D/RDY/BUSY/RCLK	L3C_A0	L5C_A0
M4	M1	VDDIO7_CL	2	PL14C/VREF_CL_02	L3T_A0	L5T_A0
L1	N3	VDDIO7_CL	2	PL15D/A13	L4C_A0	L6C_A0
M1	N2	VDDIO7_CL	2	PL15C/A12	L4T_A0	L6T_A0
M3	P4	VDDIO7_CL	3	PL16D	L5C_A0	L7C_A0
M2	P3	VDDIO7_CL	3	PL16C	L5T_A0	L7T_A0
NC	R5	VDDIO7_CL	3	PL16A	_	_
N1	N1	VDDIO7_CL	3	PL17D/A11	L6C_A0	L8C_A0
N2	P2	VDDIO7_CL	3	PL17C/VREF_CL_03	L6T_A0	L8T_A0
NC	R4	VDDIO7_CL	3	PL17A	_	_
NC	P1	VDDIO7_CL	3	PL18D	_	L9C_A0
NC	R2	VDDIO7_CL	3	PL18C	_	L9T_A0
U14	PLANE	_	_	VDD15	_	_
NC	R1	VDDIO7_CL	3	PL18A	_	L10T_A0
NC	T2	VDDIO7_CL	3	PL18B	_	L10C_A0
N3	T5	VDDIO7_CL	4	PL19D/RD/MPI_STRB	L7C_A0	L11C_A0
N4	T4	VDDIO7_CL	4	PL19C/VREF_CL_04	L7T_A0	L11T_A0
NC	T3	VDDIO7_CL	4	PL19A	_	L12T_D1
NC	U5	VDDIO7_CL	4	PL19B	_	L12C_D1
P4	T1	VDDIO7_CL	4	PL20D/PLCK0C	L8C_A0	L13C_D1
P3	U3	VDDIO7_CL	4	PL20C/PLCK0T	L8T_A0	L13T_D1
NC	U4	VDDIO7_CL	4	PL20B		L14C_A1
NC	U2	VDDIO7_CL	4	PL20A		L14T_A1
P1	V1	VDDIO7_CL	5	PL21D/A10	L9C_A0	L15C_A0
R1	V2	VDDIO7_CL	5	PL21C/A9	L9T_A0	L15T_A0
NC	V3	VDDIO7_CL	5	PL21B	_	L16C_A0
NC	V4	VDDIO7_CL	5	PL21A	_	L16T_A0
R2	V5	VDDIO7_CL	5	PL22D/A8	L10C_A0	L17C_A0
R3	W4	VDDIO7_CL	5	PL22C/VREF_CL_05	L10T_A0	L17T_A0
AF26	PLANE		_	VDD15	_	_
NC	W3	VDDIO7_CL	5	PL23D		L18C_A0
NC	W2	VDDIO7_CL	5	PL23C	_	L18T_A0
NC	Y1	VDDIO7_CL	5	PL23A	_	_
T1	W5	VDDIO7_CL	6	PL24D/PLCK1C	L11C_A0	L19C_A0
T2	Y4	VDDIO7_CL	6	PL24C/PLCK1T	L11T_A0	L19T_A0
NC	Y2	VDDIO7_CL	6	PL24A	_	_
T4	Y5	VDDIO7_CL	6	PL25D/VREF_CL_06	L12C_A0	L20C_D1

Table 19. PBGA Pinout Table (continued)

416 BGA Ball	680 BGA Ball	V <sub>DDIO</sub> Bank	V <sub>REF</sub> Group	ORLI10G Pin Description	416 BGA Pair	680 BGA Pair
R4	AA3	VDDIO7_CL	6	PL25C/A7	L12T_A0	L20T_D1
NC	AA2	VDDIO7_CL	6	PL25A	_	
U1	AA1	VDDIO7_CL	6	PL26D/A6	L13C_A0	L21C_A0
U2	AB1	VDDIO7_CL	6	PL26C/A5	L13T_A0	L21T_A0
V1	AA4	VDDIO7_CL	7	PL26B	_	
V2	AB2	VDDIO7_CL	7	PL27D/WR/MPI_RW	L14C_D0	L22C_A0
U3	AB3	VDDIO7_CL	7	PL27C/VREF_CL_07	L14T_D0	L22T_A0
NC	AA5	VDDIO7_CL	7	PL27B	_	L23C_A0
NC	AB4	VDDIO7_CL	7	PL27A	_	L23T_A0
W1	AC2	VDDIO7_CL	8	PL28D/A4	L15C_A0	L23C_A0
Y1	AC1	VDDIO7_CL	8	PL28C/VREF_CL_08	L15T_A0	L23T_A0
V4	AB5	VDDIO7_CL	8	PL29D/A3	L16C_A0	L23C_A0
U4	AC4	VDDIO7_CL	8	PL29C/A2	L16T_A0	L23T_A0
NC	AD2	VDDIO7_CL	8	PL29A	_	_
V3	AC5	VDDIO7_CL	8	PL30D/A1	L17C_D0	L24C_D1
W2	AD3	VDDIO7_CL	8	PL30C/A0	L17T_D0	L24T_D1
Y2	AE1	VDDIO7_CL	8	PL31D/DP0	L18C_D0	L25C_A0
W3	AE2	VDDIO7_CL	8	PL31C/DP1	L18T_D0	L25T_A0
NC	AF1	VDDIO7_CL	8	PL31A	_	_
AA1	AD5	VDDIO6_BL	1	PL32D/D8	L1C_A0	L1C_A0
AA2	AD4	VDDIO6_BL	1	PL32C/VREF_BL_01	L1T_A0	L1T_A0
NC	AE3	VDDIO6_BL	1	PL32A	_	_
Y3	AE5	VDDIO6_BL	1	PL33D/D9	L2C_D0	L2C_A0
W4	AE4	VDDIO6_BL	1	PL33C/D10	L2T_D0	L2T_A0
Y4	AF2	VDDIO6_BL	2	PL34D	L3C_D0	L3C_A0
AA3	AG1	VDDIO6_BL	2	PL34C/VREF_BL_02	L3T_D0	L3T_A0
NC	AF3	VDDIO6_BL	2	PL34B		L4C_A1
NC	AF5	VDDIO6_BL	2	PL34A		L4T_A1
AB2	AG2	VDDIO6_BL	3	PL35B/D11	L4C_D0	L5C_D1
AC1	AF4	VDDIO6_BL	3	PL35A/D12	L4T_D0	L5T_D1
NC	AH1	VDDIO6_BL	3	PL36D	_	L6C_D1
NC	AG3	VDDIO6_BL	3	PL36C	_	L6T_D1
AC2	AH2	VDDIO6_BL	3	PL36B/VREF_BL_03	L5C_D0	L7C_A0
AB3	AJ1	VDDIO6_BL	3	PL36A/D13	L5T_D0	L7T_A0
NC	AG4	VDDIO6_BL	4	PL37D	_	
NC	AH3	VDDIO6_BL	4	PL37B		L8C_D1
AD1	AG5	VDDIO6_BL	4	PL37A/VREF_BL_04	_	L8T_D1
NC	AJ2	VDDIO6_BL	4	PL38C		
NC	AK1	VDDIO6_BL	4	PL38B	_	_

Table 19. PBGA Pinout Table (continued)

