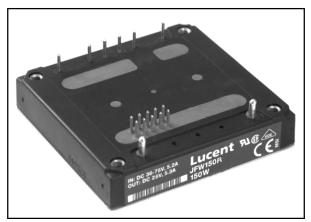


# JFW050R, JFW075R, JFW100R, JFW150R Power Modules: dc-dc Converters; 36 to 75 Vdc Input; 28 Vdc Output; 50 W to 150 W



The JFW-Series Power Modules use advanced, surface-mount technology and deliver high-quality, efficient, compact dc-dc conversion.

# **Applications**

- Redundant and/or distributed power architectures
- Workstations
- EDP equipment
- Telecommunications

# **Options**

- Choice of primary remote on/off logic configurations
- Delayed current-limit shutdown

# **Description**

The JFW-Series Power Modules are dc-dc converters that operate over an input voltage range of 36 Vdc to 75 Vdc and provide a precisely regulated dc output. The output is fully isolated from the input, allowing versatile polarity configurations and grounding connections. The modules have maximum power ratings from 50 W to 150 W at typical full-load efficiencies of 90%.

The sealed modules have metal baseplates for excellent thermal performance. Threaded-through holes are provided for easy mounting or adding a heat sink for high-temperature applications. Listed above are the enhanced features for convenience and flexibility in redundant and/or distributed power applications.

#### **Features**

- Small size: 61.0 mm x 57.9 mm x 12.7 mm (2.40 in. x 2.28 in. x 0.50 in.)
- High power density
- High efficiency: 90% typical
- Low output noise
- Constant frequency
- Metal baseplate
- 2:1 input voltage range
- Anti-rollback circuit
- Synchronization
- Forced load sharing (parallelable)
- Current monitor
- Current-limit set-point adjustment
- Overvoltage shutdown set-point adjustment
- Power good signal
- Thermal warning signal
- Overtemperature protection
- Remote sense
- Primary and secondary remote on/off
- Adjustable output voltage
- Case ground pin
- Parallelable with FW250R1, FW300R1
- *UL\** Recognized, *CSA*<sup>†</sup> Certified, and VDE Licensed
- CE mark meets 73/23/EEC and 93/68/EEC directives<sup>‡</sup>
- \* *UL* is a registered trademark of Underwriters Laboratories, Inc. † *CSA* is a registered trademark of Canadian Standards Assn.
- ‡This product is intended for integration into end-use equipment. All the required procedures for CE marking of end-use equipment should be followed. (The CE mark is placed on selected products.)

# **Absolute Maximum Ratings**

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only. Functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the data sheet. Exposure to absolute maximum ratings for extended periods can adversely affect device reliability.

Parameter	Symbol	Min	Max	Unit
Input Voltage	Vı	_	80	V
I/O Isolation Voltage	_	_	1500	Vdc
Operating Case Temperature (See Thermal Considerations section.)	Тс	-40	100	°C
Storage Temperature	Tstg	<b>-</b> 55	125	°C

# **Electrical Specifications**

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions.

**Table 1. Input Specifications** 

Parameter	Symbol	Min	Тур	Max	Unit
Operating Input Voltage	Vı	36	48	75	Vdc
Maximum Input Current					
(V <sub>I</sub> = 0 V to 75 V; Io = Io, max; see Figure 2.):					
JFW050R	II, max	<del>_</del>	_	1.7	A
JFW075R	II, max	_		2.6	A
JFW100R	II, max	_	_	3.5	A
JFW150R	II, max	_	_	5.2	Α
Inrush Transient	i <sup>2</sup> t	_	_	1.0	A <sup>2</sup> s
Input Reflected-ripple Current, Peak-to-peak	_	_	5		mAp-p
(5 Hz to 20 MHz, 12 μH source impedance;					
see Figure 15.)					
Input Ripple Rejection (120 Hz)	_		60	_	dB

#### **Fusing Considerations**

#### CAUTION: This power module is not internally fused. An input line fuse must always be used.

This encapsulated power module can be used in a wide variety of applications, ranging from simple stand-alone operation to an integrated part of a sophisticated power architecture. To preserve maximum flexibility, internal fusing is not included; however, to achieve maximum safety and system protection, always use an input line fuse. The safety agencies require a normal-blow, dc fuse with a maximum rating of 20 A (see Safety Considerations section). Based on the information provided in this data sheet on inrush energy and maximum dc input current, the same type of fuse with a lower rating can be used. Refer to the fuse manufacturer's data for further information.

