

How to Use the NM93C86A Serial EEPROM as a PC/Laptop Detachable Printer File Memory Card (DPFMC)

Fairchild
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INTRODUCTION

This applications note describes how to build a DPFMC. The card will be designed around a COP888CG microcontroller and four NM93C86A serial EEPROMs. The card will be designed to plug into any standard IBM-PC/Laptop parallel port. Once the card has been installed, the user can download any document (text, graphic, or combination) and print out that document at a later time. The DPFMC will be designed to make the computer think a printer is actually connected by simulating the printer's input port. Once all documents have been sent, the user needs to press the SEND-DOC button once to save the pointer address. Next the user can remove the card and turn its power off. The documents contained in the card's EEPROMs can be stored for hours, days, months, or even years if needed. However, hours will probably be a more realistic time frame. When the user is ready to print-out the documents saved, the card can be plugged into a stand along printer by either using the printer's DB-25 cable or (with an appropriate adapter) the printer itself. After switching on the cards power, all the user has to do is press the SEND DOC button and the printer will begin to print out the saved documents.

NM93C86A DESCRIPTION

The NM93C86A is a 16,384-bit CMOS non-volatile serial EEPROM that can be configured to have a 1024 x 16 or a 2048 x 8 architecture. The configuration is determined by the state of the ORG pin. If the ORG pin is tied low the NM93C86A is configured as a 2048-byte-wide memory. If the ORG pin is left floating or tied to V_{CC} , the 1024 word wide configuration is enabled. An internal pull-up resistor to V_{CC} assures that a floating ORG pin is pulled high. Figure 1 shows the NM93C86A pin arrangement.

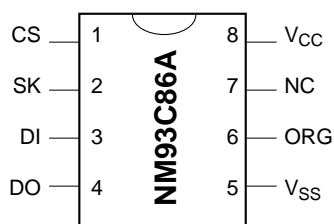
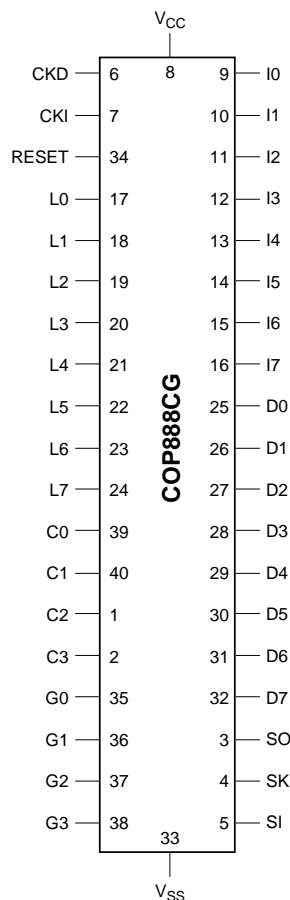


FIGURE 1. NM93C86A Pin Out

The NM93C86A has 7 instructions that can be performed. The instructions are: Read a byte/word (READ), Enable programming (EWEN), Disable programming (EWDS), Erase a byte/word (ERASE), Write a byte/word (WRITE), Erase all bytes/words (ERALL), and write a data pattern to all bytes/words (WALL). The NM93C86A uses the industry standard MICROWIRE™ interface.

COP888CG DESCRIPTION

The COP888CG is an 8-bit microcontroller. Its a fully static CMOS device containing RAM, ROM, and Microwire interface. The microcontroller contains 4,096 bytes of ROM used to store program code and 192 bytes of RAM used to store register data. It contains an 8-bit input, an 8-bit output, and two 8-bit bi-directional ports. The microcontroller also has a Microwire interface which will be used to connect the NM93C86A to it. These attributes make the COP888CG a good choice for this particular application.



The MICROWIRE Interface of the COP888CG uses pins 3(SO),

4(SK), and 5(SI). These pins are connect to the equivalent pins of the EEPROM. The MS-nibble of the D-port is used as chip select outputs to the four EEPROMs. Since the data the DPFMC will be processing is 1-byte length data, the NM93C86A will be configured to deal with 8-bit chunks instead of 16-bit chunks of data.