416 BGA Ball	680 BGA Ball	V <sub>DDIO</sub> Bank	V <sub>REF</sub> Group	ORLI10G Pin Description	416 BGA Pair	680 BGA Pair
NC	AH4	VDDIO6_BL	4	PL38A	_	_
AA4	AJ3	VDDIO6_BL	4	PL39D/PLL_CK7C	L6C_A0	L9C_A0
AB4	AK2	VDDIO6_BL	4	PL39C/PLL_CK7T	L6T_A0	L9T_A0
NC	AH5	VDDIO6_BL	4	PL39B	_	L10C_A0
NC	AJ4	VDDIO6_BL	4	PL39A	_	L10T_A0
AC3	AK3	_	_	PTEMP	_	_
R14	PLANE	_	_	VDD15	_	_
AE2	AN1	_	_	LVDS_R	_	_
AD3	AJ5	_	_	VDD33	_	_
AC4	AL5	_	_	VDD33	_	_
T13	PLANE	_	_	VDD15	_	_
AE3	AM5	VDDIO6_BL	5	PB2A/DP2	_	L11T_A0
NC	AN4	VDDIO6_BL	5	PB2B	_	L11C_A0
AC5	AK6	VDDIO6_BL	5	PB2C/PLL_CK6T	L7T_D0	L12T_A0
AD4	AL6	VDDIO6_BL	5	PB2D/PLL_CK6C	L7C_D0	L12C_A0
NC	AK7	VDDIO6_BL	5	PB3A	_	_
NC	AN5	VDDIO6_BL	5	PB3C	_	L13T_A0
NC	AM6	VDDIO6_BL	5	PB3D	_	L13C_A0
AE4	AN6	VDDIO6_BL	5	PB4A/VREF_BL_05	L8T_D0	L14T_A0
AF3	AP5	VDDIO6_BL	5	PB4B/DP3	L8C_D0	L14C_A0
AC6	AL7	VDDIO6_BL	6	PB4C	L9T_D0	L15T_A0
AD5	AM7	VDDIO6_BL	6	PB4D	L9C_D0	L15C_A0
AF4	AN7	VDDIO6_BL	6	PB5C/VREF_BL_06	L10T_D0	L16T_A0
AE5	AP6	VDDIO6_BL	6	PB5D/D14	L10C_D0	L16C_A0
NC	AK8	VDDIO6_BL	6	PB6A	_	L17T_A0
AD6	AL8	VDDIO6_BL	6	PB6B	_	L17C_A0
AC7	AM8	VDDIO6_BL	7	PB6C/D15	L11T_A0	L18T_D1
AC8	AK9	VDDIO6_BL	7	PB6D/D16	L11C_A0	L18C_D1
NC	AP7	VDDIO6_BL	7	PB7A	_	_
AD7	AL9	VDDIO6_BL	7	PB7C/D17	L12T_D0	L19T_A0
AE6	AK10	VDDIO6_BL	7	PB7D/D18	L12C_D0	L19C_A0
NC	AN8	VDDIO6_BL	7	PB8A	_	_
AE7	AM9	VDDIO6_BL	7	PB8C/VREF_BL_07	L13T_D0	L20T_A0
AD8	AL10	VDDIO6_BL	7	PB8D/D19	L13C_D0	L20C_A0
NC	AP8	VDDIO6_BL	8	PB9A	_	_
AF6	AL11	VDDIO6_BL	8	PB9C/D20	L14T_A0	L21T_A0
AF7	AK11	VDDIO6_BL	8	PB9D/D21	L14C_A0	L21C_A0
NC	AM10	VDDIO6_BL	8	PB10A	_	_
AE8	AN9	VDDIO6_BL	8	PB10C/VREF_BL_08	L15T_D0	L22T_A0

Table 19. PBGA Pinout Table (continued)

416 BGA Ball	680 BGA Ball	V <sub>DDIO</sub> Bank	V <sub>REF</sub> Group	ORLI10G Pin Description	416 BGA Pair	680 BGA Pair
T14	PLANE	_	_	VDD15	_	_
AD9	AP9	VDDIO6_BL	8	PB10D/D22	L15C_D0	L22C_A0
NC	AM11	VDDIO6_BL	9	PB11A	_	L23T_D1
NC	AK12	VDDIO6_BL	9	PB11B	_	L23C_D1
AC9	AN10	VDDIO6_BL	9	PB11C/D23	L16T_A0	L24T_A0
AC10	AP10	VDDIO6_BL	9	PB11D/D24	L16C_A0	L24C_A0
NC	AL12	VDDIO6_BL	9	PB12A	_	L25T_A0
NC	AK13	VDDIO6_BL	9	PB12B	_	L25C_A0
AF8	AN11	VDDIO6_BL	9	PB12C/VREF_BL_09	L17T_D0	L26T_A0
AE9	AN12	VDDIO6_BL	9	PB12D/D25	L17C_D0	L26C_A0
NC	AK14	VDDIO6_BL	9	PB13A	_	L27T_A0
NC	AL13	VDDIO6_BL	9	PB13B	_	L27C_A0
AD10	AP12	VDDIO6_BL	1	PB13C/D26	L18T_A0	L28T_A0
AE10	AN13	VDDIO6_BL	1	PB13D/D27	L18C_A0	L28C_A0
NC	AL14	VDDIO6_BL	1	PB14A	_	L29T_A0
NC	AK15	VDDIO6_BL	1	PB14B	_	L29C_A0
AE11	AP13	VDDIO6_BL	1	PB14C/VREF_BL_10	L19T_A0	L30T_A0
AD11	AP14	VDDIO6_BL	1	PB14D/D28	L19C_A0	L30C_A0
NC	AN14	VDDIO6_BL	11	PB15A	_	_
AC12	AM14	VDDIO6_BL	11	PB15C/D29	L20T_A0	L31T_A0
AC11	AL15	VDDIO6_BL	11	PB15D/D30	L20C_A0	L31C_A0
NC	AN15	VDDIO6_BL	11	PB16A	_	_
AF10	AM16	VDDIO6_BL	11	PB16C/VREF_BL_11	L21T_A0	L32T_A0
AF11	AL16	VDDIO6_BL	11	PB16D/D31	L21C_A0	L32C_A0
NC	AP15	VDDIO5_BC	1	PB17A	_	_
AD12	AN16	VDDIO5_BC	1	PB17C	L1T_A0	L1T_A0
AE12	AP16	VDDIO5_BC	1	PB17D	L1C_A0	L1C_A0
NC	AK16	VDDIO5_BC	1	PB18A	_	_
AF12	AL17	VDDIO5_BC	1	PB18C/VREF_BC_01	L2T_A0	L2T_A0
P16	PLANE	_	_	VDD15	_	_
AF13	AK17	VDDIO5_BC	1	PB18D	L2C_A0	L2C_A0
NC	AM17	VDDIO5_BC	2	PB19A	_	L3T_A0
NC	AN17	VDDIO5_BC	2	PB19B	_	L3C_A0
AD13	AP18	VDDIO5_BC	2	PB19C/PBCK0T	L3T_A0	L4T_A1
AE13	AM18	VDDIO5_BC	2	PB19D/PBCK0C	L3C_A0	L4C_A1
NC	AL18	VDDIO5_BC	2	PB20B		L5C_A1
NC	AN18	VDDIO5_BC	2	PB20A	_	L5T_A1
AC14	AN19	VDDIO5_BC	2	PB20C/VREF_BC_02	L4T_A0	L6T_D2
AC13	AK18	VDDIO5_BC	2	PB20D	L4C_A0	L6C_2

Table 19. PBGA Pinout Table (continued)

416 BGA Ball	680 BGA Ball	V <sub>DDIO</sub> Bank	V <sub>REF</sub> Group	ORLI10G Pin Description	416 BGA Pair	680 BGA Pair
NC	AM19	VDDIO5_BC	2	PB21A	_	L7T_D1
NC	AP20	VDDIO5_BC	2	PB21B	_	L7C_D1
R13	PLANE	_	_	VDD15	_	_
AE14	AL19	VDDIO5_BC	3	PB21C	L5T_A0	L8T_D1
AD14	AN20	VDDIO5_BC	3	PB21D/VREF_BC_03	L5C_A0	L8C_D1
NC	AP21	VDDIO5_BC	3	PB22A	_	_
AF15	AL20	VDDIO5_BC	3	PB22C	L6T_A0	L9T_A0
AE15	AK19	VDDIO5_BC	3	PB22D	L6C_A0	L9C_A0
NC	AN21	VDDIO5_BC	3	PB23A	_	_
AD15	AK20	VDDIO5_BC	3	PB23C/PBCK1T	L7T_D0	L10T_D1
AE16	AM21	VDDIO5_BC	3	PB23D/PBCK1C	L7C_D0	L10C_D1
NC	AP22	VDDIO5_BC	3	PB24A	_	_
AC15	AL21	VDDIO5_BC	4	PB24C	L8T_A0	L11T_D1
AC16	AN22	VDDIO5_BC	4	PB24D	L8C_A0	L11C_D1
NC	AP23	VDDIO5_BC	4	PB25A	_	_
AD16	AN23	VDDIO5_BC	4	PB25C	L9T_D0	L12T_A0
AE17	AN24	VDDIO5_BC	4	PB25D/VREF_BC_04	L9C_D0	L12C_A0
NC	AK21	VDDIO5_BC	4	PB26A	_	L13T_A0
NC	AL22	VDDIO5_BC	4	PB26B	_	L13C_A0
AF18	AP25	VDDIO5_BC	5	PB26C	L10T_A0	L14T_D1
AE18	AM24	VDDIO5_BC	5	PB26D/VREF_BC_05	L10C_A0	L14C_D1
NC	AK22	VDDIO5_BC	5	PB27A	_	L15T_A0
NC	AL23	VDDIO5_BC	5	PB27B	_	L15C_A0
AF19	AN25	VDDIO5_BC	5	PB27C	L11T_A0	L16T_D1
AF20	AL24	VDDIO5_BC	5	PB27D	L11C_A0	L16T_D1
NC	AP26	VDDIO5_BC	6	PB28A	_	_
AC18	AM25	VDDIO5_BC	6	PB28C	L12T_A0	L17T_D1
AC17	AK23	VDDIO5_BC	6	PB28D/VREF_BC_06	L12C_A0	L17C_D1
NC	AN26	VDDIO5_BC	6	PB29A	_	_
NC	AL25	VDDIO5_BC	6	PB29C	_	L18T_A0
NC	AK24	VDDIO5_BC	6	PB29D	_	L18C_A0
NC	AP27	VDDIO5_BC	7	PB30A	_	_
AD18	AM26	VDDIO5_BC	7	PB30C	L13T_D0	L19T_A0
AE19	AN27	VDDIO5_BC	7	PB30D	L13C_D0	L19C_A0
AE20	AP28	VDDIO5_BC	7	PB31C/VREF_BC_07	L14T_D0	L20T_D1
AD19	AM27	VDDIO5_BC	7	PB31D	L14C_D0	L20C_D1
AF21	AL26	VDDIO5_BC	7	PB32C	L15T_A0	L21T_A0
AE21	AK25	VDDIO5_BC	7	PB32D	L15C_A0	L21C_A0
AC19	AN28	VDDIO5_BC	8	PB33C	_	L22T_A0

