

## 131,072/262,144-BIT SPI SERIAL ELECTRICALLY ERASABLE PROM

PRELIMINARY INFORMATION  
NOVEMBER 2001

### FEATURES

- 2.1 MHz Clock Rate
- Low power CMOS
  - Active current less than 3.0 mA (5.5V)
  - Standby current less than 10  $\mu$ A (5.5V)
- Low-voltage Operation
  - IS25C256-3 & IS25C128-3 (Vcc = 2.5V to 5.5V)
  - IS25C256-2 & IS25C128-2 (Vcc = 1.8V to 5.5V)
- Block Write Protection
  - Protect 1/4, 1/2, or Entire Array
- 64 byte page write mode
- Serial Peripheral Interface (SPI) Compatible
  - Supports SPI Modes 0 (0,0) and 3 (1,1)
- Self timed write cycles (5 ms Typical)
- High-reliability
  - Endurance: 1 million cycles per byte
  - Data retention: 100 years
  - ESD protection >4000V
- Industrial temperature available
- 8-pin PDIP or SOIC, and 14-pin TSSOP Packages

### DESCRIPTION

The IS25C128-2 is a 1.8V (1.8V-5.5V) 128K-bit (16364x8) electrically Erasable PROM, IS25C128-3 is a 2.5V (2.5V-5.5V) 128K-bit (16364x8) electrically Erasable PROM, IS25C256-2 is a 1.8V (1.8V-5.5V) 256K-bit (32768x8) electrically Erasable PROM, IS25C256-3 is a 2.5V (2.5V-5.5V) 256K-bit (32768x8) electrically Erasable PROM.

This IS25Cxxx family is a low-cost and low-voltage/ low-power SPI Serial EEPROM. It is fabricated using ISSI's advanced CMOS EEPROM technology and provides for low-power industrial and commercial applications. The IS25Cxxx family is available in 8-pin PDIP, 8-pin SOIC, and 14-pin TSSOP packages.

Each device in this family is enabled through the Chip Select ( $\overline{CS}$ ) and accessed via a 3-wire interface consisting of Serial Data Input (SI), Serial Data Output (SO), and Serial Clock (SCK). All programming cycles are completely self-timed, and no separate ERASE cycle is required before WRITE. BLOCK WRITE protection is enabled by programming the status register with one of four configurations of write protection. Separate program enable and program disable instructions are provided for additional data protection. Hardware data protection is provided via the #WP pin to protect against inadvertent write attempts to the status register. The HOLD pin can suspend communications without re-initializing the serial sequence.

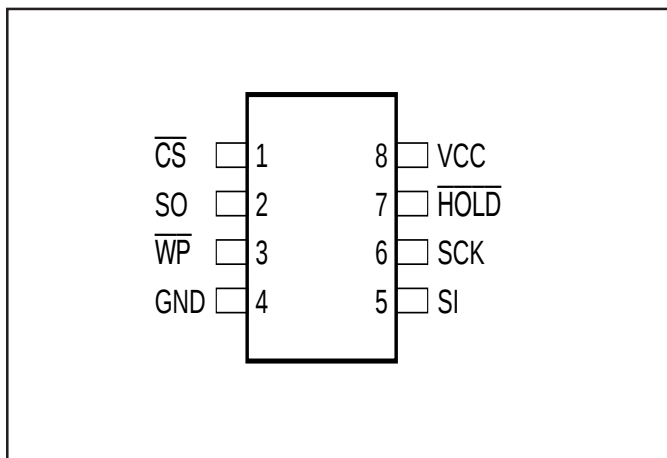
### PRODUCT OFFERING OVERVIEW

| Part No    | Voltage   | Speed   | Standby ICC  | Read ICC | Write ICC | Temperature |
|------------|-----------|---------|--------------|----------|-----------|-------------|
| IS25C256-2 | 1.8V-5.5V | 500 KHz | < 5 $\mu$ A  | 1 mA     | 3 mA      | C,I         |
| IS25C256-3 | 2.5V-5.5V | 2.1MHz  | < 10 $\mu$ A | 1 mA     | 3 mA      | C,I         |
| IS25C128-2 | 1.8V-5.5V | 500 KHz | < 5 $\mu$ A  | 1 mA     | 3 mA      | C,I         |
| IS25C128-3 | 2.5V-5.5V | 2.1MHz  | < 10 $\mu$ A | 1 mA     | 3 mA      | C,I         |

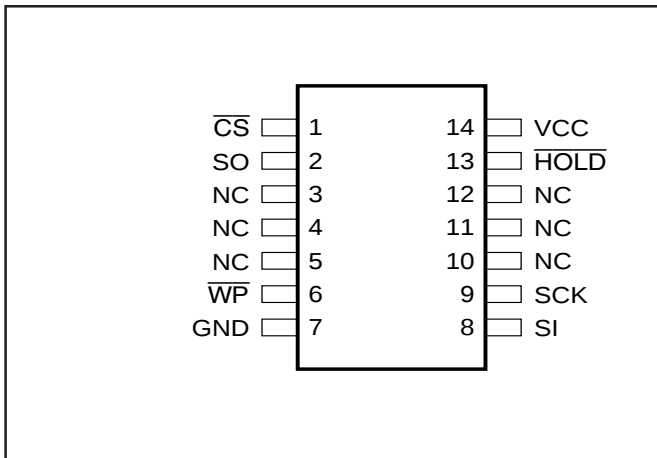
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## PIN CONFIGURATION

