

PRODUCT NUMBER: HML3530

DESCRIPTION: L5363 × 3 ELEMENT LINEAR IMAGE SENSOR

ISSUE DATE: 06/03/1997

REVISED DATA: _____

*THIS SPECIFICATION ARE SUBJECT TO BE CHANGED
WITHOUT NOTICE.

HUALON MICROELECTRONICS CORPORATION

NO 1,R&D 4 TH RD. SCIENCE-BASED INDUSTRIAL PARK

HSIN-CHU CITY , TAIWAN .R.O.C

TEL:(02)25377811,25628813 FAX:(02)25313241

(03)5774945,5783221 (03) 5789569

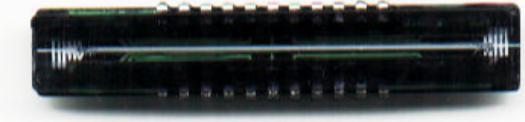


HML3530

L5363 ELEMENTS LINEAR IMAGE SENSOR

GENERAL DESCRIPTION

◆ The HML3530 is a low power and high sensitive color linear image sensor with 5363×3 elements of sensor. The sensor size is $8\mu\text{m} \times 8\mu\text{m}$ on $8\mu\text{m}$ pitch and the distance between two sensor line is $64\mu\text{m}$. The device is operated by 12V power supply and 5V puls. The device are manufactured using charge coupled device P-WELL buried-channel technology.



