



SERIAL INTERFACE PRODUCTS

# Using the ISD33000 Device with a Microcontroller

This application note describes how to use ISD33000 with a microcontroller. The purpose of this application note is to illustrate the ease of use of the ISD33000 series with any SPI compatible microcontroller.

Unlike other families of single-chip record and playback from ISD, the ISD33000 is a microcontroller slave peripheral device. It is controlled with a microcontroller either with an SPI compatible hardware already on the microcontroller or with I/O ports that emulate SPI protocol. For the ease of use and illustration a microcontroller with an SPI compatible serial interface is used in this application note.

# **SERIAL PERIPHERAL INTERFACE (SPI)**

ISD33000 operates from an SPI serial interface. The SPI protocol is a synchronous serial data transfer protocol. The SPI interface has 4 control I/O pins.

- 1. Slave Select ( $\overline{SS}$ ): This pin when low will select the ISD33000.
- **2.** Master Out Slave In (MOSI): This is the serial input to the ISD33000.
- **3.** Master In Slave Out (MISO): This is the serial input to the ISD33000.
- **4.** Serial Clock (SCLK): This is the clock input to the ISD33000. The master microcontroller provides this clock.

The data transfer protocol assumes that the microcontroller's SPI shift registers are clocked on falling edge of the SCLK. On the ISD33000, data is clocked in on the MOSI input on the positive clock edge and data is clocked out on the MISO output on the negative clock edge.

All serial data transfers begin with the falling edge of  $\overline{SS}$  pin. Slave Select is held low during all serial interface and it is held high between instructions. Each operation that ends in an EOM (End of Message) or an OVF (Overflow) from the ISD33000 will generate an Interrupt. The interrupt will be cleared the next time an SPI cycle is initiated. As the interrupt data is shifted out of the ISD33000 MISO pin, control and address data are simultaneously shifted into the ISD33000 MOSI pin. Care should be taken such that the data shifted in is compatible with current system operation. An operation begins with the RUN bit set and ends with the RUN bit reset. All operations begin with the rising edge of the  $\overline{SS}$ .

# **SPI CONTROL REGISTER**

The SPI control register provides control of individual device functions such as play, record, stop/pause, message cueing (fast forward), power-up, power-down, start and stop operations and ignore address pointers.

There are five control bits associated with the ISD33000 that control the device. These bits are:

# C0 = MC

When this bit is set to 1 during playback it starts a message cueing cycle (Fast forward to the next EOM). C0 operation is not defined during Record.

#### C1 = IAB

When this bit is set to 1, any address data shifted into the SPI MOSI shift register is ignored. A resulting Record, Playback or Message Cueing operation

will begin at the next address in the device memory at the end of the proceeding operation.

When IAB (Ignore Address Bit) is set LOW, a playback or record operation starts from address (A9–A0) and ends at the end of that row. If no other control data is input to the SPI port, the device will continue that operation over again at the same address and therefore "loop" on that row. To continue playback or record consecutively through the memory, a second SPI cycle should immediately be input with the IAB bit changed HIGH before the device reaches the end of a row. To stop an operation it is important to note that if the IAB bit is LOW, the data shifted into address bit locations will be transferred to the device's internal address register and the device's internal address prior to the stop instruction will be lost.

It is recommended to set AB = HIGH when a stop/pause command is issued if address read back is desired.

# C2 = PU

When this bit is set HIGH, the device powers-up and is ready for an operation after  $T_{PUD}$  (approximately 25 ms). Wait  $T_{PUD}$  before issuing an operational command. It is important to wait  $T_{PUD}$  after the power-up command is issued before sending another command; the device will not function properly if a record or playback command with power-up command is issued in the same SPI cycle. For example to record from address 00 the following program cycle should be used.

- 1. Send power-up command (00100 < X-X)
- **2.** Wait T<sub>PUD</sub> (per device specification, approximately 25 ms)
- **3.** Start recording (10100 < A9 A0 >)
- **4.** Continue consecutive recording (10110 <X-X>)
- **5.** C3 = P/R. When this bit is set HIGH, the device goes to playback mode and when it is LOW the device goes to record mode.
- **6.** C4 = RUN. When this bit is pulled HIGH, the device begins an operation and when LOW, stops an operation.

# SPI OPCODE FORMAT

The ISD33000 accepts either an 8-bit command or 16-bit command from a microcontroller through the SPI port. The opcode format is 5 control bits and 11 address bits for a 16-bit command. The opcode format is 5 control bits and 3 address bits for an 8 bit command with the 3 address bits being "don't care" bits.

