Document Title

128M x 8 Bit / 64M x 16 Bit NAND Flash Memory

Revision History

Revision No History Draft Date Remark

0.0 1. Initial issue Aug. 24th. 2003 Advance

The attached data sheets are prepared and approved by SAMSUNG Electronics. SAMSUNG Electronics CO., LTD. reserve the right to change the specifications. SAMSUNG Electronics will evaluate and reply to your requests and questions about device. If you have any questions, please contact the SAMSUNG branch office near your office.



128M x 8 Bit NAND Flash Memory

PRODUCT LIST

Part Number	Vcc Range	Organization	PKG Type		
K9F1G08Q0A-Y,P	1.70 ~ 1.95V				
K9F1G08D0A-Y,P	2.4 ~ 2.9V	Vo	TSOP1		
K9F1G08U0A-Y,P	2.7 ~ 3.6V	X8			
K9F1G08U0A-V,F	2.1 ~ 3.0V		WSOP1		

FEATURES

Voltage Supply

-1.8V device(K9F1G08Q0A): 1.70V~1.95V - 2.65V device(K9F1G08D0A): 2.4~2.9V -3.3V device(K9F1G08U0A): 2.7 V ~3.6 V

Organization

- Memory Cell Array: (128M + 4,096K)bit x 8bit

Data Register: (2K + 64)bit x8bit
Cache Register: (2K + 64)bit x8bit
Automatic Program and Erase
Page Program: (2K + 64)Byte
Block Erase: (128K + 4K)Byte

Page Read Operation
Page Size: 2K-Byte
Random Read: 25µs(Max.)
Serial Access: 50ns(Min.)

• Fast Write Cycle Time

- Program time : 300μs(Typ.)- Block Erase Time : 2ms(Typ.)

• Command/Address/Data Multiplexed I/O Port

• Hardware Data Protection

- Program/Erase Lockout During Power Transitions

• Reliable CMOS Floating-Gate Technology - Endurance : 100K Program/Erase Cycles

Data Retention : 10 YearsCommand Register Operation

• Cache Program Operation for High Performance Program

Power-On Auto-Read OperationIntelligent Copy-Back Operation

• Unique ID for Copyright Protection

• Package :

- K9F1G08X0A-YCB0/YIB0

48 - Pin TSOP I (12 x 20 / 0.5 mm pitch)

- K9F1G08U0A-VCB0/VIB0 48 - Pin WSOP I (12X17X0.7mm)

- K9F1G08X0A-PCB0/PIB0

48 - Pin TSOP I (12 x 20 / 0.5 mm pitch)- Pb-free Package

- K9F1G08U0A-FCB0/FIB0

48 - Pin WSOP I (12X17X0.7mm)- Pb-free Package

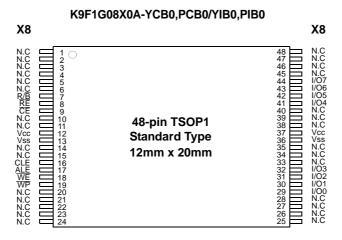
* K9F1G08U0A-V,F(WSOPI) is the same device as
K9F1G08U0A-Y,P(TSOP1) except package type.

GENERAL DESCRIPTION

Offered in 128Mx8bit or 64Mx16bit, the K9F1G08X0A is 1G bit with spare 32M bit capacity. Its NAND cell provides the most cost-effective solution for the solid state mass storage market. A program operation can be performed in typical 300µs on the 2112-byte(X8 device) or 1056-word(X16 device) page and an erase operation can be performed in typical 2ms on a 128K-byte block. Data in the data page can be read out at 50ns cycle time per byte. The I/O pins serve as the ports for address and data input/output as well as command input. The on-chip write controller automates all program and erase functions including pulse repetition, where required, and internal verification and margining of data. Even the write-intensive systems can take advantage of the K9F1G08X0A's extended reliability of 100K program/erase cycles by providing ECC(Error Correcting Code) with real time mapping-out algorithm. The K9F1G08X0A is an optimum solution for large nonvolatile storage applications such as solid state file storage and other portable applications requiring non-volatility.

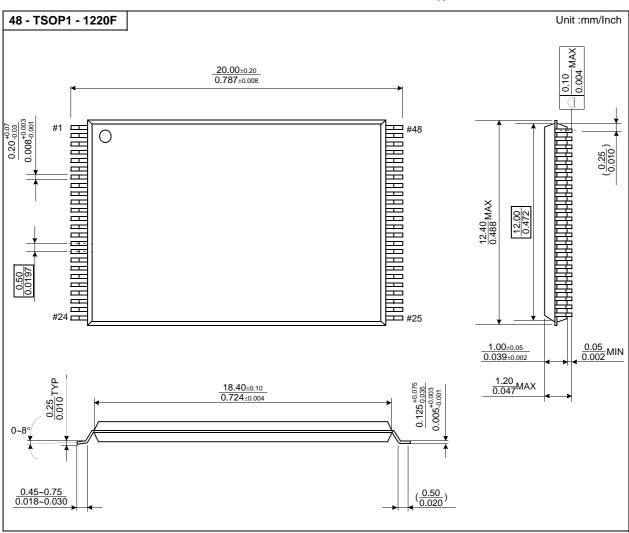


PIN CONFIGURATION (TSOP1)



PACKAGE DIMENSIONS

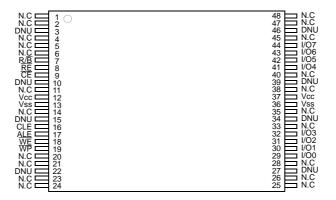
48-PIN LEAD/LEAD FREE PLASTIC THIN SMALL OUT-LINE PACKAGE TYPE(I)





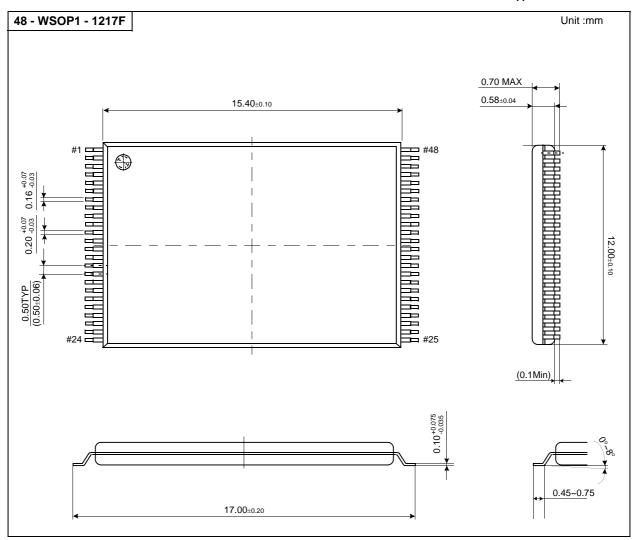
PIN CONFIGURATION (WSOP1)

K9F1G08U0A-VCB0,FCB0/VIB0,FIB0



PACKAGE DIMENSIONS

48-PIN LEAD/LEAD FREE PLASTIC VERY VERY THIN SMALL OUT-LINE PACKAGE TYPE (I)



PIN DESCRIPTION

Pin Name	Pin Function
I/Oo ~ I/O7	DATA INPUTS/OUTPUTS The I/O pins are used to input command, address and data, and to output data during read operations. The I/O pins float to high-z when the chip is deselected or when the outputs are disabled.
CLE	COMMAND LATCH ENABLE The CLE input controls the activating path for commands sent to the command register. When active high, commands are latched into the command register through the I/O ports on the rising edge of the WE signal.
ALE	ADDRESS LATCH ENABLE The ALE input controls the activating path for address to the internal address registers. Addresses are latched on the rising edge of WE with ALE high.
CE	CHIP ENABLE The CE input is the device selection control. When the device is in the Busy state, CE high is ignored, and the device does not return to standby mode.
RE	READ ENABLE The RE input is the serial data-out control, and when active drives the data onto the I/O bus. Data is valid tREA after the falling edge of RE which also increments the internal column address counter by one.
WE	WRITE ENABLE The WE input controls writes to the I/O port. Commands, address and data are latched on the rising edge of the WE pulse.
WP	WRITE PROTECT The WP pin provides inadvertent write/erase protection during power transitions. The internal high voltage generator is reset when the WP pin is active low.
R/B	READY/BUSY OUTPUT The R/B output indicates the status of the device operation. When low, it indicates that a program, erase or random read operation is in process and returns to high state upon completion. It is an open drain output and does not float to high-z condition when the chip is deselected or when outputs are disabled.
Vcc	POWER Vcc is the power supply for device.
Vss	GROUND
N.C	NO CONNECTION Lead is not internally connected.