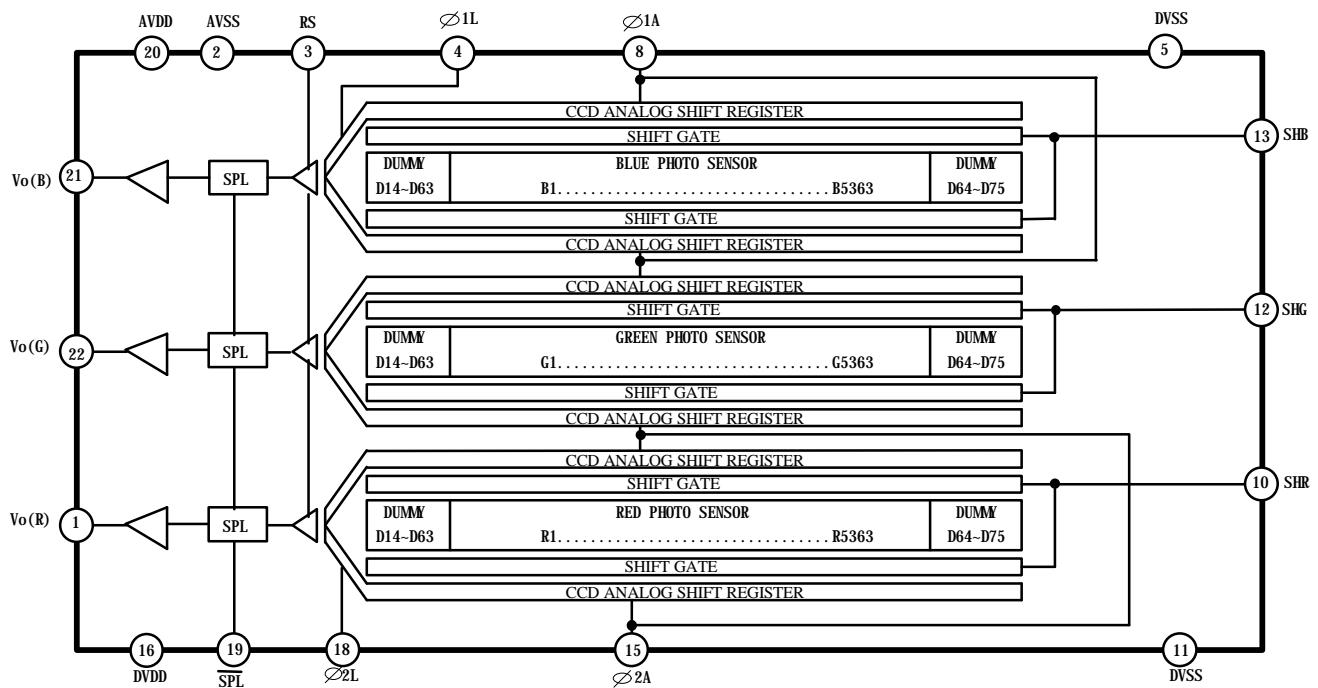
APPLICATIONS

◆ color image scanner 600DPI for A4 size documents.
◆ color image scanner 400DPI for A3 size documents.

FEATURES

- ◆ 5363'3 elements of image sensor.
- ◆ sensor size 8mm'8mm on 8mm pitch .
- ◆ sensor line spacing 64mm
- ◆ operation frequency(max) : 3MHZ.
- ◆ high sensitive pin photodiode
- ◆ 2 phase clocking.
- ◆ 12V DC power, 5V pulse clocking.
- ◆ built in sample and hold circuit
- ◆ red , green , blue three output
- ◆ 22 pin plastic package

CIRCUIT DIAGRAM



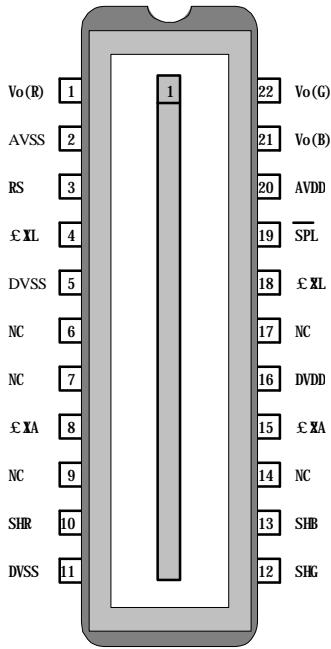
- 1 -



HML3530

L5363 ELEMENTS LINEAR IMAGE SENSOR

PIN ASSIGNMENT



PIN DESCRIPTION		
Pin NO	Name	Description
1	Vo(R)	Red signal output
21	Vo(B)	Blue signal output
22	Vo(G)	Green signal output
16	DVDD	Digital DC power supply
20	AVDD	Analog DC power supply
5 , 11	DVSS	Digital Ground
2	AVSS	Analog Ground
3	RS	Reset gate clock input
4 , 18	φ1L, φ2L	Final stage clock input
8	φ1A	Clock1 pulse gate input
15	φ2A	Clock2 pulse gate input
10	SHR	Shift gate clock input
12	SHG	Shift gate clock input
13	SHB	Shift gate clock input
19	SPL	Sample and hold clock input
7,9,14,6,17	NC	Nonconnection

ABSOLUTE MAXIMUM RATINGS

Parameter	Rating		
	Min	Max	Unit
Operating temperature	-25	+60	°C
Storage temperature	-40	+80	°C
Operating humidity	35%	80%	at 40°C
Storage humidity	20%	90%	at 40°C
Clock pulse voltage	-0.2	Vdd	V
Shift pulse voltage	-0.2	Vdd	V
Reset pulse voltage	-0.2	Vdd	V
Power supply voltage	-0.2	+13	V



HML3530

L5363 ELEMENTS LINEAR IMAGE SENSOR

OPTICAL /ELECTRICAL CHARACTERISTICS

Temperature=25°C, Vdd=12V, φ1(φ2, RS, SH)=5V pulse, f_{CK}=0.5MHZ, f_{RS}=1MHZ, Tint =10ms
, Load resistance=100KΩ, Light source = 3200°K halogen lamp +CM500(infrared IR cutoff filter)

