LM135
LM235 - LM335,A

PRECISION TEMPERATURE SENSORS

- DIRECTLY CALIBRATED IN °K
- 1°C INITIAL ACCURACY
- OPERATES FROM 450µA TO 5mA
- LESS THAN 1Ω DYNAMIC IMPEDANCE

DESCRIPTION

The LM135, LM235, LM335 are precision temperature sensors which can be easily calibrated. They operate as a 2-terminal Zener and the breakdown voltage is directly proportional to the absolute temperature at 10mV/°K.
The circuit has a dynamic impedance of less than 1Ω and operates within a range of current from 450µA to 5mA without alteration of its characteristics.
Calibrated at +25°C, the LM135, LM235, LM335 have a typical error of less than 1°C over a 100°C temperature range. Unlike other sensors, the LM135, LM235, LM335 have a linear output.

Z
TO92
(Plastic Package)

D
SO8
(Plastic Micropackage)

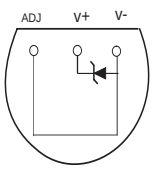
ORDER CODE

Part Number	Temperature Range	Package	
		Z	D
LM135	-55°C, +150°C	•	•
LM235	-40°C, +125°C	•	•
LM335,A	-40°C, +100°C	•	•

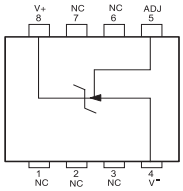
Z = TO92 Plastic package - also available in Bulk (Z), Tape & Reel (ZT) and Ammo Pack (AP)e
D = Small Outline Package (SO) - also available in Tape & Reel (DT)

PIN CONNECTIONS (top view)

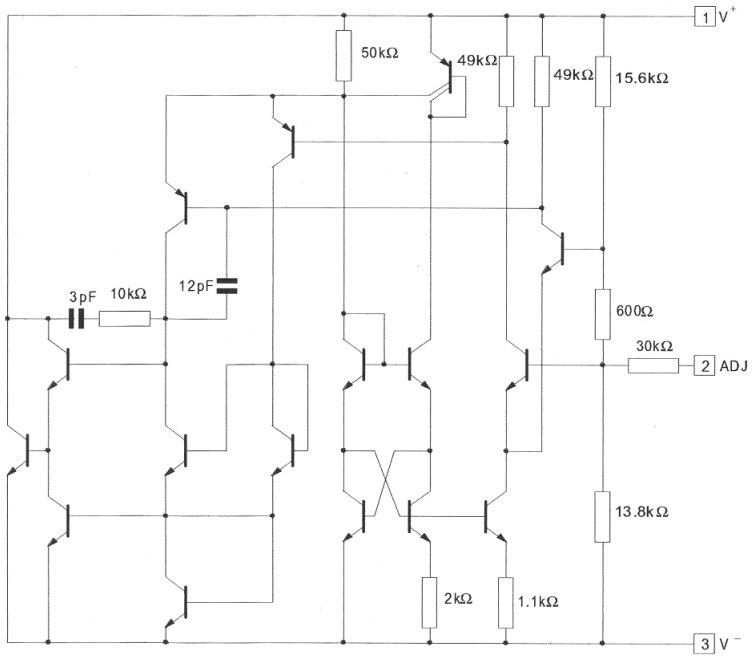
TO92
(Top view)



SO8
(Top view)



SCHEMATIC DIAGRAM



ABSOLUTE MAXIMUM RATINGS

Symbol	Parameter	LM135	LM235	LM335,A	Unit
I_R I_F	Current Reverse Forward	15 10			mA
Toper	Operating Free-air Temperature Range [1] Continuous Intermittent	-55 to +150 +150 to +200	-40 to +125 +125 to +150	-40 to +100 +100 to +125	°C
T_{Stg}	Storage Temperature Range	-65 to +150			°C

1. Tj ≤ 150°C

TEMPERATURE ACCURACY

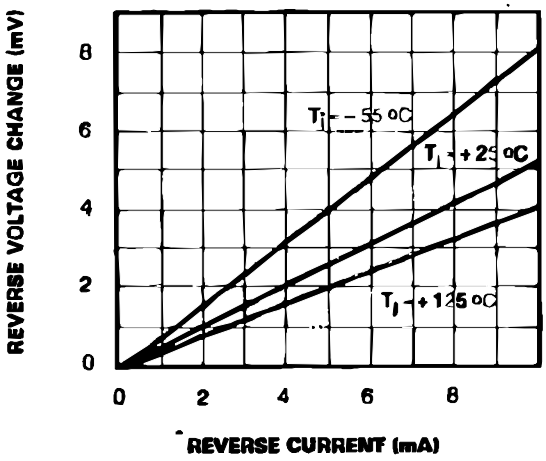
Parameter		LM135 - LM235 - LM335A			LM335			Unit
		Min.	Typ.	Max.	Min.	Typ.	Max.	
Operating Output Voltage T_{case} = +25°C, I_R = 1mA		2.95	2.98	3.01	2.92	2.98	3.04	V
Uncalibrated Temperature Error (I_R = 1mA) T_{case} = +25°C $T_{min.} \le T_{case} \le T_{max.}$			1 2	3 5		5 4	6 9	°C
Temperature Error with 25°C Calibration $T_{min.} \le T_{case} \le T_{max.}$, I_R = 1mA	LM135 - LM235 LM335 LM335A		0.5 0.5	1.5 1		 1 	 2 	°C
Calibrated Error at Extended Temperature $T_{case} = T_{max.}$ (intermittent)			2			2		°C
Non-linearity (I_R = 1mA)	LM135 - LM235 LM335 LM335A		0.3 0.3	1 1.5		0.3	1.5	°C

