

#### 4M x 4 12/10 EDO DRAM

#### **Features**

- 4,194,304 word by 4 bit organization
- Single 3.3V  $\pm$  0.3V or 5.0V  $\pm$  0.5V power supply
- Standard Power (SP) and Low Power (LP)
- 4096 Refresh Cycles
  - 64 ms Refresh Rate (SP version)
  - 256 ms Refresh Rate (LP version)
- · High Performance:

		-50	-60	Units
t <sub>RAC</sub>	RAS Access Time	50	60	ns
t <sub>CAC</sub>	CAS Access Time	13	15	ns
t <sub>AA</sub>	Column Address Access Time	25	30	ns
t <sub>RC</sub>	Cycle Time	84	104	ns
t <sub>HPC</sub>	EDO (Hyper Page) Mode Cycle Time	20	25	ns

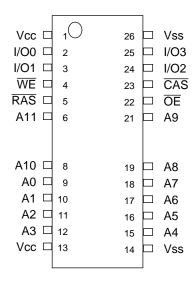
- Low Power Dissipation
  - Active (max) 55 mA / 50 mA
  - Standby: TTL Inputs (max) 1.0 mA
  - Standby: CMOS Inputs (max)
    - 1.0 mA (SP version)
    - 0.1 mA (LP version)
  - Self Refresh (LP version only)
    - 200μA (3.3 Volt)
    - 300μA (5.0 Volt)
- Extended Data Out (Hyper Page) Mode
- · Read-Modify-Write
- RAS Only and CAS before RAS Refresh
- Hidden Refresh
- Package: SOJ 26/24 (300milx675mil) TSOP-26/24 (300milx675mil)

#### **Description**

The IBM0116405 is a dynamic RAM organized 4,194,304 words by 4 bits, which has a very low "sleep mode" power consumption option. These devices are fabricated in IBM's advanced  $0.5\mu m$  CMOS silicon gate process technology. The circuit and process have been carefully designed to pro-

vide high performance, low power dissipation, and high reliability. The devices operate with a single  $3.3V \pm 0.3V$  or  $5.0V \pm 0.5V$  power supply. The 22 addresses required to access any bit of data are multiplexed (12 are strobed with  $\overline{RAS}$ , 10 are strobed with  $\overline{CAS}$ ).

#### Pin Assignments (Top View)



#### **Pin Description**

RAS	Row Address Strobe
CAS	Column Address Strobe
WE	Read/Write Input
A0 - A11	Address Inputs
ŌĒ	Output Enable
I/O0 - I/O3	Data Input/Output
V <sub>CC</sub>	Power (+3.3V or +5.0V)
V <sub>SS</sub>	Ground



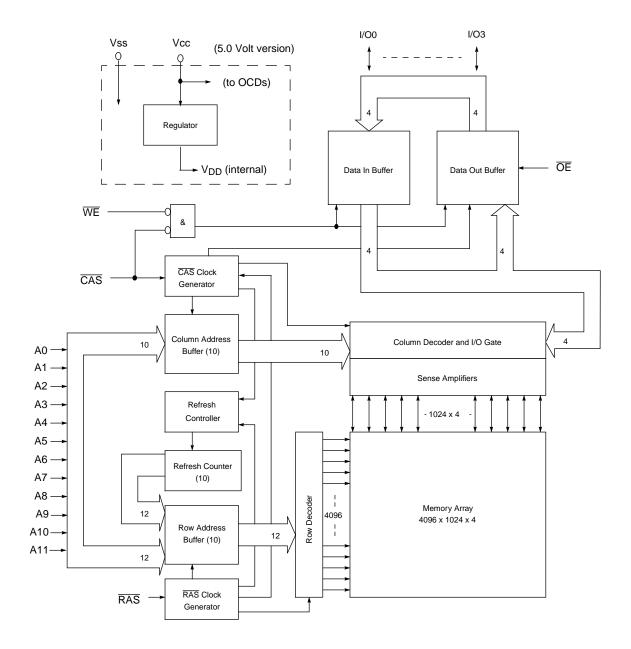
#### **Ordering Information**

Part Number	SP/LP	Self Refresh	Power Supply	Speed	Package	Notes
IBM0116405T1 -50	SP	No	5.0V	50ns	300mil TSOP-II 26/24	1
IBM0116405T1 -60	SP	No	5.0V	60ns	300mil TSOP-II 26/24	1
IBM0116405BT1 -50	SP	No	3.3V	50ns	300mil TSOP-II 26/24	1
IBM0116405BT1 -60	SP	No	3.3V	60ns	300mil TSOP-II 26/24	1
IBM0116405J1 -50	SP	No	5.0V	50ns	300mil SOJ 26/24	1
IBM0116405J1 -60	SP	No	5.0V	60ns	300mil SOJ 26/24	1
IBM0116405BJ1 -50	SP	No	3.3V	50ns	300mil SOJ 26/24	1
IBM0116405BJ1 -60	SP	No	3.3V	60ns	300mil SOJ 26/24	1
IBM0116405MT1 -50	LP	Yes	5.0V	50ns	300mil TSOP-II 26/24	1
IBM0116405MT1 -60	LP	Yes	5.0V	60ns	300mil TSOP-II 26/24	1
IBM0116405PT1 -50	LP	Yes	3.3V	50ns	300mil TSOP-II 26/24	1
IBM0116405PT1 -60	LP	Yes	3.3V	60ns	300mil TSOP-II 26/24	1
IBM0116405MJ1 -50	LP	Yes	5.0V	50ns	300mil TSOJ 26/24	1
IBM0116405MJ1 -60	LP	Yes	5.0V	60ns	300mil TSOJ 26/24	1
IBM0116405PJ1 -50	LP	Yes	3.3V	50ns	300mil TSOJ 26/24	1
IBM0116405PJ1 -60	LP	Yes	3.3V	60ns	300mil TSOJ 26/24	1

<sup>1.</sup> SP = Standard Power version (IBM0116405 and IBM0116405B); LP = Low Power version (IBM0116405M and IBM00116405P)



### **Block Diagram**



# Discontinued (9/98 - last order; 3/99 last ship)

IBM0116405 IBM0116405M IBM0116405B IBM0116405P **4M x 4 12/10 EDO DRAM** 



#### **Truth Table**

Function		RAS	CAS	WE	ŌĒ	Row Address	Column Address	I/O0 - I/O3
Standby		Н	Н→Х	Х	Х	Х	Х	High Impedance
Read		L	L	Н	L	Row	Col	Data Out
Early-Write		L	L	L	Х	Row	Col	Data In
Delayed-Write		L	L	H→L	Н	Row	Col	Data In
Read-Modify-Write		L	L	H→L	L→H	Row	Col	Data Out, Data In
EDO (Hyper Page) Mode	1st Cycle	L	H→L	Н	L	Row	Col	Data Out
Read	2nd Cycle	L	H→L	Н	L	N/A	Col	Data Out
EDO (Hyper Page) Mode	1st Cycle	L	H→L	L	Х	Row	Col	Data In
Write	2nd Cycle	L	H→L	L	Х	N/A	Col	Data In
EDO (Hyper Page) Mode	1st Cycle	L	H→L	H→L	L→H	Row	Col	Data Out, Data In
Read-Modify-Write	2nd Cycle	L	H→L	H→L	L→H	N/A	Col	Data Out, Data In
RAS-Only Refresh		L	Н	Х	Х	Row	N/A	High Impedance
CAS-Before-RAS Refresh		H→L	L	Н	Х	Х	N/A	High Impedance
Lliddon Dofrach	Read	L→H→L	L	Н	L	Row	Col	Data Out
Hidden Refresh	Write	L→H→L	L	L→H	L	Row	Col	Data In
Self Refresh (LP version only)		H→L	L	Н	Х	Х	Х	High Impedance