NOTE: Connect all Vcc and Vss pins of each device to common power supply outputs. Do not leave Vcc or Vss disconnected.



Figure 1-1. K9F1G08X0A (X8) Functional Block Diagram

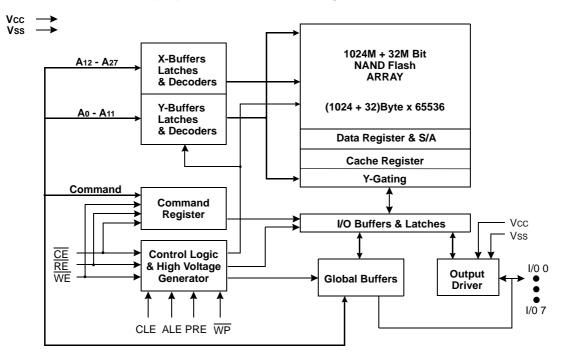
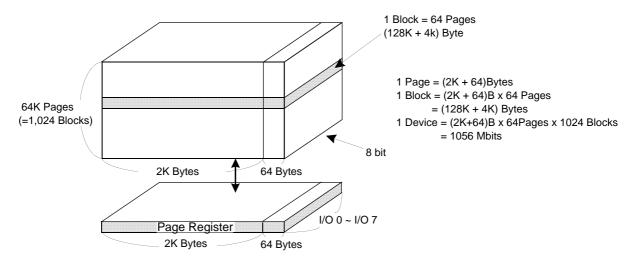


Figure 2-1. K9F1G08X0A (X8) Array Organization



	I/O 0	I/O 1	I/O 2	I/O 3	I/O 4	I/O 5	I/O 6	I/O 7	
1st Cycle	Ao	A1	A ₂	Аз	A4	A 5	A ₆	A ₇	Column Address
2nd Cycle	A8	A 9	A10	A11	*L	*L	*L	*L	Column Address
3rd Cycle	A12	A13	A14	A15	A16	A17	A18	A19	Row Address
4th Cycle	A20	A21	A22	A23	A24	A25	A26	A27	Row Address

 $\mbox{\bf NOTE}:$ Column Address : Starting Address of the Register.

^{*} The device ignores any additional input of address cycles than reguired.



^{*} L must be set to "Low".

Product Introduction

The K9F1G08X0A is a 1056Mbit(1,107,296,256 bit) memory organized as 65,536 rows(pages) by 2112x8 columns. Spare 64 columns are located from column address of 2048~2111. A 2112-byte data register and a 2112-byte cache register are serially connected to each other. Those serially connected registers are connected to memory cell arrays for accommodating data transfer between the I/O buffers and memory cells during page read and page program operations. The memory array is made up of 32 cells that are serially connected to form a NAND structure. Each of the 32 cells resides in a different page. A block consists of two NAND structured strings. A NAND structure consists of 32 cells. Total 1081344 NAND cells reside in a block. The program and read operations are executed on a page basis, while the erase operation is executed on a block basis. The memory array consists of 1024 separately erasable 128K-byte blocks. It indicates that the bit by bit erase operation is prohibited on the K9F1G08X0A.

The K9F1G08X0A has addresses multiplexed into 8 I/Os. This scheme dramatically reduces pin counts and allows system upgrades to future densities by maintaining consistency in system board design. Command, address and data are all written through I/O's by bringing $\overline{\text{WE}}$ to low while $\overline{\text{CE}}$ is low. Those are latched on the rising edge of $\overline{\text{WE}}$. Command Latch Enable(CLE) and Address Latch Enable(ALE) are used to multiplex command and address respectively, via the I/O pins. Some commands require one bus cycle. For example, Reset Command, Status Read Command, etc require just one cycle bus. Some other commands, like page read and block erase and page program, require two cycles: one cycle for setup and the other cycle for execution. The 128M byte physical space requires 28 addresses, thereby requiring four cycles for addressing: 2 cycles of column address, 2 cycles of row address, in that order. Page Read and Page Program need the same four address cycles following the required command input. In Block Erase operation, however, only the two row address cycles are used. Device operations are selected by writing specific commands into the command register. Table 1 defines the specific commands of the K9F1G08X0A.

The device provides cache program in a block. It is possible to write data into the cache registers while data stored in data registers are being programmed into memory cells in cache program mode. The program performace may be dramatically improved by cache program when there are lots of pages of data to be programmed.

The device embodies power-on auto-read feature which enables serial access of data of the 1st page without command and address input after power-on.

In addition to the enhanced architecture and interface, the device incorporates copy-back program feature from one page to another page without need for transporting the data to and from the external buffer memory. Since the time-consuming serial access and data-input cycles are removed, system performance for solid-state disk application is significantly increased.

Table 1. Command Sets

Function	1st. Cycle	2nd. Cycle	Acceptable Command during Busy
Read	00h	30h	
Read for Copy Back	00h	35h	
Read ID	90h	-	
Reset	FFh	-	0
Page Program	80h	10h	
Cache Program	80h	15h	
Copy-Back Program	85h	10h	
Block Erase	60h	D0h	
Random Data Input*	85h	-	
Random Data Output*	05h	E0h	
Read Status	70h		0

NOTE: 1. Random Data Input/Output can be executed in a page.

2. Command not specified in command sets table is not permitted to be entered to the device, which can raise erroneous operation.

Caution: Any undefined command inputs are prohibited except for above command set of Table 1.



ABSOLUTE MAXIMUM RATINGS

Parameter		Cymhal	l	Unit			
Fai	rameter	Symbol	1.8V DEVICE	3.3V/2.65V DEVICE	Unit		
Valtage on any nin rele	ative to Vec	Vin/out	-0.6 to + 2.45	-0.6 to + 4.6	V		
Voltage on any pin relative to Vss		Vcc	-0.2 to + 2.45	-0.6 to + 4.6	v		
Temperature Under	K9F1G08X0A-XCB0	TBIAS	-10 to +125		-10 to +125		°C
Bias	K9F1G08X0A-XIB0	TBIAS	-4(
Ctarra a Tarra a rationa	K9F1G08X0A-XCB0	T	0.0	5 to +150	00		
Storage Temperature	K9F1G08X0A-XIB0	Tstg	-00	°C			
Short Circuit Current		los		mA			

NOTE:

- 1. Minimum DC voltage is -0.6V on input/output pins. During transitions, this level may undershoot to -2.0V for periods <30ns. Maximum DC voltage on input/output pins is Vcc,+0.3V which, during transitions, may overshoot to Vcc+2.0V for periods <20ns.
- 2. Permanent device damage may occur if ABSOLUTE MAXIMUM RATINGS are exceeded. Functional operation should be restricted to the conditions as detailed in the operational sections of this data sheet. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

RECOMMENDED OPERATING CONDITIONS

(Voltage reference to GND, K9F1G08X0A-XCB0 : Ta=0 to 70° C, K9F1G08X0A-XIB0: Ta=-40 to 85° C)

Doromotor Sum		K9F1G08Q0A(1.8V)		K9F1G08D0A(2.65V)			K9F1G08U0A(3.3V)			Unit	
Parameter Symbol	Min	Тур.	Max	Min	Тур.	Max	Min	Тур.	Max	Unit	
Supply Voltage	Vcc	1.70	1.8	1.95	2.4	2.65	2.9	2.7	3.3	3.6	V
Supply Voltage	Vss	0	0	0	0	0	0	0	0	0	V



DC AND OPERATING CHARACTERISTICS (Recommended operating conditions otherwise noted.)