ELECTRICAL CHARACTERISTICS - (note 1)

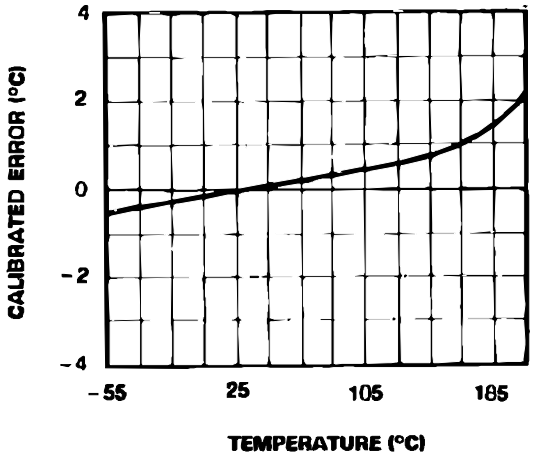
Parameter		LM135 - LM235			LM335,A			Unit
		Min.	Typ.	Max.	Min.	Typ.	Max.	
Operating output voltage change with current 450µA ≤ I_R ≤ 5mA at constant temperature			2.5	10		3	14	mV
Dynamic Impedance (I_R = 1mA)			0.5			0.6		Ω
Output Voltage Temperature Drift			+10			+10		mV/°C
Time Constant	Still Air Air 0.5m/s Stirred Oil		80 10 1			80 10 1		s
Time Stability (T_{case} = +125°C)			0.2			0.2		°C/kh