### 8-Pin DIP and SOIC



### 14-pin TSSOP



## PIN DESCRIPTIONS

|                   |                       |
|-------------------|-----------------------|
| $\overline{CS}$   | Chip Select           |
| SCK               | Serial Data Clock     |
| SI                | Serial Data Input     |
| SO                | Serial Data Output    |
| GND               | Ground                |
| Vcc               | Power                 |
| $\overline{WP}$   | Write Protect         |
| $\overline{HOLD}$ | Suspends Serial Input |
| NC                | No Connect            |

## PIN DESCRIPTIONS

**Serial Clock (SCK)** - This pin is used to synchronize the communication between the microcontroller and the IS25C256, IS25C128. Op-codes, byte addresses, or data present on the SI pin and latched on the rising edge of the SCK. Data on the SO pin is updated on the falling edge of the SCK for SPI modes (0,0 & 1,1).

**Serial Data Input (SI)** - The SI pin is used to input all op-codes, byte addresses, and data to be written to the device. Input data is latched on the rising edge of the serial clock for SPI modes (0,0 & 1,1).

**Serial Data Output (SO)** - The SO pin is used to transfer data out of the device. During a read cycle, data is shifted out on the falling edge of the serial clock for SPI modes (0,0 & 1,1).

**Chip Select ( $\overline{CS}$ ):** When the  $\overline{CS}$  pin is low, the device is enabled. When the  $\overline{CS}$  pin is high the device is disabled.  $\overline{CS}$  high takes the SO output pin to high impedance and forces the devices into a Standby Mode (unless an internal write operation is underway). The devices draws zero current in the Standby mode. A high-to-low transition on  $\overline{CS}$  is required prior to any sequence being initiated. A low-to-high transition on  $\overline{CS}$  after a valid write sequence is what initiates an internal write cycle.

## PIN DESCRIPTIONS Continued:

**Write Protect ( $\overline{WP}$ )** - The  $\overline{WP}$  Pin will allow normal read/write operations when held high. When  $\overline{WP}$  is tied low and the WPEN bit in the status register is set to "1", all write operations to the status register are inhibited.  $\overline{WP}$  going low while CS is still low will interrupt a write to the status register. If the internal write cycle has already been initiated,  $\overline{WP}$  going low will have no effect on any write operation to the status register. The  $\overline{WP}$  pin function is blocked when the WPEN bit is set to 0. Figure 10 illustrates the  $\overline{WP}$  timing sequence during a write operation.

**Hold ( $\overline{HOLD}$ )**: The  $\overline{HOLD}$  pin is used to pause transmission to the device while in the middle of a serial sequence without having to retransmit entire sequence at a later time. To pause,  $\overline{HOLD}$  must be brought low while SCK is low. The SO pin is in a high impedance state during the time the part is paused, and transition on the SI pins will be ignored. To resume communication,  $\overline{HOLD}$  is brought high, while SCK is low. ( $\overline{HOLD}$  should be held high any time this function is not being used.)  $\overline{HOLD}$  may be tied high directly to Vcc or tied to Vcc through a resistor. The  $\overline{HOLD}$  Timing Diagram illustrates hold timing sequence.

## SERIAL INTERFACE DESCRIPTION

**MASTER:** This device that generates the serial clock.

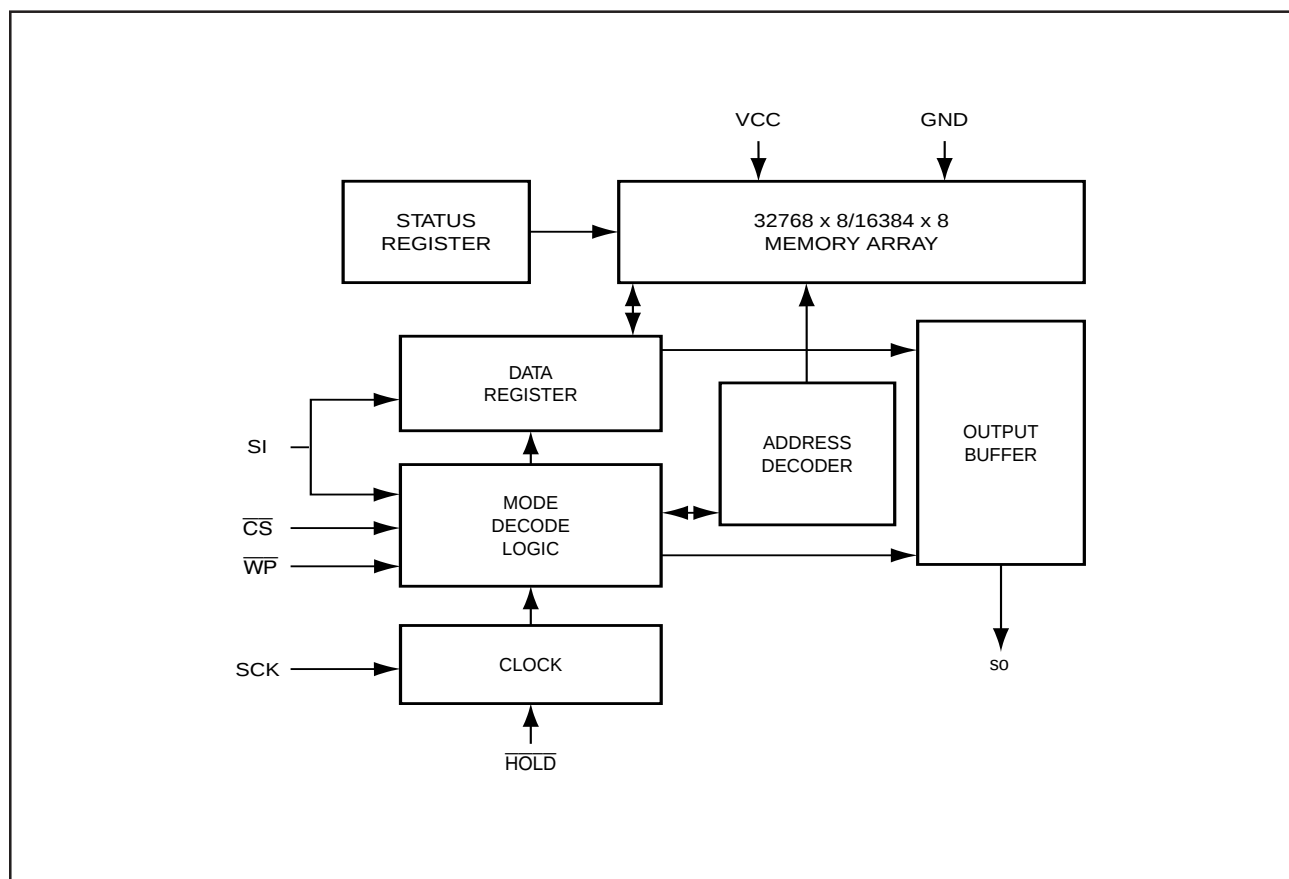
**SLAVE:** Because the Serial Clock pin (SCK) is always an input, the device always operates as a slave.