Table 19. PBGA Pinout Table (continued)

416 BGA Ball	680 BGA Ball	V <sub>DDIO</sub> Bank	V <sub>REF</sub> Group	ORLI10G Pin Description	416 BGA Pair	680 BGA Pair
NC	AP29	VDDIO5_BC	8	PB33D/VREF_BC_08	_	L22C_A0
AF23	AK26	_	_	VDD33	_	_
AC20	AL27	_	_	RX_DAT_IN_10_P	L1_D2	L1_A0
AF22	AM28	_	_	RX_DAT_IN_10_N	L1_D2	L1_A0
AE22	AN29	_	_	RX_DAT_IN_11_P	L2_D0	L2_A0
AD21	AP30	_	_	RX_DAT_IN_11_N	L2_D0	L2_A0
AE23	AL28	_	_	RX_DAT_IN_12_P	L3_D0	L3_A0
AF24	AM29	_	_	RX_DAT_IN_12_N	L3_D0	L3_A0
AC21	AK27	_	_	RX_DAT_IN_13_P	L4_D0	L4_A0
NC	AN30	_	_	VDD33	_	_
AD22	AK28	_	_	RX_DAT_IN_13_N	L4_D0	L4_A0
AD23	AL29	_	_	RX_CLK_IN_1_P	L5_D0	L5_A0
AE24	AM30	_	_	RX_CLK_IN_1_N	L5_D0	L5_A0
AC22	AN31	_	_	LVCTAP_1	_	_
AC23	AP32	_	_	VssA_4	_	_
NC	PLANE	_	_	VDD15	_	_
AD24	AK30	_	_	VDD33A_4	_	_
AE25	AK31	_	_	VDD33A_5	_	_
AC24	AJ30	_	_	VDD33	_	_
AD25	AK32	_	_	VssA_5	_	_
AD26	AJ31	_	_	LVCTAP_2	_	_
NC	AH30			VDD33	_	
NC	PLANE			VDD15	_	
AB23	AK33			RX_DAT_IN_20_P	L6_A0	L6_A0
AA23	AJ32			RX_DAT_IN_20_N	L6_A0	L6_A0
AC25	AH31			RX_DAT_IN_21_P	L7_D0	L7_A0
AB24	AG30			RX_DAT_IN_21_N	L7_D0	L7_A0
AB25	AF30			RX_DAT_IN_22_P	L8_D0	L8_A0
AA24	AG31			RX_DAT_IN_22_N	L8_D0	L8_A0
AC26	AK34			RX_DAT_IN_23_P	L9_A0	L9_A0
AB26	AJ33			RX_DAT_IN_23_N	L9_A0	L9_A0
NC	PLANE	_	_	VDD15	_	_
Y24	AH32	_	_	VDD33	_	_
W23	AE30	_	_	LVCTAP_3	_	_
NC	PLANE	_	_	VDD15	_	_
AA25	AG32			RX_CLK_IN_2_P	L10_A0	L10_A0
AA26	AF31			RX_CLK_IN_2_N	L10_A0	L10_A0
NC	AF32		_	VDD33	_	
Y23	AC30			RX_DAT_IN_30_P	L11_D0	L11_A0

Table 19. PBGA Pinout Table (continued)

416 BGA Ball	680 BGA Ball	V <sub>DDIO</sub> Bank	V <sub>REF</sub> Group	ORLI10G Pin Description	416 BGA Pair	680 BGA Pair
W24	AD30	<u> </u>	_	RX_DAT_IN_30_N	L11_D0	L11_A0
NC	PLANE	<u> </u>	_	VDD15	_	_
Y25	AE31	<u> </u>	_	RX_DAT_IN_31_P	L12_A0	L12_A0
Y26	AE32	<u> </u>	_	RX_DAT_IN_31_N	L12_A0	L12_A0
NC	AF33	<u> </u>	_	VDD33	_	_
W25	AD31	<del></del>	_	RX_DAT_IN_32_P	L13_D0	L13_A0
V24	AD32	<del>_</del>	_	RX_DAT_IN_32_N	L13_D0	L13_A0
NC	PLANE	_	_	VDD15	_	_
W26	AB30	<del>_</del>	_	LVCTAP_4	_	_
V23	AC31	<del>_</del>	_	RX_DAT_IN_33_P	L14_A0	L14_A0
U23	AC32	<del>_</del>	_	RX_DAT_IN_33_N	L14_A0	L14_A0
NC	AC33	<del>_</del>	_	VDD33	_	_
V25	AB31	<del></del>	_	RX_CLK_IN_3_P	L15_D0	L15_A0
U24	AB32	<del>_</del>	_	RX_CLK_IN_3_N	L15_D0	L15_A0
V26	AA30	<u> </u>	_	LVCTAP_5	_	_
NC	PLANE	<del></del>	_	VDD15	_	_
U26	AB33	<u> </u>	_	VDD33	_	_
U25	AA31	<u> </u>	_	RX_CLK_IN_4_P	L16_D0	L16_A0
T24	Y30	<u> </u>	_	RX_CLK_IN_4_N	L16_D0	L16_A0
R23	AA32	<del></del>	_	RX_DAT_IN_40_P	L17_A0	L17_A0
T23	AA33	<del>_</del>	_	RX_DAT_IN_40_N	L17_A0	L17_A0
NC	PLANE	_	_	VDD15	_	_
T25	Y31	_	_	RX_DAT_IN_41_P	L18_A0	L18_A0
T26	Y32	_	_	RX_DAT_IN_41_N	L18_A0	L18_A0
NC	W30	_	_	VDD33	_	_
NC	Y33	_	_	VDD33	_	_
R24	W31	_	_	RX_DAT_IN_42_P	L19_A0	L19_A0
R25	W32	_	_	RX_DAT_IN_42_N	L19_A0	L19_A0
R26	V30	_	_	RX_DAT_IN_43_P	L20_D0	L20_A0
P25	V31	_	_	RX_DAT_IN_43_N	L20_D0	L20_A0
P24	W33	_	_	VDD33	_	_
P26	V32	_	_	LV_REF10	_	_
N26	V33		_	LV_REF14	_	
N23	U33		_	LV_RESHI	_	
P23	U31		_	LV_RESLO	_	
NC	U30	_	_	VDD33	_	
NC	PLANE		_	VDD15	_	_
N25	U32		_	TX_CLK_OUT_1_P	L21_A0	L21_A0
N24	T33	_	_	TX_CLK_OUT_1_N	L21_A0	L21_A0

Table 19. PBGA Pinout Table (continued)