#### **Absolute Maximum Ratings**

Cumbal	Parameter	Rat	ting	Units	Notes
Symbol	Parameter	3.3 Volt Device	5.0 Volt Device		Notes
V <sub>CC</sub>	Power Supply Voltage	-0.5 to +4.6	-1.0 to +7.0	V	1
V <sub>IN</sub>	Input Voltage	-0.5 to min (V <sub>CC</sub> +0.5, 4.6)	-0.5 to min (V <sub>CC</sub> +0.5, 7.0)	V	1
V <sub>OUT</sub>	Output Voltage	-0.5 to min (V <sub>CC</sub> +0.5, 4.6)	-0.5 to min (V <sub>CC</sub> +0.5, 7.0)	V	1
T <sub>OPR</sub>	Operating Temperature	0 to +70	0 to +70	°C	1
T <sub>STG</sub>	Storage Temperature	-55 to +150	-55 to +150	°C	1
P <sub>D</sub>	Power Dissipation	1.0	1.0	W	1
I <sub>OUT</sub>	Short Circuit Output Current	50	50	mA	1

Stresses greater than those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a
stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational
sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

#### **Recommended DC Operating Conditions** (T<sub>A</sub>= 0 to 70°C)

Cumbal	Cumbal Daramatar		3.3 Volt Device			.0 Volt Devic	е	Units	Notes
Symbol	Symbol Parameter	Min.	Тур.	Max.	Min.	Тур.	Max.	Units	Notes
V <sub>CC</sub>	Supply Voltage	3.0	3.3	3.6	4.5	5.0	5.5	V	1
V <sub>IH</sub>	Input High Voltage	2.0	<del>_</del>	V <sub>CC</sub> + 0.5	2.4	<del>_</del>	V <sub>CC</sub> + 0.5	V	1, 2
V <sub>IL</sub>	Input Low Voltage	-0.5	_	0.8	-0.5	_	0.8	V	1, 2

<sup>1.</sup> All voltages referenced to  $V_{SS}$ .

#### **Capacitance** ( $T_A$ = 25°C, $V_{CC}$ = 3.3 $V \pm 0.3V$ or $V_{CC}$ = 5.0 $V \pm 0.5V$ )

Symbol	Parameter	Min.	Max.	Units	Notes
C <sub>I1</sub>	Input Capacitance (A0 - A11)	_	5	pF	1
C <sub>I2</sub>	Input Capacitance (RAS, CAS, WE, OE)	_	7	pF	1
Co	Output Capacitance (I/O0 - I/O3)	<del>-</del>	7	pF	1

<sup>1.</sup> Input capacitance measurements made with rise time shift method with  $\overline{CAS}$  &  $\overline{RAS}$  =  $V_{IH}$  to disable output.

<sup>2.</sup>  $V_{IH}$  may overshoot to  $V_{CC}$  + 1.2V for pulse widths of  $\leq$  4.0ns with 3.3 Volt, or  $V_{CC}$  + 2.0V for pulse widths of  $\leq$  4.0ns (or  $V_{CC}$  + 1.0V for  $\leq$  8.0ns) with 5.0 Volt. Additionally,  $V_{IL}$  may undershoot to -2.0V for pulse widths  $\leq$  4.0ns with 3.3 Volt, or to -2.0V for pulse widths  $\leq$  4.0ns (or -1.0V for  $\leq$  8.0ns) with 5.0 Volt. Pulse widths measured at 50% points with amplitude measured peak to DC reference.



### **DC Electrical Characteristics** $(T_A=0 \text{ to } +70^{\circ}\text{C}, \ V_{CC}=3.3\text{V} \pm 0.3\text{V or } V_{CC}=5.0\text{V} \pm 0.5\text{V})$

Symbol	Parameter		Min.	Max.	Units	Notes
	Operating Current	-50	_	55	A	4.0.0
I <sub>CC1</sub>	Average Power Supply Operating Current (RAS, CAS, Address Cycling: $t_{RC} = t_{RC}$ min.)	-60	_	50	mA	1, 2, 3
I <sub>CC2</sub>	Standby Current (TTL) Power Supply Standby Current (RAS = CAS = V <sub>IH</sub> )		_	1	mA	
	RAS Only Refresh Current	-50	<del>_</del>	55		1, 3
I <sub>CC3</sub>	Average Power Supply Current, $\overline{RAS}$ Only Mode ( $\overline{RAS}$ Cycling, $\overline{CAS} = V_{IH}$ : $t_{RC} = t_{RC}$ min)	-60	_	50	mA	
	EDO (Hyper Page) Mode Current	-50	_	35	A	4.0.0
I <sub>CC4</sub>	Average Power Supply Current (RAS = $V_{IL}$ , CAS, Address Cycling: $t_{PC} = t_{PC}$ min)	-60	_	30	mA	1, 2, 3
	Standby Current (CMOS)	SP version	_	1	Λ	
I <sub>CC5</sub>	Power Supply Standby Current (RAS = CAS = $V_{CC}$ - 0.2V)	LP version	_	0.1	mA	
	CAS Before RAS Refresh Current  Average Power Supply Current, CAS Before RAS Mode  (RAS, CAS, Cycling: t <sub>RC</sub> = t <sub>RC</sub> min)	-50	_	55		1, 3
ICC6		-60	_	50	mA	
	Self Refresh Current, LP version only	3.3V	_	200		
I <sub>CC7</sub>	Average Power Supply Current during Self Refresh CBR cycle with RAS $\geq$ t <sub>RASS</sub> (min); CAS held low; WE = V <sub>CC</sub> - 0.2V; Addresses and D <sub>IN</sub> = V <sub>CC</sub> - 0.2V or 0.2V.	5.0V	_	300	μΑ	
I <sub>I(L)</sub>	Input Leakage Current Input Leakage Current, any input $(0.0 \le V_{IN} \le (V_{CC} + 0.3V))$ , All Other Pins Not Under Test =	0V	-5	+5	μΑ	
I <sub>O(L)</sub>	Output Leakage Current ( $D_{OUT}$ is disabled, $0.0 \le V_{OUT} \le V_{CC}$ )		-5	+5	μΑ	
V <sub>OH</sub>	Output Level (TTL) Output "H" Level Voltage (I <sub>OUT</sub> = -2.0mA for 3.3V, or I <sub>OUT</sub> = -5mA for 5.0V)	2.4	V <sub>CC</sub>	V		
V <sub>OL</sub>	Output Level (TTL) Output "L" Level Voltage (I <sub>OUT</sub> = +2.0mA for 3.3V, or I <sub>OUT</sub> = +4.2mA for 5.0V)	0.0	0.4	V		

<sup>1.</sup>  $I_{CC1},\,I_{CC3},\,I_{CC4}$  and  $I_{CC6}$  depend on cycle rate.

<sup>2.</sup>  $I_{\text{CC1}}$  and  $I_{\text{CC4}}$  depend on output loading. Specified values are obtained with the output open.

<sup>3.</sup> Address can be changed once or less while  $\overline{RAS} = V_{IL}$ . In the case of  $I_{CC4}$ , it can be changed once or less when  $\overline{CAS} = V_{IH}$ .