CHARACTERISTIC	SYMBOL	MIN	TYP	MAX	UNIT	NOTE
Responsivity	Rred	4.0	5.8	7.5	V/ lx•sec	
	Rgreen	4.0	5.8	7.5	V/ lx•sec	
	Rblue	2.8	4	5.2	V/ lx•sec	
Dynamic range	DR	---	3200	---		1
Saturation Voltage	V _{sat}	2	3.2	---	V	2
Saturation exposure	SE _R		0.91		lx•sec	2
	SE _G		0.91		lx•sec	2
	SE _B	---	1.1	---	lx•sec	2
Total transfer efficiency	TTE	92	96	---	%	
Output impedance	Z	---	450	1000	Ω	
DC power dissipation	P	---	250	500	mW	
Photorespons non-uniformity	PRNU1	---	6	20	%	3
Photorespons non-uniformity	PRNU2	---	6	20	%	3
Register imbalance	RI	---	60	80	mV	4
Dark signal voltage	DS	---	2	5	mV	5
Dark signal non-uniformity	DSNU	---	---	10	mV	6
Output DC level	V _o	4.5	5.0	6.5	V	7
Linearity inequality	Li		3	10		8

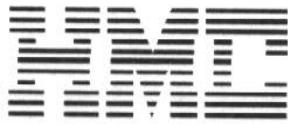
NOTE:

1.Dynamic range (DR):

Dynamic range is defined as

$$DR = \frac{V_{SAT}}{DS}$$

* DS is proportional to Tint (integration time)



HML3530

L5363 ELEMENTS LINEAR IMAGE SENSOR

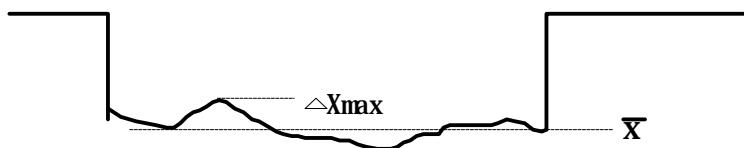
2.Saturation voltage (Vsat) and Saturation exposure(SE):

V_{sat} is defined as the minimum saturation output voltage of all effective pixels.

And the saturation exposure is defined as follows

$$SE = \frac{V_{sat}}{R} \quad \text{where R indicates Rred , Rgreen, Rblue, and SE indicates } SE_R, SE_G, SE_B.$$

3,Photorespons nonuniformity (PRNU):



$$PRNU1 \text{ is defined as } PRNU1 = \frac{\Delta X_{max}}{\bar{X}} \times 100\%$$

\bar{X} is average of total output signal ,

ΔX_{max} is the maximum deviation from \bar{X}

$$PRNU2 \text{ is defined as } PRNU2 = \frac{\Delta X_{next}}{\bar{X}} \times 100\%$$

ΔX_{next} is maximum difference of next pixel

4.Register Imbalance (RI):

RI is defined as follows

$$RI = \frac{\sum_{n=1}^{5362} |X_n - X_{n+1}|}{5362 \times \bar{X}} \times 100\%$$

Where X_n and X_{n+1} are output signal of each pixel .

\bar{X} is average of total output signal.

5,Dark signal voltage (DS):

Dark signal is defined as average dark signal voltage of all effective pixels under room temperature 25°C, and integration time 10ms.