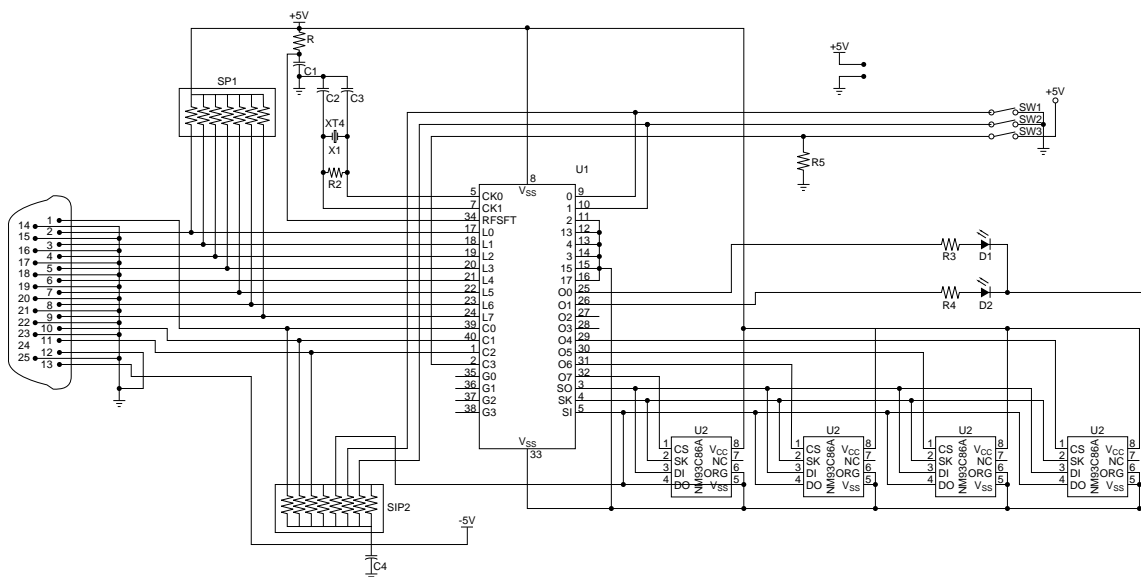


FIGURE 3. DPFMC Schematic

The DPFMC will have three inputs. Two are tied HIGH through 10 k Ω resistors. The third is tied LOW. The first input when LOW (pin 9) will indicate RECEIVE MODE. A LOW on the second input (pin 10) will indicate WRITE MODE. A HIGH on the third input (pin 11) will tell the microcontroller to save the current pointer address and begin sending the document data to the printer.

There are also two LED outputs. LED1 will inform the user that the DPFMC cannot accept any more data. LED1 also informs the user that the pointer address has been saved. If LED1 flashes continuously the DPFMC is out of memory. If LED1 flashes irregularly the DPFMC has saved the pointer address and is ready for power to be removed. LED2 informs the user of the current mode. Two flashes indicate the READ MODE and one flash indicates the WRITE MODE.

SOFTWARE DESCRIPTION

For simplicity and structure the software part of this application will be divided into three parts. The first or main block will monitor the three inputs and decide which mode the DPFMC will enter. The second block will control the interface logic between the computer's parallel port and the DPFMC.

In the case of a read operation, this block of code will start by configuring the STROBE and BUSY pins as inputs and the ACKNLG pin as an output. The routine then waits for the BUSY pin to fall LOW. When the BUSY pin falls low, the routine will begin monitoring the STROBE pin for a 0.5 μ s LOW. When this happens, the routine reads the data port and stores that data into accumulator A. After the data is safely stored into accumulator A, the ACKNLG pin will be pulsed

LOW for 5 μ s to inform the computer that the data was received. Control is now passed to the final routine. This routine takes the data from ACC A stores the data into the EEPROMs. This routine basically will control the memory matrix part of the card. After the data is stored into the EEPROMs, control is passed back to the interface routine and the loop continues.

The write sequence will be just the opposite. The BUSY and STROBE pins are first configured to be outputs and the ACKNLG pin configured to be a input. The routine will then wait for the SEND DOC input to go low. When this happens the BUSY will go LOW to indicate the card is about to send a byte to the printer. The memory matrix routine then stores the first byte of data into accumulator A. After that the interface routine sends that data to the port. The STROBE pin is pulsed LOW for 5 μ s. From this point on the routine monitors the ACKNLG pin for a 5 μ s LOW. When a LOW has occurred the routine loops back to the top, fetches the next byte, and starts a write loop.