							K9F	1G08	X0A					
P	Parameter	Symbol	ymbol Test Conditions		1.8V			2.65V			3.3V		Unit	
				Min	Тур	Max	Min	Тур	Max	Min	Тур	Max		
Operating	Page Read with Icc1 tRC=50ns, CE=VIL IOUT=0mA		-	8	15	-	10	20	-	10	20			
Current	Program	Icc2	-	1	8	15	-	10	20	1	10	20	mA	
	Erase	Icc3	-	1	8	15	-	10	20	1	10	20		
Stand-by	Current(TTL)	Is _B 1	CE=VIH, WP=PRE=0V/Vcc	1	-	1	-	1	1	1	-	1		
Stand-by	tand-by Current(CMOS) ISB2 CE=Vcc-0.2, WP=PRE=0V/Vcc			-	10	50	-	10	50	-	10	50		
Input Leakage Current ILI		ILI	VIN=0 to Vcc(max)	1	-	±10	-	1	±10	1	-	±10	±10 μA	
Output Leakage Current ILO		ILO	Vout=0 to Vcc(max)	-	-	±10	-	1	±10	1	-	±10		
Input High	n Voltage	VIH*	-	Vcc -0.4	-	Vcc +0.3	Vcc -0.4	-	Vcc +0.3	2.0	-	Vcc +0.3		
Input Low	Voltage, All inputs	VIL*	-	-0.3	-	0.4	-0.3	-	0.5	-0.3	-	0.8		
Output High Voltage Level Voн		Vон	K9F1G08Q0A :IoH=-100μA K9F1G08D0A :IoH=-100μA K9F1G08U0A :IoH=-400μA	Vcc -0.1	-	-	Vccq -0.4	1	-	2.4	-	-	V	
Output Low Voltage Level Vol		K9F1G08Q0A :IoL=100uA K9F1G08D0A :IoL=100μA K9F1G08U0A :IoL=2.1mA	-	-	0.1	-	-	0.4	-	-	0.4			
Output Low Current(R/B) K9F1G08Q0A :VoL=0.1V K9F1G08D0A :VoL=0.1V K9F1G08D0A :VoL=0.1V K9F1G08U0A :VoL=0.4V		3	4	-	3	4	-	8	10	-	mA			

NOTE: VIL can undershoot to -0.4V and VIH can overshoot to VCC +0.4V for durations of 20 ns or less.



VALID BLOCK

Parameter	Symbol	Min	Тур.	Max	Unit
Valid Block Number	N∨B	1004	-	1024	Blocks

NOTE

- 1. The K9F1G08X0A may include invalid blocks when first shipped. Additional invalid blocks may develop while being used. The number of valid blocks is presented with both cases of invalid blocks considered. Invalid blocks are defined as blocks that contain one or more bad bits. Do not erase or program factory-marked bad blocks. Refer to the attached technical notes for appropriate management of invalid blocks.
- 2. The 1st block, which is placed on 00h block address, is guaranteed to be a valid block, does not require Error Correction up to 1K program/erase cycles.

AC TEST CONDITION

(K9F1G08X0A-XCB0:TA=0 to 70°C, K9F1G08X0A-XIB0:TA=-40 to 85°C

K9F1G08Q0A: Vcc=1.70V~1.95V, K9F1G08D0A: Vcc=2.4V~2.9V, K9F1G08U0A: Vcc=2.7V~3.6V unless otherwise noted)

Parameter	K9F1G08Q0A	K9F1G08D0A	K9F1G08U0A
Input Pulse Levels	0V to Vcc	0V to Vcc	0.4V to 2.4V
Input Rise and Fall Times	5ns	5ns	5ns
Input and Output Timing Levels	Vcc/2	Vcc/2	1.5V
K9F1G08Q0A:Output Load (Vcc:1.8V +/-10%) K9F1G08D0A:Output Load (Vccq:2.65V +/-10%) K9F1G08U0A:Output Load (Vcc:3.0V +/-10%)	1 TTL GATE and CL=30pF	1 TTL GATE and CL=30pF	1 TTL GATE and CL=50pF
K9F1G08U0A:Output Load (Vcc:3.3V +/-10%)	-	-	1 TTL GATE and CL=100pF

CAPACITANCE(TA=25°C, VCC=1.8V/2.65V/3.3V, f=1.0MHz)

Item	Symbol	Test Condition	Min	Max	Unit
Input/Output Capacitance	Cı/o	VIL=0V	-	10	pF
Input Capacitance	CIN	VIN=0V	-	10	pF

NOTE: Capacitance is periodically sampled and not 100% tested.

MODE SELECTION

CLE	ALE	CE	WE	RE	WP	PRE		Mode	
Н	L	L		Н	Х	Х	Read Mode	Command Input	
L	Н	L	_	Н	Х	Х	rtcau Mode	Address Input(4clock)	
Н	L	L	_	Н	Н	Х	Write Mode	Command Input	
L	Н	L		Н	Н	Х	WINC WOOC	Address Input(4clock)	
L	L	L	F	Н	Н	Х	Data Input		
L	L	L	Н	T	Х	Х	Data Outpu	t	
Х	Х	X	X	Н	Х	Х	During Rea	d(Busy)	
Х	Х	X	X	Х	Н	Х	During Prog	gram(Busy)	
Х	X	X	X	X	Н	Х	During Eras	se(Busy)	
Х	X ⁽¹⁾	X	X	Х	L	Х	Write Protect		
Х	X	Н	Χ	X	0V/Vcc ⁽²⁾	0V/Vcc ⁽²⁾	Stand-by		

NOTE: 1. X can be VIL or VIH.

2. $\overline{\text{WP}}$ and $\overline{\text{PRE}}$ should be biased to CMOS high or CMOS low for standby.



Program / Erase Characteristics

Parameter	Symbol	Min	Тур	Max	Unit	
Program Time	tprog	-	300	700	μS	
Dummy Busy Time for Cache Program	tcbsy		3	700	μS	
Number of Partial Program Cycles	Main Array	Non	-	-	4	cycles
in the Same Page	Spare Array	Nop	-	-	4	cycles
Block Erase Time		tbers	-	2	3	ms

NOTE: 1. Max. time of tCBSY depends on timing between internal program completion and data in

AC Timing Characteristics for Command / Address / Data Input

Doromotor	Cumbal	Min				Unit			
Parameter	Symbol	K9F1G08Q0A	K9F1G08D0A	K9F1G08U0A	K9F1G08Q0A	K9F1G08D0A	K9F1G08U0A	Unit	
CLE setup Time	tcls	0	0	0	-	-	-	ns	
CLE Hold Time	tclh	10	10	10	-	-	-	ns	
CE setup Time	tcs	0	0	0	-	-	-	ns	
CE Hold Time	tсн	10	10	10	-	-	-	ns	
WE Pulse Width	twp	25(1)	25(1)	25(1)	-	-	-	ns	
ALE setup Time	tALS	0	0	0	-	-	-	ns	
ALE Hold Time	talh	10	10	10	-	-	-	ns	
Data setup Time	tDS	20	20	20	-	-	-	ns	
Data Hold Time	tDH	10	10	10	-	-	-	ns	
Write Cycle Time	twc	45	45	45	-	-	-	ns	
WE High Hold Time	twn	15	15	15	-	-	-	ns	

NOTE: 1. If tCS is set less than 10ns, tWP must be minimum 35ns, otherwise, tWP may be minimum 25ns.