# **EXAMPLES OF RECORD/PLAYBACK OPERATION**

### RECORD AT AN ADDRESS

# **Power Up the Device**

Send 00100 < xxxx > to the SPI

Wait T<sub>PUD</sub>

Send 00100 < xxxx > to the SPI

Wait 2 x T<sub>PUD</sub>

# Start Recording at <10 bit address >

Send 10100 < x > < 10bit address> (note; |AB = 0) Send 10110 < xxxx > (note; |AB = 1)

Recording will continue until memory is full or a new SPI cycle with RUN = 0 is input or until the end of memory is reached (Overflow Interrupt).

#### **Stop Record and Power down**

Send 00000 < xxxx > to the SPI

OR

# Stop/Pause Record and Do Not Power-Down

Send 0 0110 < xxxx>

### RECORD A MESSAGE AT THE NEXT AVAILABLE ADDRESS

#### If the Device is Not Powered Up

Send 00100 < xxxx > to the SPI

Wait T<sub>PUD</sub>

Send 00100 < xxxx > to the SPI

Wait 2 x T<sub>PUD</sub>

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# **Record the Next Message**

Send 10110 < xxx >

Recording continues until ready to stop (or device runs out of memory space)

# **PLAYBACK AT AN ADDRESS**

# **Power Up the Device**

Send 01100 < xxx > to the device.

Wait T<sub>PUD</sub>

# Start Playback at <10 bit Address>

Send 11100 < x > < 10 bit address >

Send 11110<xxx> to continue playback.

Playback continues until memory overflows or ready to end (reaches EOM).

Stop playback and power down.

Send 01010 < xxx > .

OR

Stop Playback don't power down.

Send 01110 < xxx > 1

# PLAYBACK AT THE NEXT MESSAGE

# If the device is Not Powered Up

Send 01100 < xxxx >

Wait T<sub>PUD</sub>

Playback the next message

Send 111110<xxx>

Playback continues until an EOM is reached (or chip runs out of memory space)

# PLAYBACK THE "3RD" MESSAGE (FAST FORWARD TO MESSAGE NUMBER 3 AND PLAY IT)

#### Power up the device

Send 01100 < xxx >

Wait T<sub>PUD</sub>

# Start Message Cueing Cycle at "0" Address

Send 11101<x><00 0000 0000>

Send 111111<xxx>

Device runs at 800 times normal play speed, audio muted.

Device stops at next EOM, gives EOM interrupt, increments address counter 1 count, now the address pointers points to '2nd" Message. Execute second message cueing cycle at "next" message.

Send 111111<xxx>

Device runs at 800 times normal play speed, audio muted.

Device stops at next EOM, gives EOM interrupt, incumbents address counter 1 count, now the address pointers points to '3rd" message. Play "next" message.

Send 11110<xxx>

The third message will play at normal speed. When message ends EOM interrupt occurs

# **READ INTERRUPT STATUS BITS AND CURRENT ADDRESS**

#### **Clock in Instruction**

Send <xxxxx><xxx>

Device will execute the operation as specified by the instruction.

If there is no desire to change the status of the device, care should be taken that the command is compatible with current operation.

Send SPI 8 clocks to read the status bits (OVF and EOM)

Send SPI 16 clocks to read status and current address.

3

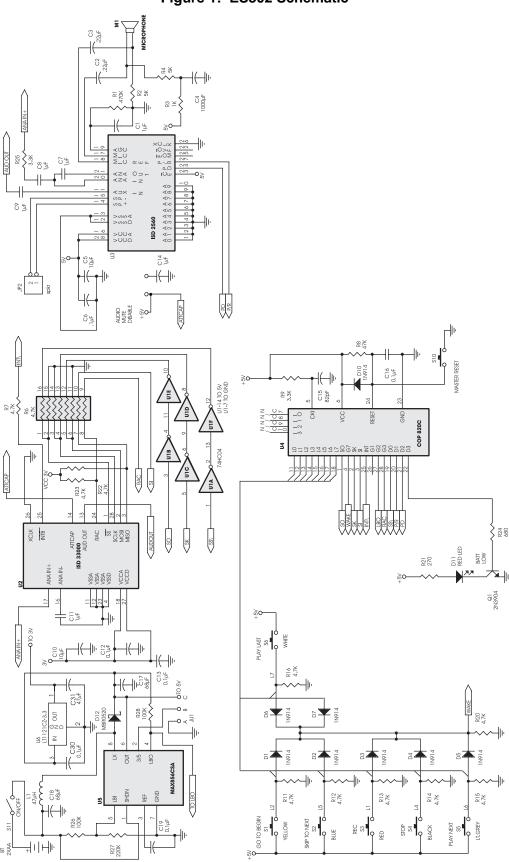


Figure 1: ES302 Schematic

NOTE: L1 is a Sumida CD43-470. C17 and C18 are 10V Tantalum (SMD). D12 substitute 1N817 SCHOTTKY.