**MSB:** The Most Significant Bit (MSB) is the first bit transmitted and received.

**SERIAL OP-CODE:** After the device is selected with CS going low, the first byte will be received. This byte contains the op-code that defines the operations to be performed.

**INVALID OP-CODE:** If an invalid op-code is received, no data will be shifted into the device, and the serial output pin (SO) will remain in a high impedance state until the falling edge of CS is detected again. This will reinitialize the serial communications.

## BLOCK DIAGRAM



## FUNCTIONAL DESCRIPTIONS

The IS25C128/256 utilizes an 8-bit instruction register. The list of instructions and their operation codes are contained in Table 1. All instructions, addresses, and data are transferred with the MSB first and start with a high-to-low CS transition.

Table 1. Instruction Set

| Name  | Instruction Format | Operation                   |
|-------|--------------------|-----------------------------|
| WREN  | 0000 X110          | Set Write Enable Latch      |
| WRDI  | 0000 X100          | Reset Write Enable Latch    |
| RDSR  | 0000 X101          | Read Status Register        |
| WRSR  | 0000 X001          | Write Status Register       |
| READ  | 0000 X011          | Read Data from Memory Array |
| WRITE | 0000 X010          | Write Data to Memory Array  |

**WRITE ENABLE (WREN):** This device will power-up in the write disable state when VCC is applied. All programming instructions must therefore be preceded by a Write Enable instruction.

**WRITE DISABLE (WRDI):** To protect the device against inadvertent writes, the Write Disable instruction disables all programming modes. The WRDI instruction is independent of the status of the  $\overline{WP}$  pin.

**READ STATUS REGISTER (RDSR):**

The Read Status Register instruction provides access to the status register. The READY/BUSY and Write Enable status of the device can be determined by the RDSR instruction. Similarly, the Block Write Protection bits indicate the extent of protection employed. These bits are set by using the WRSR instruction.

Table 2. Status Register Format

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit1 | Bit 0            |
|-------|-------|-------|-------|-------|-------|------|------------------|
| WPEN  | x     | x     | x     | BP1   | BP0   | WEN  | $\overline{RDY}$ |

Table 3. Read Status Register Bit Definition

| Bit                        | Definition                                                                                                        |
|----------------------------|-------------------------------------------------------------------------------------------------------------------|
| Bit 0 ( $\overline{RDY}$ ) | Bit 0 = 0 ( $\overline{RDY}$ ) indicates the device is READY. Bit 0 = 1 indicates the write cycle is in progress. |
| Bit 1(WEN)                 | Bit 1 = 0 indicates the device is not WRITE ENABLED. Bit 1 = 1 indicates the device is WRITE ENABLED.             |
| Bit 2 (BPO)                | See Table 4                                                                                                       |
| Bit 3 (BP1)                | See Table 4                                                                                                       |
| Bits 4 - 6                 | are 0s when the device is not an internal write cycle.                                                            |
| Bits 7 (WPEN)              | See Table 5.                                                                                                      |
| Bits 0-7                   | are 1s during an internal write cycle.                                                                            |

**WRITE STATUS REGISTER (WRSR):** The WRSR instruction allows the user to select one of four levels of protection. The device is divided into four array segments. One quarter (1/4), one half (1/2) or all of the memory segments can be protected. Any of the data within any selected segment will therefore be READ only. The block write protection levels and corresponding status register control bits are shown in Table 4.

The three bits, BP0, BP1 and WPEN are nonvolatile cells that have the same properties and functions as the regular memory cells (e.g. WREN, twc, RDSR).