AC Characteristics for Operation

D	Symbol		Min		Max			
Parameter		K9F1G08Q0A	K9F1G08D0A	K9F1G08U0A	K9F1G08Q0A	K9F1G08D0A	K9F1G08U0A	Unit
Data Transfer from Cell to Register	tr	-	-	-	25	25	25	μS
ALE to RE Delay	tar	10	10	10	-	-	-	ns
CLE to RE Delay	tclr	10	10	10	-	-	-	ns
Ready to RE Low	trr	20	20	20	-	-	-	ns
RE Pulse Width	trp	25	25	25	-	-	-	ns
WE High to Busy	twB	-	-	=	100	100	100	ns
Read Cycle Time	trc	50	50	50	-	-	-	ns
RE Access Time	trea	-	-	-	35	30	30	ns
CE Access Time	tCEA	-	-	-	45	45	45	ns
RE High to Output Hi-Z	trhz	-	-	-	30	30	30	ns
CE High to Output Hi-Z	tcHZ	-	-	-	20	20	20	ns
RE or CE High to Output hold	tон	15	15	15	-	-	-	ns
RE High Hold Time	treh	15	15	15	-	-	-	ns
Output Hi-Z to RE Low	tır	0	0	0	-	-	-	ns
WE High to RE Low	twhr	60	60	60	-	-	-	ns
Device Resetting Time (Read/Program/Erase)	trst	-	-	-	5/10/500(1)	5/10/500(1)	5/10/500(1)	μS

NOTE: 1. If reset command(FFh) is written at Ready state, the device goes into Busy for maximum 5us.



NAND Flash Technical Notes

Invalid Block(s)

Invalid blocks are defined as blocks that contain one or more invalid bits whose reliability is not guaranteed by Samsung. The information regarding the invalid block(s) is so called as the invalid block information. Devices with invalid block(s) have the same quality level as devices with all valid blocks and have the same AC and DC characteristics. An invalid block(s) does not affect the performance of valid block(s) because it is isolated from the bit line and the common source line by a select transistor. The system design must be able to mask out the invalid block(s) via address mapping. The 1st block, which is placed on 00h block address, is guaranteed to be a valid block, does not require Error Correction up to 1K program/erase cycles.

Identifying Invalid Block(s)

All device locations are erased(FFh) except locations where the invalid block(s) information is written prior to shipping. The invalid block(s) status is defined by the 1st byte in the spare area. Samsung makes sure that either the 1st or 2nd page of every invalid block has non-FFh data at the column address of 2048. Since the invalid block information is also erasable in most cases, it is impossible to recover the information once it has been erased. Therefore, the system must be able to recognize the invalid block(s) based on the original invalid block information and create the invalid block table via the following suggested flow chart(Figure 3). Any intentional erasure of the original invalid block information is prohibited.

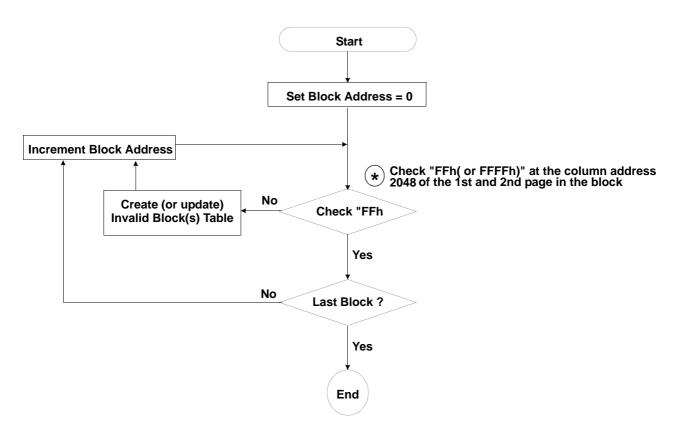


Figure 3. Flow chart to create invalid block table.

NAND Flash Technical Notes (Continued)

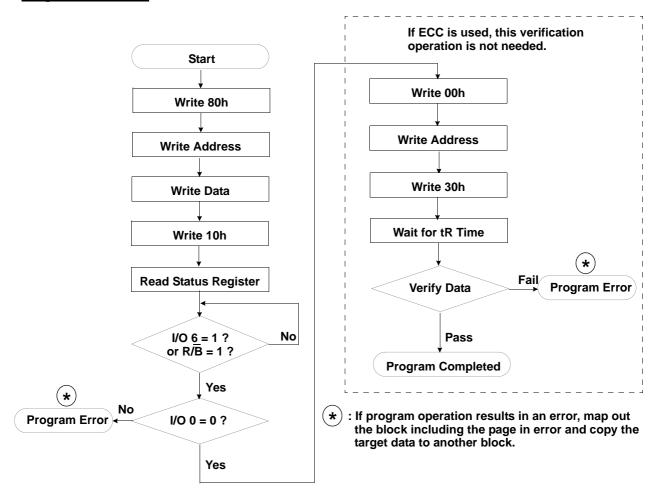
Error in write or read operation

Within its life time, additional invalid blocks may develop with NAND Flash memory. Refer to the qualification report for the actual data. The following possible failure modes should be considered to implement a highly reliable system. In the case of status read failure after erase or program, block replacement should be done. Because program status fail during a page program does not affect the data of the other pages in the same block, block replacement can be executed with a page-sized buffer by finding an erased empty block and reprogramming the current target data and copying the rest of the replaced block. To improve the efficiency of memory space, it is recommended that the read or verification failure due to single bit error be reclaimed by ECC without any block replacement. The said additional block failure rate does not include those reclaimed blocks.

Failure Mode		Detection and Countermeasure sequence
	Erase Failure	Status Read after Erase> Block Replacement
Write	Program Failure	Status Read after Program> Block Replacement Read back (Verify after Program)> Block Replacement or ECC Correction
Read Single Bit Failure		Verify ECC -> ECC Correction

ECC : Error Correcting Code --> Hamming Code etc.
Example) 1bit correction & 2bit detection

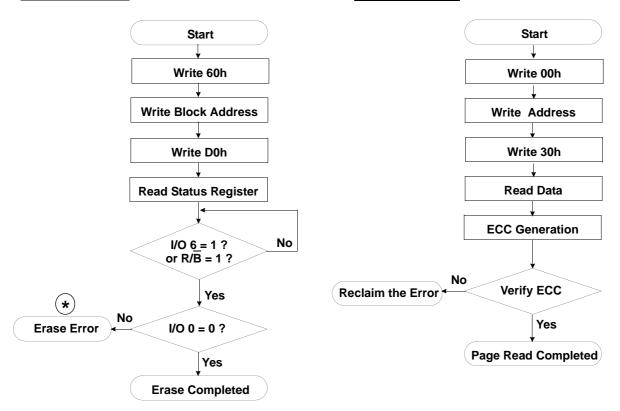
Program Flow Chart



NAND Flash Technical Notes (Continued)

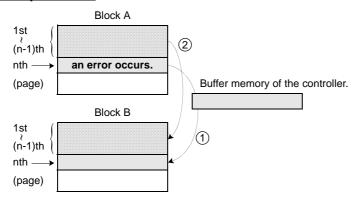
Erase Flow Chart

Read Flow Chart



* : If erase operation results in an error, map out the failing block and replace it with another block.

Block Replacement



* Step1

When an error happens in the nth page of the Block 'A' during erase or program operation.

* Step2

Copy the nth page data of the Block 'A' in the buffer memory to the nth page of another free block. (Block 'B')

* Step3

Then, copy the data in the 1st \sim (n-1)th page to the same location of the Block 'B'.

