

SBOS247A - JUNE 2002 - REVISED SEPTEMBER 2002

## Low-Noise, Low-Distortion INSTRUMENTATION AMPLIFIER Replacement for SSM2017

#### **FEATURES**

● LOW NOISE: 1.3nV/√Hz at 1kHz

LOW THD+N: 0.004% at 1kHz, G = 100
WIDE BANDWIDTH: 800kHz at G = 100
WIDE SUPPLY RANGE: ±4.5V to ±18V

● HIGH CMR: > 100dB

GAIN SET WITH EXTERNAL RESISTOR

DIP-8 AND SOL-16 WIDEBODY PACKAGES

#### **APPLICATIONS**

- PROFESSIONAL MICROPHONE PREAMPS
- MOVING-COIL TRANSDUCER AMPLIFIERS
- DIFFERENTIAL RECEIVERS
- BRIDGE TRANSDUCER AMPLIFIERS

# $V_{\text{IN}} = 0$ $V_{\text{IN}} =$

#### **DESCRIPTION**

The INA217 is a low-noise, low-distortion, monolithic instrumentation amplifier. Current-feedback circuitry allows the INA217 to achieve wide bandwidth and excellent dynamic response over a wide range of gain. The INA217 is ideal for low-level audio signals such as balanced low-impedance microphones. Many industrial, instrumentation, and medical applications also benefit from its low noise and wide bandwidth.

Unique distortion cancellation circuitry reduces distortion to extremely low levels, even in high gain. The INA217 provides near-theoretical noise performance for  $200\Omega$  source impedance. The INA217 features differential input, low noise, and low distortion that provides superior performance in professional microphone amplifier applications.

The INA217 features wide supply voltage, excellent output voltage swing, and high output current drive making it an optimal candidate for use in high-level audio stages.

The INA217 is available in the same DIP-8 and SOL-16 wide body packages and pin outs as the SSM2017. For a smaller package, see the INA163 in SO-14 narrow. The INA217 is specified over the temperature range of -40°C to +85°C.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.



#### **ABSOLUTE MAXIMUM RATINGS(1)**

Supply Voltage, V+ to V	±18V
Signal Input Terminals, Voltage(2)	(V–) – 0.5V to (V+) + 0.5V
Current <sup>(2)</sup>	10mA
Output Short-Circuit(3)	Continuous
Operating Temperature	55°C to +125°C
Storage Temperature	55°C to +150°C
Junction Temperature	+150°C
Lead Temperature (soldering, 10s)	+300°C

NOTES: (1) Stresses above these ratings may cause permanent damage. Exposure to absolute maximum conditions for extended periods may degrade device reliability. (2) Input terminals are diode-clamped to the power-supply rails. Input signals that can swing more than 0.5V beyond the supply rails should be current limited to 10mA or less. (3) Short-circuit to ground, one amplifier per package.

### ELECTROSTATIC DISCHARGE SENSITIVITY

This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

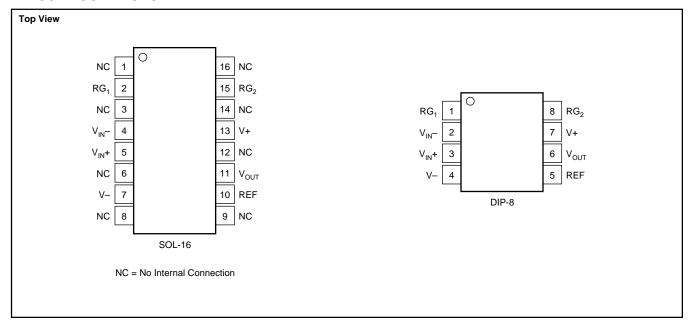
ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### PACKAGE/ORDERING INFORMATION

PRODUCT	PACKAGE-LEAD	PACKAGE DESIGNATOR <sup>(1)</sup>	SPECIFIED TEMPERATURE RANGE	PACKAGE MARKING	ORDERING NUMBER	TRANSPORT MEDIA, QUANTITY
INA217	SOL-16	DW	-40°C to +125°C	INA217	INA217AIDWT	Tape and Reel, 250
"	II .	"	II	"	INA217AIDWR	Tape and Reel, 1000
INA217	DIP-8	Р	-40°C to +125°C	INA217	INA217AIP	Rails, 50

NOTES: (1) For the most current specifications and package information, refer to our web site at www.ti.com.