Table 4. Status Register Format

| Level  | Status Register Bits |     | Array Addresses Protected |               |
|--------|----------------------|-----|---------------------------|---------------|
|        | BP1                  | BP0 | IS25C128                  | IS25C256      |
| 0      | 0                    | 0   | None                      | None          |
| 1(1/4) | 0                    | 1   | 3000<br>-3FFF             | 6000<br>-7FFF |
| 2(1/2) | 1                    | 0   | 2000<br>-3FFF             | 4000<br>-7FFF |
| 3(All) | 1                    | 1   | 0000<br>-3FFF             | 0000<br>-7FFF |

The WRSR instruction also allows the user to enable or disable the write protect ( $\overline{WP}$ ) pin through the use of the Write Protect Enable (WPEN) bit. Hardware write protection is enabled when the  $\overline{WP}$  pin is low and the WPEN bit is "1". Hardware write protection is disabled when either the  $\overline{WP}$  pin is high or the WPEN bit is "0". When the device is hardware write protected, writes to the Status Register, including the Block Protect bits and the WPEN bit, and the block-protected sections in the memory array are disabled. Writes are only allowed to sections of the memory which are not block-protected.

Note: When the WPEN bit is hardware write protected, it cannot be changed back to "0", as long as the  $\overline{WP}$  pin is held low.

**Table 5. WPEN Operation**

| WPEN | $\overline{WP}$ | WEN | Protected Blocks | Unprotected Blocks | Protected Register |
|------|-----------------|-----|------------------|--------------------|--------------------|
| 0    | X               | 0   | Protected        | Protected          | Protected          |
| 0    | X               | 1   | Protected        | Writable           | Writable           |
| 1    | Low             | 0   | Protected        | Protected          | Protected          |
| 1    | Low             | 1   | Protected        | Writable           | Protected          |
| X    | High            | 0   | Protected        | Protected          | Protected          |
| X    | High            | 1   | Protected        | Writable           | Writable           |

**READ SEQUENCE (READ):** Reading the device via the SO (Serial Output) pin requires the following sequence. After the  $\overline{CS}$  line is pulled low to select a device, the READ op-code is transmitted via the SI line followed by the byte address to be read (A15-A0, Refer to Table 6). Upon completion, any data on the SI line will be ignored. The data (D7-D0) at the specified address is then shifted out onto the SO line. If only one byte is to be read, the  $\overline{CS}$  line should be driven high after the data comes out. The READ sequence can be continued since the byte address is automatically incremented and data will continue to be shifted out. When the highest address is reached, the address counter will roll over to the lowest address allowing the entire memory to be read in one continuous READ cycle.

**WRITE SEQUENCE (READ):** In order to program the device, two separate instructions must be executed. First, the device must be write enabled via the Write Enable (WREN) Instruction. Then a Write (WRITE) Instruction may be executed. Also the address of the memory location(s) to be programmed must be outside the protected address field location selected by the Block Write Protection Level. During an internal write cycle, all commands will be ignored except the RDSR instruction.

A Write Instruction requires the following sequence. After the  $\overline{CS}$  line is pulled low to select the device, the WRITE op-code is transmitted via the SI line followed by the byte address (A15-A0) and the data (D7-D0) to be programmed (Refer to Table 6). Programming will start after the  $\overline{CS}$  pin is brought high. (The Low to High transition of the  $\overline{CS}$  pin must occur during the SCK low-time immediately after clocking in the D0 (LSB) data bit.

The READY/BUSY status of the device can be determined by initiating a READ STATUS REGISTER (RDSR) Instruction. If Bit 0 = 1, the WRITE cycle is still in progress. If Bit 0 = 0, the WRITE cycle has ended. Only the READ STATUS REGISTER instruction is enabled during the WRITE programming cycle.

The device is capable of the 64-byte PAGE WRITE operation. After each byte of data is received, the five low order address bits are internally incremented by one; the high order bits of the address will remain constant. If more than 64 bytes of data are transmitted, the address counter will roll over the previously written data will be overwritten. The device is automatically returned to the write disable state at the completion of a WRITE cycle.

**NOTE:** If the device is not Write enabled (WREN), the device will ignore the Write instruction and will return to the standby state, when  $\overline{CS}$  is brought high. A new  $\overline{CS}$  falling edge is required to re-initiate the serial communication.

**Table 6. Address Key**

| Name            | IS25C128        | IS25C256     |
|-----------------|-----------------|--------------|
| $A_N$           | $A_{13}-A_0$    | $A_{14}-A_0$ |
| Don't Care Bits | $A_{15}-A_{14}$ | $A_{15}$     |

## ABSOLUTE MAXIMUM RATINGS<sup>(1)</sup>

| Symbol            | Parameter              | Value           | Unit |
|-------------------|------------------------|-----------------|------|
| V <sub>S</sub>    | Supply Voltage         | -0.5 to +6.25   | V    |
| V <sub>P</sub>    | Voltage on Any Pin     | -1.0V to + 7.0V | V    |
| T <sub>BIAS</sub> | Temperature Under Bias | -40 to +85      | °C   |
| T <sub>STG</sub>  | Storage Temperature    | -65 to +150     | °C   |
| I <sub>OUT</sub>  | Output Current         | 5               | mA   |

### Notes:

1. Stress greater than those listed under ABSOLUTE MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions outside those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