#### Discontinued (9/98 - last order; 3/99 last ship)



IBM0116405 IBM0116405M IBM0116405B IBM0116405P 4M x 4 12/10 EDO DRAM

#### AC Characteristics ( $T_A$ = 0 to +70°C, $V_{CC}$ = 3.3V $\pm$ 0.3V or $V_{CC}$ = 5.0V $\pm$ 0.5V)

- 1. An initial pause of 200µs is required after power-up followed by 8 RAS only refresh cycles before proper device operation is achieved. In case of using the internal refresh counter, a minimum of 8 CAS before RAS refresh cycles instead of 8 RAS only refresh cycles is required.
- 2. AC measurements assume  $t_T$ =2ns.
- 3. V<sub>IH</sub>(min.) and V<sub>IL</sub>(max.) are reference levels for measuring timing of input signals. Also, transition times are measured between V<sub>IH</sub> and V<sub>IL</sub>.
- 4. Valid column addresses are A0 through A9

#### Read, Write, Read-Modify-Write and Refresh Cycles (Common Parameters)

Symbol	Parameter		-50		-60	Units	Notes
Syllibol	Falametei	Min.	Max.	Min.	Max.	Units	Notes
t <sub>RC</sub>	Random Read or Write Cycle Time	84	_	104	_	ns	
$t_{RP}$	RAS Precharge Time	30	_	40	_	ns	
t <sub>CP</sub>	CAS Precharge Time	8	_	10	_	ns	
t <sub>RAS</sub>	RAS Pulse Width	50	10K	60	10K	ns	
t <sub>CAS</sub>	CAS Pulse Width	8	10K	10	10K	ns	
t <sub>ASR</sub>	Row Address Setup Time	0	_	0	_	ns	
t <sub>RAH</sub>	Row Address Hold Time	10	_	10	_	ns	
t <sub>ASC</sub>	Column Address Setup Time	0	<del>-</del>	0	_	ns	
t <sub>CAH</sub>	Column Address Hold Time	8	_	10	_	ns	
t <sub>RCD</sub>	RAS to CAS Delay Time	14	37	14	45	ns	1
t <sub>RAD</sub>	RAS to Column Address Delay Time	12	25	12	30	ns	2
t <sub>RSH</sub>	RAS Hold Time	8	<del>_</del>	10	_	ns	
t <sub>CSH</sub>	CAS Hold Time	38	_	45	_	ns	
t <sub>CRP</sub>	CAS to RAS Precharge Time	5	<del>_</del>	5	_	ns	
t <sub>DZO</sub>	OE Delay Time from D <sub>IN</sub>	0	_	0	_	ns	3
t <sub>DZC</sub>	CAS Delay Time from D <sub>IN</sub>	0	_	0	_	ns	3
t <sub>T</sub>	Transition Time (Rise and Fall)	2	50	2	50	ns	4

<sup>1.</sup> Operation within the  $t_{RCD}(max.)$  limit ensures that  $t_{RAC}(max.)$  can be met.  $t_{RCD}(max.)$  is specified as a reference point only. If  $t_{RCD}$  is greater than the specified  $t_{RCD}(max.)$  limit, then access time is controlled by  $t_{CAC}$ .

- 3. Either t<sub>DZC</sub> or t<sub>DZO</sub> must be satisfied.
- 4. AC measurements assume t<sub>T</sub>=2ns.

<sup>2.</sup> Operation within the t<sub>RAD</sub>(max.) limit ensures that t<sub>RAD</sub>(max.) can be met. t<sub>RAD</sub>(max.) is specified as a reference point only. If t<sub>RAD</sub> is greater than the specified t<sub>RAD</sub>(max.) limit, then access time is controlled by t<sub>AA</sub>.

#### Discontinued (9/98 - last order; 3/99 last ship)

IBM0116405 IBM0116405M IBM0116405B IBM0116405P **4M x 4 12/10 EDO DRAM** 



#### **Write Cycle**

Courada a l	Parameter	-50			-60	l laita	Notes
Symbol	Parameter	Min.	Max.	Min.	Max.	Units	Notes
t <sub>WCS</sub>	Write Command Set Up Time	0	_	0	_	ns	1
$t_{\text{WCH}}$	Write Command Hold Time	7	_	10		ns	
$t_{WP}$	Write Command Pulse Width	7	_	10	_	ns	
t <sub>RWL</sub>	Write Command to RAS Lead Time	7	_	10	_	ns	
t <sub>CWL</sub>	Write Command to CAS Lead Time	7	_	10	_	ns	
t <sub>OED</sub>	OE to D <sub>IN</sub> Delay Time	13	_	15	_	ns	2
t <sub>DS</sub>	D <sub>IN</sub> Setup Time	0	_	0	_	ns	3
t <sub>DH</sub>	D <sub>IN</sub> Hold Time	7	_	10	_	ns	3

<sup>1.</sup> t<sub>WCS</sub>, t<sub>RWD</sub>, t<sub>CWD</sub> and t<sub>AWD</sub> are not restrictive operating parameters. They are included in the data sheet as electrical characteristics only. If t<sub>WCS</sub> ≥ t<sub>WCS</sub> (min), the cycle is an early write cycle and the data pin will remain open circuit (high impedance) through the entire cycle. If t<sub>RWD</sub> ≥ t<sub>RWD</sub> (min), t<sub>CWD</sub> ≥ t<sub>CWD</sub> (min) and t<sub>AWD</sub> ≥ t<sub>AWD</sub> (min), the cycle is a Read-Modify-Write cycle and the data out will contain data read from the selected cell. If neither of the above sets of conditions are satisfied, the condition of the data out (at access time) is indeterminate.

- 2. Either t<sub>CDD</sub> or t<sub>OED</sub> must be satisfied.
- 3. These parameters are referenced to  $\overline{\text{CAS}}$  leading edge in early write cycles and to  $\overline{\text{WE}}$  leading edge in Read-Modify-Write cycles.



#### **Read Cycle**

Oh. al	Description		-50		-60	11-7-	Notos
Symbol	Parameter	Min.	Max.	Min.	Max.	Units	Notes
t <sub>RAC</sub>	Access Time from RAS	_	50	_	60	ns	1, 2, 3
t <sub>CAC</sub>	Access Time from CAS	_	13	_	15	ns	1, 3
t <sub>AA</sub>	Access Time from Address	_	25	_	30	ns	2, 3
t <sub>OEA</sub>	Access Time from OE	_	13	_	15	ns	3
t <sub>RCS</sub>	Read Command Setup Time	0	_	0	_	ns	
t <sub>RCH</sub>	Read Command Hold Time to CAS	0	_	0	_	ns	4
t <sub>RRH</sub>	Read Command Hold Time to RAS	0	_	0	_	ns	4
t <sub>RAL</sub>	Column Address to RAS Lead Time	25	_	30	_	ns	
t <sub>CLZ</sub>	CAS to Output in Low-Z	0	_	0	_	ns	3
t <sub>OFF</sub>	Output Buffer Turn-Off Delay	_	13	_	15	ns	5, 6
t <sub>CDD</sub>	CAS to D <sub>IN</sub> Delay Time	13	_	15	_	ns	7
t <sub>OEZ</sub>	Output Buffer Turn-Off Delay from $\overline{\text{OE}}$	_	13	_	15	ns	5
t <sub>OES</sub>	OE Setup Time Prior to CAS	5	_	5	_	ns	
t <sub>ORD</sub>	OE Setup Time Prior to RAS (Hidden Refresh)	0	_	0	_	ns	

- Operation within the t<sub>RCD</sub>(max.) limit ensures that t<sub>RAC</sub>(max.) can be met. t<sub>RCD</sub>(max.) is specified as a reference point only. If t<sub>RCD</sub> is greater than the specified t<sub>RCD</sub>(max.) limit, then access time is controlled by t<sub>CAC</sub>.
- 2. Operation within the  $t_{RAD}$ (max.) limit ensures that  $t_{RAD}$ (max.) can be met.  $t_{RAD}$ (max.) is specified as a reference point only. If  $t_{RAD}$  is greater than the specified  $t_{RAD}$ (max.) limit, then access time is controlled by  $t_{AA}$ .
- 3. Measured with the specified current load and 100pF at  $V_{OL} = 0.8V$  and  $V_{OH} = 2.0V$ .
- 4. Either  $t_{\mbox{\scriptsize RCH}}$  or  $t_{\mbox{\scriptsize RRH}}$  must be satisfied for a read cycle.
- 5.  $t_{OFF}$  (max) and  $t_{OEZ}$  (max) define the time at which the output achieves the open circuit condition and are not referenced to output voltage levels.
- 6.  $t_{OFF}$  is referenced from the rising edge of  $\overline{RAS}$  or  $\overline{CAS}$ , which ever is last.
- 7. Either t<sub>CDD</sub> or t<sub>OED</sub> must be satisfied.