416 BGA Ball	680 BGA Ball	V <sub>DDIO</sub> Bank	V <sub>REF</sub> Group	ORLI10G Pin Description	416 BGA Pair	680 BGA Pair
NC	T32	_	_	VDD33	_	_
M26	T31	_	_	TX_DAT_OUT_10_P	L22_A0	L22_A0
M25	T30	_	_	TX_DAT_OUT_10_N	L22_A0	L22_A0
M24	R33	_	_	TX_DAT_OUT_11_P	L23_A0	L23_A0
M23	R32	_	_	TX_DAT_OUT_11_N	L23_A0	L23_A0
NC	PLANE	_	_	VDD15	_	
L26	R31	_	_	TX_DAT_OUT_12_P	L24_A0	L24_A0
L25	R30	_	_	TX_DAT_OUT_12_N	L24_A0	L24_A0
NC	P33	_	_	VDD33	_	_
L23	P32	_	_	TX_DAT_OUT_13_N	L25_A0	L25_A0
L24	N33	_	_	TX_DAT_OUT_13_P	L25_A0	L25_A0
K25	P31	_	_	TX_CLK_OUT_2_N	L26_D0	L26_A0
J26	P30	_	_	TX_CLK_OUT_2_P	L26_D0	L26_A0
J25	N32	_	_	TX_DAT_OUT_20_P	L27_D0	L27_A0
K24	N31	_	_	TX_DAT_OUT_20_N	L27_D0	L27_A0
NC	PLANE	_	_	VDD15	_	_
K26	N30	_	_	VDD33	_	_
H26	M33	_	_	TX_DAT_OUT_21_P	L28_A0	L28_A0
G26	M32	_	_	TX_DAT_OUT_21_N	L28_A0	L28_A0
K23	M31	_	_	TX_DAT_OUT_22_P	L29_A0	L29_A0
J23	M30	_	_	TX_DAT_OUT_22_N	L29_A0	L29_A0
NC	L33	_	_	VDD33	_	_
NC	PLANE	_	_	VDD15	_	_
J24	L32	_	_	TX_DAT_OUT_23_P	L30_D0	L30_A0
H25	K32	_	_	TX_DAT_OUT_23_N	L30_D0	L30_A0
G25	L31	_	_	TX_CLK_OUT_3_N	L31_D0	L31_A0
H24	L30	_	_	TX_CLK_OUT_3_P	L31_D0	L31_A0
F26	K31	_	_	TX_DAT_OUT_30_N	L32_A0	L32_A0
E26	J31	_	_	TX_DAT_OUT_30_P	L32_A0	L32_A0
NC	K30	_	_	VDD33	_	_
H23	J32	_	_	TX_DAT_OUT_31_N	L33_D0	L33_A0
G24	H33			TX_DAT_OUT_31_P	L33_D0	L33_A0
G23	H32		_	VDD33	_	_
F25	H31		_	TX_CLK_IN_P	L34_A0	L34_A0
E25	J30	_	_	TX_CLK_IN_N	L34_A0	L34_A0
F24	G32		_	LVCTAP_6	_	_
D26	G31		_	TX_DAT_OUT_32_P	L35_A0	L35_A0
D25	F32		_	TX_DAT_OUT_32_N	L35_A0	L35_A0
NC	H30		_	VDD33	_	_

Table 19. PBGA Pinout Table (continued)

416 BGA Ball	680 BGA Ball	V <sub>DDIO</sub> Bank	V <sub>REF</sub> Group	ORLI10G Pin Description	416 BGA Pair	680 BGA Pair
C25	E33	_	_	TX_DAT_OUT_33_P	L36_D0	L36_A0
D24	E32	_	_	TX_DAT_OUT_33_N	L36_D0	L36_A0
F23	F31	_	_	TX_CLK_OUT_4_P	L37_D0	L37_A0
E24	E31	_	_	TX_CLK_OUT_4_N	L37_D0	L37_A0
NC	G30	_	_	VDD33	_	_
NC	PLANE	_	_	VDD15	_	_
C26	F30	_	_	VDD33	_	_
B25	E30	_	_	VssA_6	_	_
E23	B32	_	_	VDD33	_	_
C24	C31	_	_	VDD33A_6	_	_
D23	E29	_	_	VDD33A_7	_	_
NC	PLANE	_	_	VDD15	_	_
B24	E28	_	_	VssA_7	_	_
D22	A32	_	_	TX_DAT_OUT_40_N	L38_D0	L38_A0
C23	B31	_	_	TX_DAT_OUT_40_P	L38_D0	L38_A0
A24	E27		_	TX_DAT_OUT_41_N	L39_D0	L39_A0
B23	E26	_	_	TX_DAT_OUT_41_P	L39_D0	L39_A0
D21	D29	_	_	TX_DAT_OUT_42_N	L40_A0	L40_A0
NC	PLANE	_	_	VDD15	_	_
C22	B30	_	_	VDD33	_	_
C21	C29	_	_	TX_DAT_OUT_42_P	L40_A0	L40_A0
A23	C28	_	_	TX_DAT_OUT_43_N	L41_D0	L41_A0
B22	D27	_	_	TX_DAT_OUT_43_P	L41_D0	L41_A0
A22	A30	_	_	PWRDN	_	_
B21	E25	_	_	RESET_RX	_	_
D20	B29	_	_	RESET_TX	_	_
D19	A29	_	_	PLL_BYPASS	_	_
NC	C27	VDDIO1_TC	9	PT32D	_	_
C20	D26	VDDIO1_TC	9	PT32C	_	_
B20	B28	VDDIO1_TC	1	PT31D	L1C_D0	L1C_A0
C19	A28	VDDIO1_TC	1	PT31C/VREF_TC_10	L1T_D0	L1T_A0
NC	PLANE	_	_	VDD15	_	_
NC	B27	VDDIO1_TC	1	PT30D	_	_
NC	C26	VDDIO1_TC	1	PT30A	_	_
A21	B26	VDDIO1_TC	1	PT29D	L2C_A0	L2C_A0
A20	A27	VDDIO1_TC	1	PT29C	L2T_A0	L2T_A0
L13	PLANE	_	_	VDD15	_	_
NC	D25	VDDIO1_TC	1	PT29A	_	L3T_A0
NC	E24	VDDIO1_TC	1	PT29B	_	L3C_A0

Table 19. PBGA Pinout Table (continued)

416 BGA Ball	680 BGA Ball	V <sub>DDIO</sub> Bank	V <sub>REF</sub> Group	ORLI10G Pin Description	416 BGA Pair	680 BGA Pair
B19	D24	VDDIO1_TC	1	PT28D	L3C_D0	L4C_A0
C18	C25	VDDIO1_TC	1	PT28C	L3T_D0	L4T_A0
NC	A26	VDDIO1_TC	1	PT28A	_	L5T_A0
NC	B25	VDDIO1_TC	1	PT28B	_	L5C_A0
D18	E23	VDDIO1_TC	1	PT27D/VREF_TC_01	L4C_A0	L6C_A0
D17	D23	VDDIO1_TC	1	PT27C	L4T_A0	L6T_A0
B18	C24	VDDIO1_TC	1	PT27B	L5C_D0	L7C_D1
C17	A25	VDDIO1_TC	1	PT27A	L5T_D0	L7T_D1
A18	E22	VDDIO1_TC	2	PT26D	L6C_D0	L8C_A0
B17	E21	VDDIO1_TC	2	PT26C/VREF_TC_02	L6T_D0	L8T_A0
NC	B24	VDDIO1_TC	2	PT26B	_	L9C_D1
NC	D22	VDDIO1_TC	2	PT26A	_	L9T_D1
A17	B23	VDDIO1_TC	2	PT25D	L7C_D0	L10C_A0
B16	A23	VDDIO1_TC	2	PT25C	L7T_D0	L10T_A0
D16	D21	VDDIO1_TC	3	PT24D	L8C_A0	L11C_D1
C16	B22	VDDIO1_TC	3	PT24C/VREF_TC_03	L8T_A0	L11T_D1
NC	A22	VDDIO1_TC	3	PT24A	_	
A16	D20	VDDIO1_TC	3	PT23D	L9C_A0	L12C_A0
A15	E20	VDDIO1_TC	3	PT23C	L9T_A0	L12T_A0
NC	C21	VDDIO1_TC	3	PT23A	_	_
NC	B21	VDDIO1_TC	3	PT22D	_	L13C_A0
NC	A21	VDDIO1_TC	3	PT22C	_	L13T_A0
NC	B20	VDDIO1_TC	3	PT22A	_	_
C15	C19	VDDIO1_TC	4	PT21D	L10C_A0	L14C_D1
C14	A20	VDDIO1_TC	4	PT21C	L10T_A0	L14T_D1
L14	PLANE	_	_	VDD15	_	_
NC	D19	VDDIO1_TC	4	PT20D	_	L15C_A0
NC	E19	VDDIO1_TC	4	PT20C	_	L15T_A0
B14	B19	VDDIO1_TC	4	PT19D	L11C_A0	L16C_A0
A14	B18	VDDIO1_TC	4	PT19C/VREF_TC_04	L11T_A0	L16T_A0
NC	E18	VDDIO1_TC	4	PT19A	_	L17T_A0
NC	D18	VDDIO1_TC	4	PT19B	_	L17C_A0
D13	B17	VDDIO1_TC	5	PT18D/PTCK1C	L12C_A0	L18C_A0
C13	C17	VDDIO1_TC	5	PT18C/PTCK1T	L12T_A0	L18T_A0
NC	C18	VDDIO1_TC	5	PT18A	_	L19T_A0
NC	D17	VDDIO1_TC	5	PT18B	_	L19C_A0
B13	A16	VDDIO1_TC	5	PT17D/PTCK0C	L13C_A0	L20C_A0
A13	B16	VDDIO1_TC	5	PT17C/PTCK0T	L13T_A0	L20T_A0
NC	E17	VDDIO1_TC	5	PT17A	_	