#### **PIN CONFIGURATIONS**



#### ELECTRICAL CHARACTERISTICS: $V_S = \pm 15V$

**Boldface** limits apply over the specified temperature range,  $T_A = -40^{\circ}C$  to  $+85^{\circ}C$ .

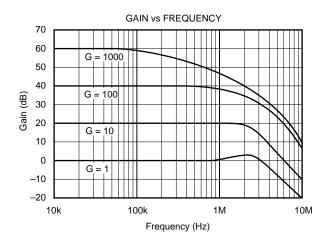
 $\rm T_A$  = +25°C,  $\rm R_L$  = 2k $\Omega,~\rm V_S$  = ±15V, unless otherwise noted.

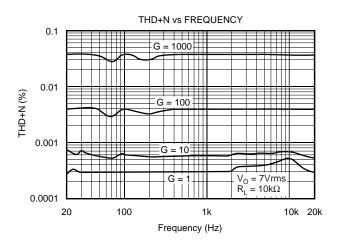
		INA217			1
PARAMETER	CONDITIONS	MIN TYP		MAX	UNITS
GAIN EQUATION Range Gain Error, G = 1			G = 1 + 10k/R <sub>G</sub> 1 to 10000 ±0.1	±0.25	V/V %
G = 10 G = 100 G = 1000			±0.2 ±0.2 ±0.5	±0.7	% % %
Gain Temp Drift Coefficient, G = 1 G > 10  Nonlinearity, G = 1 G = 100			±3 ±40 ±0.0003 ±0.0006	±10 ±100	ppm/°C ppm/°C % of FS % of FS
INPUT STAGE NOISE  Voltage Noise $f_O = 1 \text{kHz}$ $f_O = 100 \text{Hz}$ $f_O = 10 \text{Hz}$	R <sub>SOURCE</sub> = 0Ω		1.3 1.5 3.5		nV/√Hz nV/√Hz nV/√Hz
Current Noise $f_O = 1kHz$			0.8		pA/√Hz
OUTPUT STAGE NOISE Voltage Noise, f <sub>O</sub> = 1kHz			90		nV/√Hz
INPUT OFFSET VOLTAGE Input Offset Voltage vs Temperature vs Power Supply	$V_{CM} = V_{OUT} = 0V$ $T_A = T_{MIN} \text{ to } T_{MAX}$ $V_S = \pm 4.5V \text{ to } \pm 18V$		50 + 2000/G <b>1 + 20/G</b> 1 + 50/G	250 + 5000/G 3 + 200/G	μV μ <b>V/°C</b> μV/V
INPUT VOLTAGE RANGE Common-Mode Voltage Range Common-Mode Rejection, G = 1	$V_{IN} + - V_{IN} - = 0V$ $V_{IN} + - V_{IN} - = 0V$ $V_{CM} = \pm 11V, R_{SRC} = 0\Omega$	(V+) - 4 (V-) + 4 70	(V+) - 3 (V-) + 3 80		V V dB
G = 100  INPUT BIAS CURRENT Initial Bias Current vs Temperature Initial Offset Current vs Temperature		100	116 2 10 0.1 0.5	12 1	dB μΑ n <b>A/°C</b> μΑ n <b>A/°C</b>
INPUT IMPEDANCE	Differential Common-Mode		60    2 60    2		MΩ    pF MΩ    pF
DYNAMIC RESPONSE  Bandwidth, Small Signal, -3dB, G = 1 G = 100  Slew Rate THD+Noise, f = 1kHz Settling Time, 0.1% 0.01%  Overload Recovery	G = 100 G = 100, 10V Step G = 100, 10V Step 50% Overdrive		3.4 800 15 0.004 2 3.5		MHz kHz V/μs % μs μs
OUTPUT Voltage	R <sub>L</sub> to GND	(V+) - 2 (V-) + 2	(V+) - 1.8 (V-) + 1.8		V V
Load Capacitance Stability Short-Circuit Current	Continuous-to-Common		1000 ±60		pF mA
POWER SUPPLY Rated Voltage Voltage Range Current, Quiescent	I <sub>O</sub> = 0mA	±4.5	±15 ±10	±18 ±12	V V mA
TEMPERATURE RANGE Specification Operating DIP-8 $\theta_{\rm JA}$		-40 -40	85 90	+85 +125	°C °C °C

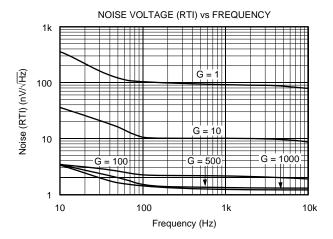
NOTE: (1) Gain accuracy is a function of external R<sub>G</sub>.