# APPLICATION EXAMPLE (ISD33000 DEMO BOARD)

The ISD-ES302 Demo Board is designed to enable listeners hear the voice quality of the 3-volt part and to demonstrate some of the features available through the SPI control bus.

#### FEATURES OF THE ISD-ES302 DEMO BOARD

- Record
- · Play—last
- Play—next
- Stop/pause
- Go-to- beginning of memory
- Fast forward through messages.

### **HARDWARE**

The three major integrated circuits on the board are the ISD33000 voice chip, U2, the NSC COP820C microcontroller, U4, and an audio chip, U3. The audio chip is an ISD2560 of which only the microphone preamplifier and the speaker driver are used. It is run on five volts whereas the ISD33000 is run on three volts. The audio chip would not normally be needed because the audio input and speaker output functions are already on the board in a cellular phone, for example. The board is powered by two AA cells. These cells drive a voltage converter to get the five volts for the audio chip and the microcontroller. This voltage is then regulated down to three volts (or 3.3 VDC) for the ISD33000 device.

#### **SOFTWARE**

COP8 is an 8-bit microcontroller from National Semi Conductor with 1 Kbytes of on-chip ROM and 64 bytes of on-chip RAM. The serial interface on-chip "microwire" is compatible with the ISD33000 SPI port.

The COP microcontroller provides the interface between the user's fingers on the keyboard and the ISD33000 device. It interprets the key strokes and issues the appropriate commands to the ISD33000. It also monitors the ISD33000 status registers and interrupt output to keep track of operations. The program also handles any interrupt that is generated by the ISD33000 during playback.

The following flowchart is used to create the demo software. The interrupt is a background routine. Every time an EOM or OVF is detected the ISD33000 will generate an interrupt. The microcontroller issues a stop command when EOM is detected and when an OVF is detected, the microcontroller re-initializes the address pointer to beginning of the memory in play mode followed by a stop command.

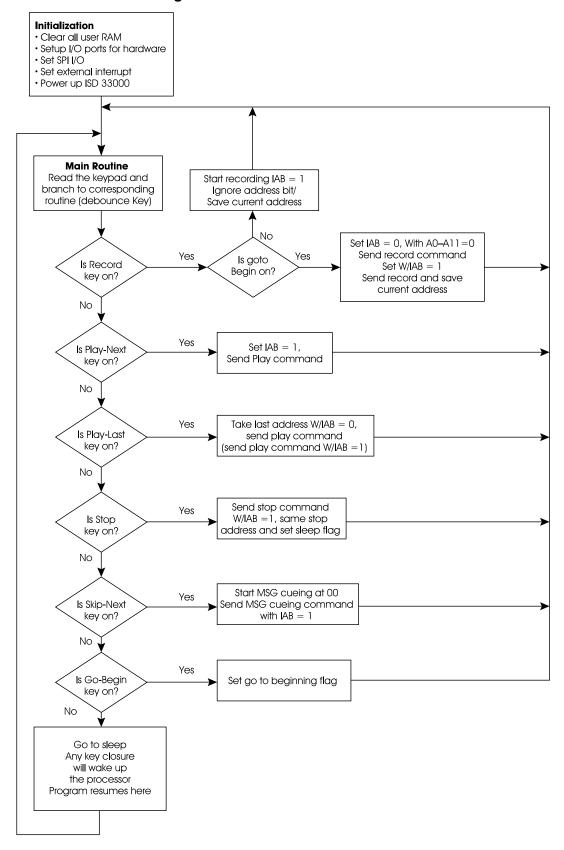


Figure 2: Demo Software Flowchart

**Interrupt Routine** The interrupt pin of ISD33000 is connected to the ext. interrupt pin of microcontroller. When an interrupt occurs the program branches here. Error, goto No Is it external software trap interrupt? routine Yes Read status bits EOM EOM Send stop Return from or command and set Int interrupt **OVF OVF** Clear Int, send play A0->A9 = 00 w/IAB = 0send stop command and set Int Return from interrupt