1. Accuracy measurements are made in a well-stirred oil bath. For other conditions, self heating must be considered

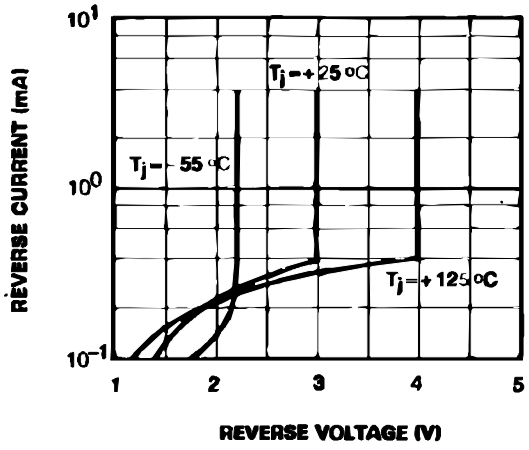
REVERSE VOLTAGE CHANGE



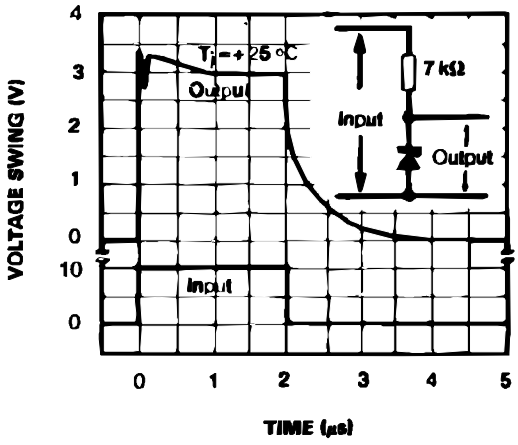
CALIBRATED ERROR



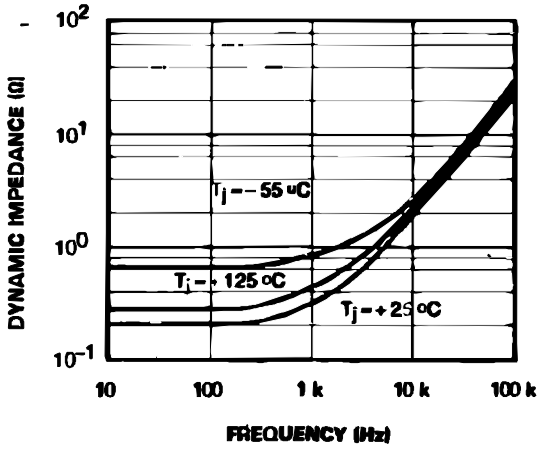
REVERSE CHARACTERISTICS



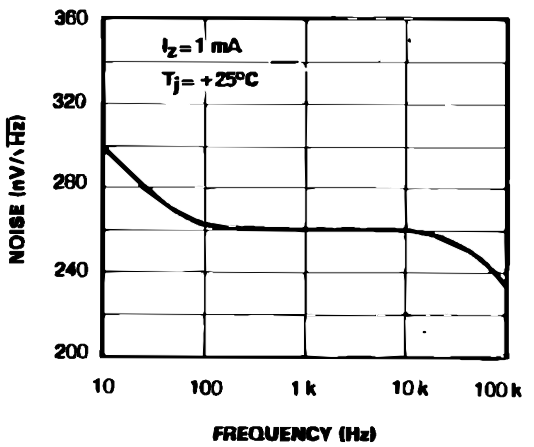
RESPONSE TIME



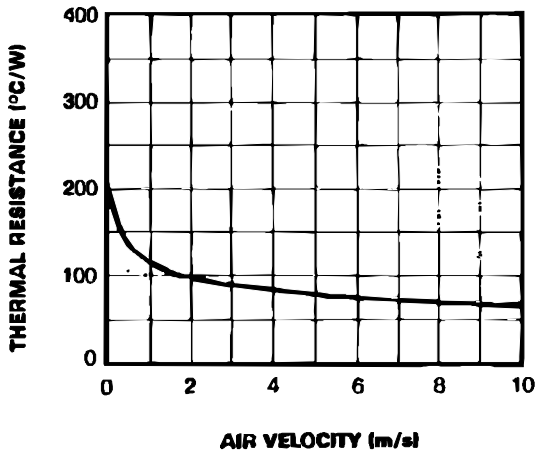
DYNAMIC IMPEDANCE



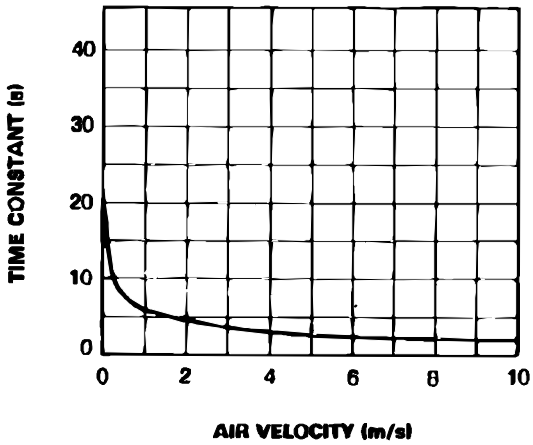
NOISE VOLTAGE



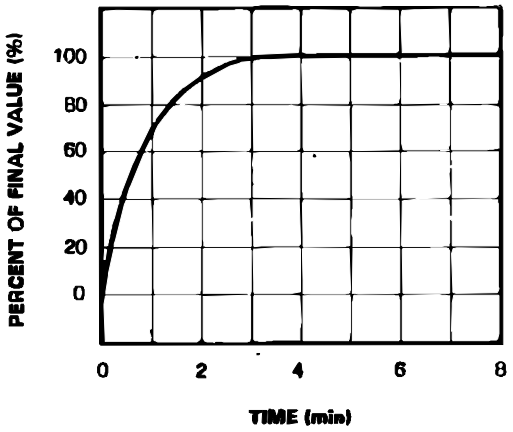
THERMAL RESISTANCE JUNCTION TO AIR



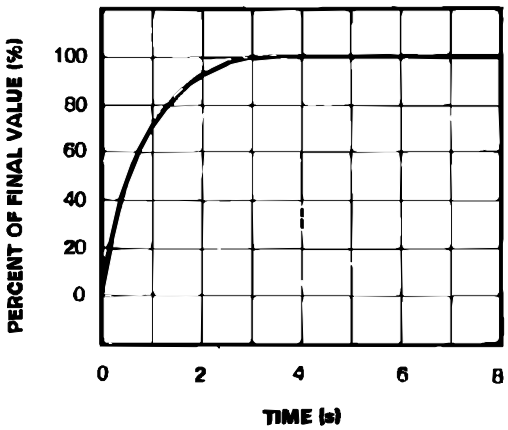
THERMAL TIME CONSTANT



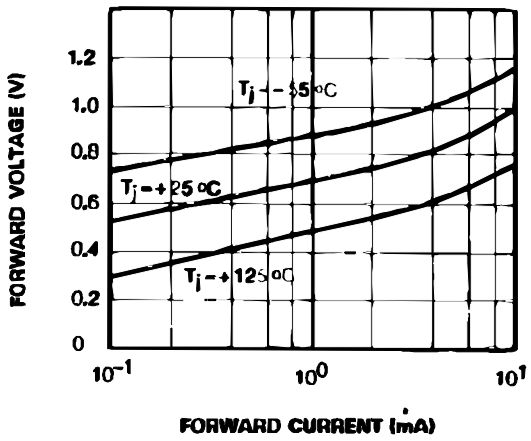
THERMAL RESPONSE IN STILL AIR



THERMAL RESPONSE IN STIRRED OIL BATH



FORWARD CHARACTERICS



APPLICATION HINTS

There is an easy method of calibrating the device for higher accuracies (see typical applications).

The single point calibration works because the output of the LM135, LM235, LM335 is proportional to the absolute temperature with the extrapolated output of sensor going to 0V at 0°K (-273.15°C). Errors in output voltage versus temperature are only slope. Thus a calibration of the slope at one temperature corrects errors at all temperatures.

The circuit output (calibrated or not) can be given by the equation: $V_{OT} + VO_{TO} \times \frac{T}{To}$

where T is the unknown temperature and To is the reference temperature (in °K).

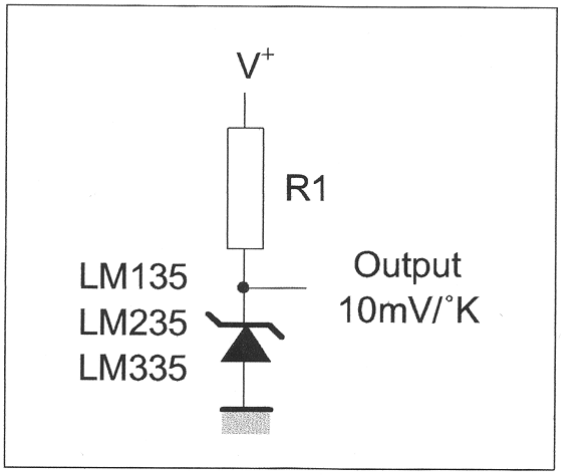
Nominally the output is calibrated at 10mV/°K.