IBM0116405 IBM0116405M IBM0116405P IBM0116405P IBM0116405P



#### **Read-Modify-Write Cycle**

Symbol	Parameter	-50			-60	Units	Notes
Symbol	Parameter	Min.	Max.	Min.	Max.	Units	Notes
t <sub>RWC</sub>	Read-Modify-Write Cycle Time	110	_	135	_	ns	
t <sub>RWD</sub>	RAS to WE Delay Time	67	_	79	_	ns	1
t <sub>CWD</sub>	CAS to WE Delay Time	30	_	34	_	ns	1
t <sub>AWD</sub>	Column Address to WE Delay Time	42	_	49	_	ns	1
t <sub>OEH</sub>	OE Command Hold Time	7	_	10	_	ns	

<sup>1.</sup> t<sub>WCS</sub>, t<sub>RWD</sub>, t<sub>CWD</sub> and t<sub>AWD</sub> are not restrictive operating parameters. They are included in the data sheet as electrical characteristics only. If t<sub>WCS</sub> ≥ t<sub>WCS</sub> (min), the cycle is an early write cycle and the data pin will remain open circuit (high impedance) through the entire cycle. If t<sub>RWD</sub> ≥ t<sub>RWD</sub> (min), t<sub>CWD</sub> ≥ t<sub>CWD</sub> (min) and t<sub>AWD</sub> ≥ t<sub>AWD</sub> (min), the cycle is a Read-Modify-Write cycle and the data out will contain data read from the selected cell. If neither of the above sets of conditions are satisfied, the condition of the data out (at access time) is indeterminate.

#### **Extended Data Out (Hyper Page) Mode Cycle**

Cumbal	Doromotor	-50		-60		L Latte	Niere
Symbol	Parameter		Max.	Min.	Max.	Units	Notes
t <sub>HCAS</sub>	EDO (Hyper Page) Mode CAS Pulse Width	8	10K	10	10K	ns	
t <sub>HPC</sub>	EDO (Hyper Page) Mode Cycle Time (Read/Write)	20	_	25	_	ns	
t <sub>HPRWC</sub>	EDO (Hyper Page) Mode Read Modify Write Cycle Time	51	_	60	_	ns	
t <sub>DOH</sub>	Data-out Hold Time from CAS	5	_	5	_	ns	
$t_{WHZ}$	Output buffer Turn-Off Delay from WE	0	10	0	10	ns	
$t_{WPZ}$	WE Pulse Width to Output Disable at CAS High	7	_	10	_	ns	
t <sub>CPRH</sub>	RAS Hold Time from CAS Precharge	30	_	35	_	ns	
t <sub>CPA</sub>	Access Time from CAS Precharge	_	28	_	35	ns	1
t <sub>RASP</sub>	EDO (Hyper Page) Mode RAS Pulse Width	50	200K	60	200K	ns	
t <sub>OEP</sub>	OE Precharge	5	_	5	_	ns	
t <sub>OEHC</sub>	OE High Hold Time from CAS High	5	_	5	_	ns	

<sup>1.</sup> Measured with the specified current load and 100pF at  $V_{OL} = 0.8V$  and  $V_{OH} = 2.0V$ .



#### Refresh Cycle

Symbol	Parameter	-50		-60		Units	Notes
Symbol		Min.	Max.	Min.	Max.	Units	Notes
t <sub>CSR</sub>	CAS Setup Time (CAS before RAS Refresh Cycle)	5	_	5	_	ns	
t <sub>CHR</sub>	CAS Hold Time (CAS before RAS Refresh Cycle)	10	_	10	_	ns	
t <sub>WRP</sub>	WE Setup Time (CAS before RAS Refresh Cycle)	10	_	10	_	ns	
t <sub>WRH</sub>	WE Hold Time (CAS before RAS Cycle)	10	_	10	_	ns	
t <sub>RPC</sub>	RAS Precharge to CAS Hold Time	5	_	5	_	ns	

#### Self Refresh Cycle - Low Power Version Only

Symbol	Parameter	-50		-60		Units	Notes
Symbol		Min.	Max.	Min.	Max.	Units	ivoles
t <sub>RASS</sub>	RAS Pulse Width During Self Refresh Cycle	100	_	100	_	μs	1
t <sub>RPS</sub>	RAS Precharge Time During Self Refresh Cycle	89	_	104	_	ns	1
t <sub>CHS</sub>	CAS Hold Time From RAS Rising During Self Refresh Cycle	-50	_	-50	_	ns	1, 2
t <sub>CHD</sub>	CAS Hold Time From RAS Falling During Self Refresh Cycle	350	<u>—</u>	350	_	μs	1, 2

When using Self Refresh mode, the following refresh operations must be performed to ensure proper DRAM operation:
 If row addresses are being refreshed in an EVENLY DISTRIBUTED manner over the refresh interval using CBR refresh cycles,
 then only one CBR cycle must be performed immediately after exit from Self Refresh.
 If row addresses are being refreshed in any other manner (ROR- Distributed/Burst; or CBR-Burst) over the refresh interval, then a
 full set of row refreshes must be performed immediately before entry to and immediately after exit from Self Refresh.

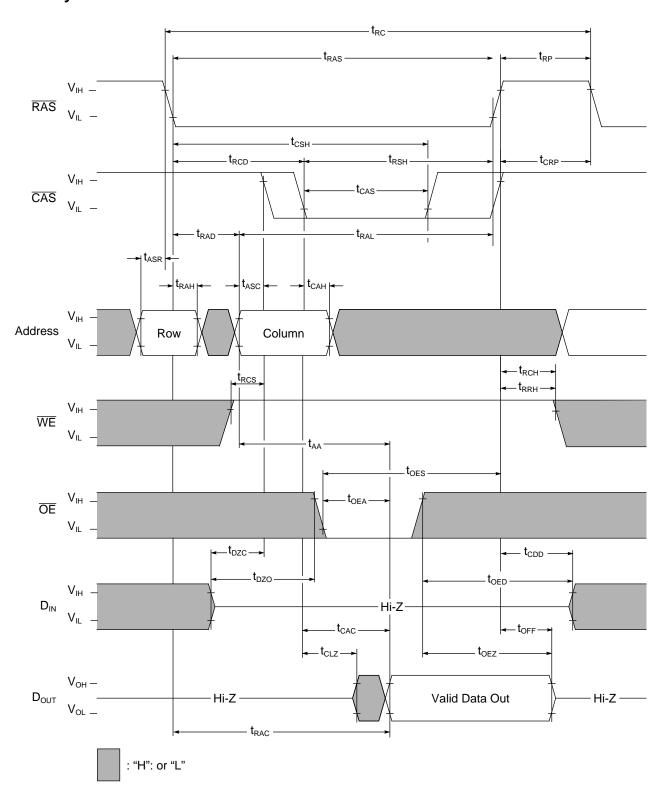
#### Refresh

Symbol	Parameter		-50		-60		Lloito	Notos
			Min.	Max.	Min.	Max.	Units	Notes
4	Refresh Period	SP version	_	64	_	64	ms	1
t <sub>REF</sub>		LP version	_	256	_	256		
1 4096 cycles								

<sup>2.</sup> If  $t_{RASS} > t_{CHD}$  (min) then  $t_{CHD}$  applies. If  $t_{RASS} \le t_{CHD}$  (min) then  $t_{CHS}$  applies.