**Figure 3: Interrupt Routine Flowchart** 

```
*******************
; *
  ISD33000 DEMO
                    PROGRAM
; *
   SECOND VERSION
; *
; *
   (C) 1996 INFORMATION STORAGE DEVICES
; *
; *
; *
    MICROCONTROLLER : COP820C
; *
    DATE OF LAST REVISION: 06.03.96
; *
    NAME OF SOURCE FILE : demo.asm
    CLOCK SPEED
                    : 2.8 - 2.2 MHz
.INCLD COP820.INC ;SYMBOLS USED FREQUENTLY BY COP820
;Assignment For ISD33000 DEMO
;* CONSTANT DECLARATIONS
  SS = 0 ; SLAVE SELECT
            2
                 ; D PORT PIN 2
  D2
      =
  D1
      =
            1
                  ; D PORT PIN 1
  LED
            3
                 ; LED INDICTOR PIN
            2
                 ; LOW BAT DETECTOR
  T<sub>1</sub>BO
; REGISTERS
  DELC2 = 0F0
                 ; COUNTER FOR SOFTWARE TIME LOOPS
            0F1
                 ; COUNTER FOR SOFTWARE TIME LOOPS
  DELC1 =
            0F2
  DBU =
                 ; COUNTER FOR DEBOUNCE TIME
  0FC
                  ; RESERVED FOR X POINTER
  0FD
                  ; RESERVED FOR STACK POINTER
  0FE
                  ; RESERVED FOR B POINTER
; MEMORY
STAT
            0C
                  ; STATUS REGISTER
            00
                 ; STOP OR COMPLETION
  NEW =
  OVF
            01
                 ; OVERFLOW
                 ; BEGGIN OF MEMORY
  BEG
      =
            02
           03
  HALT =
                 ; OPERATION COMPLETED
  EOM =
            04
                 ; 1 END OF MESSAGE
  EOS
            05
                 ; 1 EXTERNAL INTERRUPT PENDING
      =
         06
  EXTIN =
                 ; 1=EXTERNAL INTERRUP PENDING
;______
  ADDR0 =
            001
                 ; BCD TO BINARY LOCATION BINARY IN [1,0] BCD IN [3,2]
  TDBUFF =
            002
                 ; TOP OF DATA BUFFER HOLDS STOP ADDRESS BYTE 1
  ADDR1 =
            003
                  ; MEMORY LOCATION FORM TEMPORARY DATA
            004
  TEMP =
                 ; TEMPORARY REGISTER
  TDBUF1 =
            005
                 ; TOP OF DATA BUFFER1 HOLDS STOP ADDRESS BYTE 2
            006
  KEYBUF =
                 ; COMMAND BUFFER
  KEYIN =
            007
                 ; HOLDS ADDRESS LOWER BYTE
            800
                 ; HOLDS ADDRESS UPPER BYTE
  KEYIN1 =
  SAVEA =
            009
                 ; SAVE ACUMULATOR WHEN IN INTERRUPT
            A00
  SAVEB =
                 ; B REGISTER SAVE AREA
  SAVEX = 00B
                 ; X POINTER SAVE AREA
```

```
;026.....02F; RESERVED STACK AREA
  STACK = 02F ; TOP OF STACK
.FORM
INTIALIZE REGISTERS
     POWER UP AND PRESET ROUTINE
.SECT CODE, ROM, ABS=0
CLRRAM:
  LD
        B,#00 ; CLEAR ALL USER RAM including I/O ports
  LD
       X,#0FC ; AND REGISTERS
DONE:CLR A
  X
        A,[B+]
  DRSZ
       Χ
  JΡ
       DONE
;START PROGRAM EXECUTION
       SP, #02F DEFAULT STACK INITIALIZATION
REST:LD
        B, #PORTLD; CONFIGURE L-PORT
  _{
m LD}
       [B+],#0FF
  LD
       [B],#000; MAKE ALL L PINS INPUT
  _{
m LD}
  _{
m LD}
        B, #PORTGD; CONFIGURE G PORT
  LD
       [B+],#01F; IRQ LOW, PORTG DATA REGISTER
  LD
       [B],#030; SET I/O FOR G POR & Microwire
       PORTD, #07; initialize portd
; ENABLE INTERRUPT
*************************
  LD
        B, #CNTRL
  LD
        [B+],#08C; CNTRL REGISTER SELECT MUIRE
  LD
       [B],#003; INITIALIZE PSW
       B,#0FF
  _{
m LD}
A,#000 ; INITIALIZE ADDRESS TO 00
  RBIT