## OPERATING RANGE (IS25C256-2 and IS25C128-2)

| Range      | Ambient Temperature | V <sub>CC</sub> |
|------------|---------------------|-----------------|
| Commercial | 0°C to +70°C        | 1.8V to 5.5V    |
| Industrial | -40°C to +85°C      | 1.8V to 5.5V    |

## OPERATING RANGE (IS25C256-3 and IS25C128-3)

| Range      | Ambient Temperature | V <sub>CC</sub> |
|------------|---------------------|-----------------|
| Commercial | 0°C to +70°C        | 2.5V to 5.5V    |
| Industrial | -40°C to +85°C      | 2.5V to 5.5V    |

## CAPACITANCE<sup>(1,2)</sup>

| Symbol           | Parameter          | Conditions            | Max. | Unit |
|------------------|--------------------|-----------------------|------|------|
| C <sub>IN</sub>  | Input Capacitance  | V <sub>IN</sub> = 0V  | 6    | pF   |
| C <sub>OUT</sub> | Output Capacitance | V <sub>OUT</sub> = 0V | 8    | pF   |

### Notes:

1. Tested initially and after any design or process changes that may affect these parameters and not 100% tested.
2. Test conditions: T<sub>A</sub> = 25°C, f = 1 MHz, V<sub>CC</sub> = 5.0V.

## DC ELECTRICAL CHARACTERISTICS

| Symbol           | Parameter              | Test Conditions                                   | Min.                  | Max.                  | Unit |
|------------------|------------------------|---------------------------------------------------|-----------------------|-----------------------|------|
| V <sub>OL1</sub> | Output LOW Voltage     | V <sub>CC</sub> = 1.8V, I <sub>OL</sub> = 0.15 mA | —                     | 0.2                   | V    |
| V <sub>OL2</sub> | Output LOW Voltage     | V <sub>CC</sub> = 2.5V, I <sub>OL</sub> = 1.0 mA  | —                     | 0.4                   | V    |
| V <sub>OH1</sub> | Output HIGH Voltage    | V <sub>CC</sub> = 1.8V, I <sub>OH</sub> = -100uA  | V <sub>CC</sub> - 0.2 | —                     | V    |
| V <sub>OH2</sub> | Output HIGH Voltage    | V <sub>CC</sub> = 2.5V, I <sub>OH</sub> = -1mA    | V <sub>CC</sub> - 0.8 | —                     | V    |
| V <sub>IH</sub>  | Input HIGH Voltage     |                                                   | V <sub>CC</sub> x 0.7 | V <sub>CC</sub> + 0.5 | V    |
| V <sub>IL</sub>  | Input LOW Voltage      |                                                   | -1.0                  | V <sub>CC</sub> x 0.3 | V    |
| I <sub>LI</sub>  | Input Leakage Current  | V <sub>IN</sub> = V <sub>CC</sub> max.            | -3.0                  | 3                     | μA   |
| I <sub>LO</sub>  | Output Leakage Current |                                                   | -3.0                  | 3                     | μA   |

## POWER SUPPLY CHARACTERISTICS

| Symbol           | Parameter                         | Test Conditions                                                  | Min. | Max. | Unit |
|------------------|-----------------------------------|------------------------------------------------------------------|------|------|------|
| I <sub>CC1</sub> | V <sub>CC</sub> Operating Current | READ at 500 KHz (V <sub>CC</sub> =5V)                            | —    | 1.0  | mA   |
| I <sub>CC2</sub> | V <sub>CC</sub> Operating Current | WRITE at 500 KHz (V <sub>CC</sub> =5V)                           | —    | 3.0  | mA   |
| I <sub>SB1</sub> | Standby Current                   | V <sub>CC</sub> = 1.8V, V <sub>IN</sub> = V <sub>CC</sub> or GND | —    | 5    | μA   |
| I <sub>SB2</sub> | Standby Current                   | V <sub>CC</sub> = 5.5V, V <sub>IN</sub> = V <sub>CC</sub> or GND | —    | 10   | μA   |

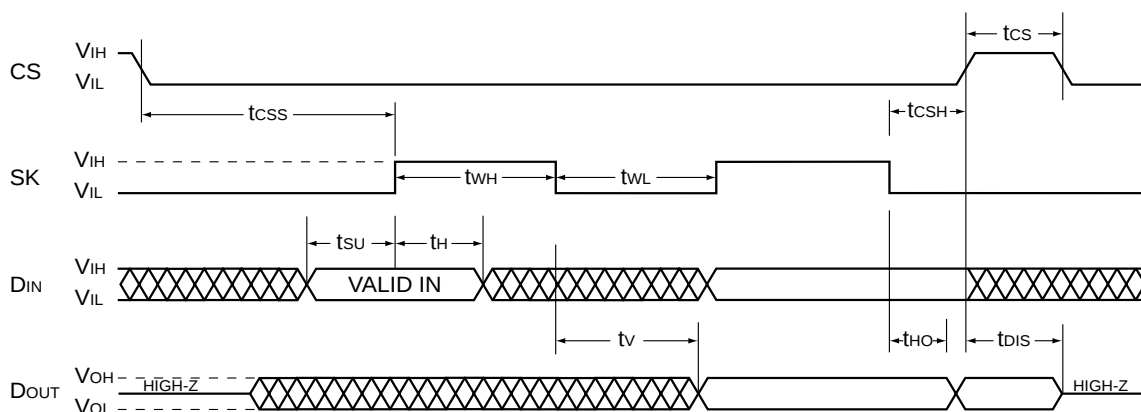
## AC Characteristics

Applicable over recommended operating range from  $T_A = -40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$ ,  $V_{CC} = \text{As Specified}$ ,  
 $CL = 1$  TTL Gate and 100 pF (unless otherwise noted).