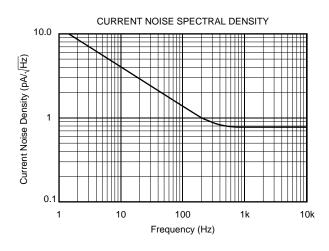
#### TYPICAL CHARACTERISTICS

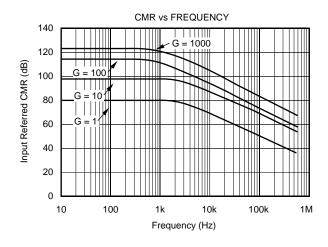
At  $T_A$  = +25°C,  $V_S$  = ±15V,  $R_L$  = 2k $\Omega$ , unless otherwise noted.

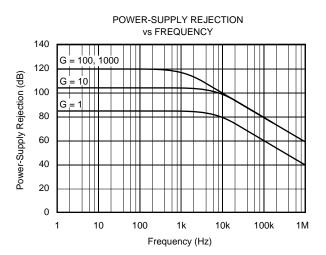








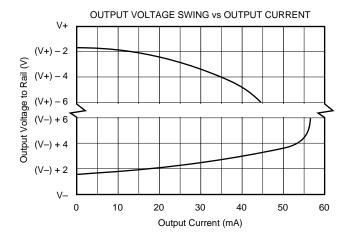


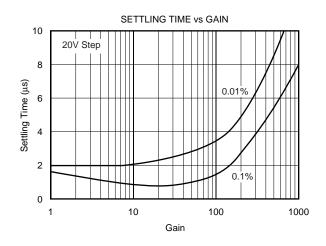


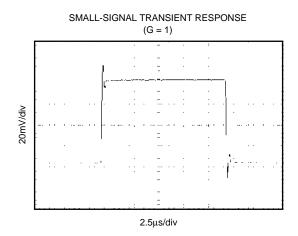


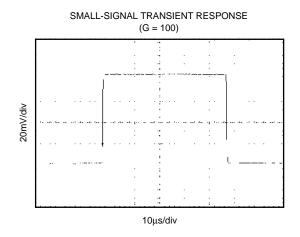
#### **TYPICAL CHARACTERISTICS (Cont.)**

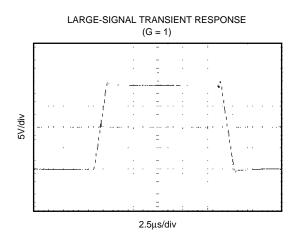
At  $T_A$  = +25°C,  $V_S$  = ±15V,  $R_L$  = 2k $\Omega$ , unless otherwise noted.

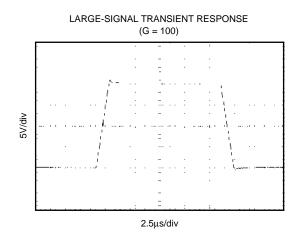












#### APPLICATIONS INFORMATION

Figure 1 shows the basic connections required for operation. Power supplies should be bypassed with  $0.1\mu F$  tantalum capacitors near the device pins. The output Reference (pin 5) should be a low-impedance connection. Resistance of a few ohms in series with this connection will degrade the common-mode rejection of the INA217.

#### **GAIN-SET RESISTOR**

Gain is set with an external resistor,  $R_G$ , as shown in Figure 1. The two internal  $5k\Omega$  feedback resistors are laser-trimmed to  $5k\Omega$  within approximately  $\pm 0.2\%$ . The gain equation for the INA217 is:

$$G = 1 + \frac{10,000}{R_G}$$

The temperature coefficient of the internal  $5k\Omega$  resistors is approximately  $\pm 25 ppm/^{\circ}C$ . Accuracy and TCR of the external  $R_G$  will also contribute to gain error and temperature drift. These effects can be inferred from the gain equation. Make a short, direct connection to the gain set resistor,  $R_G$ . Avoid running output signals near these sensitive input nodes.