# **Electrical Specifications** (continued)

**Table 2. Output Specifications** 

Parameter	Device	Symbol	Min	Тур	Max	Unit
Output Voltage Set Point	All	Vo, set	27.49	28.0	28.50	Vdc
$(V_1 = 48 \text{ V}; I_0 = I_0, \text{max}; T_c = 25 \text{ °C})$						
Output Voltage (Over all operating input voltage,	All	Vo	27.16	_	28.84	Vdc
resistive load, and temperature conditions until						
end of life; see Figure 17.)						
Output Regulation:						
Line (V <sub>I</sub> = 36 V to 75 V)	All	_	_	0.01	0.1	%
Load (Io = Io, min to Io, max)	All	_	_	0.05	0.2	%
Temperature (Tc = -40 °C to +100 °C)	All	_	_	100	300	mV
Output Ripple and Noise Voltage (See Figure						
16.):						.,
RMS	All	_	<del>-</del>	_	150	mVrms
Peak-to-peak (5 Hz to 20 MHz)	All	_		_	400	mVp-p
External Load Capacitance (electrolytic)	All	_	0	_	10,000	μF
Output Current	JFW050Rx	lo	0.3	_	1.8	Α
(At lo < lo, min, the module may exceed output	JFW075Rx	lo	0.3	_	2.7	Α
ripple specifications.)	JFW100Rx	lo	0.3	_	3.6	A
	JFW150Rx	lo	0.3	_	5.3	Α
Output Current-limit Inception	JFW050Rx	IO, cli	_	2.0	2.4	A
(untrimmed; Vo = 90% of Vo, nom)	JFW075Rx	IO, cli	_	3.1	3.5	A
	JFW100Rx	IO, cli	_	4.1	4.7	A
0 + +0 + + + +0 + +0 + +0 +0 +0 +0 +0 +0	JFW150Rx	IO, cli	_	6.1	6.9	A
Output Short-circuit Current (Vo = 250 mV)	All	_	<u> </u>	170	_	%IO, max
Efficiency	JFW050Rx	η	TBD	TBD	_	%
(V <sub>I</sub> = 48 V; Io = Io, max; Tc = 70 °C; see Figure	JFW075Rx	η	TBD	TBD	_	%
17.)	JFW100Rx	η	TBD	TBD	_	%
	JFW150Rx	η	88	90	_	%
Dynamic Response						
$(\Delta Io/\Delta t = 1 \text{ A}/10 \text{ µs}, V_I = 48 \text{ V}, T_C = 25 ^{\circ}\text{C})$ :						
Load Change from Io = 50% to 75% of Io, max: Peak Deviation	All			3		%Vo, set
Settling Time (Vo < 10% of peak deviation)	All			300		1 1
Load Change from Io = 50% to 25% of Io, max:		_	_	300		μs
Peak Deviation	All	_	_	3	_	%Vo, set
Settling Time (Vo < 10% of peak deviation)	All	_	_	300	_	µs

# **Table 3. Isolation Specifications**

Parameter	Min	Тур	Max	Unit
Isolation Capacitance	_	2500	_	pF
Isolation Resistance	10	_	_	ΜΩ

# **General Specifications**

Parameter	Min	Тур	Max	Unit
Calculated MTBF (Io = 80% of Io, max; Tc = 40 °C)		2,000,000		hr
Weight	_	_	100 (3.5)	g (oz.)

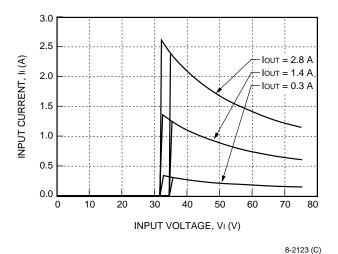
# **Feature Specifications**

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions and Design Considerations sections for further information.

Parameter	Symbol	Min	Тур	Max	Unit
Remote On/Off Signal Interface					
(VI = 0 V to 75 V; open collector or equivalent compatible; signal referenced to VI(–) terminal; see Figure 18 and					
Feature Descriptions.):					
JFWxxxR1 Preferred Logic:					
Both Primary and Secondary Referenced Remote On/Off:					
Logic Low—Module On Logic High—Module Off					
JFWxxxR Optional Logic (optional for primary referenced					
remote on/off only):					
Primary Referenced Remote On/Off:					
Logic Low—Module Off Logic High—Module On					
Secondary Referenced Remote On/Off:					
Logic Low—Module On					
Logic High—Module Off					
Logic Low: lon/off = 1.0 mA	Von/off	0	_	1.2	V
Von/off = 0.0 V	Ion/off	l —	_	1.0	mA
Logic High (open collector):	\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \			4.5	V
Ion/off = 0.0 µA	Von/off Ion/off		_	15 50	μA
Leakage Current Turn-on Time	—	_	20	35	ms
(Io = 80% of Io, max; Vo within ±1% of steady state)					
Output Voltage Adjustment (See Feature Descriptions.):					
Output Voltage Remote-sense Range	_	_	_	0.5	V
Output Voltage Set-point Adjustment (trim) Range (Note: Ensure that the combination of remote-sense and trim	_	60	_	102	%VO, nom
do not exceed 28.5 V on the output.)					
Output Overvoltage Shutdown	_	4.0		5.0	V
Output Current Monitor (Io = max, Tc = 70 °C):					
JFW050Rx	IO, mon	l —	2.28	_	V/A
JFW075Rx	IO, mon	_	1.52	_	V/A V/A
JFW100Rx JFW150Rx	IO, mon IO, mon		1.14 0.77		V/A V/A
Synchronization:	10, 11011		0		7// 1
Clock Amplitude	_	4.00	_	5.00	V
Clock Pulse Width	_	0.4	_	_	μs
Fan-out Capture Frequency Range		425		1 575	— kHz
Overtemperature Shutdown (See Figure 25.)	Tc	423	105	- 373 	°C
Current Share Accuracy	_		100	_	%IO, rated
Power Good Output			10		7010, 14104
(Open collector output: low level indicates power good.):					
Output Sink Current (Vo ≤ 1.5 V)	_	_	_	50	mA
Maximum Voltage High-state Internal Impedance to Ground	_	_	200	36	V V
· · · · · · · · · · · · · · · · · · ·			200	_	kΩ
Thermal Warning (Open collector output; low level indicates overtemperature					
shutdown is imminent.):					
Output Sink Current (Vo ≤ 1.5 V)	-	—	_	6	mΑ
Maximum Voltage High-state Internal Impedance to Ground	_	—	200	36	V kΩ
Overvoltage Shutdown Threshold Adjustment Range	<del>-</del>	50	200	100	%VO, clamp, nom
Overcurrent Threshold Adjustment Range		10	<u> </u>	100	%IO, cli, nom
Overcurrent Shutdown Delay (optional)			4		·
Overcurrent Shutuown Delay (optional)		_	4		S

## **Characteristic Curves**

The following figures provide typical characteristics for the JFW075R and JFW150R power module. The figures are applicable to both on/off configurations.