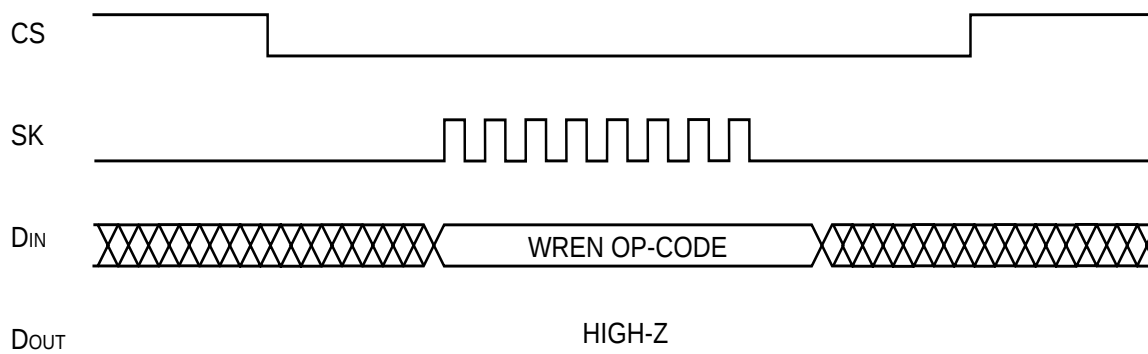
| Symbol                   | Parameter                                 | 1.8V |      | 2.5V |     | Units        |
|--------------------------|-------------------------------------------|------|------|------|-----|--------------|
|                          |                                           | Min  | Max  | Min  | Max |              |
| f <sub>SCK</sub>         | SCK Clock Frequency                       | 0    | 0.5  | 0    | 2.1 | MHz          |
| t <sub>RI</sub>          | Input Rise Time                           | —    | 2    | —    | 2   | μs           |
| t <sub>FI</sub>          | Input Fall Time                           | —    | 2    | —    | 2   | μs           |
| t <sub>WH</sub>          | SCK High Time                             | 800  | —    | 200  | —   | ns           |
| t <sub>WL</sub>          | SCK Low Time                              | 800  | —    | 200  | —   | ns           |
| t <sub>CS</sub>          | $\overline{\text{CS}}$ High Time          | 1000 | —    | 250  | —   | ns           |
| t <sub>CSS</sub>         | $\overline{\text{CS}}$ Setup Time         | 1000 | —    | 250  | —   | ns           |
| t <sub>CSH</sub>         | $\overline{\text{CS}}$ Hold Time          | 1000 | —    | 250  | —   | ns           |
| t <sub>SU</sub>          | Data In Setup Time                        | 100  | —    | 50   | —   | ns           |
| t <sub>H</sub>           | Data In Hold Time                         | 100  | —    | 50   | —   | ns           |
| t <sub>HD</sub>          | $\overline{\text{Hold}}$ Setup Time       | 400  | —    | 100  | —   | ns           |
| t <sub>CD</sub>          | $\overline{\text{Hold}}$ Time             | 400  | —    | 300  | —   | ns           |
| t <sub>V</sub>           | Output Valid                              | 0    | 800  | 0    | 200 | ns           |
| t <sub>HO</sub>          | Output Hold Time                          | 0    | —    | 0    | —   | ns           |
| t <sub>LZ</sub>          | $\overline{\text{Hold}}$ to Output Low Z  | 0    | 200  | 0    | 200 | ns           |
| t <sub>HZ</sub>          | $\overline{\text{Hold}}$ to Output High Z | —    | 200  | —    | 200 | ns           |
| t <sub>DIS</sub>         | Output Disable Time                       | —    | 1000 | —    | 250 | ns           |
| t <sub>WC</sub>          | Write Cycle Time                          | —    | 20   | —    | 10  | ms           |
| Endurance <sup>(1)</sup> | 5.0V, 25°C, Page Mode                     | 1M   | —    | 1M   | —   | Write Cycles |