Precautions should be taken to ensure good sensing accuracy. As in the case of all temperatures sensors, self heating can decrease accuracy. The LM135, LM235, LM335 should operate with a low current but sufficient to drive the sensor and its calibration circuit to their maximum operating temperature.

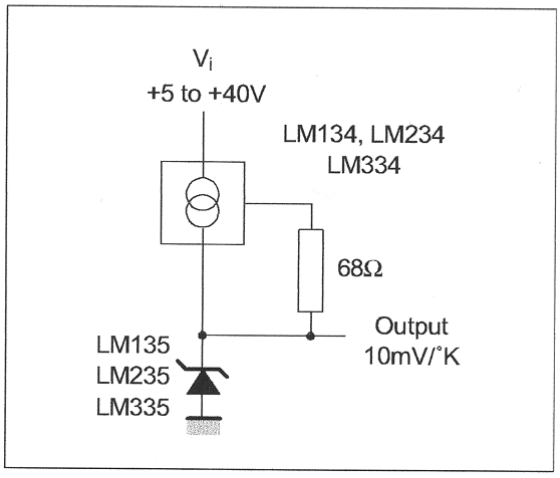
If the sensor is used in surroundings where the thermal resistance is constant, the errors due to self heating can be externally calibrated. This is possible if the circuit is biased with a temperature stable current. Heating will then be proportional to zener voltage and therefore temperature. In this way the error due to self heating is proportional to the absolute temperature as scale factor errors.