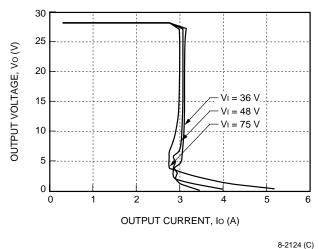
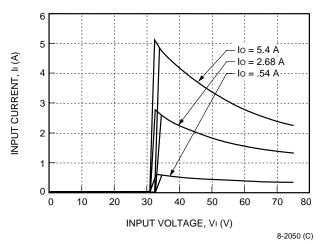


Figure 1. Typical JFW075R Input Characteristics at Room Temperature, lo = Full Load

Figure 3. Typical JFW075R Output Characteristics at Room Temperature, VIN = 48 V





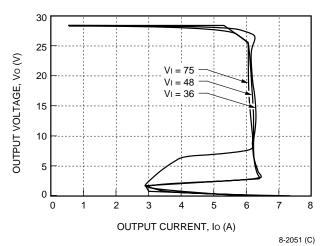


Figure 4. Typical JFW150R Output Characteristics at Room Temperature, VIN = 48 V

# Characteristic Curves (continued)

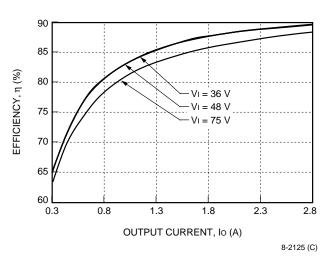


Figure 5. Typical JFW075R Converter Efficiency vs.
Output Current at Room Temperature

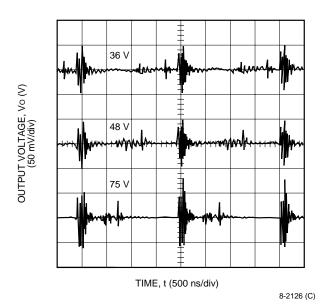


Figure 7. Typical JFW075R Output Ripple Voltage at Room Temperature, 36 Vdc to 75 V Input, and 30 A Output

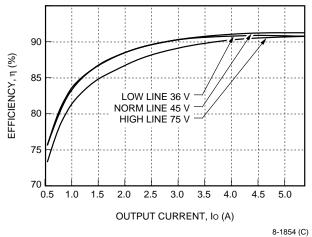


Figure 6. Typical JFW150R Converter Efficiency vs.
Output Current at Room Temperature

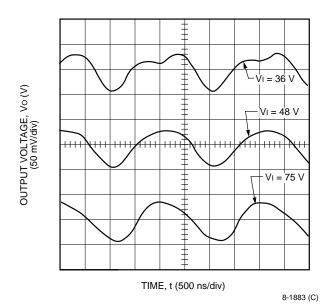


Figure 8. Typical JFW150R Output Ripple Voltage at Room Temperature, 36 Vdc to 75 V Input, and 30 A Output

# Characteristic Curves (continued)

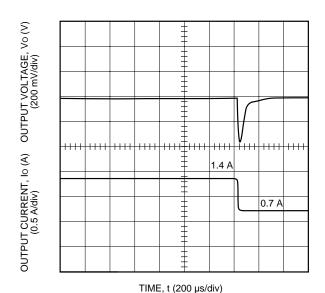
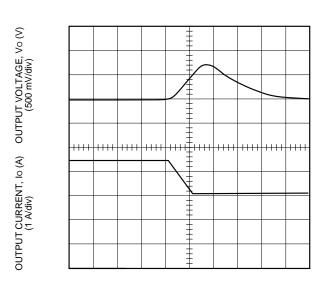


Figure 9. Typical JFW075R Transient Response to Step Decrease in Load from 50% to 25% of Full Load at Room Temperature and 36 Vdc to 75 V Input (Waveform Averaged to Eliminate Ripple Component.)



TIME, t (20 µs/div)

8-1882 (C)

OUTPUT CURRENT, Io (A) OUTPUT VOLTAGE, Vo (V) (1 A/div) (500 mV/div)

8-2127 (C)

Figure 10. Typical JFW150R Transient Response to Step Decrease in Load from 50% to 25% of Full Load at Room Temperature and 36 Vdc to 75 V Input (Waveform Averaged to Eliminate Ripple Component.)

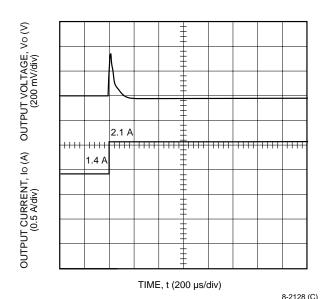


Figure 11. Typical JFW075R Transient Response to Step Increase in Load from 50% to 75% of Full Load at Room Temperature and 36 Vdc to 75 V Input (Waveform Averaged to Eliminate Ripple Component.)

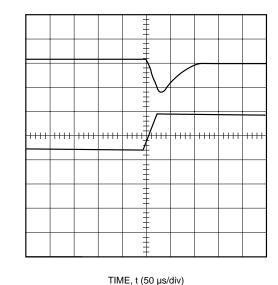


Figure 12. Typical JFW150R Transient Response to Step Increase in Load from 50% to 75% of Full Load at Room Temperature and 36 Vdc to 75 V Input (Waveform Averaged to Eliminate Ripple Component.)

Lucent Technologies Inc.