Table 19. PBGA Pinout Table (continued)

416 BGA Ball	680 BGA Ball	V <sub>DDIO</sub> Bank	V <sub>REF</sub> Group	ORLI10G Pin Description	416 BGA Pair	680 BGA Pair
A12	C16	VDDIO1_TC	5	PT16D/VREF_TC_05	L14C_A0	L21C_A0
B12	D16	VDDIO1_TC	5	PT16C	L14T_A0	L21T_A0
NC	A15	VDDIO1_TC	5	PT16A	_	_
C12	B15	VDDIO1_TC	6	PT15D	L15C_A0	L22C_A1
D12	D15	VDDIO1_TC	6	PT15C	L15T_A0	L22T_A1
NC	A14	VDDIO1_TC	6	PT15A	_	_
B11	E16	VDDIO1_TC	6	PT14D	L16C_A0	L23C_D1
A11	C14	VDDIO1_TC	6	PT14C/VREF_TC_06	L16T_A0	L23T_D1
NC	B14	VDDIO1_TC	6	PT14A	_	_
D11	E15	VDDIO0_TL	1	PT13D/MPI_RTRY	L1C_A0	L1C_A0
C11	D14	VDDIO0_TL	1	PT13C/MPI_ACK	L1T_A0	L1T_A0
NC	A13	VDDIO0_TL	1	PT13B	_	L2C_A0
C10	B13	VDDIO0_TL	1	PT13A/VREF_TL_01	_	L2T_A0
B10	A12	VDDIO0_TL	1	PT12D/M0	L2C_D0	L3C_A0
A9	B12	VDDIO0_TL	1	PT12C/M1	L2T_D0	L3T_A0
B9	D13	VDDIO0_TL	2	PT12B/MPI_CLK	L3C_A0	L4C_A0
C9	E14	VDDIO0_TL	2	PT12A/A21/MPI_BURST	L3T_A0	L4T_A0
D10	B11	VDDIO0_TL	2	PT11D/M2	L4C_A0	L5C_A0
D9	A10	VDDIO0_TL	2	PT11C/M3	L4T_A0	L5T_A0
A8	E13	VDDIO0_TL	2	PT11B/VREF_TL_02	L5C_A0	L6C_A0
B8	D12	VDDIO0_TL	2	PT11A/MPI_TEA	L5T_A0	L6T_A0
NC	C11	VDDIO0_TL	3	PT10D	_	L7C_A0
NC	B10	VDDIO0_TL	3	PT10C	_	L7T_A0
NC	A9	VDDIO0_TL	3	PT10A	_	_
K13	PLANE	_	_	VDD15	_	_
A7	D11	VDDIO0_TL	3	PT9D/VREF_TL_03	L6C_A0	L8C_D1
A6	В9	VDDIO0_TL	3	PT9C	L6T_A0	L8T_D1
NC	A8	VDDIO0_TL	3	PT9A	_	_
C8	E12	VDDIO0_TL	3	PT8D/D0/DIN	L7C_D0	L9C_D1
B7	C10	VDDIO0_TL	3	PT8C/TMS	L7T_D0	L9T_D1
C7	D10	VDDIO0_TL	4	PT7D/A20/MPI_BDIP	L8C_D0	L10C_A0
B6	C9	VDDIO0_TL	4	PT7C/A19/MPI_TSZ1	L8T_D0	L10T_A0
D7	E11	VDDIO0_TL	4	PT6D/A18/MPI_TSZ0	L9C_A0	L11C_D1
D8	D9	VDDIO0_TL	4	PT6C/D3	L9T_A0	L11T_D1
NC	A7	VDDIO0_TL	4	PT6B/VREF_TL_04	_	L12C_A0
NC	B8	VDDIO0_TL	4	PT6A		L12T_A0
C6	E10	VDDIO0_TL	5	PT5D/D1	L10C_D0	L13C_D1
B5	C8	VDDIO0_TL	5	PT5C/D2	L10T_D0	L13T_D1
NC	B7	VDDIO0_TL	5	PT5B	_	L14C_A0

Table 19. PBGA Pinout Table (continued)

416 BGA Ball	680 BGA Ball	V <sub>DDIO</sub> Bank	VREF Group	ORLI10G Pin Description	416 BGA Pair	680 BGA Pair
NC	A6	VDDIO0_TL	5	PT5A/VREF_TL_05	_	L14T_A0
A4	D8	VDDIO0_TL	5	PT4D/TDI	L11C_D1	L15C_D1
NC	C7	VDDIO0_TL	5	PT4B	_	L16C_D1
C5	В6	VDDIO0_TL	5	PT4C/TCK	L11T_D1	L15T_D1
NC	A5	VDDIO0_TL	5	PT4A	_	L16T_D1
В3	C6	VDDIO0_TL	6	PT3D	L12C_A0	L17C_A0
NC	E9	VDDIO0_TL	6	PT3B	_	L18C_D1
А3	B5	VDDIO0_TL	6	PT3C/VREF_TL_06	L12T_A0	L17T_A0
NC	D7	VDDIO0_TL	6	PT3A	_	L18T_D1
D5	C5	VDDIO0_TL	6	PT2D/PLL_CK1C	L13C_A0	L19C_A0
D6	D6	VDDIO0_TL	6	PT2C/PLL_CK1T	L13T_A0	L19T_A0
NC	E8	VDDIO0_TL	6	PT2B	_	L20C_A0
NC	E7	VDDIO0_TL	6	PT2A	_	L20T_A0
B4	A4	VDDIO0_TL	_	PCFG_MPI_IRQ/CFG_IRQ/MPI_IRQ	_	_
B2	B4	_	_	PCCLK	_	
K14	PLANE	_	_	V <sub>DD</sub> 15	_	
C4	E6	_	_	PDONE	_	_
C3	D5	_	_	V <sub>DD</sub> 33	_	_
M14	A31	_	_	V <sub>DD</sub> 15	_	
N10	C30	_	_	V <sub>DD</sub> 15	_	
N11	C33	_	_	V <sub>DD</sub> 15	_	
N12	C34	_	_	V <sub>DD</sub> 15	_	_
N15	D28	_	_	V <sub>DD</sub> 15	_	_
N16	D32	_	_	V <sub>DD</sub> 15	_	_
N17	D34	_	_	V <sub>DD</sub> 15	_	_
P10	F34	_	_	V <sub>DD</sub> 15	_	_
P11	G33	_	_	V <sub>DD</sub> 15	_	_
P12	G34	_	_	V <sub>DD</sub> 15	_	_
M13	J34	_	_	V <sub>DD</sub> 15	_	_
P15	K33	_	_	V <sub>DD</sub> 15	_	_
NC	K34		_	V <sub>DD</sub> 15	_	
NC	M34			V <sub>DD</sub> 15	_	
NC	N16		_	V <sub>DD</sub> 15	_	
NC	N17			V <sub>DD</sub> 15	_	
P17	N18		_	V <sub>DD</sub> 15	_	
AF1	N19		_	V <sub>DD</sub> 15	_	
NC	N34		_	V <sub>DD</sub> 15	_	
NC	P16		_	V <sub>DD</sub> 15	_	_
NC	P17		_	V <sub>DD</sub> 15	_	

Table 19. PBGA Pinout Table (continued)