TYPICAL APPLICATIONS

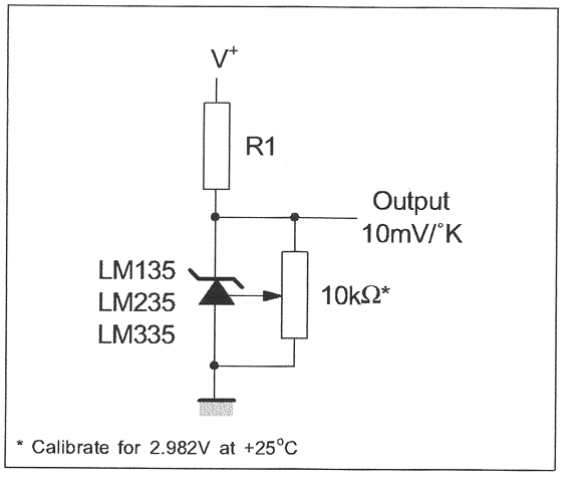
BASIC TEMPERATURE SENSOR



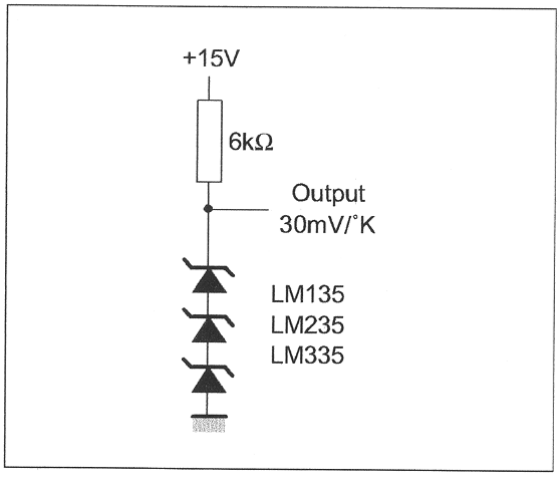
WIDE OPERATING SUPPLY



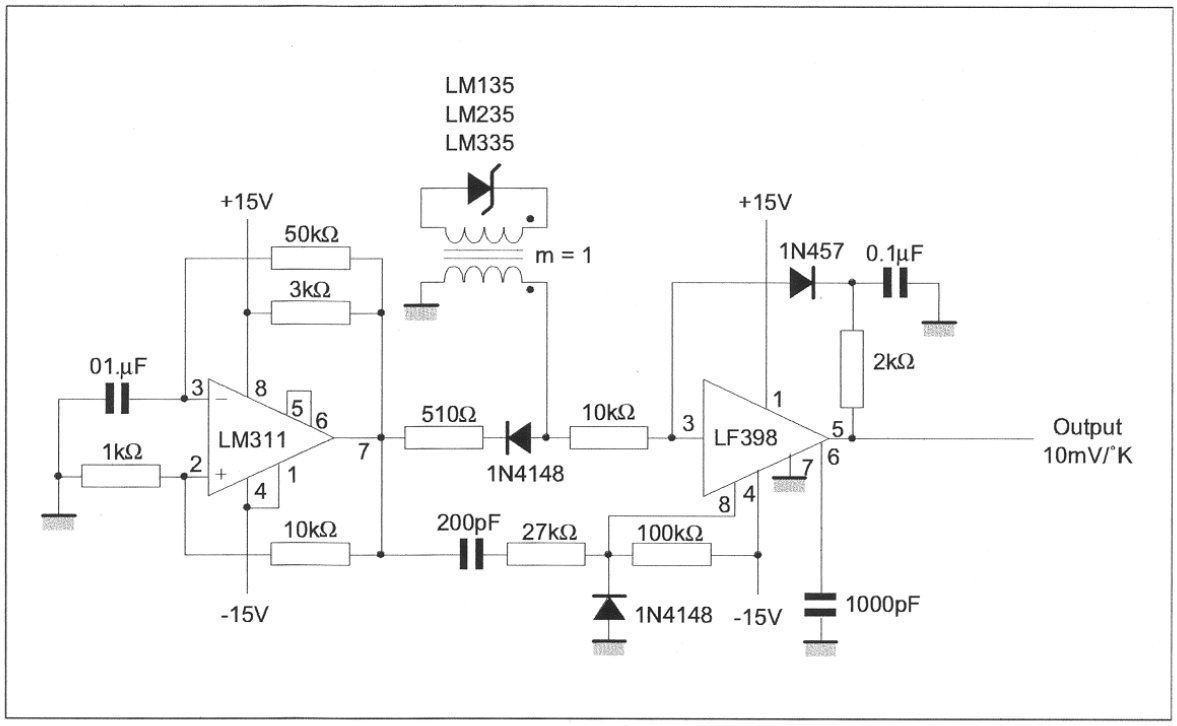
CALIBRATED SENSOR



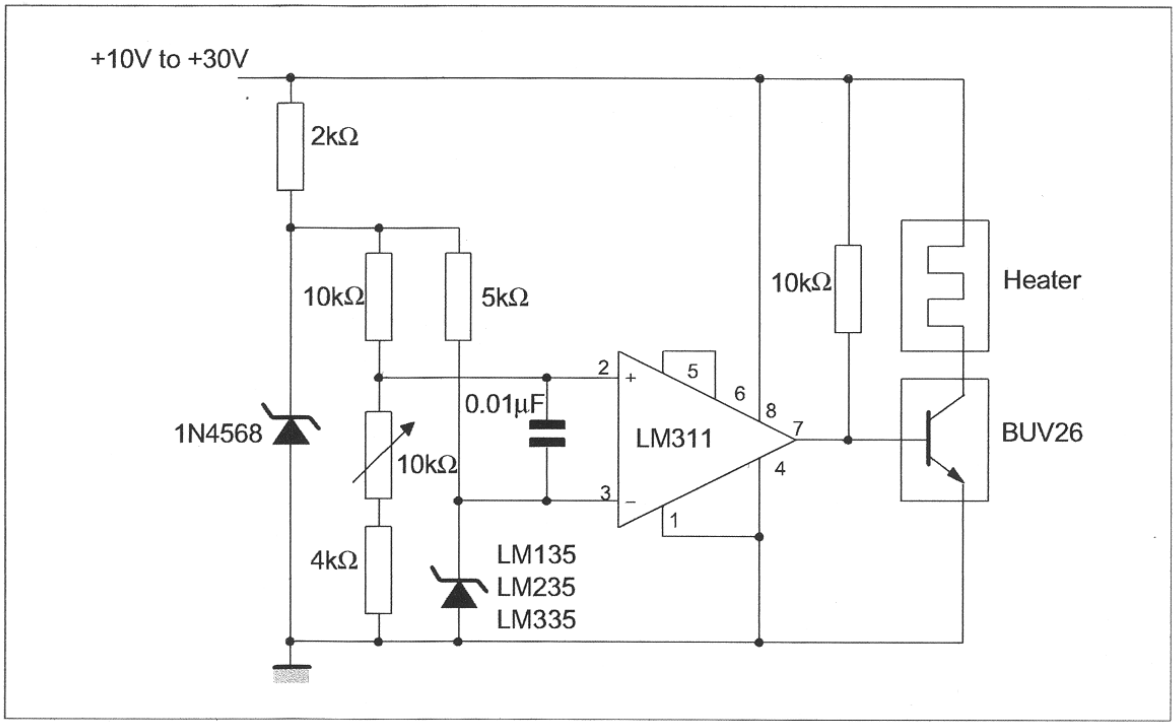
AVERAGE TEMPERATURE SENSING