8-1881 (C)

## Characteristic Curves (continued)

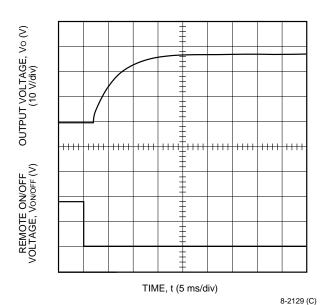


Figure 13. Typical Start-Up from Remote On/Off JFW075R1; lo = Full Load

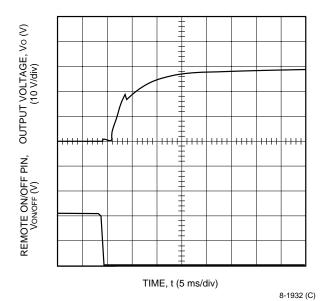
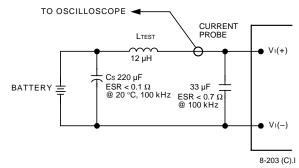


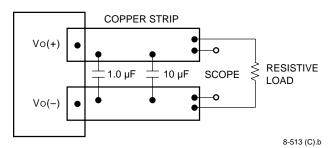
Figure 14. Typical Start-Up from Remote On/Off JFW150R1; lo = Full Load

# **Test Configurations**



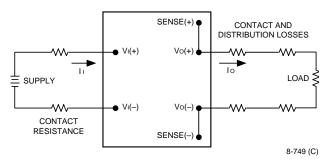
Note: Measure input reflected-ripple current with a simulated source inductance (LTEST) of 12 µH. Capacitor Cs offsets possible battery impedance. Measure current as shown above.

Figure 15. Input Reflected-Ripple Test Setup



Note: Use a 1.0  $\mu$ F ceramic capacitor and a 10  $\mu$ F aluminum or tantalum capacitor. Scope measurement should be made using a BNC socket. Position the load between 51 mm and 76 mm (2 in. and 3 in.) from the module.

Figure 16. Peak-to-Peak Output Noise Measurement Test Setup



Note: All measurements are taken at the module terminals. When socketing, place Kelvin connections at module terminals to avoid measurement errors due to socket contact resistance.

$$\eta = \left(\frac{[Vo(+) - (Vo(-))]Io}{[Vi(+) - (Vi(-))]Ii}\right) \times 100$$

Figure 17. Output Voltage and Efficiency Measurement Test Setup

# **Design Considerations**

#### **Input Source Impedance**

The power module should be connected to a low ac-impedance input source. Highly inductive source impedances can affect the stability of the power module. For the test configuration in Figure 15, a 33  $\mu\text{F}$  electrolytic capacitor (ESR < 0.7  $\Omega$  at 100 kHz) mounted close to the power module helps ensure stability of the unit. For other highly inductive source impedances, consult the factory for further application quidelines.

# **Safety Considerations**

For safety-agency approval of the system in which the power module is used, the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standard, i.e., *UL*-1950, *CSA* 22.2-950, and EN60950.

For the converter output to be considered meeting the requirements of safety extra-low voltage (SELV), one of the following must be true:

- All inputs are SELV and floating, with the output also floating.
- All inputs are SELV and grounded, with the output also grounded.
- Any non-SELV input must be provided with reinforced insulation from any other hazardous voltages, including the ac mains, and must have a SELV reliability test performed on it in combination with the converters. Inputs must meet SELV requirements.

If the input meets extra-low voltage (ELV) requirements, then the converter's output is considered ELV.

The input to these units is to be provided with a maximum 20 A normal-blow fuse in the ungrounded lead.

# **Electrical Considerations**

#### **Current Limit**

To provide protection in a fault (output overload) condition, the unit is equipped with internal current-limiting circuitry and optional delayed shutdown. At the point of current-limit inception, the unit shifts from voltage control to current control. If the output voltage is pulled very low during a severe fault, the current-limit circuit can exhibit either foldback or tailout characteristics (output current decrease or increase). The unit will

operate normally once the output current is brought back into its specified range. If the module has the optional delayed current-limit shutdown, the unit will operate normally once the output current is brought back into its specified range, provided the overcurrent condition is removed before the module shuts down.

The current-limit set point can be reduced by connecting a resistor between the overcurrent trim (OCTRIM) pin and SENSE(–) pin. The resistor value is derived by the following equation:

$$R_{\text{Cl-adj}} = \left(\frac{11 \ \text{Itrim} - 1.15 \ \text{Irated}}{1.15 \ \text{Irated} - \text{Itrim}}\right) \ k\Omega$$

Where:

Rcl-adj is the value of an external resistor between the OCTRIM pin and SENSE(-) pin.

Irated is the output current rating of the module. (not the output current-limit inception).

ltrim is the trimmed value of the output current-limit set point.

# **Feature Descriptions**

#### Remote On/Off

There are two remote on/off signals, a primary referenced signal and a secondary referenced signal. Both signals must be asserted on for the module to deliver output power. If either signal is asserted off, the module will not deliver output power. Both signals have internal pull-up circuits and are designed to interface with an open collector pull-down device. Typically one on/off signal will be permanently enabled by hardwiring it to its return while the other on/off signal is used exclusively for control.

#### **Primary Remote On/Off**

The primary remote on/off signal (ON/OFF) is available with either positive or negative logic. Positive logic turns the module on during a logic high and off during a logic low. Negative logic remote on/off turns the module off during a logic high and on during a logic low. Negative logic (code suffix 1) is the factory-preferred configuration.

To turn the power module on and off, the user must supply a switch to control the voltage between the primary remote on/off terminal ( $V_{On/off, pri}$ ) and the  $V_I(-)$  terminal. The switch can be an open collector or equivalent (see Figure 18). A logic low is  $V_{On/off, pri} = 0$  V to 1.2 V. The maximum  $I_{On/off, pri}$  during a logic low is 1 mA. The switch should maintain a logic-low voltage while sinking 1 mA.