* Step4

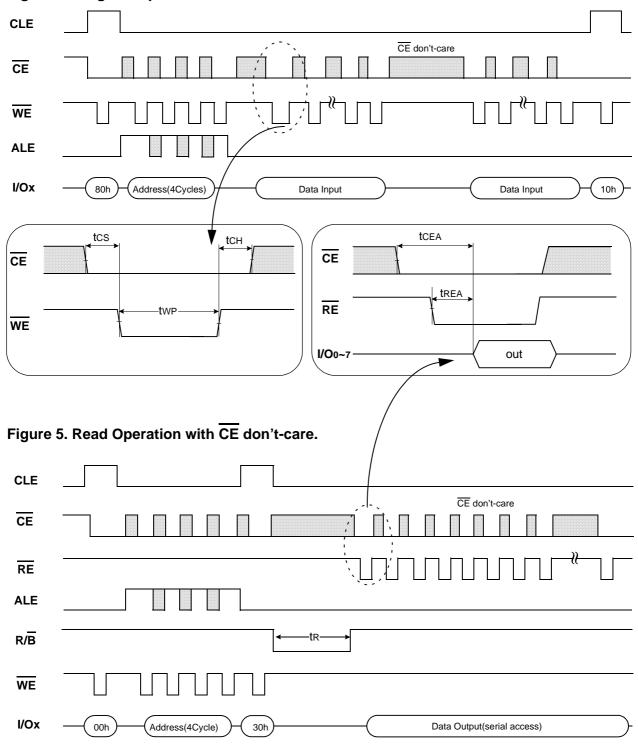
Do not further erase Block 'A' by creating an 'invalid Block' table or other appropriate scheme.



System Interface Using $\overline{\text{CE}}$ don't-care.

For an easier system interface, $\overline{\text{CE}}$ may be inactive during the data-loading or serial access as shown below. The internal 2112byte data registers are utilized as separate buffers for this operation and the system design gets more flexible. In addition, for voice or audio applications which use slow cycle time on the order of u-seconds, de-activating $\overline{\text{CE}}$ during the data-loading and serial access would provide significant savings in power consumption.

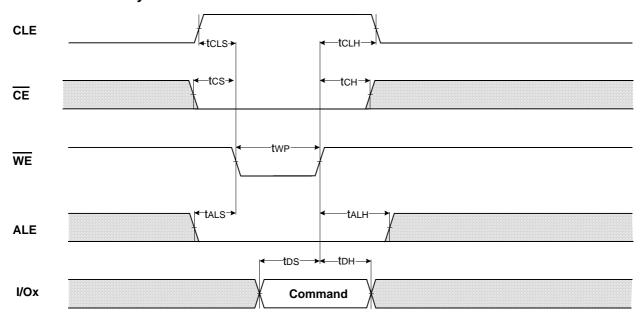
Figure 4. Program Operation with CE don't-care.



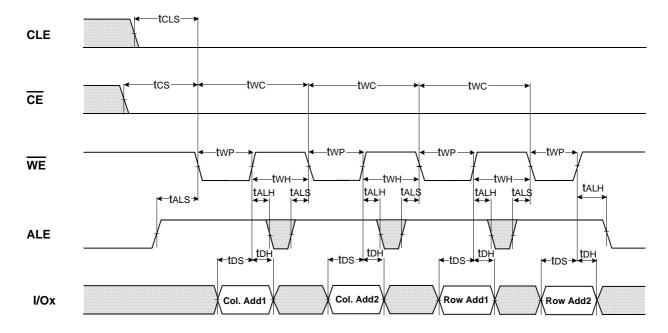
NOTE

Device	1/0	DATA	ADDRESS			
Device	I/Ox	Data In/Out	Col. Add1	Col. Add2	Row Add1	Row Add2
K9F1G08X0A	I/O 0 ~ I/O 7	~2112byte	A0~A7	A8~A11	A12~A19	A20~A27

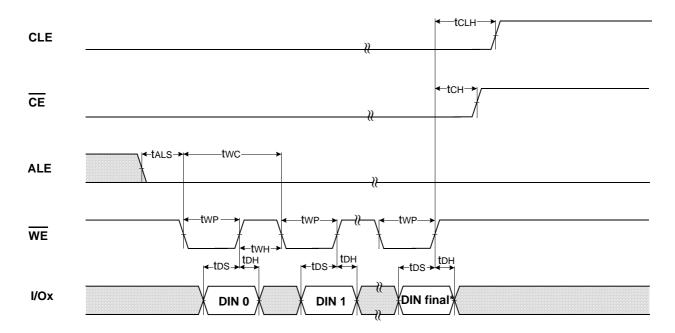
Command Latch Cycle



Address Latch Cycle

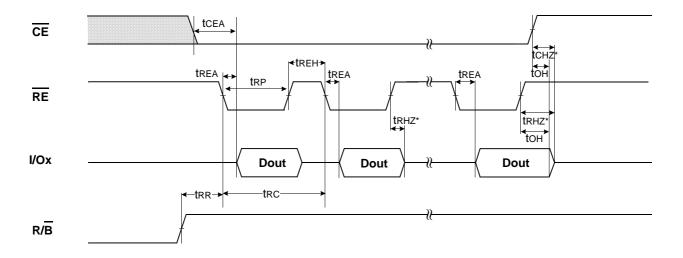


Input Data Latch Cycle



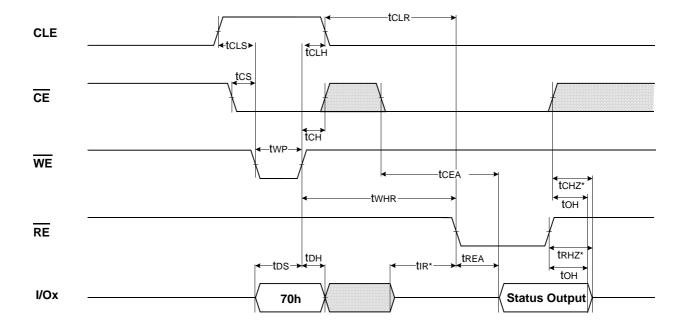
NOTES: DIN final means 2112

Serial Access Cycle after Read(CLE=L, WE=H, ALE=L)

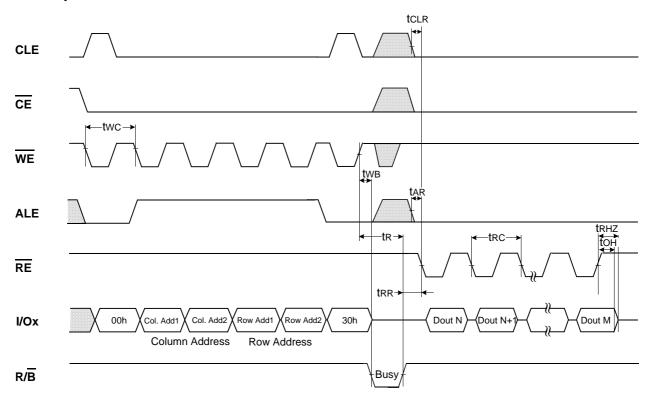


NOTES: Transition is measured $\pm 200 \text{mV}$ from steady state voltage with load. This parameter is sampled and not 100% tested.