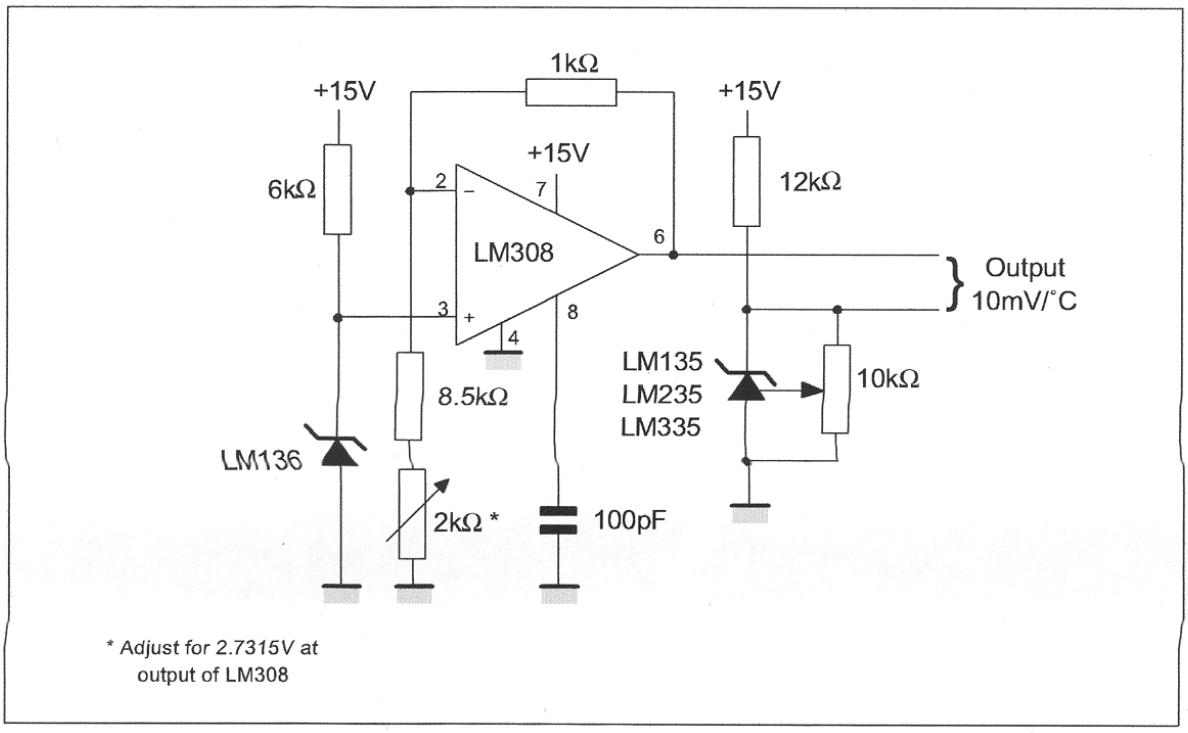
ISOLATED TEMPERATURE SENSOR



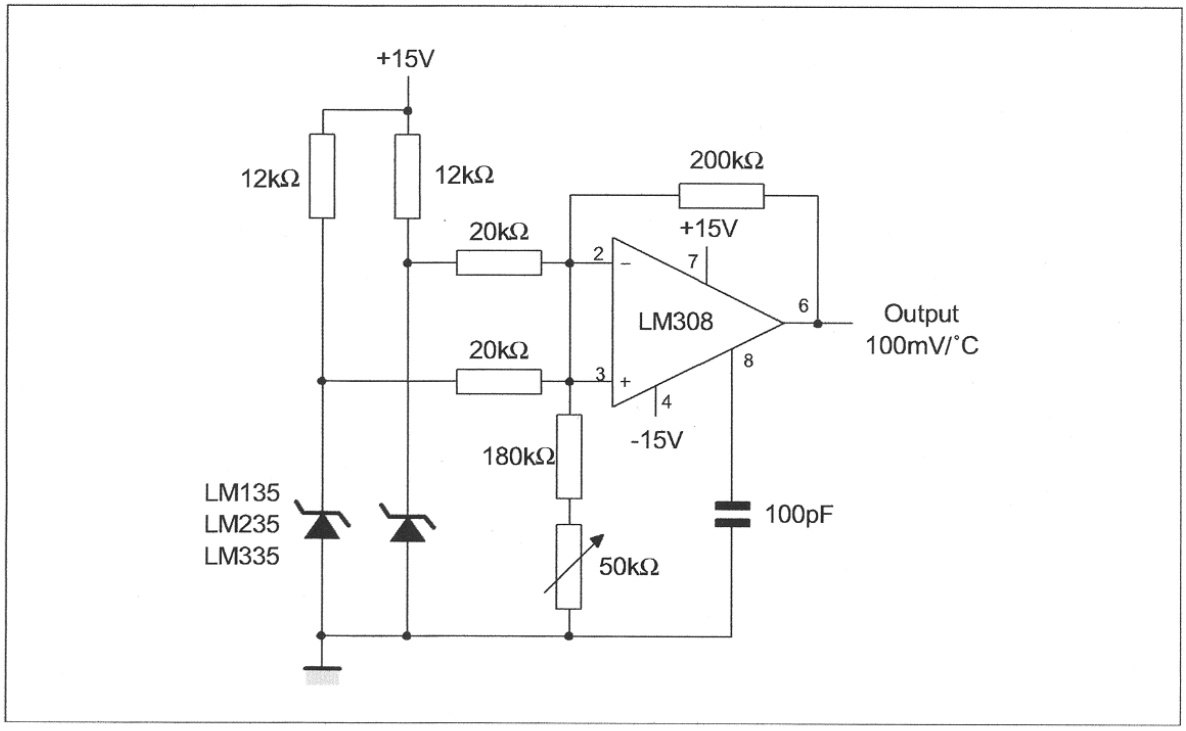
SIMPLE TEMPERATURE CONTROLLER



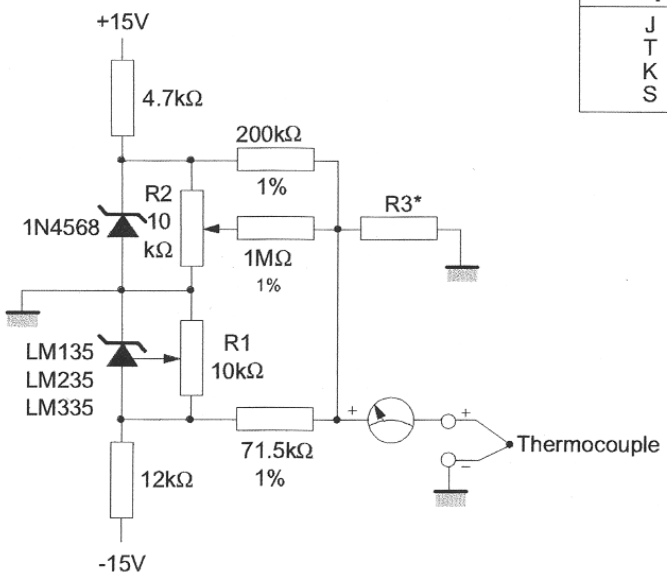
CENTIGRADE THERMOMETER



DIFFERENTIAL TEMPERATURE SENSOR



THERMOCOUPLE COLD JUNCTION COMPENSATION
(compensation for grounded thermocouple)