       SS, PORTD; ENABLE SPI
  JSR
       SPIX
            ; SEND OUT THE COMMAND
       A,#000 ; POWER UP, USE INPUT ADDRESS REG.
  LD
       SPIX
  SBIT
       SS, PORTD; DISABLE SPI
       DELC1, #02; INITIALIZE DELAY COUNTER
        PWRUP ; SEND POWER-UP COMMAND
;************* WAIT FOR AN INPUT HERE **********************
              MAIN LOOP WAITING FOR A SWITCH CLOSER
READ:
  IFBIT LBO, PORTGP; IF LOW BATT PIN IS LOW GO TO WARNING ROUTINE
  JΡ
       READ1 ;ELSE PROCEED
       WARNING; GO TO WARNING ROUTINE
; BRANCH ACCORDING TO THE KEY PUSHED ON THE KEY PAD
READ1:
        PORTLC, #000; CONFIGURE L PORT AS INPUT PORT
  LD
        PORTLD, #0FF; WEAK PULL-UP
```

```
LD
        A, PORTLP; READ PORT L
  LD
        DELC1, #30; DE-BOUNCE THE SWITCH
  JSR
        DELAY1
        A, #0FF ; SELECT THE SWITCHES
  AND
  IFEO
      A,#040
  JΡ
        PLAY
            ; PLAY AT THE "NEXT" ADDRESS
  IFEQ
        A,#02
        REC ; RECORD AT THE "NEXT" ADDRESS
  JΡ
  IFEO
      A,#010
  JΡ
        STOP
             ; STOP PLAYBACK OR RECORD
  IFEQ
        A,#080
  JΡ
       PLAYO ; PLAY ADDRESS 0
       A,#008
  IFEO
  JΡ
        REC0
             ; RECORD AT ADDRESS 0
  IFEQ
        A,#020
        MSGCUE ; DO A MESSAGE CUEING CYCLE
  JΡ
        A,#004
  IFEQ
  JMP
        GOTOB
  IFBIT HALT, STAT; IF SLEEP MODE IS SET GO TO SLEEP ROUTINE
  JΡ
       HALT1 ; GO TO SLEEP ROUTINE
        READ ; ELSE BACK TO MAIN
  JΡ
HALT1:
  RBIT HALT, STAT; RESET SLEEP MODE FLAG
  SBIT 7, PORTGD; MICRO IS PUT TO SLEEP MODE FOR
       ; POWER SAVING
  NOP
  NOP
       ; THE PROGRAM RESUMES HERE WHEN A KEY
  NOP
       ; RESET BUTTON IS PUSHED
  NOP
        READ
            ; GO WAIT FOR AN INPUT
INITIALIZE ISD33000 Routine
PWRUP:
  LD
       A,#004 ; 00100 POWER UP ISD33000
  RBIT SS, PORTD; SELECT ISD33000
        SPIX ; SEND OUT THE POWER UP COMMAND
        SS, PORTD; DISABLE SPI
  SBIT
  RET
GENERIC DELAY ROUTINE 256TC X 256TC( TC= INSTRUCTION CYCLE )
DELAY1:LD DELC2,#0FF
DELAY2:DRSZDELC2 ; DELAY ROUTINE MAX LENGTH 256 LOOPS
  JΡ
        DELAY2
  DRSZ
      DELC1
  JΡ
       DELAY1
  RET
; MESSAGE CUEING CYCLE
MSGCUE:
        LED, PORTD; FLASH LED FOR 50MS TO INDICATE
  SBIT
  ; A MSG CUEING CYCLE
        DELC1, #0F; DE-BOUNCE THE SWITCH
  JSR
        DELAY1 ; USE DELAY1 ROUTINE
```

```
RBIT
       LED, PORTD; LED OFF
       A, #01F ; SEND MESSAGE CUEING COMMAND ;
  ; WITH IAB = 1
  RBIT
       SS, PORTD; ENABLE SPI
       SPIX
           ; SEND OUT THE COMMAND
  SBIT
       SS, PORTD; DISABLE SPI
       READ ; DONE GO TO MAIN ROUTINE
  JMP
.FORM
*BEGIN INTERRUPT ROUTINE
.=X'OOFF
;INTERRUPT SERVICE ROUTINE , THE PROGRAM BRANCHES HERE WHEN THE PROCESSOR IS INTERRUPTED
INT1:
  IFBIT IPND, PSW; CHECK IF EXTERNAL INTERRUPT PENDING
            ; GO SERVICE EXT. INTERRUPT
  JΡ
       EXT
       CLRRAM ; ELSE ILLEGAL CONDITION RESET PROCESSOR
EXT:
       PUSH
            ; SAVE REGISTERS
  JSR
       IPND, PSW; RESET EXTERNAL INTERRUPT PENDING
  RBIT
  JSR
       STOPX ; ISSUE A STOP COMMAND IF END OF MESSAGE
  IFBIT 07, TDBUFF; CHECK IF OVERFLOW ?
  JSR
       OVFPO ; YES GO TO OVERFLOW RECOVERY ROUTINE
  JSR
       POP
             ; RETURN FROM INTERRUPT
  RETI
; RECORD AT "LAST" ADDRESS
IFBIT BEG, STAT; IF BEG OF MEMORY GO RECORD FROM 0
       RECO\ ; ELSE
       A,#000 ; READ THE ADDRESS POINTER
       SS, PORTD
  RBIT
                  ;
  JSR