## TIMING DIAGRAMS

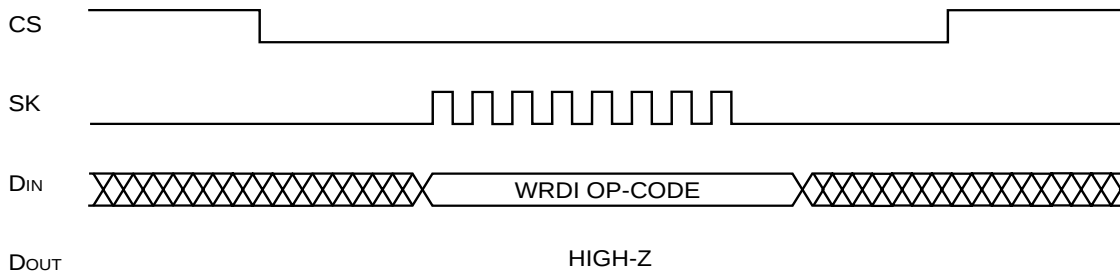
### Synchronous Data Timing



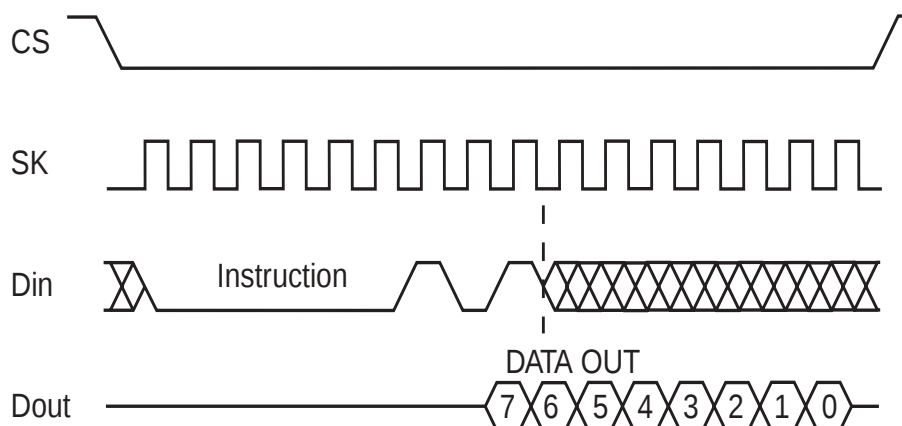
### WREN Timing



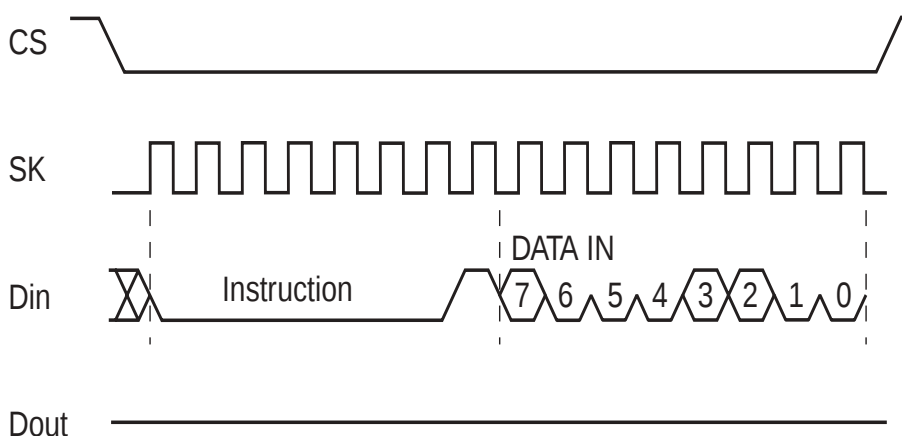
### WRDI Timing



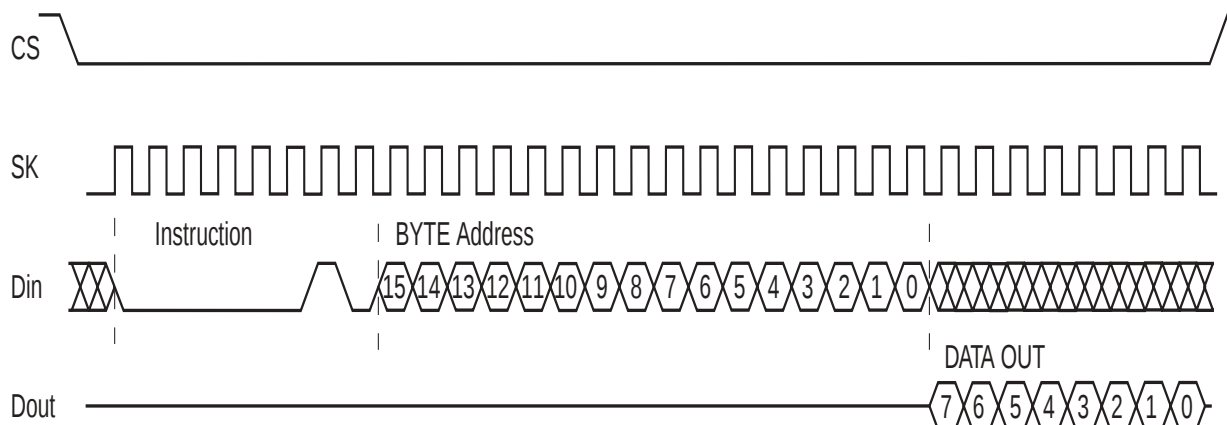
### RDST Timing



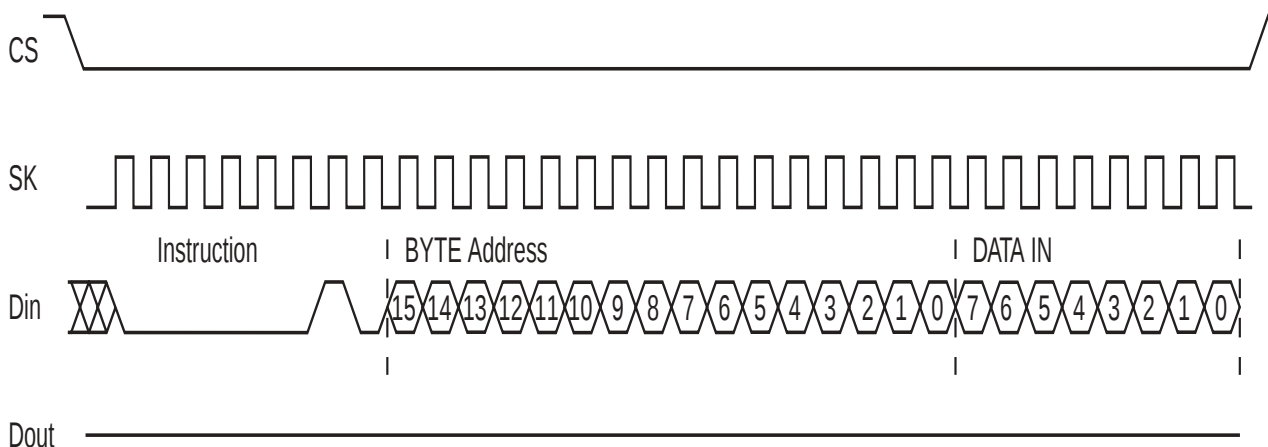
### WRSR Timing



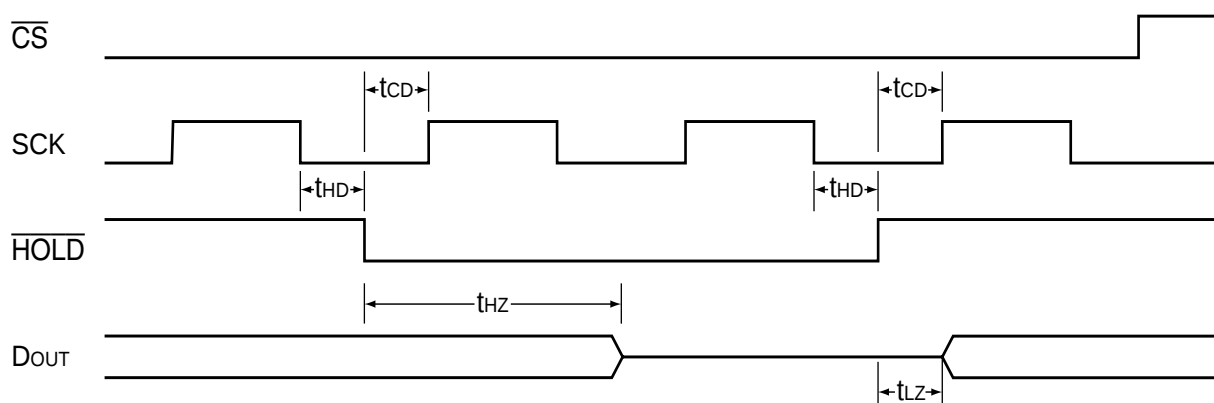
### READ Timing



## WRITE Timing



## $\overline{HOLD}$ Timing



## ORDERING INFORMATION

Commercial Range: 0°C to +70°C

| Frequency | Voltage Range   | Part Number | Package                   |
|-----------|-----------------|-------------|---------------------------|
| 500 KHz   | 1.8V<br>to 5.5V | IS25C128-2P | 300-mil Plastic DIP       |
|           |                 | IS25C128-2G | Small Outline (JEDEC STD) |
|           |                 | IS25C128-2Z | 14-pin TSSOP              |
| 500 KHz   | 1.8V<br>to 5.5V | IS25C256-2P | 300-mil Plastic DIP       |
|           |                 | IS25C256-2G | Small Outline (JEDEC STD) |
|           |                 | IS25C256-2Z | 14-pin TSSOP              |
| 2.1 MHz   | 2.5V<br>to 5.5V | IS25C128-3P | 300-mil Plastic DIP       |
|           |                 | IS25C128-3G | Small Outline (JEDEC STD) |
|           |                 | IS25C128-3Z | 14-pin TSSOP              |