416 BGA Ball	680 BGA Ball	V <sub>DDIO</sub> Bank	V <sub>REF</sub> Group	ORLI10G Pin Description	416 BGA Pair	680 BGA Pair
NC	P18	_	_	VDD15	_	_
NC	P19	_	_	VDD15	_	_
NC	R16	_	_	VDD15	_	_
NC	R17	_	_	VDD15	_	_
NC	R18	_	_	VDD15	_	_
NC	R19	_	_	VDD15	_	_
NC	R34	_	_	VDD15	_	_
NC	T13	_	_	VDD15	_	_
NC	T14	_	_	VDD15	_	_
NC	T15	_	_	VDD15	_	_
NC	T20	_	_	VDD15	_	_
NC	T21	_	_	VDD15	_	_
NC	T22	_	_	VDD15	_	_
NC	T34	_	_	VDD15	_	_
NC	U13	_	_	VDD15	_	_
NC	U14	_	_	VDD15	_	_
NC	U15	_	_	VDD15	_	_
NC	U20	_	_	VDD15	_	_
NC	U21	_	_	VDD15	_	_
NC	U22	_	_	VDD15	_	_
NC	V13	_	_	VDD15	_	_
NC	V14	_	_	VDD15	_	_
NC	V15	_	_	VDD15	_	1
NC	V20	_	_	VDD15	_	1
NC	V21	_	_	VDD15	_	
NC	V22	_	_	VDD15	_	
NC	V34	_	_	VDD15	_	
NC	W13	_		VDD15	_	_
NC	W14	_	_	VDD15	_	_
NC	W15	_		VDD15	_	_
NC	W20	_		VDD15	_	_
NC	W21	_	_	VDD15	_	_
NC	W22	_	_	VDD15	_	_
NC	W34	_	_	VDD15		_
NC	Y16	_		VDD15	_	_
NC	Y17	_	_	VDD15	_	_
NC	Y18	_	_	VDD15	_	_
NC	Y19	_		VDD15	_	_
NC	AA16	_	_	VDD15	_	_

Table 19. PBGA Pinout Table (continued)

416 BGA Ball	680 BGA Ball	V <sub>DDIO</sub> Bank	V <sub>REF</sub> Group	ORLI10G Pin Description	416 BGA Pair	680 BGA Pair
NC	AA17	_	_	VDD15	_	_
NC	AA18	_	_	VDD15	_	_
NC	AA19	_	_	VDD15	_	_
NC	AA34	_	_	VDD15	_	_
NC	AB16	_	_	VDD15	_	_
NC	AB17	_	_	VDD15	_	_
NC	AB18		_	VDD15	_	_
NC	AB19	_	_	VDD15	_	_
NC	AB34	_	_	VDD15	_	_
NC	AD33	_	_	VDD15	_	_
NC	AD34	_	_	VDD15	_	_
NC	AE34	_	_	VDD15	_	_
NC	AG33	_	_	VDD15	_	_
NC	AG34	_	_	VDD15	_	_
NC	AH34	_	_	VDD15	_	_
NC	AK29	_	_	VDD15	_	_
NC	AL32	_	_	VDD15	_	_
NC	AL33	_	_	VDD15	_	_
NC	AL34	_	_	VDD15	_	_
NC	AM31	_	_	VDD15	_	_
NC	AM33	_	_	VDD15	_	_
NC	AM34	_	_	VDD15	_	_
NC	AN32	_	_	VDD15	_	
NC	AP31	_	_	VDD15	_	
A2	A1	_	_	Vss	_	
A25	A18	_	_	Vss	_	
B1	A33	_	_	Vss	_	_
NC	A34	_	_	Vss	_	_
NC	B2	_	_	Vss	_	
NC	B33	_	_	Vss	_	_
U16	B34	_	-	Vss	_	_
U17	C3	_	_	Vss	_	_
AE1	C13	_	_	Vss	_	_
AE26	C22	_	-	Vss	_	_
AF2	C32	_	_	Vss	_	_
AF25	D4	_	_	Vss	_	_
NC	D30	_	-	Vss	_	_
NC	D31	_	_	Vss	_	_
NC	D33	_	_	Vss	_	_

Table 19. PBGA Pinout Table (continued)

416 BGA Ball	680 BGA Ball	V <sub>DDIO</sub> Bank	V <sub>REF</sub> Group	ORLI10G Pin Description	416 BGA Pair	680 BGA Pair
NC	E34	_	_	Vss	_	_
T16	F33	_	_	Vss	_	_
T17	H34	_	_	Vss	_	_
U10	J33	_	_	Vss	_	_
U11	L34	_	_	Vss	_	_
U12	N13	_		Vss	_	_
U15	N14	_	_	Vss	_	_
NC	N15	_		Vss	_	_
NC	N20	_		Vss	_	_
NC	N21	_		Vss	_	_
NC	N22	_		Vss	_	_
NC	P13	_		Vss	_	_
NC	P14	_	_	Vss	_	_
NC	P15	_	_	Vss	_	_
R16	P20	_	_	Vss	_	_
R17	P21	_	_	Vss	_	_
T10	P22	_	_	Vss	_	_
T11	P34	_	_	Vss	_	_
T12	R13	_		Vss	_	_
T15	R14	_		Vss	_	_
NC	R15	_		Vss	_	_
NC	R20	_	_	Vss	_	_
NC	R21	_	_	Vss	_	_
NC	R22	_	_	Vss	_	_
NC	T16	_	_	Vss	_	_
NC	T17	_	_	Vss	_	_
K12	T18	_	_	Vss	_	_
K15	T19		_	Vss	_	
K16	U16	_	_	Vss	_	
K17	U17	_	_	Vss	_	
L10	U18	_	_	Vss	_	
L11	U19	_	_	Vss	_	
NC	U34	_	_	Vss	_	_
NC	V16	_	_	Vss	_	
NC	V17	_	_	Vss	_	_
NC	V18		_	Vss		
NC	V19	_	_	Vss	_	_
NC	W16	_	_	Vss	_	
NC	W17	_	_	Vss	_	_

Table 19. PBGA Pinout Table (continued)

416 BGA Ball	680 BGA Ball	V <sub>DDIO</sub> Bank	VREF Group	ORLI10G Pin Description	416 BGA Pair	680 BGA Pair
NC	W18	_	_	Vss	_	_
NC	W19	_	_	Vss	_	_
NC	Y13	_	_	Vss	_	_
NC	Y14	_	_	Vss	_	_
B26	Y15	_	_	Vss	_	_
K10	Y20	_	_	Vss	_	_
K11	Y21	_	_	Vss	_	_
NC	Y22	_	_	Vss	_	_
L12	Y34	_	_	Vss	_	_
L15	AA13	_	_	Vss	_	_
L16	AA14	_	_	Vss	_	_
L17	AA15	_	_	Vss	_	_
M10	AA20	_	_	Vss	_	_
M11	AA21	_	_	Vss	_	_
M12	AA22	_	_	Vss	_	_
M15	AB13	_	_	Vss	_	_
M16	AB14	_	_	Vss	_	_
M17	AB15	_	_	Vss	_	_
N13	AB20	_	_	Vss	_	_
N14	AB21	_	_	Vss	_	_
P13	AB22	_	_	Vss	_	_
P14	AC34	_	_	Vss	_	_
R10	AE33	_	_	Vss	_	
R11	AF34	_	_	Vss	_	
R12	AH33	_	_	Vss	_	_
R15	AJ34	_	_	Vss	_	
NC	AL2	_	_	Vss	_	
NC	AL4	_	_	Vss	_	
NC	AL30	_	_	Vss	_	
NC	AL31	_		Vss	_	_
NC	AM3	_	_	Vss	_	_
NC	AM13	_		Vss	_	_
NC	AM22	_		Vss	_	_
NC	AM32	_	_	Vss	_	_
NC	AN2	_		Vss	_	_
NC	AN33	_		Vss	_	_
NC	AN34	_		Vss	_	_
NC	AP1	_		Vss	_	_
NC	AP4			Vss	_	_

Table 19. PBGA Pinout Table (continued)