       SPIX
       A,KEYBUF
                 ; READ THE OUTPUT DATA
  LD
  X
       A,KEYIN
                 ; SAVE IT IN KEY IN
  LD
       A,#00D
       SPIX
           ; GET THE DATA FROM THE INCOMING BUFFER
  JSR
       A, KEYBUF; READ THE OUTPUT DATA
  LD
       A, KEYIN1; SAVE SECOND BYTE
  X
  SBIT
       SS, PORTD;
  SBIT
       NEW, STAT
                 ; INDICATE A NEW RECORDING CYCLE
  RBIT
       D2,PORTD
                 ; POWER AMPS ON
  RBIT
       D1,PORTD
                 ; RECORD MODE
  SBIT
       LED, PORTD
                  ; REC OPERATION IN PROGRESS
           ; DONE WAIT FOR ANOTHER COMMAND OR OVF
       READ
;THIS ROUTINE SENDS ANY GIVEN COMMAND AND RETURNS THE ADDRESS
; POINTER ONE BYTE AT THE TIME SAVES THE RETURN ADDRESS IN KEYBUF
;BE AWARE THAT ANY UN READ KEYBUF WILL BE LOST WITH THE NEXT SPI
```

```
SPIX:
        A, SIOR ; LOAD THE SPI SHIFT REGISTER
  X
         #BUSY, PSW; ENABLE THE SPI SHIFT REGISTER
WAIT: IFBIT #BUSY, PSW; IF IN THE MIDDLE OF TRANSMISSION
        WAIT
              ; WAIT until done
  X
        A,SIOR ; READ SPI SHIFT REGISTER
  X
         A, KEYBUF; SAVE THE STATUS IN KEYBUF
  RET
; STOP WITH IAB=1
STOP: JSRSTOPX; SEND A STOP COMMAND
  JMP
       READ
STOP ROUTINE
STOPX: RBIT LED, PORTD; LED OFF
  SBIT D2, PORTD; DISABLE POWER AMPS
  T<sub>1</sub>D
        A, #000 ; SET THE STOP COMMAND WITH POWER UP BIT
  RBIT SS, PORTD; DISABLE SPI
  JSR
        SPIX
        A, KEYBUF; GET THE ADDRESS FROM THE BUFFER
  LD
  Х
        A, TDBUFF; SAVE IT IN TDBUFF MEMORY LOCATION
        A, #00E; SET THE STOP COMMAND WITH POWER UP BIT
  ; IN PLAY MODE WITH IAB = 1
  JSR
       SPIX
  T<sub>1</sub>D
       A, KEYBUF;
       A, TDBUF1; SAVE THE 2ND BYTE
  SBIT SS, PORTD; DISABLE SPI
  SBIT
        HALT, STAT; GO TO SLEEP MODE
  RET
IGNORE ADDRESS BITS
   ; PLAY AT "LAST" ADDRESS
                       ROUTINE
PIAY:
  RBIT D2, PORTD
  SBIT D1, PORTD; UT ISD1000A IN PLAY MODE
  SBIT LED, PORTD; INDICATE PLAY IN PROGRESS
  IFBIT BEG, STAT; CHECK IF PLAY FROM BEG OF MEMORY
        PLAY2 ; YES, RESET ADDRESS TO 00 AND PLAY
  JMP
PLAYN:
  LD
        A, \#00E; PLAY IAB = 1, PU =1, P/R =1 RUN =0
  RBIT SS, PORTD;
             ;
  JSR
        SPIX
  SBIT
        SS, PORTD;
        A,\#00F; PLAY IAB = 1, PU =1, P/R =1 RUN =1
  L'D
  RBIT
        SS, PORTD;
       SPIX
  JSR
  SBIT SS, PORTD;
        READ ; DONE GO WAIT FOR ANOTHER COMMAND
  JMP
        A,\#000; PLAY IAB = 1, PU =1, P/R =1 RUN =0
PLAY2:LD
  RBIT SS, PORTD;
  JSR
        SPIX
        A,\#007 ; PLAY IAB = 1, PU =1, P/R =1 RUN =1
  LD
  RBIT SS, PORTD;
```

```
JSR
         SPIX
         SS, PORTD;
   SBIT
   RBIT
         BEG, STAT; RESET BEG OF MEMORY FLAG
   JMP
         PLAYN ; GO CONTINUE
;GO TO BEGINNING OF MEMORY THIS ROUTINE ONLY FLASHES AN LED AND SETS
; A FLAG TO INDICATE THE BEG OF MEMORY BUTTON IS PUSHED
GOTOB:
   SBIT
         LED, PORTD; LED ON
   SBIT
         BEG, STAT;
   LD
         DELC1, #0F; DE-BOUNCE THE SWITCH
   JSR
         DELAY1
   RBIT
         LED, PORTD; LED OFF
         DELC1, #0F; DELAY
   LD
   JSR
         DELAY1 ;
         LED, PORTD; LED ON
   SBIT
         DELC1, #0F; DELAY
   LD
   JSR
         DELAY1 ;
   RBIT
        LED, PORTD; LED OFF
              ; DONE WAIT FOR ANOTHER COMMAND
   JMP
         READ
;START PLAY AT ADDRESS 0 IGNORE ADDRESS BITS
PLAY0:JSR PLAY1 ; USE THE PLAY1 ROUTINE