#### **NOISE PERFORMANCE**

The INA217 provides very low-noise with low-source impedance. Its  $1.3 \text{nV}/\sqrt{\text{Hz}}$  voltage noise delivers near-theoretical noise performance with a source impedance of  $200\Omega$ . The input stage design used to achieve this low noise, results in

relatively high input bias current and input bias current noise. As a result, the INA217 may not provide the best noise performance with a source impedance greater than  $10k\Omega$ . For source impedance greater than  $10k\Omega$ , other instrumentation amplifiers may provide improved noise performance.

#### INPUT CONSIDERATIONS

Very low source impedance (less than  $10\Omega$ ) can cause the INA217 to oscillate. This depends on circuit layout, signal source, and input cable characteristics. An input network consisting of a small inductor and resistor, as shown in Figure 2, can greatly reduce any tendency to oscillate. This is especially useful if a variety of input sources are to be connected to the INA217. Although not shown in other figures, this network can be used as needed with all applications shown.

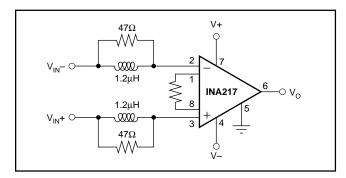


FIGURE 2. Input Stabilization Network.

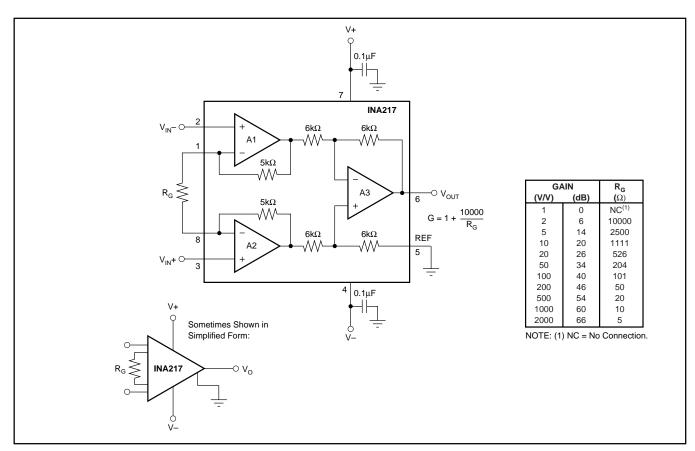


FIGURE 1. Basic Circuit Connections.



#### **OFFSET VOLTAGE TRIM**

A variable voltage applied to pin 5, as shown in Figure 3, can be used to adjust the output offset voltage. A voltage applied to pin 5 is summed with the output signal. An op amp connected as a buffer is used to provide a low impedance at pin 5 to assure good common-mode rejection.

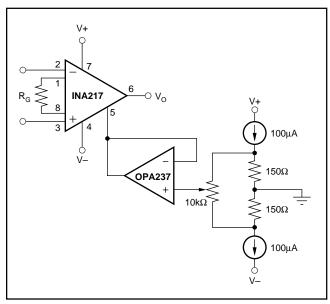


FIGURE 3. Offset Voltage Adjustment Circuit.

#### MICROPHONE AMPLIFIER

Figure 4 shows a typical circuit for a professional microphone input amplifier.  $R_1$  and  $R_2$  provide a current path for conventional 48V phantom power source for a remotely located microphone. An optional switch allows phantom power to be disabled.  $C_1$  and  $C_2$  block the phantom power voltage from the INA217 input circuitry. Non-polarized capacitors should be used for  $C_1$  and  $C_2$  if phantom power is to be disabled. For additional input protection against ESD and hot-plugging, four IN4148 diodes may be connected from the input to supply lines.

 $\rm R_4$  and  $\rm R_5$  provide a path for input bias current of the INA217. Input offset current (typically 100nA) creates a DC differential input voltage that will produce an output offset voltage. This is generally the dominant source of output offset voltage in this application. With a maximum gain of 1000 (60dB), the output offset voltage can be several volts. This may be entirely acceptable if the output is AC-coupled into the subsequent stage. An alternate technique is shown in Figure 4. An inexpensive FET-input op amp in a feedback loop drives the DC output voltage to 0V. A2 is not in the audio signal path and does not affect signal quality.

Gain is set with a variable resistor,  $R_7$ , in series with  $R_6$ .  $R_6$  determines the maximum gain. The total resistance,  $R_6 + R_7$ , determines the lowest gain. A special reverse-log taper potentiometer for  $R_7$  can be used to create a linear change (in dB) with rotation.