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; ASSEMBLY CODE FOe THE DETACHABLE PRINTER FILE MEMORY CARD (DPFMC)
; By Charles Watts
.INCLD COP888CG.INC
.SECT CODE, ROM, ABS=0
;-----INITIALIZE PORT & REGISTER DATA-----
DLYL      = 0F0
DLYH      = 0F1
ADDL      = 0F2
ADDH      = 0F3
BYT       = 00
HLD       = 01
STOLO     = 02
STOHI     = 03
STOHLd    = 04
;
START:    LD     PORTD, #00
          LD     PORTGC, #030
          SBIT   MSEL, CNTRL
          SBIT   SO, CNTRL
          LD     PORTLC, #00
          LD     PORTCC, #0B
          LD     B, #PORTCP
          JSR    LAST
;-----MAIN ROUTINE-----
MAIN:     LD     A, PORTI      ;
          IFEQ   A, #06        ;
          JSR    READ          ;
          IFEQ   A, #05        ;
          JSR    WRITE         ;
          JP     MAIN          ;
;-----SUBROUTINES WILL FOLLOW-----
READ:     LD     PORTLC, #00    ;CONFIGURE PORT
          LD     PORTCC, #06    ;TO READ MODE
          LD     PORTCD, #02    ;
          JSR    FLSH2         ;BLINK LED 2 TIMES
          JSR    EWEN          ;
LP1:       IFBIT 3, [B]         ;
          JSR    SAVE          ;
          IFBIT 0, [B]         ;WAIT FOR STROBE TO GO LOW
          JP     LP1           ;
          LD     PORTCD, #06    ;BRING BUSY HIGH
          LD     A, PORTLP      ;READ PORT AND SAVE IN ACCA
          X      A, BYT        ;
          JSR    PUT           ;STORE ACCA IN NVM
          LD     PORTCD, #04    ;PULSE ACKNLG
          NOP                     ;
          NOP                     ;
          LD     PORTCD, #06    ;
          NOP                     ;
          NOP                     ;
          LD     PORTCD, #02    ;
          JP     LP1           ;
;
WRITE:    LD     PORTLC, #0FF   ;TO CONFIGURE PORT
          LD     PORTCC, #01    ;TO WRITE MODE
          LD     PORTCD, #01    ;
          JSR    FLSH1         ;
LP2:       IFBIT 3, [B]         ;
          JP     LP3           ;

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        JP      LP2                ;
LP3:    IFBIT 2, [B]              ;WAIT FOR BUSY LOW
        JP      LP3                ;
        JSR     GET                ;GET BYTE FROM
        LD      A, BYT            ;
        X       A, PORTLD         ;NVM.
        NOP                     ;
        NOP                     ;
        LD      PORTCD, #00        ;PULSE STORE
        NOP                     ;
        NOP                     ;
        LD      PORTCD, #01        ;
        NOP                     ;
        NOP                     ;
        JP      LP3                ;
;
GET:    LD      A, HLD             ;SET CS HIGH
        X       A, PORTD          ;
        LD      A, ADDH           ;SEND OPCOCE AND
        OR      A, #030           ;HI ADDRESS
        X       A, SIOR           ;
        SBIT    BUSY, PSW         ;
LP4:    IFBIT    BUSY, PSW         ;
        JP      LP4                ;
        LD      A, ADDL           ;SEND LOW ADD
        X       A, SIOR           ;
        SBIT    BUSY, PSW         ;
LP5:    IFBIT    BUSY, PSW         ;
        JP      LP5                ;
        LD      SIOR, #000        ;
        SBIT    BUSY, PSW         ;RECEIVE BYTE
        RBIT    BUSY, PSW         ;
        SBIT    BUSY, PSW         ;
LP6:    IFBIT    BUSY, MPSW        ;
        JP      LP6                ;
        X       A, SIOR           ;
        X       A, BYT           ;
        LD      PORTD, #00        ;
        JSR     COUNT            ;
        LD      A, HLD           ;
        IFEQ    A, STOHL         ;
        JP      SKIP1           ;
        RET      ;
SKIP1:  LD      A, ADDL           ;
        IFEQ    A, STOLO         ;
        JP      SKIP2           ;
        RET      ;
SKIP2:  LD      A, ADDH           ;
        IFEQ    A, STOHI         ;
        JP      ZD               ;
        RET      ;
;
PUT:    LD      A, HLD             ;SET CS HIGH
        X       A, PORTD          ;
        LD      A, ADDH           ;SEND OPPCOCE AND
        OR      A, #028           ;HI ADDRESS
        X       A, SIOR           ;
        SBIT    BUSY, PSW         ;
LP7:    IFBIT    BUSY, PSW         ;
        JP      LP7                ;