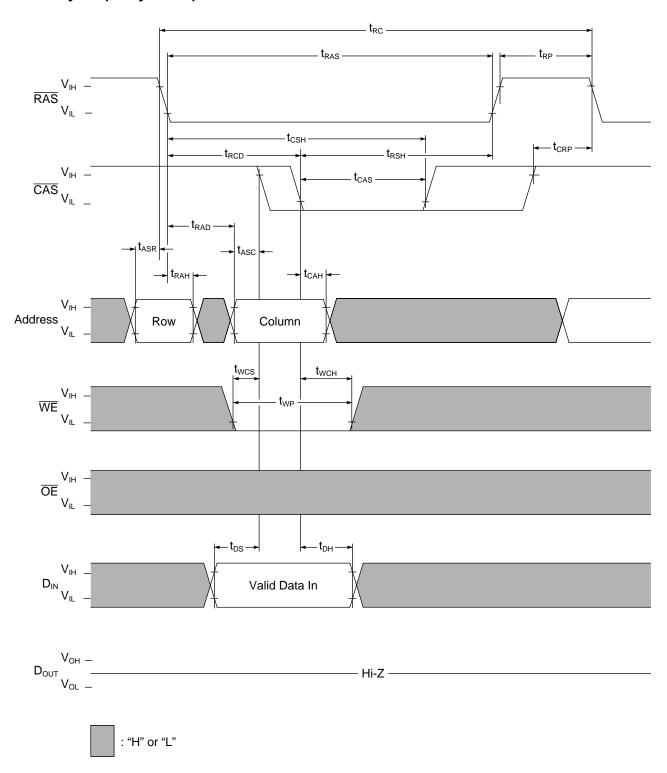


### **Read Cycle**



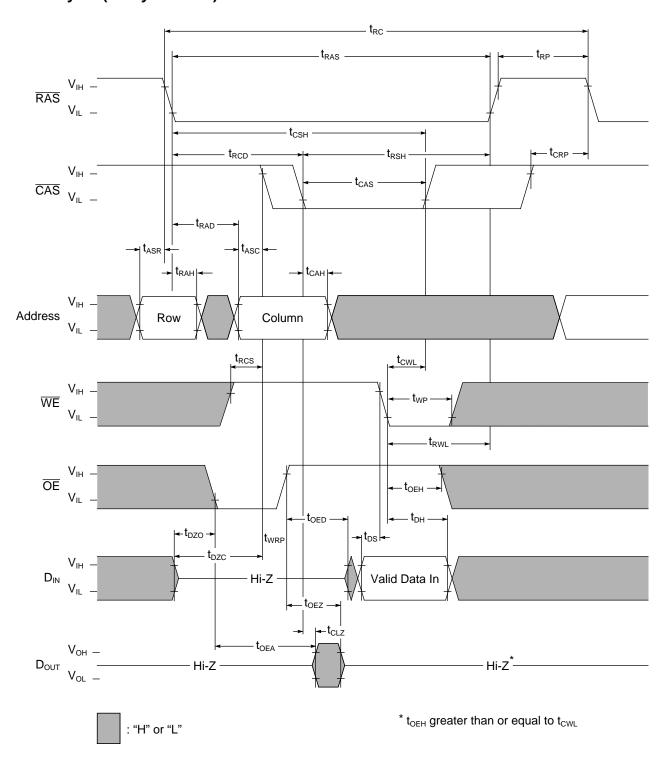


### Write Cycle (Early Write)



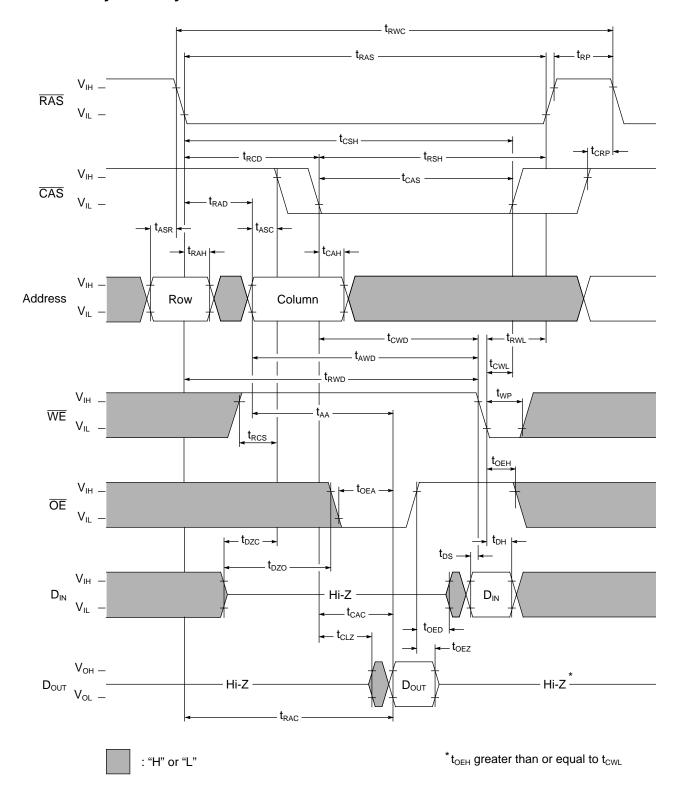


### **Write Cycle (Delayed Write)**



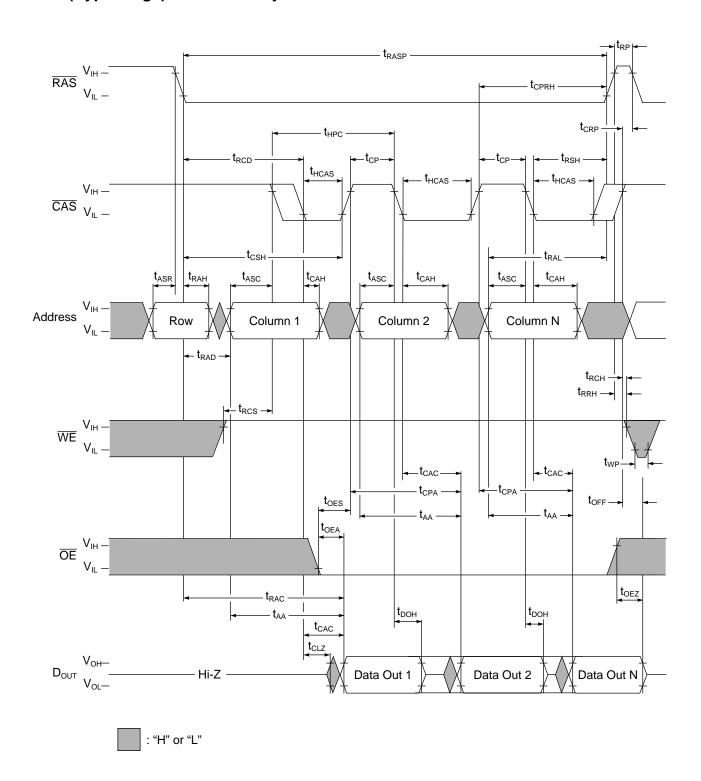


### **Read-Modify-Write Cycle**



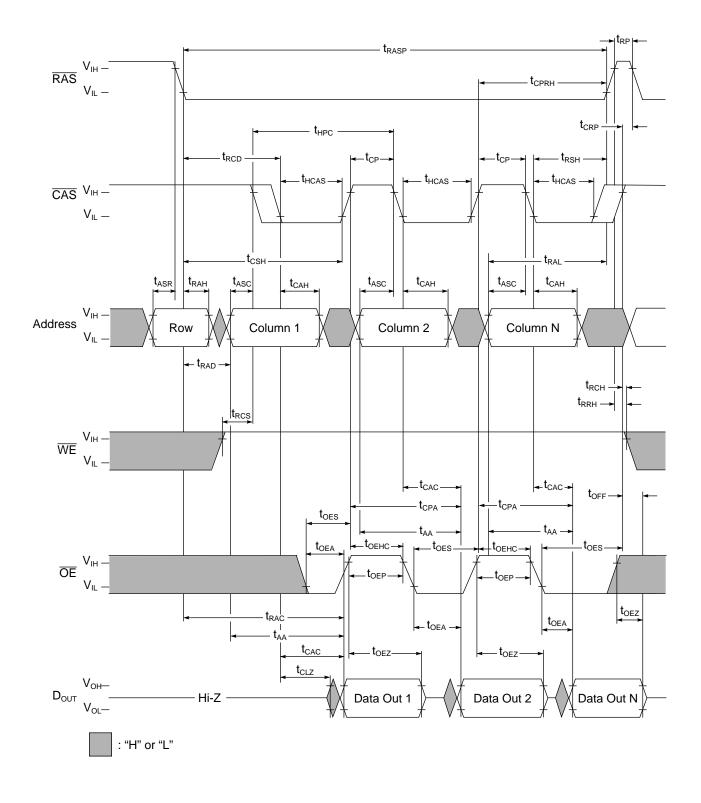


### **EDO (Hyper Page) Mode Read Cycle**



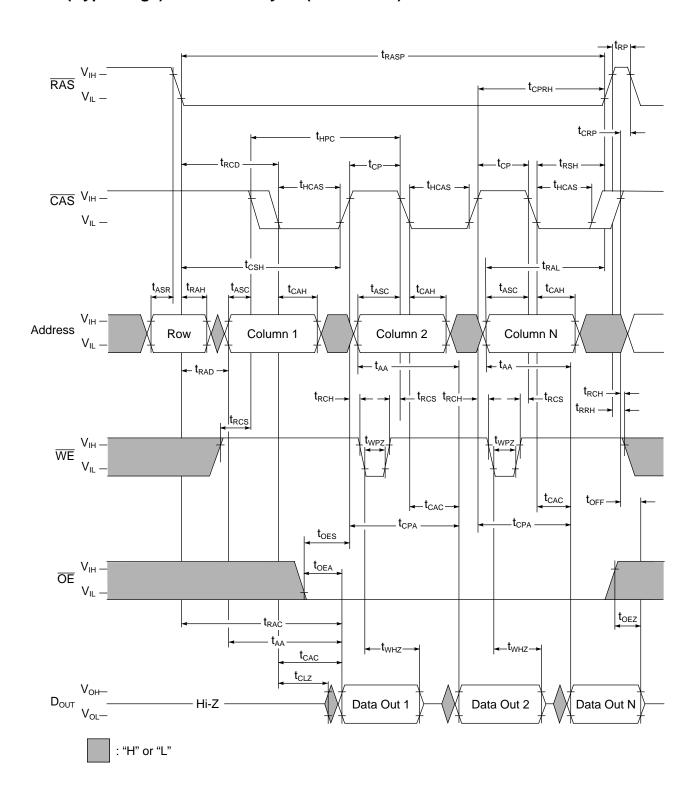