#### Remote On/Off (continued)

During a logic high, the maximum  $V_{on/off, pri}$  generated by the power module is 15 V. The maximum allowable leakage current of the switch at  $V_{on/off, pri} = 15 \text{ V}$  is 50  $\mu\text{A}$ .

If not using the primary remote on/off feature, do one of the following:

- For negative logic, short the ON/OFF pin to V<sub>I</sub>(–).
- For positive logic, leave the ON/OFF pin open.

#### Secondary Remote On/Off

The secondary remote on/off signal (S-ON/OFF pin) is only available with negative logic. The negative logic signal turns the module off during a logic high and on during a logic low. To turn the power module on and off, the user must supply a switch to control the voltage between the S-ON/OFF pin and the SENSE(–) pin (Von/off, sec). The switch can be an open collector or equivalent (see Figure 18). A logic low is Von/off, sec = 0 V to 1.2 V. The maximum lon/off, sec during a logic low is 1 mA. The switch should maintain a logic-low voltage while sinking 1 mA.

During a logic high, the maximum  $V_{on/off, sec}$  generated by the power module is 15 V. The maximum allowable leakage current of the switch at  $V_{on/off, sec} = 15 \text{ V}$  is 50  $\mu\text{A}$ .

If not using the secondary remote on/off feature, short the S-ON/OFF pin to the SENSE(–) pin.

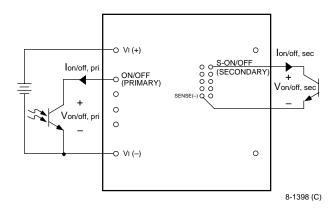


Figure 18. Remote On/Off Implementation

#### Remote Sense

Remote sense minimizes the effects of distribution losses by regulating the voltage at the remote-sense connections. The voltage between the remote-sense pins and the output terminals must not exceed the

output voltage sense range given in the Feature Specifications table, i.e.:

$$[Vo(+) - Vo(-)] - [SENSE(+) - SENSE(-)] \le 0.5 \text{ V}$$

The voltage between the Vo(+) and Vo(-) terminals must not exceed the output overvoltage shutdown voltage. This limit includes any increase in voltage due to remote-sense compensation and output voltage setpoint adjustment (trim), see Figure 19.

For remote-sense operation with multiple paralleled units, see Forced Load Sharing (Parallel Operation) section.

If not using the remote-sense feature to regulate the output at the point of load, then connect SENSE(+) to Vo(+) and SENSE(-) to Vo(-) at the module.

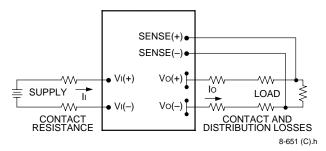


Figure 19. Effective Circuit Configuration for Single-Module Remote-Sense Operation

# **Output Voltage Set-Point Adjustment (Trim)**

Output voltage trim (VoTRIM pin) enables the user to increase or decrease the output voltage set point of a module. This is accomplished by connecting an external resistor between the VoTRIM pin and either the SENSE(+) or SENSE(-) pins. With an external resistor between the VoTRIM and SENSE(-) pins (Radj-down), the output voltage set point (Vo, adj) decreases (see Figure 20).

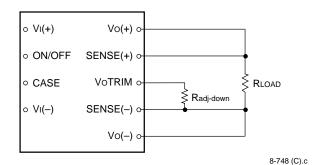


Figure 20. Circuit Configuration to Decrease Output Voltage

# **Output Voltage Set-Point Adjustment (Trim)** (continued)

The following equation determines the required external-resistor value to obtain a percentage output voltage change of  $\Delta$ %.

$$R_{\text{adj-down}} \, = \, \left( \frac{100}{\sqrt[]{\%}} - 2 \right) \, k \Omega$$

The test results for this configuration are displayed in Figure 21. This figure applies to all output voltages.

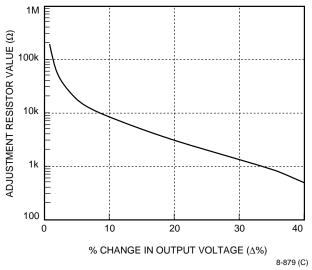


Figure 21. Resistor Selection for Decreased **Output Voltage** 

With an external resistor connected between the VoTRIM and SENSE(+) pins (Radj-up), the output voltage set point (Vo, adj) increases (see Figure 22).

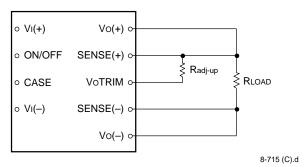


Figure 22. Circuit Configuration to Increase **Output Voltage** 

Note: The output voltage of this module may be increased to a maximum of 0.5 V. The 0.5 V is the combination of both the remote-sense and the output voltage set-point adjustment (trim). Do not exceed 28.5 V between the Vo(+) and Vo(-) terminals.

The following equation determines the required external-resistor value to obtain a percentage output voltage change of  $\Delta$ %.

$$\mathsf{Radj\text{-}up} \ = \ \left( \frac{Vo(100 + \Delta\%)}{1.225\Delta\%} - \frac{(100 + 2\Delta\%)}{\Delta\%} \right) \ k\Omega$$

#### Only trim up to 0.5 V maximum. See note above.

The test results for this configuration are displayed in Figure 23.

The voltage between the Vo(+) and Vo(-) terminals must not exceed the output overvoltage shutdown voltage. This limit includes any increase in voltage due to remote-sense compensation and output voltage setpoint adjustment (trim).

# Output Voltage Set-Point Adjustment (Trim) (continued)

If not using the trim feature, leave the VoTRIM pin open.