         READ
               ; DONE GO WAIT FOR ANOTHER COMMAND
   JMP
PLAY1:
         D2, PORTD; PD PIN TO 0
  RBIT
   SBIT
         D1, PORTD; PUT ISD1000A IN PLAY MODE (P/R)
         LED, PORTD;
   SBIT
   IFBIT NEW, STAT; IF THERE IS NO NEW RECORD SKIP
         PLAYNW ;
   JMP
   JMP
         PLAYA ; PLAYA ELSE
PLAYNW:
   LD
         TEMP, #00; THIS ROUTINE READS THE ADDRESS POINTER
   IFBIT
         5, KEYIN; PREPARES IT FOR SPI REGISTER
         7, TEMP ; SAVE THE FISRT BYTE IN KEYIN AND SECOND
   SBIT
   IFBIT 4, KEYIN; BYTE IN KEYIN1 MEMORY LOCATIONS
   SBIT
         6,TEMP
   IFBIT
         3,KEYIN
   SBIT
         5,TEMP
         2,KEYIN
   IFBIT
   SBIT
         4,TEMP
   IFBIT 1, KEYIN
   SBIT
         3,TEMP
   IFBIT
         0,KEYIN
   SBIT
         2,TEMP
   LD
         A,TEMP
   Χ
         A, KEYIN
   LD
         A, KEYIN1
         A,TEMP
   Χ
   IFBIT 7,TEMP
   SBIT
         1,KEYIN
   IFBIT
         6,TEMP
   SBIT
         0,KEYIN
```

```
LD
        A,#00
   Х
        A, KEYIN1
   IFBIT 5,TEMP
        7,KEYIN1
   SBIT
   IFBIT 4, TEMP
   SBIT
         6,KEYIN1
        NEW, STAT
   RBIT
PLAYA:
        A, KEYIN; READ THE KEYIN BUFFER
  LD
  RBIT
        SS, PORTD; SEND OUT THE ADDRESS
   JSR
        SPIX
   _{
m LD}
        A, \#007; PLAY IAB = 0, PU =1, P/R =1 RUN =1
       A, KEYIN1;
   OR
   JSR
        SPIX
              ;
   SBIT
       SS, PORTD; DISABLE SPI
        SS, PORTD
        A,\#00E; PLAY IAB = 1, PU =1, P/R =1 RUN =0
   LD
        SS, PORTD
   RBIT
   JSR
        SPIX
   SBIT SS, PORTD;
   RBIT
        SS, PORTD;
   LD
        A,\#00F; PLAY IAB = 1, PU =1, P/R =1 RUN =1
   RBIT
        SS, PORTD;
        SPIX
   JSR
   SBIT
        SS, PORTD;
   RET
; RECORD AT ADDRESS 0
REC0:
  RBIT
        D2, PORTD; POWER AMPS OFF
  RBIT
       D1, PORTD; RECORD MODE
       LED, PORTD
   SBIT
   _{
m LD}
        A,#000 ; INITIALIZE ROWS =000
   RBIT SS, PORTD; ENABLE SPI
   JSR
         SPIX
  LD
       A, \#005; REC IAB = 0, PU = 1, P/R = 0 RUN = 1
   JSR
       SPIX
              ;
  SBIT
        SS, PORTD; DISABLE SPI
        A, \#00D; REC IAB = 1, PU = 1, P/R = 0 RUN = 1
   LD
   RBIT SS, PORTD;
   JSR
        SPIX
   SBIT
        SS, PORTD;
  RBIT
        BEG, STAT;
   JMP
        READ
; PUSH AND POP ROUTINES FOR SAVING REG. DURING INTERRUPT
******************
  LD
        A, SAVEX
   Χ
        A,X
   LD
        A, SAVEB
   Χ
        A,B
   LD
        A, LCDPTR
   Х
        A, PORTLD
```

```
LD
        A, SAVEA
  RET
PUSH:
   Χ
        A, SAVEA
  _{
m LD}
        A,B
  Χ
        A, SAVEB
  LD
        A,X
  Χ
        A, SAVEX
        A, PORTLD
  LD
        A,LCDPTR
  Χ
  RET
WARNING:
   SBIT
        LED, PORTD
  LD
        DELC1, #50; DE-BOUNCE THE SWITCH
  JSR
        DELAY1
        LED, PORTD
  RBIT
  LD
        DELC1, #50; DE-BOUNCE THE SWITCH
   JSR
        DELAY1
        WARNING
OVERFLOW RECOVERY ROUTINE
; INITIALIZE ADDRESS POINTERS TO 00 IN PLAY MODE AND IMMEDIATELY STOP THE OPERATION.
OVFPO:
        SS, PORTD
  RBIT
        A,#000 ; POWER UP, USE INPUT ADDRESS REG.
        SPIX
  JSR
        A, \#007; PLAY MODE WITH IAB = 0
  LD
   JSR
        SPIX
   SBIT
        SS, PORTD
        A,#000 ; POWER UP, USE INPUT ADDRESS REG.
  _{
m LD}
        SS,PORTD
  RBIT
   JSR
        SPIX
  LD
        A,\#006 ; STOP MODE WITH IAB = 0
   JSR
        SPIX
   SBIT
        SS, PORTD
  RET
 .ENDCLRRAM
```