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        LD    A, ADDL        ;SEND LOW ADD
        X     A, SIOR        ;
        SBIT  BUSY, PSW      ;
LP8:    IFBIT  BUSY, PSW      ;
        JP    LP8            ;
        LD    A, BYT         ;SEND BYTE
        SBIT  BUSY, PSW      ;
LP9:    IFBIT  BUSY, PSW      ;
        JP    LP9            ;
LP10:   IFBIT  SI, PORTGP     ;
        JP    LP10           ;
LP11:   IFBIT  SI, PORTGP     ;
        JP    LP12           ;
        JP    LP11           ;
LP12:   LD     PORTD, #00     ;
        LP    A, HLD          ;
        X     A, PORTD       ;
        LD     SIOR, #0FF     ;
        SBIT  BUSY, PSW      ;
        RBIT  BUSY, PSW      ;
        LD     PORTD, #00     ;
        JSR   COUNT          ;
        RET                     ;
;
EWEN:   LD     PORTD, #0F0     ;Enable EE
        LD     SIOR, #026     ;
        SBIT  BUSY, PSW      ;
LP13:   IFBIT  BUSY, PSW      ;
        JP    LP13           ;
        LD     BUSY, PSW      ;
        SBIT  BUSY, PSW      ;
LP14:   IFBIT  BUSY, PSW      ;
        JP    LP14           ;
        LD     PORTD, #00     ;
        RET                     ;
;
COUNT: LD     A, ADDL        ;Address Counter
        IFEQ  A, #0FF         ;
        JP    ZA              ;
        INC   A               ;
        X     A, ADDL         ;
        RET                     ;
ZA:     LD     A, ADDH         ;
        IFEQ  A, #07          ;
        JP    ZC              ;
        INC   A               ;
        X     A, ADDH         ;
        LD     ADDL, #00      ;
        RET                     ;
ZC:     LD     A, HLD          ;
        IFEQ  A, #080         ;
        JP    ZE              ;
        LD     A, HLD          ;
        ADD   A, HLD          ;
        X     A, HLD          ;
        LD     ADDL, #00      ;
        LD     ADDH, #00      ;
ZE:     JSR   SAVE            ;

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ZD:      LD      PORTD, #02      ;
        JSR     DELAY           ;
        LD      PORTD, #00      ;
        JSR     DELAY           ;
        JP      ZD              ;

;
SAVE:    LD      A, ADDL        ;Save Pointer
        X       A, STOLO       ;
        LD      ADDL, #0FD      ;
        LD      A, ADDH        ;
        X       A, STOHI       ;
        LD      ADDH, #07      ;
        LD      A, HLD         ;
        X       A, STOHL       ;
        LD      HLD, #084      ;
        LD      A, STOLO       ;
        X       A, BYT         ;
        JSR     PUT            ;
        LD      A, STOHI       ;
        X       A, BYT         ;
        JSR     PUT            ;
        IFBIT 3, [B]           ;
        JSR     GOTIT          ;
        RET

GOTIT:   LD      PORTD, #02      ;LED Flashing sequence
        JSR     DELAY           ;
        LD      PORTD, #00      ;
        JSR     DELAY           ;
        LD      PORTD, #02      ;
        JSR     DELAY           ;
        LD      PORTD, #00      ;
        JSR     DELAY           ;
        JSR     DELAY           ;
        JSR     DELAY           ;
        JSR     DELAY           ;
        JP      GOTIT          ;

;
LAST:    LD      ADDL, #0FD      ;Get pointer
        LD      ADDH, #07      ;
        LD      HLD, #084      ;
        JSR     GET            ;
        LD      A, BYT         ;
        X       A, STOLO       ;
        JSR     GET            ;
        LD      A, BYT         ;
        X       A, STOHI       ;
        JSR     GET            ;
        LD      A, BYT         ;
        X       A, STOHL       ;
        LD      ADDL, #00      ;
        LD      ADDH, #00      ;
        LD      HLD, #010      ;
        RET      ;

;
FLSH2:   LD      PORTD, #001     ;FLASH LED 2 TIMES
        JSR     DELAY           ;
        LD      PORTD, #00      ;

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        JSR    DELAY        ;
        LD     PORTD, #001  ;
        JSR    DELAY        ;
        LD     PORTD, #00   ;
        RET                     ;
;
FLSH1:   LD     PORTD, #001  ;FLASH LED ONCE
        JSR    DELAY        ;
        LD     PORTD, #00   ;
        JSR    DELAY        ;
        RET                     ;
;
DELAY:   LD     DLYH, #040   ;
LP15:    LD     DLYL, #0FF   ;
LP16:    DRSZ   DLYL        ;
        JP     LP16         ;
        DRSZ   DLYH        ;
        JP     LP15         ;
        RET     ;
        .END   START       ;

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2. A critical component is any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.

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