416 BGA Ball	680 BGA Ball	V <sub>DDIO</sub> Bank	V <sub>REF</sub> Group	ORLI10G Pin Description	416 BGA Pair	680 BGA Pair
NC	AP33	_	_	Vss	_	_
NC	AP34	_	_	Vss	_	_
C2	A2	VDDIO0_TL	_	VDDIO0_TL	_	_
NC	А3	VDDIO0_TL	_	VDDIO0_TL	_	_
NC	B1	VDDIO0_TL	_	VDDIO0_TL	_	_
G3	В3	VDDIO0_TL		VDDIO0_TL	_	_
NC	C2	VDDIO0_TL		VDDIO0_TL	_	_
A10	C4	VDDIO0_TL		VDDIO0_TL	_	_
NC	D2	VDDIO0_TL		VDDIO0_TL	_	_
NC	D3	VDDIO0_TL		VDDIO0_TL	_	_
A5	E1	VDDIO0_TL		VDDIO0_TL	_	_
NC	E3	VDDIO0_TL		VDDIO0_TL	_	_
NC	A11	VDDIO1_TC	_	VDDIO1_TC	_	_
NC	A17	VDDIO1_TC	_	VDDIO1_TC	_	_
NC	A19	VDDIO1_TC	_	VDDIO1_TC	_	
A19	A24	VDDIO1_TC	_	VDDIO1_TC	_	
D15	C12	VDDIO1_TC	_	VDDIO1_TC	_	
B15	C15	VDDIO1_TC	_	VDDIO1_TC	_	
D14	C20	VDDIO1_TC	_	VDDIO1_TC	_	
NC	C23	VDDIO1_TC	_	VDDIO1_TC	_	
AF14	AM12	VDDIO5_BC	_	VDDIO5_BC	_	_
AF16	AM15	VDDIO5_BC	_	VDDIO5_BC	_	_
AF17	AM20	VDDIO5_BC	_	VDDIO5_BC	_	
AD17	AM23	VDDIO5_BC	_	VDDIO5_BC	_	_
NC	AP11	VDDIO5_BC	_	VDDIO5_BC	_	_
AD20	AP17	VDDIO5_BC	_	VDDIO5_BC	_	_
NC	AP19	VDDIO5_BC	_	VDDIO5_BC	_	_
NC	AP24	VDDIO5_BC		VDDIO5_BC	_	_
NC	AK4	VDDIO6_BL		VDDIO6_BL	_	_
AB1	AK5	VDDIO6_BL	_	VDDIO6_BL	_	_
NC	AL1	VDDIO6_BL		VDDIO6_BL	_	_
NC	AL3	VDDIO6_BL	_	Vddio6_BL	_	_
AD2	AM1	VDDIO6_BL	_	Vddio6_BL	_	_
NC	AM2	VDDIO6_BL	_	VDDIO6_BL	_	_
NC	AM4	VDDIO6_BL	_	VDDIO6_BL	_	_
AF5	AN3	VDDIO6_BL	_	VDDIO6_BL	_	_
AF9	AP2	VDDIO6_BL	_	VDDIO6_BL	_	_
NC	AP3	VDDIO6_BL	_	VDDIO6_BL	_	_
K1	L1	VDDIO7_CL	_	VDDIO7_CL	_	_

Table 19. PBGA Pinout Table (continued)

416 BGA Ball	680 BGA Ball	V <sub>DDIO</sub> Bank	V <sub>REF</sub> Group	ORLI10G Pin Description	416 BGA Pair	680 BGA Pair
L2	М3	VDDIO7_CL	_	VDDIO7_CL	_	_
NC	R3	VDDIO7_CL	_	VDDIO7_CL	_	_
P2	U1	VDDIO7_CL	_	VDDIO7_CL	_	_
NC	W1	VDDIO7_CL	_	VDDIO7_CL	_	_
T3	Y3	VDDIO7_CL	_	VDDIO7_CL	_	_
NC	AC3	VDDIO7_CL	_	VDDIO7_CL	_	_
NC	AD1	VDDIO7_CL	_	VDDIO7_CL		_

# Package Thermal Characteristics Summary

There are three thermal parameters that are in common use:  $\Theta JA$ ,  $\psi JC$ , and  $\Theta JC$ . It should be noted that all the parameters are affected, to varying degrees, by package design (including paddle size) and choice of materials, the amount of copper in the test board or system board, and system airflow.

#### ΘJΑ

This is the thermal resistance from junction to ambient (theta-JA, R-theta, etc.).

$$\Theta \mathsf{JA} \,=\, \frac{\mathsf{TJ} - \mathsf{TA}}{\mathsf{Q}}$$

where T<sub>J</sub> is the junction temperature, T<sub>A</sub>, is the ambient air temperature, and Q is the chip power.

Experimentally,  $\Theta$ JA is determined when a special thermal test die is assembled into the package of interest, and the part is mounted on the thermal test board. The diodes on the test chip are separately calibrated in an oven. The package/board is placed either in a JEDEC natural convection box or in the wind tunnel, the latter for forced convection measurements. A controlled amount of power (Q) is dissipated in the test chip's heater resistor, the chip's temperature (TJ) is determined by the forward drop on the diodes, and the ambient temperature (TA) is noted. Note that  $\Theta$ JA is expressed in units of  $^{\circ}$ C/watt.

#### ΨJC

This JEDEC designated parameter correlates the junction temperature to the case temperature. It is generally used to infer the junction temperature while the device is operating in the system. It is not considered a true thermal resistance, and it is defined by:

$$\Psi JC \; = \; \frac{TJ - TC}{Q}$$

where Tc is the case temperature at top dead center, TJ is the junction temperature, and Q is the chip power. During the ΘJA measurements described above, besides the other parameters measured, an additional temperature reading, Tc, is made with a thermocouple attached at top-dead-center of the case. ΨJC is also expressed in units of °C/W.

#### ΘJC

This is the thermal resistance from junction to case. It is most often used when attaching a heat sink to the top of the package. It is defined by:

$$\Theta JC = \frac{TJ - TC}{Q}$$

The parameters in this equation have been defined above. However, the measurements are performed with the case of the part pressed against a water-cooled heat sink to draw most of the heat generated by the chip out the top of the package. It is this difference in the measurement process that differentiates  $\Theta$ JC from  $\Psi$ JC.  $\Theta$ JC is a true thermal resistance and is expressed in units of  $^{\circ}$ C/W.

#### ΘJB

This is the thermal resistance from junction to board  $(\Theta J L)$ . It is defined by:

$$\Theta JB = \frac{TJ - TB}{Q}$$

where TB is the temperature of the board adjacent to a lead measured with a thermocouple. The other parameters on the righthand side have been defined above. This is considered a true thermal resistance, and the measurement is made with a water-cooled heat sink pressed against the board to draw most of the heat out of the leads. Note that  $\Theta JB$  is expressed in units of  $^{\circ}C/W$ , and that this parameter and the way it is measured are still in JEDEC committee.

#### **FPSC Maximum Junction Temperature**

Once the power dissipated by the FPSC has been determined (see the Estimating Power Dissipation section), the maximum junction temperature of the FPSC can be found. This is needed to determine if speed derating of the device from the 85 °C junction temperature used in all of the delay tables is needed. Using the maximum ambient temperature, TAmax, and the power dissipated by the device, Q (expressed in °C), the maximum junction temperature is approximated by:

$$TJmax = TAmax + (Q \cdot \Theta JA)$$

Table 20 lists the thermal characteristics for all packages used with the *ORCA* ORLI10G FPSC.

### **Package Thermal Characteristics**

Table 20. ORCA ORLI10G Plastic Package Thermal Guidelines

	ΘJA (°C/W)			Max Power
Package	0 fpm	200 fpm	500 fpm	T = 70 °C Max T <sub>J</sub> = 125 °C Max 0 fpm (W)
416-Pin PBGAM	19.5	16.5	13.5	2.8
680-Pin PBGAM	15.5	12.5	11.5	3.5

### **Heat Sink Vendors for BGA Packages**

The estimated worst-case power requirements for the ORLI10G with a programmable XGMII to XSBI interface for 10 Gbits/s Ethernet applications is 4.0 W. Consequently, for most applications an external heat sink will be required. Below, in alphabetical order, is a list of heat sink vendors who advertise heat sinks aimed at the BGA market.