| 2.1 MHz   | 2.5V<br>to 5.5V | IS25C256-3P | 300-mil Plastic DIP       |
|           |                 | IS25C256-3G | Small Outline (JEDEC STD) |
|           |                 | IS25C256-3Z | 14-pin TSSOP              |

## ORDERING INFORMATION

Industrial Range: -40°C to +85°C

| Frequency | Voltage Range   | Part Number  | Package                   |
|-----------|-----------------|--------------|---------------------------|
| 500 KHz   | 1.8V<br>to 5.5V | IS25C128-2PI | 300-mil Plastic DIP       |
|           |                 | IS25C128-2GI | Small Outline (JEDEC STD) |
|           |                 | IS25C128-2ZI | 14-pin TSSOP              |
| 500 KHz   | 1.8V<br>to 5.5V | IS25C256-2PI | 300-mil Plastic DIP       |
|           |                 | IS25C256-2GI | Small Outline (JEDEC STD) |
|           |                 | IS25C256-2ZI | 14-pin TSSOP              |
| 2.1 MHz   | 2.5V<br>to 5.5V | IS25C128-3PI | 300-mil Plastic DIP       |
|           |                 | IS25C128-3GI | Small Outline (JEDEC STD) |
|           |                 | IS25C128-3ZI | 14-pin TSSOP              |
| 2.1 MHz   | 2.5V<br>to 5.5V | IS25C256-3PI | 300-mil Plastic DIP       |
|           |                 | IS25C256-3GI | Small Outline (JEDEC STD) |
|           |                 | IS25C256-3ZI | 14-pin TSSOP              |

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