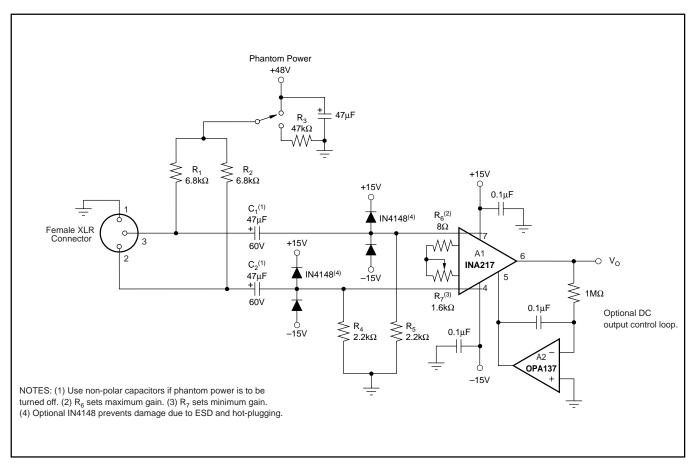


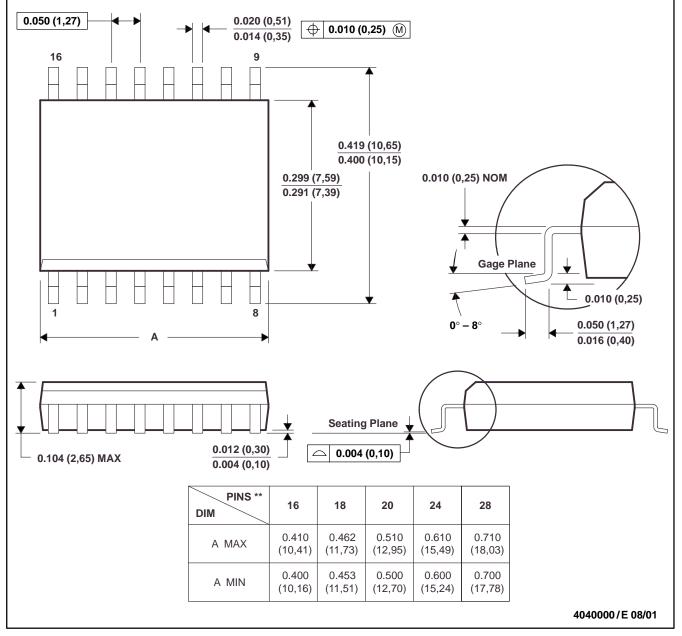
FIGURE 4. Phantom-Powered Microphone Preamplifier.



#### DW (R-PDSO-G\*\*)

#### PLASTIC SMALL-OUTLINE PACKAGE

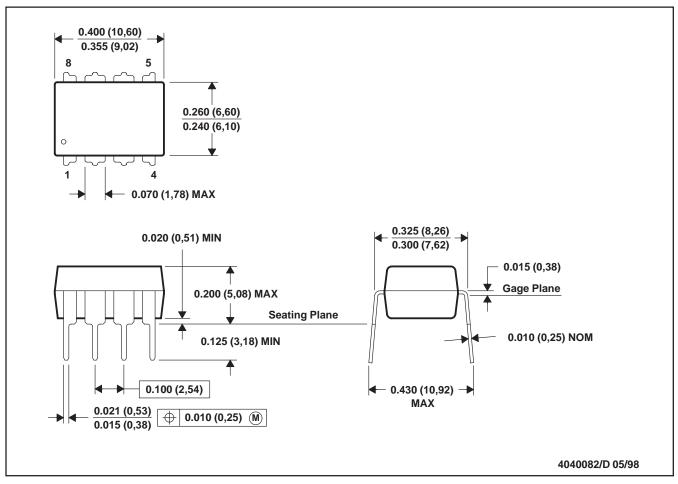
#### **16 PINS SHOWN**



NOTES: A. All linear dimensions are in inches (millimeters).

- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion not to exceed 0.006 (0,15).
- D. Falls within JEDEC MS-013

P (R-PDIP-T8) PLASTIC DUAL-IN-LINE



NOTES: A. All linear dimensions are in inches (millimeters).

- B. This drawing is subject to change without notice.
- C. Falls within JEDEC MS-001

**INA217** 

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Mailing Address:

Texas Instruments
Post Office Box 655303
Dallas, Texas 75265

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