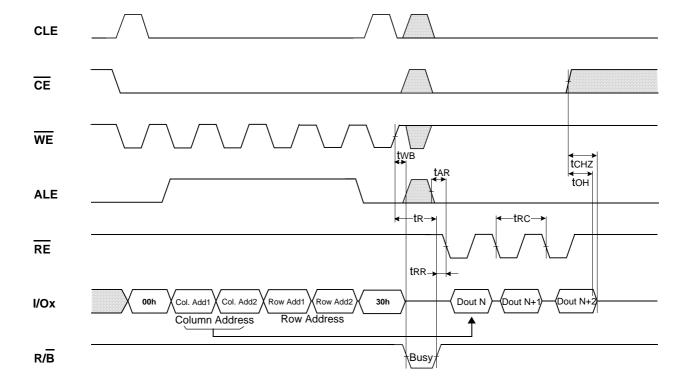
Status Read Cycle

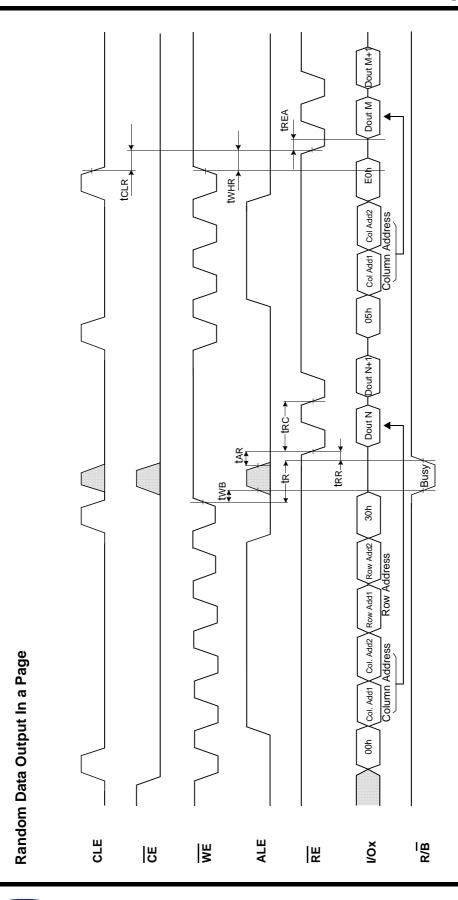


Read Operation



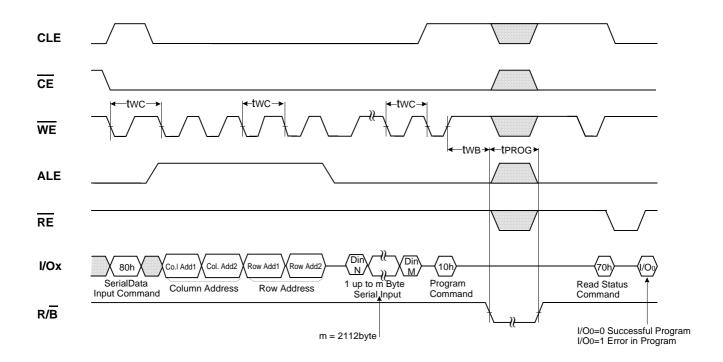
Read Operation(Intercepted by $\overline{\text{CE}}$)



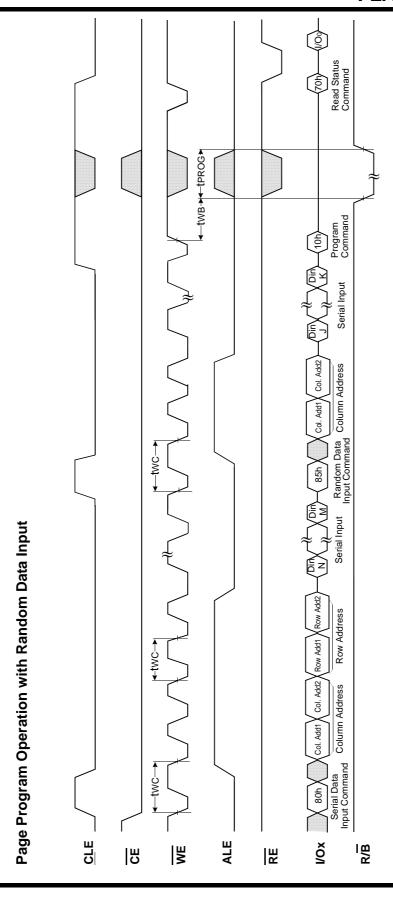




Page Program Operation







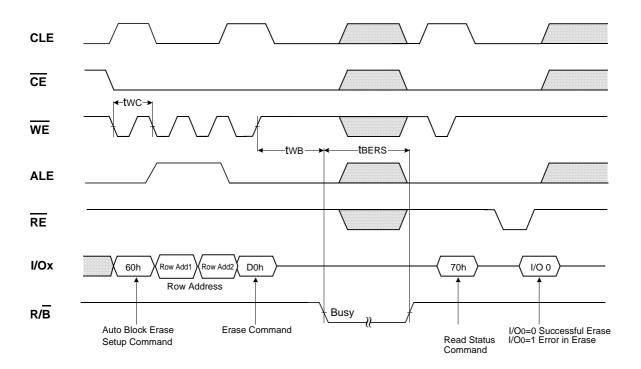


I/Oo=0 Successful Program I/Oo=1 Error in Program Read Status Command ٥ ¥ € E M B M Col Add1 Col Add2 Row Add1 Row Add2 Data 1 Copy-Back Data Input Command Copy-Back Program Operation with Random Data Input 85h 35h (Row Add2) Column Address Row Address Col Add1 Col Add2 Row Add1 ←twc-CLE RBI WE <u>×</u> 빙 RE



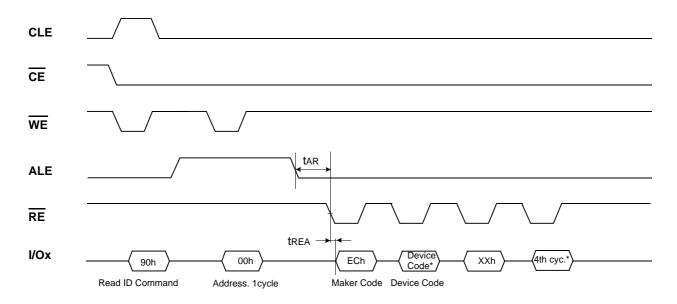
(John) ₽ P Last Page Input & Program 15h Address & Data Input tcbsy 15h) tCBSY: max. 700us Cache Program Operation (available only within a block) (15h) 80h Address & 15h Data Input Col Add1,2 & Row Add1,2 Data Max. 63 times repeatable Ex.) Cache Program Serial Data Column Address Col Add2 Col Add1 RBI <u>ŏ</u> Input Command 80h CLE ALE š WE S R

BLOCK ERASE OPERATION





Read ID Operation



Device	Device Code*(2nd Cycle)	4th Cycle*
K9F1G08Q0A	A1h	15h
K9F1G08D0A	F1h	15h
K9F1G08U0A	F1h	15h

ID Defintition Table

90 ID: Access command = 90H

	Description
1st Byte	Maker Code
2 nd Byte	Device Code
3 rd Byte	Don't care
4 th Byte	Page Size, Block Size, Spare Size, Organization, Serial access minimum



4th ID Data

	Description	1/07	1/06	1/05 1/04	I/O3	I/O2	I/O1	I/O0
Page Size (w/o redundant area)	1KB 2KB Reserved Reserved						0 0 1 1	0 1 0 1
Blcok Size (w/o redundant area)	64KB 128KB 256KB Reserved			0 0 0 1 1 0 1 1				
Redundant Area Size (byte/512byte)	8 16					0		
Organization	x8 x16		0					
Serial Access minimum	50ns 30ns Reserved Reserved	0 0 1 1			0 1 0 1			



Device Operation

PAGE READ

Upon initial device power up, the device defaults to Read mode. This operation is also initiated by writing 00h and 30h to the command register along with four address cycles. In two consecutive read operations, the second one doesn't need 00h command, which four address cycles and 30h command initiates that operation. Two types of operations are available: random read, serial page read The random read mode is enabled when the page address is changed. The 2112 bytes of data within the selected page are transferred to the data registers in less than $25\mu s(tR)$. The system controller can detect the completion of this data transfer(tR) by analyzing the output of R/B pin. Once the data in a page is loaded into the data registers, they may be read out in 50ns(1.8V device: 80ns) cycle time by sequentially pulsing RE. The repetitive high to low transitions of the RE clock make the device output the data starting from the selected column address up to the last column address.

The device may output random data in a page instead of the consecutive sequential data by writing random data output command. The column address of next data, which is going to be out, may be changed to the address which follows random data output command. Random data output can be operated multiple times regardless of how many times it is done in a page.