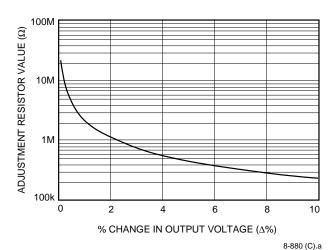


Figure 23. Resistor Selection for Increased Output Voltage

# **Output Overvoltage Shutdown**

The output overvoltage shutdown consists of control circuitry, independent of the primary regulation loop, that monitors the voltage on the output terminals. The control loop of the clamp has a higher voltage set point than the primary loop (see Feature Specifications table). This provides a redundant voltage control that reduces the risk of output overvoltage and latches the converter off if an overvoltage occurs.

Recovery from latched shutdown is accomplished by cycling the dc input power off for at least 1.0 second or by toggling the primary or secondary referenced remote on/off signal for at least 1.0 second.

The overvoltage shutdown set point can be lowered by placing a resistor between the overvoltage trim (OVTRIM) pin and SENSE(–) pin. This feature is useful if the output voltage of the converter has been trimmed down and a corresponding reduction in overvoltage trip point is desired.

The resistance required from a given overvoltage nominal set point is derived from the following equation:

$$Rov-adj = \left(\frac{30.2 - 2 \ Vov-set}{Vov-set - 30.2}\right) \ k\Omega$$

Where:

Rov-adj is the value of an external resistor between the OVTRIM pin and SENSE(–) pin.

Vov-set is the nominal adjusted set point of the overvoltage shutdown threshold.

#### **Module Synchronization**

Any module can be synchronized to any other module or to an external clock using the SYNC IN or SYNC OUT pins. The modules are not designed to operate in a master/slave configuration; that is, if one module fails, the other modules will continue to operate.

#### **SYNC IN Pin**

This pin can be connected either to an external clock or directly to the SYNC OUT pin of another JF-Series or Fx300x module.

If an external clock signal is applied to the SYNC IN pin, the signal must be a 500 kHz (±50 kHz) square wave with a 4 Vp-p amplitude. Operation outside this frequency band will detrimentally affect the performance of the module and must be avoided.

If the SYNC IN pin is connected to the SYNC OUT pin of another module, the connection should be as direct as possible, and the  $V_I(-)$  pins of the modules must be shorted together.

Unused SYNC IN pins should be tied to V<sub>I</sub>(–). If the SYNC IN pin is not used, the module will operate from its own internal clock.

#### **Module Synchronization** (continued)

#### **SYNC OUT Pin**

This pin contains a clock signal referenced to the V<sub>I</sub>(–) pin. The frequency of this signal will equal either the module's internal clock frequency or the frequency established by an external clock applied to the SYNC IN pin.

When synchronizing several modules together, the modules can be connected in a daisy-chain fashion where the SYNC OUT pin of one module is connected to the SYNC IN pin of another module. Each module in the chain will synchronize to the frequency of the first module in the chain.

To avoid loading effects, ensure that the SYNC OUT pin of any one module is connected to the SYNC IN pin of only one module. Any number of modules can be synchronized in this daisy-chain fashion.

# **Forced Load Sharing (Parallel Operation)**

For either redundant operation or additional power requirements, the power module can be configured for parallel operation with forced load sharing (see Figure 24). For a typical redundant configuration, Schottky diodes or an equivalent should be used to protect against short-circuit conditions. Because of the remote sense, the forward-voltage drops across the Schottky diodes do not affect the set point of the voltage applied to the load. For additional power requirements, where multiple units are used to develop combined power in excess of the rated maximum, the Schottky diodes are not needed.

An internal anti-rollback circuit prevents either output voltage from falling more than 1 V below the other during light load operation.

Good layout techniques should be observed for noise immunity. To implement forced load sharing, the following connections must be made:

- The parallel pins of all units must be connected together. The paths of these connections should be as direct as possible.
- All remote-sense pins must be connected to the power bus at the same point. That is, connect all remote-sense (+) pins to the (+) side of the power bus at the same point, and connect all remote-sense (−) pins to the (−) side of the power bus at the same point. Close proximity and directness are necessary for good noise immunity.

■ Add a 1000 pF capacitor across the PARALLEL pin and SENSE(-) pin of each module. Locate the capacitor as close to the module as possible.

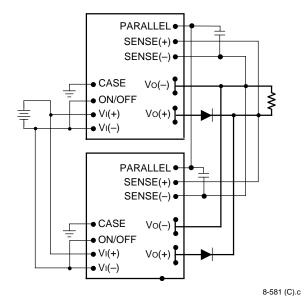


Figure 24. Wiring Configuration for Redundant Parallel Operation

**Current Monitor** 

The current monitor (CURMON) pin produces a dc voltage proportional to the dc output current of the module. The voltage is referenced to the secondary SENSE(–) pin and is typically 4.1 V at rated output current. For paralleling with Fx300x modules, consult the factory for the V/A ratio. The output impedance of this pin is approximately 20  $k\Omega$ , so customer detection circuitry must have a high-impedance input.

#### **Overtemperature Shutdown**

These modules feature an overtemperature protection circuit to safeguard against thermal damage. The circuit shuts down and latches off the module when the maximum case temperature is exceeded. The module can be restarted by cycling the dc input power for at least 1.0 second or by toggling the primary or secondary referenced remote on/off signal for at least 1.0 second.

#### **Power Good Signal**

The power good signal (PWRGOOD pin) is an opencollector, secondary-referenced pin that is pulled low when all five of the following conditions are met:

- 1. The sensed output voltage is greater than half the rated nominal output voltage.
- 2. The overvoltage shutdown latch is not set.
- 3. The thermal shutdown latch is not set.
- 4. The unit is not in current limit.
- 5. Secondary internal bias is present.