**Table 21. Heat Sink Vendors** 

Vendor	Location	Phone
Aavid Thermal Technology	Laconia, NH	(603) 527-2152
Chip Coolers	Warwick, RI	(800) 227-0254
IERC	Burbank, CA	(818) 842-7277
R-Theta	Buffalo, NY	(800) 388-5428
Sanyo Denki	Torrance, CA	(310) 783-5400
Thermalloy	Dallas, TX	(214) 243-4321
Wafefield Engineering	Wakefield, MA	(617) 246-0874

### **Package Coplanarity**

The coplanarity limits of the Lucent packages are as follows:

■ PBGAM: 8.0 mils

### **Package Parasitics**

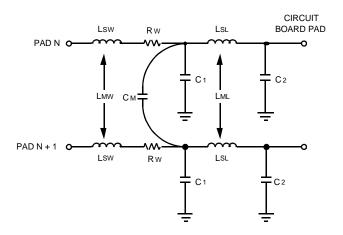
The electrical performance of an IC package, such as signal quality and noise sensitivity, is directly affected by the package parasitics. Table 22 lists eight parasitics associated with the *ORCA* packages. These parasitics represent the contributions of all components of a package, which include the bond wires, all internal package routing, and the external leads.

Four inductances in nH are listed: LSW and LSL, the self-inductance of the lead; and LMW and LML, the mutual inductance to the nearest neighbor lead. These parameters are important in determining ground bounce noise and inductive crosstalk noise. Three capacitances in pF are listed: CM, the mutual capacitance of the lead to the nearest neighbor lead; and C1 and C2, the total capacitance of the lead to all other leads (all other leads are assumed to be grounded). These parameters are important in determining capacitive crosstalk and the capacitive loading effect of the lead. Resistance values are in  $m\Omega$ .

The parasitic values in Table 22 are for the circuit model of bond wire and package lead parasitics. If the mutual capacitance value is not used in the designer's model, then the value listed as mutual capacitance should be added to each of the C<sub>1</sub> and C<sub>2</sub> capacitors.

Table 22. ORCA ORLI10G Package Parasitics

Package Type	Lsw	Lmw	Rw	C <sub>1</sub>	C <sub>2</sub>	См	LsL	LML
416-Pin PBGAM	TBD	TBD	TBD	TBD	TBD	TBD	TBD	TBD
680-Pin PBGAM	3.8	1.3	250	1.0	1.0	0.3	2.8—5	0.5—1



5-3862(C)r2

Figure 27. Package Parasitics

### **Package Outline Diagrams**

#### **Terms and Definitions**

Basic Size (BSC): The basic size of a dimension is the size from which the limits for that dimension are derived by the application of the allowance and the tolerance.

Design Size: The design size of a dimension is the actual size of the design, including an allowance for fit and tolerance.

Typical (TYP): When specified after a dimension, this indicates the repeated design size if a tolerance is specified or repeated basic size if a tolerance is not specified.

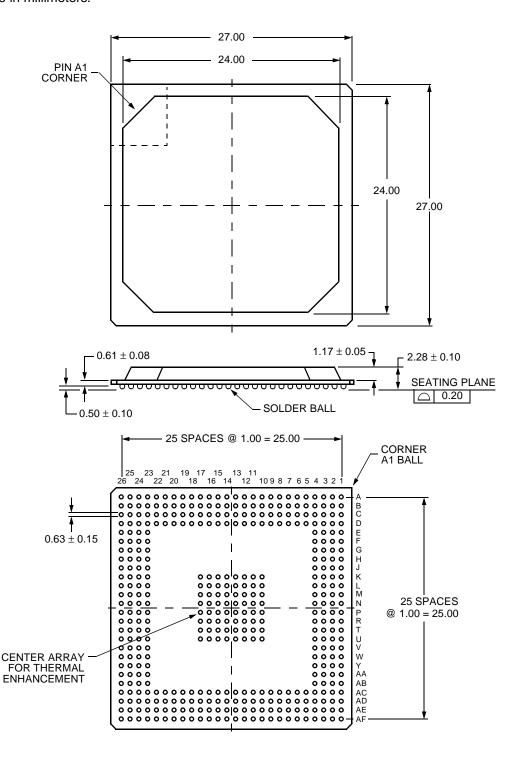
Reference (REF): The reference dimension is an untoleranced dimension used for informational purposes only. It is a repeated dimension or one that can be derived from other values in the drawing.

Minimum (MIN) or Maximum (MAX): Indicates the minimum or maximum allowable size of a dimension.

### Package Outline Diagrams (continued)

#### 416-Pin PBGAM

Dimensions are in millimeters.

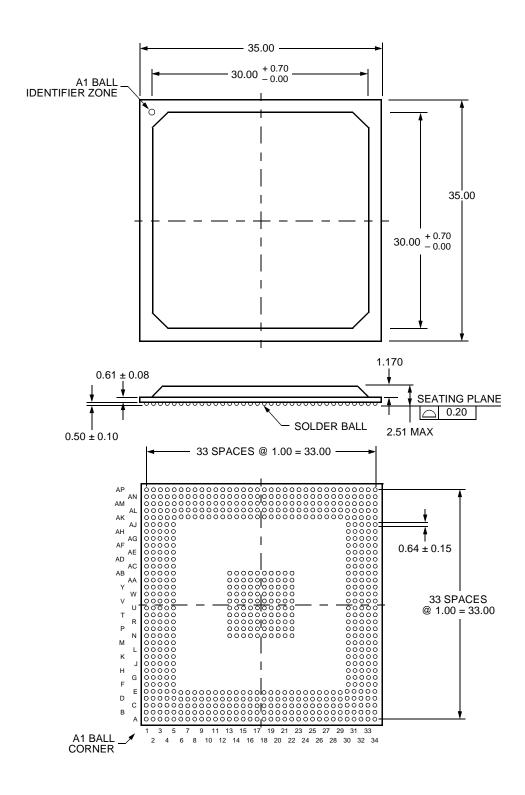


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### Package Outline Diagrams (continued)

#### 680-Pin PBGAM

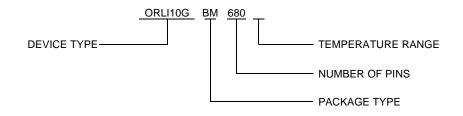
Dimensions are in millimeters.



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5-6435(F).o

### **Hardware Ordering Information**



**Table 23. Device Type Options** 

Device	Parameter	Value
ORLI10G	Voltage	1.5 V core
		3.3 V/2.5 V I/O
	Package	416-pin PBGAM (BM416)
		680-pin PBGAM (BM680)

**Table 24. Temperature Options** 

Symbol	Description	Temperature
(Blank)	Commercial	0 °C to 70 °C
I	Industrial	-40 °C to +85 °C

**Table 25. Package Type Options** 

Symbol	Description
BM	Plastic Ball Grid Array, Multilayer

Table 26. ORCA FPSC Package Matrix (Speed Grades)

	Package		
Device	416-Pin PBGAM	680-Pin PBGAM	
	BM416	BM680	
ORLI10G	-1	-1	

### **Software Ordering Information**

Implementing a design in an ORLI10G requires the *ORCA* Foundry Development System and an ORLI10G FPSC Desgin Kit. For ordering information, please visit:

http://www.lucent.com/micro/netcom/ipkits/orli10g/

For additional information, contact your Agere Systems Account Manager or the following:

INTERNET: http://www.agere.com

E-MAIL: docmaster@micro.lucent.com

N. AMERICA: Agere Systems Inc., 555 Union Boulevard, Room 30L-15P-BA, Allentown, PA 18109-3286 **1-800-372-2447**, FAX 610-712-4106 (In CANADA: **1-800-553-2448**, FAX 610-712-4106)
ASIA PACIFIC: Agere Systems Singapore Pte. Ltd., 77 Science Park Drive, #03-18 Cintech III, Singapore 118256

Tel. (65) 778 8833, FAX (65) 777 7495

CHINA: Agere Systems (Shanghai) Co., Ltd., 33/F Jin Mao Tower, 88 Century Boulevard Pudong, Shanghai 200121 PRC

Tel. (86) 21 50471212, FAX (86) 21 50472266

Agere Systems Japan Ltd., 7-18, Higashi-Gotanda 2-chome, Shinagawa-ku, Tokyo 141, Japan JAPAN:

Tel. (81) 3 5421 1600, FAX (81) 3 5421 1700

Data Requests: DATALINE: Tel. (44) 7000 582 368, FAX (44) 1189 328 148 EUROPE:

Technical Inquiries: GERMANY: (49) 89 95086 0 (Munich), UNITED KINGDOM: (44) 1344 865 900 (Ascot), FRANCE: (33) 1 40 83 68 00 (Paris), SWEDEN: (46) 8 594 607 00 (Stockholm), FINLAND: (358) 9 3507670 (Helsinki),

ITALY: (39) 02 6608131 (Milan), SPAIN: (34) 1 807 1441 (Madrid)

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