# **EDO (Hyper Page) Mode Read Cycle (OE Control)**



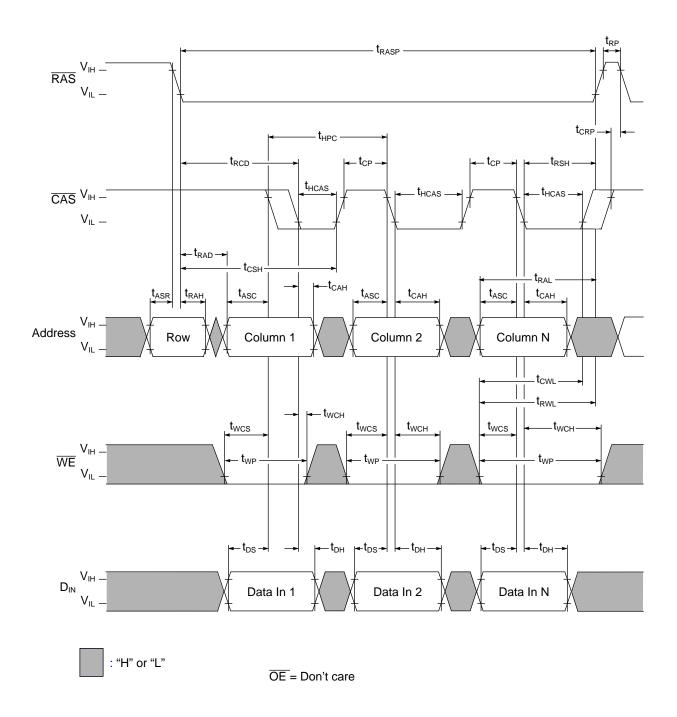


# **EDO (Hyper Page) Mode Read Cycle (WE Control)**



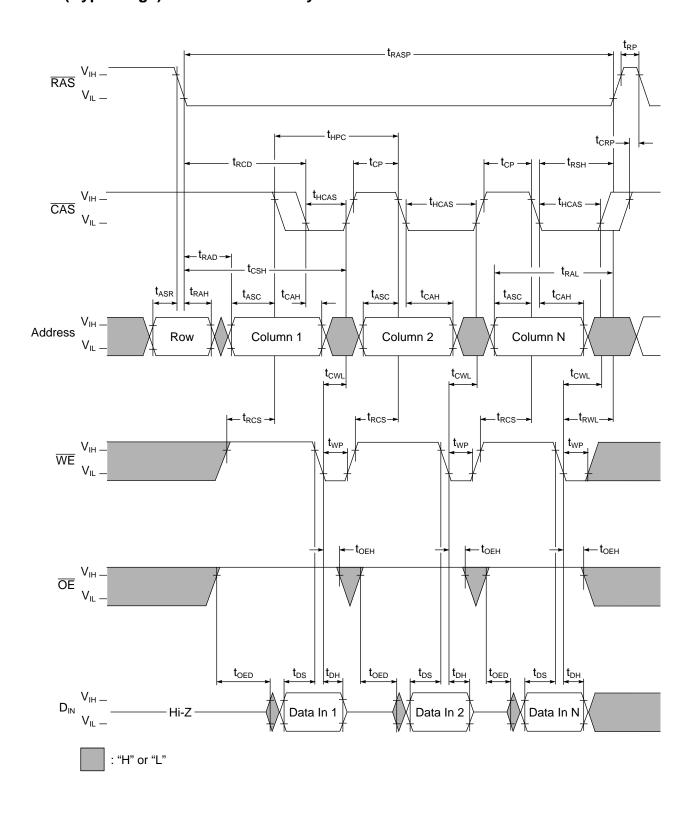


# **EDO (Hyper Page) Mode Early Write Cycle**



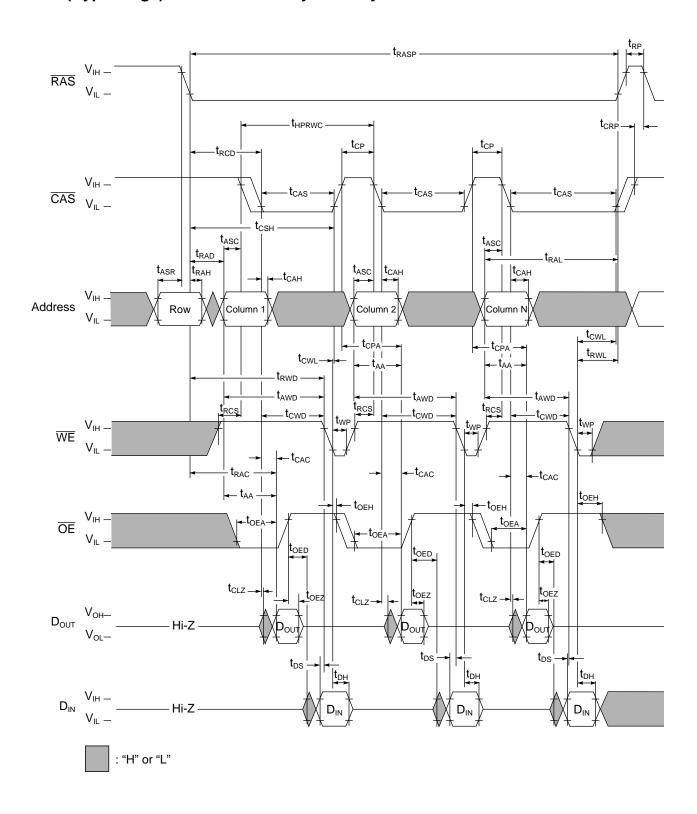


### **EDO (Hyper Page) Mode Late Write Cycle**



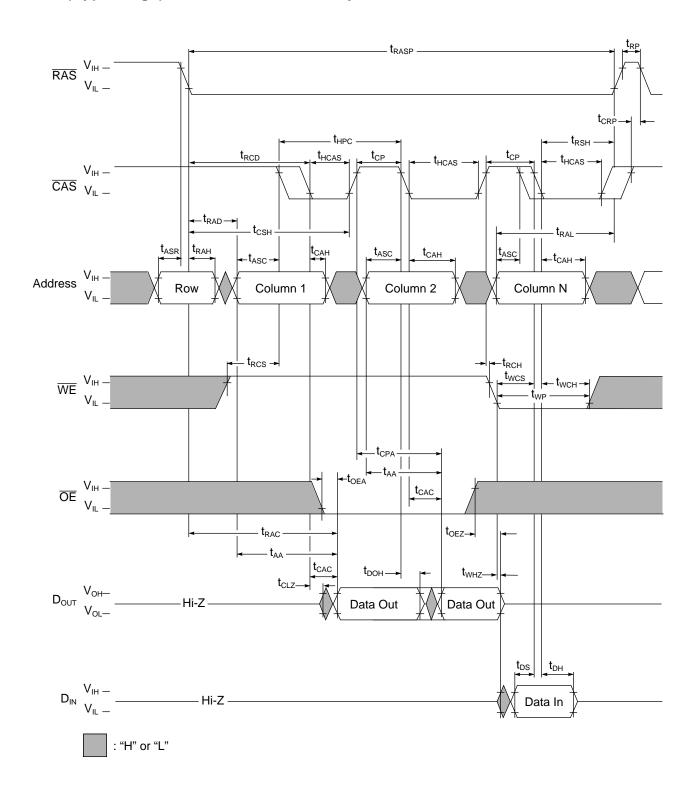