There is one situation where the power good signal can be low even though the module has failed. This can occur when the module is paralleled with other modules for additional output power (i.e., the output ORing diodes would not be used). If one module power train stops delivering power (fails), the other paralleled module(s) would provide a voltage at the output pin of the failed module. The failed module would then not detect that its output power was not being delivered. However, in this situation, the current monitor pins of the paralleled modules would indicate that current is not being delivered from one module and that module had failed.

For redundant applications, the ORing diodes would keep the other module voltages from being applied to the failed module output and the power good signal would indicate a failure.

#### **Thermal Warning**

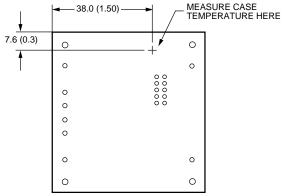
The thermal warning (TEMPWARN) pin is a secondary-referenced, open-collector output that shorts to SENSE(-) a few degrees before the module goes into thermal shutdown. When the module temperature cools, the thermal warning pin will open, but the unit will remain latched off until the input power or the primary or secondary referenced remote on/off is recycled for 1.0 second.

#### **Thermal Considerations**

#### Introduction

The JFW-Series power modules operate in a variety of thermal environments; however, sufficient cooling should be provided to help ensure reliable operation of the units. Heat-dissipating components inside the units

are thermally coupled to the case. Heat is removed by conduction, convection, and radiation to the surrounding environment. Proper cooling can be verified by measuring the case temperature. Peak temperature (Tc) occurs at the position indicated in Figure 25.



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Note: Top view, measurements shown in millimeters and (inches). Pin locations are for reference.

Figure 25. Case Temperature Measurement Location

The temperature at this location should not exceed 100 °C. The output power of the module should not exceed the rated power for the module as listed in the Ordering Information table.

Although the maximum case temperature of the power modules is 100 °C, you can limit this temperature to a lower value for extremely high reliability.

For additional information regarding this module, refer to the Lucent Technologies *Thermal Management JC-, JFC-, JW-, and JFW-Series 50 W to 150 W Board-Mounted Power Modules* Technical Note (TN97-008EPS).

#### **Heat Transfer Without Heat Sinks**

Increasing airflow over the module enhances the heat transfer via convection. Figure 26 shows the maximum power that can be dissipated by the module without exceeding the maximum case temperature versus local ambient temperature (TA) for natural convection through 4 m/s (800 ft./min.).

Note that the natural convection condition was measured at 0.05 m/s to 0.1 m/s (10 ft./min. to 20 ft./min.); however, systems in which this power module may be used typically generate a natural convection airflow rate of 0.3 m/s (60 ft./min.) due to other heat dissipating components in the system. The use of Figure 26 is shown in the following example.

# Thermal Considerations (continued)

#### **Heat Transfer Without Heat Sinks** (continued)

#### Example

What is the minimum airflow necessary for a JFW150R operating at nominal line, an output current of 5.3 A, and a maximum ambient temperature of 40 °C?

#### **Solution**

Given: VI = 54 V

Io = 5.3A  $T_A = 40 \, ^{\circ}C$ 

Determine PD (Use Figure 28.):

 $P_{D} = 15 W$ 

Determine airflow (v) (Use Figure 26.):

v = 1.6 m/s (320 ft./min.)

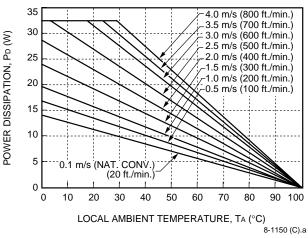


Figure 26. Forced Convection Power Derating with No Heat Sink; Either Orientation

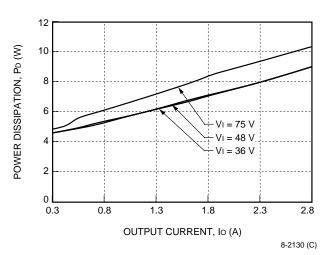


Figure 27. JFW075R Power Dissipation vs. Output
Current

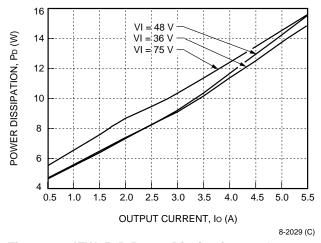


Figure 28. JFW150R Power Dissipation vs. Output
Current

## Thermal Considerations (continued)

#### **Heat Transfer with Heat Sinks**

The power module has through-threaded, M3 x 0.5 mounting holes, which enable heat sinks or cold plates to attach to the module. The mounting torque must not exceed 0.56 N/m (5 in./lb.). For a screw attachment from the pin side, the recommended hole size on the customer's PWB around the mounting holes is  $0.130 \pm 0.005$  inches. If a larger hole is used, the mounting torque from the pin side must not exceed 0.25 N-m (2.2 in.-lb.).

Thermal derating with heat sinks is expressed by using the overall thermal resistance of the module. Total module thermal resistance ( $\theta$ ca) is defined as the maximum case temperature rise ( $\Delta$ Tc,  $_{max}$ ) divided by the module power dissipation (PD):

$$\theta ca = \left[\frac{\Delta Tc, max}{P_D}\right] = \left[\frac{(Tc - T_A)}{P_D}\right]$$

The location to measure case temperature (Tc) is shown in Figure 25. Case-to-ambient thermal resistance vs. airflow for various heat sink configurations is shown in Figure 29. These curves were obtained by experimental testing of heat sinks, which are offered in the product catalog.

These measured resistances are from heat transfer from the sides and bottom of the module as well as the top side with the attached heat sink; therefore, the case-to-ambient thermal resistances shown are generally lower than the resistance of the heat sink by itself. The module used to collect the data in Figure 29 had a thermal-conductive dry pad between the case and the heat sink to minimize contact resistance. The use of Figure 29 is shown in the following example.