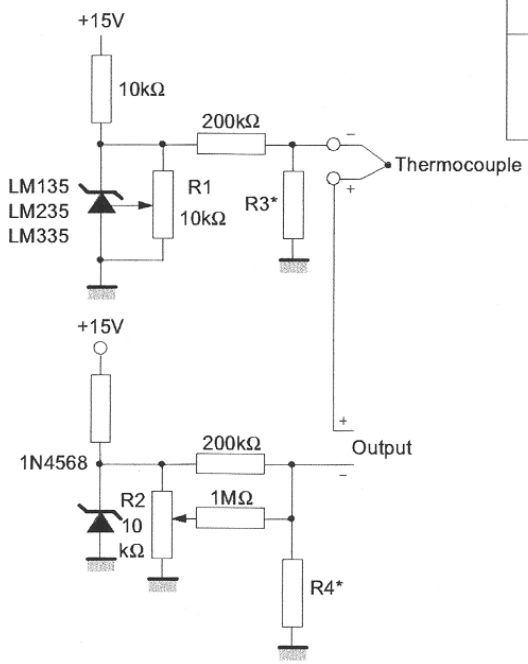
Thermo-couple	R3	Seebeck Coefficient
J	377Ω	52.3µV/°C
T	308Ω	42.8µV/°C
K	293Ω	40.8µV/°C
S	45.8Ω	6.4µV/°C

Adjustments : compensates for both sensor and resistor tolerances.
1. Short 1N4568.
2. Adjust R1 for SEEBECK coefficient times ambient temperature (in degrees K) across R3.
3. Short LM135 and adjust R2 for voltage across R3 corresponding to thermocouple type.

J 14.32mV K 11.17mV
T 11.79mV S 1.768mV

* Select R3 for proper thermocouple type

SINGLE POWER SUPPLY COLD JUNCTION COMPENSATION



Thermo-couple	R3	R4	Seebeck Coefficient
J	1.05kΩ	365Ω	52.3µV/°C
T	856Ω	315Ω	42.8µV/°C
K	816Ω	300Ω	40.8µV/°C
S	128Ω	46.3Ω	6.4µV/°C

Adjustments :
1. Adjust R1 for the voltage across R3 equal to the SEEBECK coefficient times ambient temperature in degrees Kelvin.
2. Adjust R2 for voltage across R4 corresponding to thermocouple.

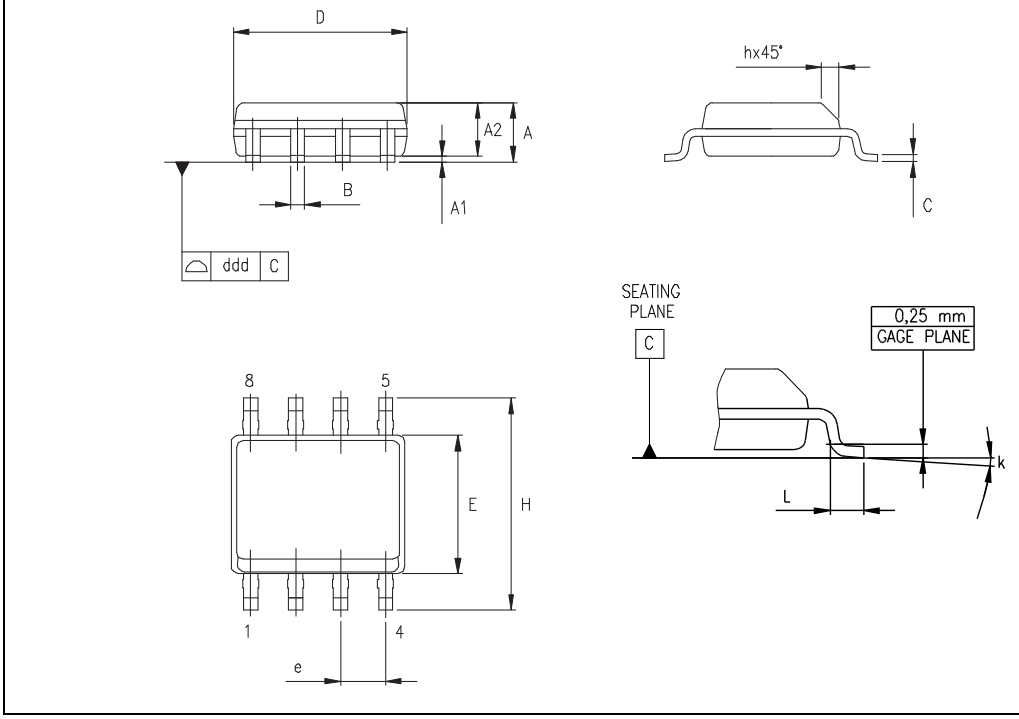
J 14.32mV K 11.17mV
T 11.79mV S 1.768mV

* Select R3 and R4 for proper thermocouple

PACKAGE MECHANICAL DATA

SO-8 MECHANICAL DATA

DIM.	mm.			inch		
	MIN.	TYP	MAX.	MIN.	TYP.	MAX.
A	1.35		1.75	0.053		0.069
A1	0.10		0.25	0.04		0.010
A2	1.10		1.65	0.043		0.065
B	0.33		0.51	0.013		0.020
C	0.19		0.25	0.007		0.010
D	4.80		5.00	0.189		0.197
E	3.80		4.00	0.150		0.157
e		1.27			0.050	
H	5.80		6.20	0.228		0.244
h	0.25		0.50	0.010		0.020
L	0.40		1.27	0.016		0.050
k	8° (max.)					
ddd			0.1			0.04