# **EDO (Hyper Page) Mode Read Modify Write Cycle**



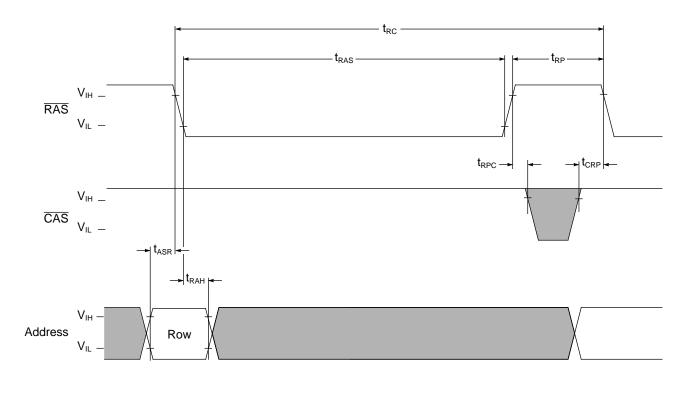


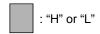
### **EDO (Hyper Page) Mode Read and Write Cycle**





# **RAS** Only Refresh Cycle

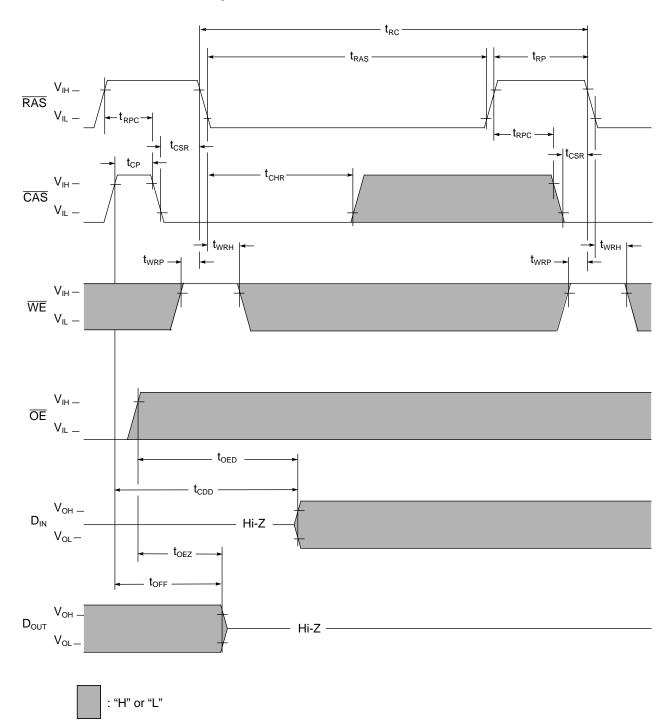




NOTE:  $\overline{\text{WE}}$ ,  $\overline{\text{OE}}$  and  $D_{\text{IN}}$  are "H" or "L"



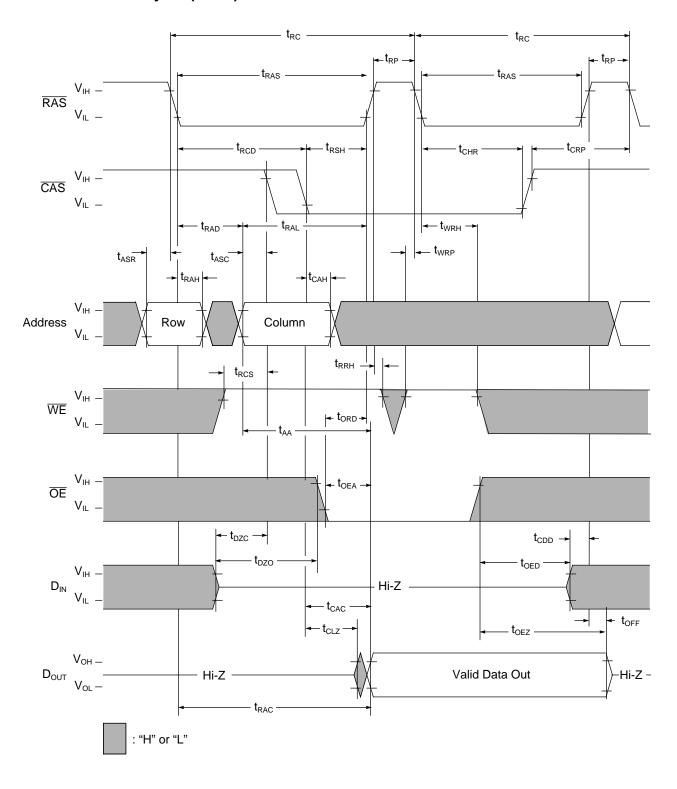
# **CAS** Before **RAS** Refresh Cycle



NOTE: Address is "H" or "L"