Figure 6. Read Operation

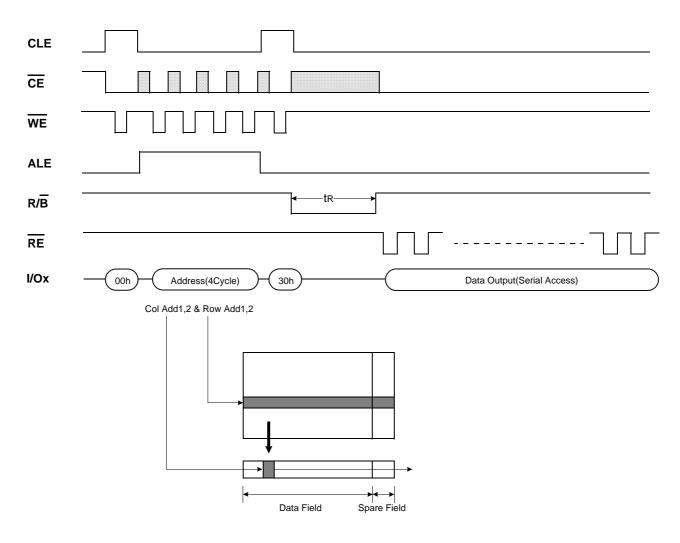
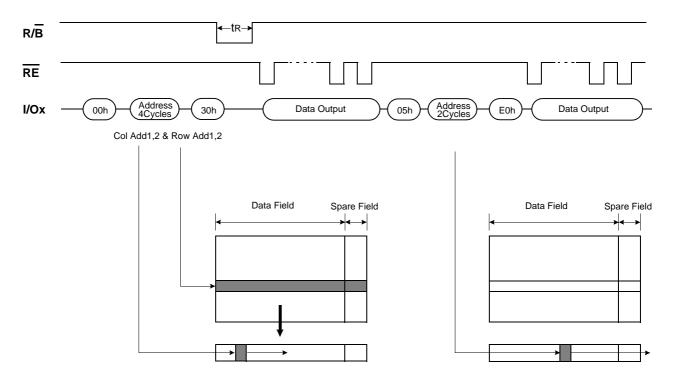




Figure 7. Random Data Output In a Page



PAGE PROGRAM

The device is programmed basically on a page basis, but it does allow multiple partial page programing of a word or consecutive bytes up to 2112, in a single page program cycle. The number of consecutive partial page programming operation within the same page without an intervening erase operation must not exceed 4 times for main array(1time/512byte) and 4 times for spare array(1time/16byte). The addressing should be done in sequential order in a block. A page program cycle consists of a serial data loading period in which up to 2112bytes of data may be loaded into the data register, followed by a non-volatile programming period where the loaded data is programmed into the appropriate cell.

The serial data loading period begins by inputting the Serial Data Input command(80h), followed by the four cycle address inputs and then serial data loading. The words other than those to be programmed do not need to be loaded. The device supports random data input in a page. The column address of next data, which will be entered, may be changed to the address which follows random data input command(85h). Random data input may be operated multiple times regardless of how many times it is done in a page.

The Page Program confirm command(10h) initiates the programming process. Writing 10h alone without previously entering the serial data will not initiate the programming process. The internal write state controller automatically executes the algorithms and timings necessary for program and verify, thereby freeing the system controller for other tasks. Once the program process starts, the Read Status Register command may be entered to read the status register. The system controller can detect the completion of a program cycle by monitoring the R/B output, or the Status bit(I/O 6) of the Status Register. Only the Read Status command and Reset command are valid while programming is in progress. When the Page Program is complete, the Write Status Bit(I/O 0) may be checked(Figure 8). The internal write verify detects only errors for "1"s that are not successfully programmed to "0"s. The command register remains in Read Status command mode until another valid command is written to the command register.

Figure 8. Program & Read Status Operation

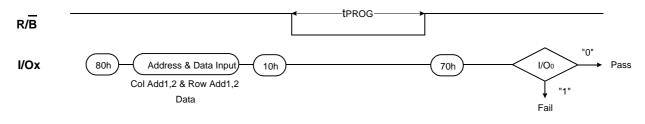
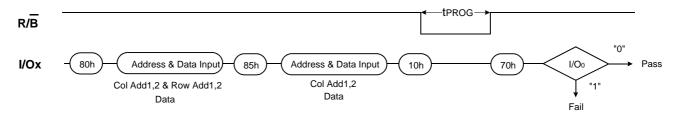




Figure 9. Random Data Input In a Page

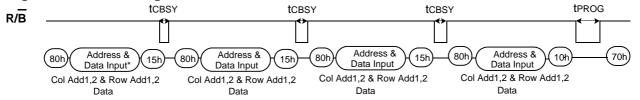


Cache Program

Cache Program is an extension of Page Program, which is executed with 2112byte data registers, and is available only within a block. Since the device has 1 page of cache memory, serial data input may be executed while data stored in data register are programmed into memory cell.

After writing the first set of data up to 2112byte into the selected cache registers, Cache Program command (15h) instead of actual Page Program (10h) is inputted to make cache registers free and to start internal program operation. To transfer data from cache registers to data registers, the device remains in Busy state for a short period of time(tCBSY) and has its cache registers ready for the next data-input while the internal programming gets started with the data loaded into data registers. Read Status command (70h) may be issued to find out when cache registers become ready by polling the Cache-Busy status bit(I/O 6). Pass/fail status of only the previouse page is available upon the return to Ready state. When the next set of data is inputted with the Cache Program command, tCBSY is affected by the progress of pending internal programming. The programming of the cache registers is initiated only when the pending program cycle is finished and the data registers are available for the transfer of data from cache registers. The status bit(I/O5) for internal Ready/Busy may be polled to identify the completion of internal programming. If the system monitors the progress of programming only with R/B, the last page of the target programming sequence must be programmed with actual Page Program command (10h).

Figure 10. Cache Program (available only within a block)





NOTE: Since programming the last page does not employ caching, the program time has to be that of Page Program. However, if the previous program cycle with the cache data has not finished, the actual program cycle of the last page is initiated only after completion of the previous cycle, which can be expressed as the following formula.

tPROG= Program time for the last page+ Program time for the (last -1)th page
- (Program command cycle time + Last page data loading time)

Copy-Back Program

The copy-back program is configured to quickly and efficiently rewrite data stored in one page without utilizing an external memory. Since the time-consuming cycles of serial access and re-loading cycles are removed, the system performance is improved. The benefit is especially obvious when a portion of a block is updated and the rest of the block also need to be copied to the newly assigned free block. The operation for performing a copy-back program is a sequential execution of page-read without serial access and copying-program with the address of destination page. A read operation with "35h" command and the address of the source page moves the whole 2112byte data into the internal data buffer. As soon as the device returns to Ready state, Page-Copy Data-input command (85h) with the address cycles of destination page followed may be written. The Program Confirm command (10h) is required to actually begin the programming operation. Data input cycle for modifying a portion or multiple distant portions of the source page is allowed as shown in Figure 12. "When there is a program-failure at Copy-Back operation, error is reported by pass/fail status. But if the source page has a bit error for charge loss, accumulated copy-back operations could also accumulate bit errors. For this reason, two bit ECC is recommended for copy-back operation."

Figure 11. Page Copy-Back program Operation

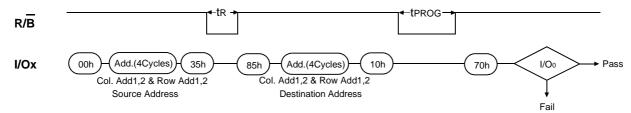
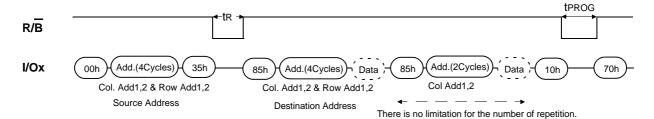


Figure 12. Page Copy-Back program Operation with Random Data Input



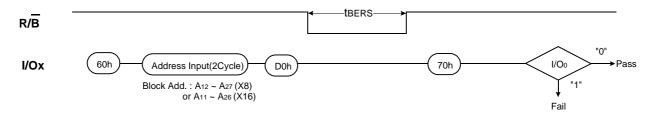


BLOCK ERASE

The Erase operation is done on a block basis. Block address loading is accomplished in two cycles initiated by an Erase Setup command(60h). Only address A₁₈ to A₂₇ is valid while A₁₂ to A₁₇ is ignored. The Erase Confirm command(D0h) following the block address loading initiates the internal erasing process. This two-step sequence of setup followed by execution command ensures that memory contents are not accidentally erased due to external noise conditions.