# **INSTRUCTIONS**

Six of the 9 push-buttons are labeled on the PCB. Pushing the yellow "GO\_TO\_BEG" button will reset the address pointer to the front of the chip or address 000. There will be a double flash of the LED, D11, in the bottom left corner of the PCB to indicate that this has been done.

Pushing the red "RECORD" button will turn on the red LED to indicate that the chip is now recording anything it hears at the microphone M1 near the top center of the board. The board will continue to record until the end of the chip is reached or the black "STOP" button is pressed. At that time, the LED will go out and the board will stop recording.

Pushing the white "PLAY\_LAST" button will playback what was just recorded. The message will play through to its end or stop when the black "STOP" button is pressed.

Pushing the yellow "GO\_TO\_BEG" button and then the white "PLAY\_NEXT" button will play messages from the beginning of memory through to the end or stop/pause when the black "STOP" button is pressed. To resume playback after pause, push PLAY\_NEXT again. To play the next message, press PLAY\_NEXT.

The blue "SKIP\_TO\_NEXT" button bypasses a message and plays the one after. For example, if three message are recorded beginning at the front of the chip, after the last message press the white "PLAY\_NEXT" button to play the first message, press the blue "SKIP\_TO\_NEXT" button to bypass the second message and then press the white "PLAY\_NEXT" to play the third message.