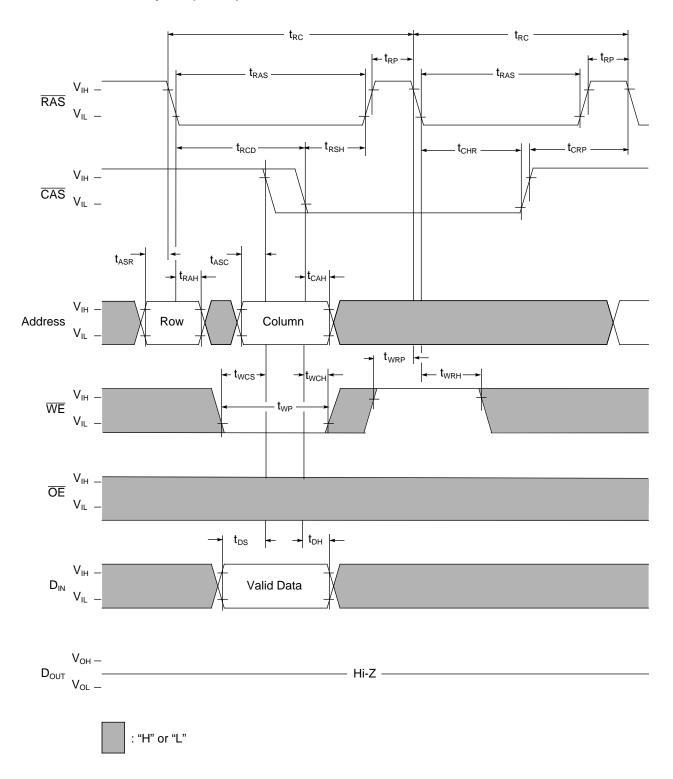


### **Hidden Refresh Cycle (Read)**



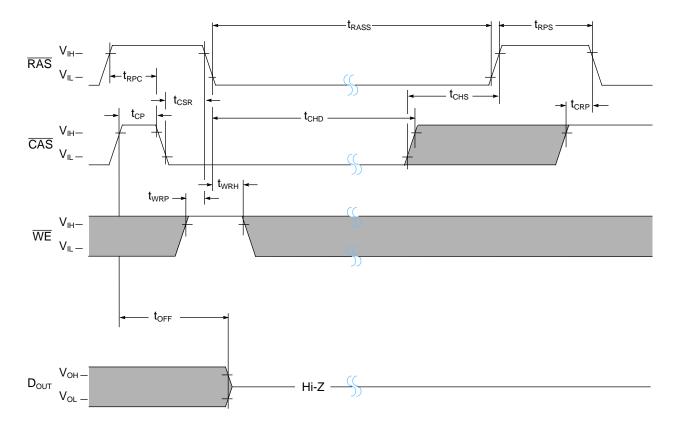


# **Hidden Refresh Cycle (Write)**





### Self Refresh Cycle (Sleep Mode) - Low Power version only





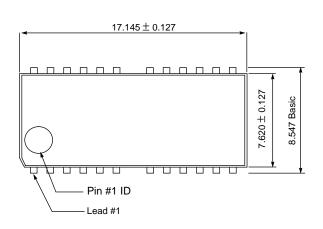
#### NOTES:

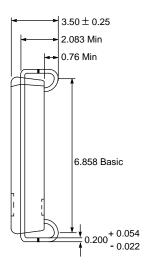
- 1. Address and OE are "H" or "L"
- 2. Once RAS (min) is provided and RAS remains low, the DRAM will be in Self Refresh, commonly known as "Sleep Mode."
- 3. If  $t_{RASS} > t_{CHD}$  (min) then  $t_{CHD}$  applies. If  $t_{RASS} \le t_{CHD}$  (min) then  $t_{CHS}$  applies.

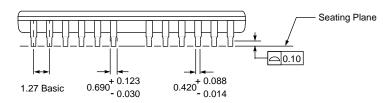




#### Package Dimensions (300 mil; 26/24 lead; Small Outline J-Lead)



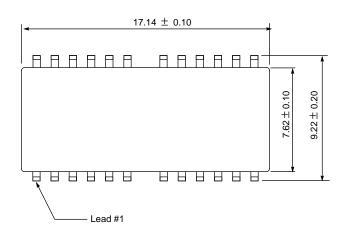


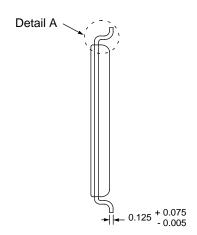


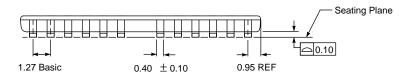
NOTE: All dimensions are in millimeters; Packages diagrams are not drawn to scale.

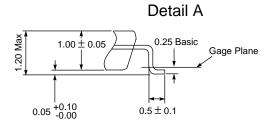


#### Package Dimensions (300 mil; 26/24 lead; Thin Small Outline Package)









NOTE: All dimensions are in millimeters; Package diagrams are not drawn to scale.



# **Revision Log**

Revision	Contents Of Modification			
11/15/95	Initial Release			
12/10/95	<ol> <li>The Low Power and Standard Power Specifications were combined. ES# 43G9059 and ES# 28H4720 were combined into ES# 28H4720.</li> </ol>			
	2. Added Die Rev E part numbers.			
	3. t <sub>CHD</sub> was added to the Self Refresh Cycle with a value of 350µs for all speed sorts.			
	<ol> <li>The Self Refresh timing diagram was changed to allow CAS to go high t<sub>CHD</sub> (350μs) after RAS falls entering Self Refresh.</li> </ol>			
	5. The CBR timing diagram was changed to allow CAS to remain low for back-to-back CBR cycles.			
	6. WE for the Hidden Refresh Write cycle in the Truth Table was changed from "L" to "H".			
	1. $I_{CC1}$ , $I_{CC3}$ , and $I_{CC6}$ were changed from 85mA to 90mA for the -50 speed sort.			
	2. I <sub>CC2</sub> was changed from 2mA to 1mA.			
	3. $I_{I(L)}$ and $I_{O(L)}$ were altered from +/- 10uA to +/- 5uA.			
	4. t <sub>RC</sub> was changed from 89ns to 84ns for the -50 speed sort.			
	5. t <sub>CSH</sub> changed from 45ns to 38ns, 50ns to 45ns, and 55ns to 50ns for the -50, -60, and -70 speed sorts, resp tively.			
09/01/96	6. t <sub>T</sub> was initially at a max of 30ns. It has been modified to 50ns for all speed sorts.			
	7. t <sub>CPA</sub> was decreased from 30ns to 28ns for the -50 speed sort.			
	8. t <sub>RASP</sub> max of 125K was raised to 200K for all speed sorts.			
	9. t <sub>OEP</sub> was changed from 10ns to 5ns for all speed sorts.			
	10. t <sub>OEHC</sub> was also lowered from 10ns to 5ns for all speed sorts.			
	11. t <sub>RP</sub> was changed from 35ns to 30ns for the -50 speed sort.			
	1. WE for the Hidden Refresh Write cycle in the Truth Table was changed from "H" to "L→H".			
	2. t <sub>OED</sub> was moved from the Common Parameters table to the Write Cycle Parameters Table.			
	3. t <sub>RWC</sub> for the -50 part was changed from 115ns to 100ns.			
	<ol> <li>The note "Implementing WE at RAS time during a Read or Write cycle is optional. Doing so will facilitate corpatibility with future EDO DRAMs." was removed from all of the Read and Write timing diagrams.</li> </ol>			
03/19/97	5. $t_{ODD}$ in the $\overline{CAS}$ before $\overline{RAS}$ timing diagram was renamed $t_{OED}$ .			
	6. Removed the -70 speed sort and timings.			
	7. $I_{cc1}$ , $I_{cc3}$ , $I_{cc6}$ for the -50 speed sort were reduced from 90mA to 55mA.			
	8. I <sub>cc4</sub> for the -50 speed sort was reduced from 75mA to 35mA.			
	9. $I_{cc1}$ , $I_{cc3}$ , $I_{cc6}$ for the -60 speed sort were reduced from 75mA to 50mA.			
	10. I <sub>cc4</sub> for the -60 speed sort was reduced from 65mA to 30mA.			
04/23/97	1. I <sub>cc5</sub> was changed from 200μA to 100μA for the Low Power Die Rev F Parts.			

# IBM ®

© International Business Machines Corp.1997

Printed in the United States of America All rights reserved

IBM and the IBM logo are registered trademarks of the IBM Corporation.

This document may contain preliminary information and is subject to change by IBM without notice. IBM assumes no responsibility or liability for any use of the information contained herein. Nothing in this document shall operate as an express or implied license or indemnity under the intellectual property rights of IBM or third parties. The products described in this document are not intended for use in implantation or other direct life support applications where malfunction may result in direct physical harm or injury to persons. NO WARRANTIES OF ANY KIND, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE, ARE OFFERED IN THIS DOCUMENT.

For more information contact your IBM Microelectronics sales representative or visit us on World Wide Web at http://www.chips.ibm.com

IBM Microelectronics manufacturing is ISO 9000 compliant.