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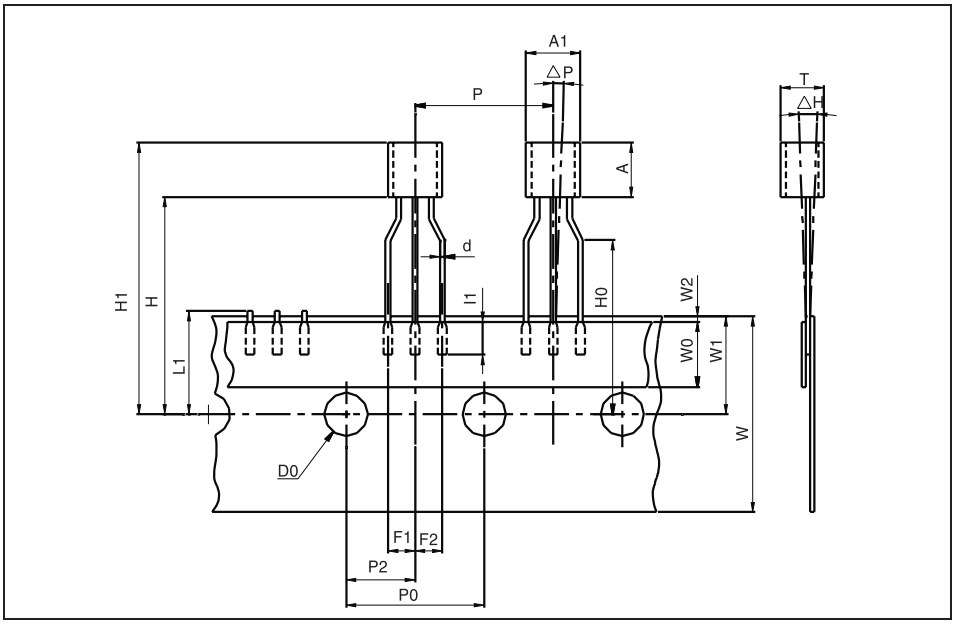
PACKAGE MECHANICAL DATA - TO92 TAPE AMMO PACK & TO92 TAPE & REEL

TO-92 MECHANICAL DATA

DIM.	mm.			inches		
	MIN.	TYP	MAX.	MIN.	TYP.	MAX.
AL			5.0			0.197
A			5.0			0.197
T			4.0			0.157
d		0.45			0.018	
I1	2.5			0.098		
P	11.7	12.7	13.7	0.461	0.500	0.539
PO	12.4	12.7	13	0.488	0.500	0.512
P2	5.95	6.35	6.75	0.234	0.250	0.266
F1/F2	2.4	2.5	2.8	0.094	0.098	0.110
h	-1	0	1	-0.039	0	0.039
P	-1	0	1	-0.039	0	0.039
W	17.5	18.0	19.0	0.689	0.709	0.748
W0	5.7	6	6.3	0.224	0.236	0.248
W1	8.5	9	9.75	0.335	0.354	0.384
W2			0.5			0.020
H			20			0.787
H0	15.5	16	16.5	0.610	0.630	0.650
H1			25			0.984
DO	3.8	4.0	4.2	0.150	0.157	0.165
L1			11			0.433

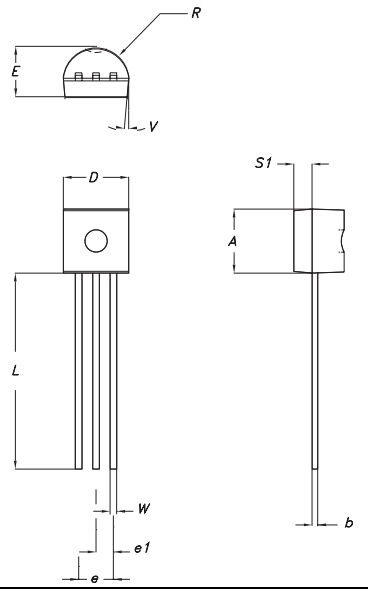


Packing information are available at: http://www.st.com/stonline/prodpres/packages/stdlin.htm

PACKAGE MECHANICAL DATA - TO92 BULK

TO-92 MECHANICA DATA

DIM.	mm.			mils		
	MIN.	TYP	MAX.	MIN.	TYP.	MAX.
A	4.32		4.95	170.1		194.9
b	0.36		0.51	14.2		20.1
D	4.45		4.95	175.2		194.9
E	3.30		3.94	129.9		155.1
e	2.41		2.67	94.9		105.1
e1	1.14		1.40	44.9		55.1
L	12.7		15.49	500.0		609.8
R	2.16		2.41	85.0		94.9
S1	0.92		1.52	36.2		59.8
W	0.41		0.56	16.1		22.0



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