At the rising edge of $\overline{\text{WE}}$ after the erase confirm command input, the internal write controller handles erase and erase-verify. When the erase operation is completed, the Write Status Bit(I/O 0) may be checked. Figure 13 details the sequence.

Figure 13. Block Erase Operation



READ STATUS

The device contains a Status Register which may be read to find out whether program or erase operation is completed, and whether the program or erase operation is completed successfully. After writing $\underline{70}$ h command to the command register, a read cycle outputs the content of the Status Register to the I/O pins on the falling edge of \overline{CE} or \overline{RE} , whichever occurs last. This two line control allows the system to poll the progress of each device in multiple memory connections even when R/\overline{B} pins are common-wired. \overline{RE} or \overline{CE} does not need to be toggled for updated status. Refer to table 2 for specific Status Register definitions. The command register remains in Status Read mode until further commands are issued to it. Therefore, if the status register is read during a random read cycle, the read command(00h) should be given before starting read cycles.

Table2. Read Staus Register Definition

I/O No.	Page Program	Block Erase	Cache Prorgam	Read	De	finition
I/O 0	Pass/Fail	Pass/Fail	Pass/Fail(N)	Not use	Pass : "0"	Fail : "1"
I/O 1	Not use	Not use	Pass/Fail(N-1)	Not use	Pass : "0"	Fail : "1"
I/O 2	Not use	Not use	Not use	Not use	"0"	
I/O 3	Not Use	Not Use	Not Use	Not Use	"0"	
I/O 4	Not Use	Not Use	Not Use	Not Use	"0"	
I/O 5	Ready/Busy	Ready/Busy	True Ready/Busy	Ready/Busy	Busy : "0"	Ready : "1"
I/O 6	Ready/Busy	Ready/Busy	Ready/Busy	Ready/Busy	Busy : "0"	Ready : "1"
I/O 7	Write Protect	Write Protect	Write Protect	Write Protect	Protected:"0"	Not Protected:"1"
I/O 8~15 (X16 device only)	Not use	Not use	Not use	Not use	Don't -care	

NOTE: 1. True Ready/Busy represents internal program operation status which is being executed in cache program mode.

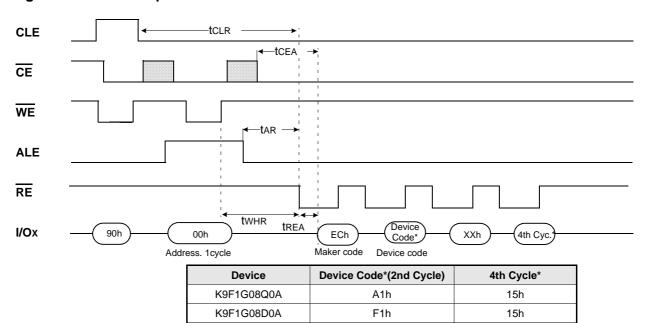
2. I/Os defined 'Not use' are recommended to be masked out when Read Status is being executed.



Read ID

The device contains a product identification mode, initiated by writing 90h to the command register, followed by an address input of 00h. Four read cycles sequentially output the manufacturer code(ECh), and the device code and XXh, 4th cycle ID, respectively. The command register remains in Read ID mode until further commands are issued to it. Figure 14 shows the operation sequence.

Figure 14. Read ID Operation



RESET

The device offers a reset feature, executed by writing FFh to the command register. When the device is in Busy state during random read, program or erase mode, the reset operation will abort these operations. The contents of memory cells being altered are no longer valid, as the data will be partially programmed or erased. The command register is cleared to wait for the next command, and the Status Register is cleared to value C0h when $\overline{\text{WP}}$ is high. Refer to table 3 for device status after reset operation. If the device is already in reset state a new reset command will be accepted by the command register. The R/B pin transitions to low for tRST after the Reset command is written. Refer to Figure 15 below.

F1h

15h

K9F1G08U0A

Figure 15. RESET Operation

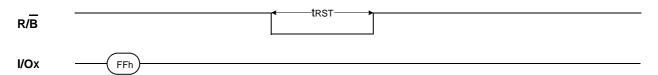


Table3. Device Status

	After Po	After Reset	
PRE status	High	Waiting for next command	
Operation Mode	First page data access is ready	00h command is latched	Waiting for flexi command



READY/BUSY

The device has a R/\overline{B} output that provides a hardware method of indicating the completion of a page program, erase and random read completion. The R/\overline{B} pin is normally high but transitions to low after program or erase command is written to the command register or random read is started after address loading. It returns to high when the internal controller has finished the operation. The pin is an open-drain driver thereby allowing two or more R/\overline{B} outputs to be Or-tied. Because pull-up resistor value is related to $tr(R/\overline{B})$ and current drain during busy(ibusy) , an appropriate value can be obtained with the following reference chart(Fig 16). Its value can be determined by the following guidance.

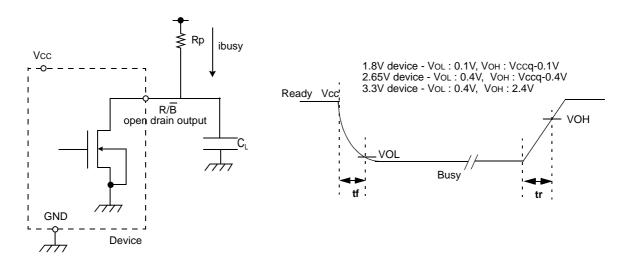
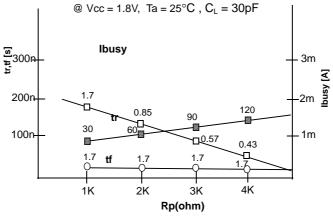
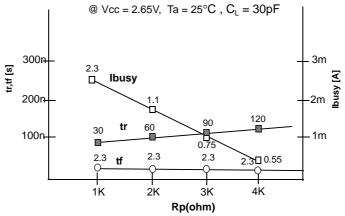
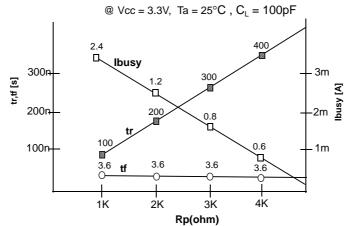


Figure 16. Rp vs tr ,tf & Rp vs ibusy







Rp value guidance

$$Rp(min, 1.8V part) = \frac{Vcc(Max.) - VoL(Max.)}{IoL + \Sigma IL} = \frac{1.85V}{3mA + \Sigma IL}$$

$$Rp(min, 2.65V part) = \frac{Vcc(Max.) - VoL(Max.)}{IoL + \Sigma IL} = \frac{2.5V}{3mA + \Sigma IL}$$

$$Rp(min, 3.3V part) = \frac{Vcc(Max.) - VoL(Max.)}{IoL + \Sigma IL} = \frac{3.2V}{8mA + \Sigma IL}$$

where IL is the sum of the input currents of all devices tied to the R/ \overline{B} pin. Rp(max) is determined by maximum permissible limit of tr

Data Protection & Power up sequence

The device is designed to offer protection from any involuntary program/erase during power-transitions. An internal voltage detector disables all functions whenever Vcc is below about 1.1V(1.8V device), 1.8V(2.65V device), 2V(3.3V device). \overline{WP} pin provides hardware protection and is recommended to be kept at V_{IL} during power-up and power-down. A recovery time of minimum 10 μ s is required before internal circuit gets ready for any command sequences as shown in Figure 17. The two step command sequence for program/erase provides additional software protection.

Figure 17. AC Waveforms for Power Transition