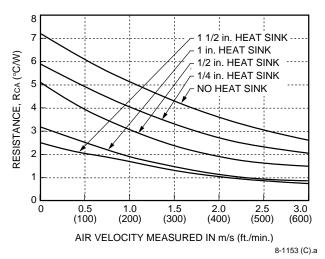


Figure 29. Case-to-Ambient Thermal Resistance Curves; Either Orientation

#### **Example**

If an 85 °C case temperature is desired, what is the minimum airflow necessary? Assume the JFW150R module is operating at nominal line and an output current of 5.3 A, maximum ambient air temperature of 40 °C, and heat sink of 0.5 in.

#### Solution

Given: VI = 54 V

Io = 5.3 A

 $T_A = 40 \, ^{\circ}C$ 

Tc = 85 °C

Heat sink = 0.5 inch.

Determine PD by using Figure 28:

$$P_{D} = 15 \text{ W}$$

Then solve the following equation:

$$\theta ca = \left[\frac{(Tc - TA)}{PD}\right]$$

$$\theta ca = \left[\frac{(85-40)}{15}\right]$$

$$\theta$$
ca = 3 °C/W

Use Figure 29 to determine air velocity for the 0.5 inch heat sink. The minimum airflow necessary for the JFW150R module is about 1.1 m/s (220 ft./min.).

#### Thermal Considerations (continued)

#### **Custom Heat Sinks**

A more detailed model can be used to determine the required thermal resistance of a heat sink to provide necessary cooling. The total module resistance can be separated into a resistance from case-to-sink ( $\theta$ cs) and sink-to-ambient ( $\theta$ sa) shown below (Figure 30).

Figure 30. Resistance from Case-to-Sink and Sink-to-Ambient

For a managed interface using thermal grease or foils, a value of  $\theta$ cs = 0.1 °C/W to 0.3 °C/W is typical. The solution for heat sink resistance is:

$$\theta$$
sa =  $\left[\frac{(Tc - TA)}{PD}\right] - \theta cs$ 

This equation assumes that all dissipated power must be shed by the heat sink. Depending on the userdefined application environment, a more accurate model, including heat transfer from the sides and bottom of the module, can be used. This equation provides a conservative estimate for such instances.

# **Layout Considerations**

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Copper paths must not be routed beneath the power module standoffs.

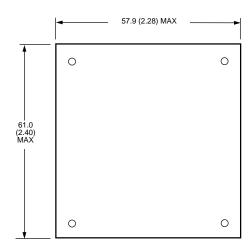
# **Outline Diagram**

Dimensions are in millimeters and (inches).

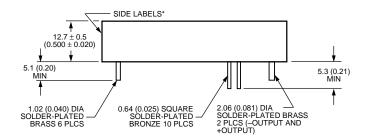
Tolerances: x.x mm ± 0.5 mm (x.xx in. ± 0.02 in.)

 $x.xx mm \pm 0.25 mm (x.xxx in. \pm 0.010 in.)$ 

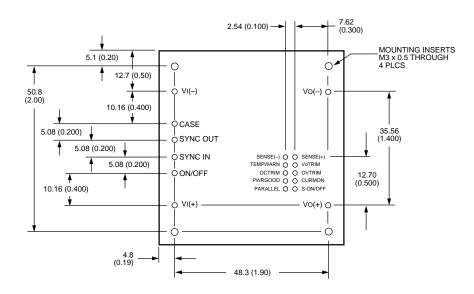
#### **Top View**



#### **Side View**



#### **Bottom View**



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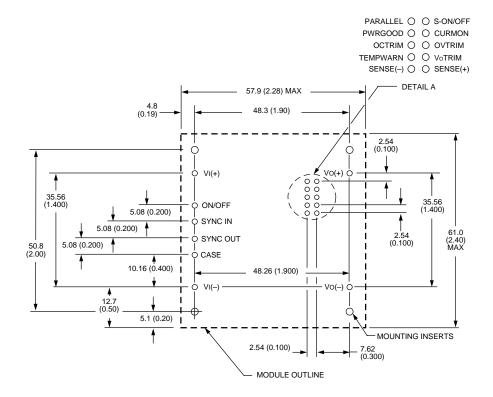
Note: The control pins are on a 2.54 mm (0.100 in.) grid.

<sup>\*</sup> Side labels include Lucent logo, product designation, safety agency markings, input/output voltage and current ratings, and bar code.

# **Recommended Hole Pattern**

Component-side footprint.

Dimensions are in millimeters and (inches).



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# **Ordering Information**

Input Voltage	Output Voltage	Output Power	Remote On/Off Logic	Device Code	Comcode
48 V	28 V	50 W	Negative	JFW050R1	TBD
48 V	28 V	75 W	Negative	JFW075R1	TBD
48 V	28 V	100 W	Negative	JFW100R1	TBD
48 V	28 V	150 W	Negative	JFW150R1	TBD
48 V	28 V	50 W	Positive	JFW050R	TBD
48 V	28 V	75 W	Positive	JFW075R	TBD
48 V	28 V	100 W	Positive	JFW100R	TBD
48 V	28 V	150 W	Positive	JFW150R	TBD

# **Optional Features**

Optional features can be ordered using the suffixes shown in Table 4. The suffixes follow the last letter of the device code and are placed in descending order. For example, the device codes for a JFW150R module with the following options are shown below:

Positive logic JFW150R

Negative logic JFW150R1

Negative logic and delayed JFW150R31

current-limit shutdown

**Table 4. Module Options and Suffixes** 

- · · · · · · · · · · · · · · · · · · ·	
Option	Suffix
Delayed current-limit shutdown	3
Negative remote on/off logic	1
Positive remote on/off logic	_

For additional information, contact your Lucent Technologies Account Manager or the following:

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