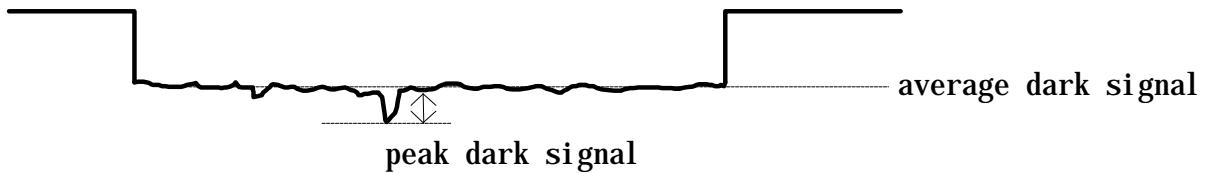


HML3530

L5363 ELEMENTS LINEAR IMAGE SENSOR

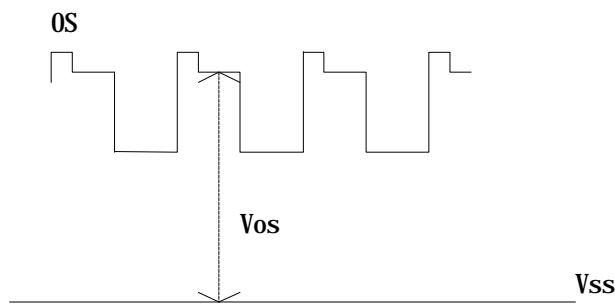
6.Dark signal nonuniformity (DSNU):

The DSNU is defined as the different dark voltage between the peak voltage and average voltage under room temperature 25°C and integration time 10ms.



7.Output DC level (Vo):

Output DC level is defined as



8.Linearity inequality:

Li is define as the output signal maximum ration of difference channel.

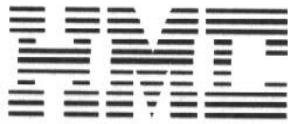
When the illumination is 30 lux and 15 lux.

$$Li_R = \frac{V_R - 15\text{lux}}{V_R - 30\text{lux}} \times 255 - \frac{V_G - 15\text{lux}}{V_G - 30\text{lux}} \times 255$$

$$Li_G = \frac{V_G - 15\text{lux}}{V_G - 30\text{lux}} \times 255 - \frac{V_B - 15\text{lux}}{V_B - 30\text{lux}} \times 255$$

$$Li_B = \frac{V_B - 15\text{lux}}{V_B - 30\text{lux}} \times 255 - \frac{V_R - 15\text{lux}}{V_R - 30\text{lux}} \times 255$$

$$Li = \text{Maximum}(|Li_R|, |Li_G|, |Li_B|)$$

**HML3530****L5363 ELEMENTS LINEAR IMAGE SENSOR**

OPERATING CONDITION

Characteristic		Symbol	Min	Typ	Max	Unit
Final clock pulse voltage	H-level	ϕ_{1L}, ϕ_{2L}	4.5	5.0	Vdd	V
	L-level		-0.2	0	0.5	V
Clock pulse voltage	H-level	ϕ_1, ϕ_2	4.5	5.0	Vdd	V
	L-level		-0.2	0	0.5	V
Shift pulse voltage	H-level	SH	4.5	5.0	Vdd	V
	L-level		-0.2	0	0.5	V
Reset pulse voltage S/H pulse voltage	H-level	\overline{RS} \overline{SPL}	4.5	5.0	Vdd	V
	L-level		-0.2	0	0.5	V
Power supply voltage		Vdd	11	12	13	V

CLOCK CHARACTERISTICS

Temperature 25°C

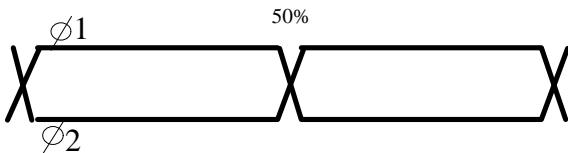
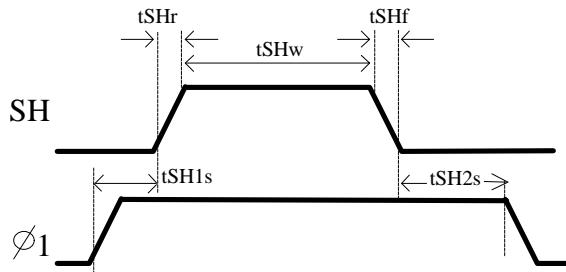
Parameter	Symbol	Min	Typ	Max	UNIT
Clock pulse frequency	$f_{\phi 1L}, f_{\phi 2L}$ $f_{\phi 1}, f_{\phi 2}$	0.05	0.5	1.5	MHZ
Reset pulse frequency	f_{RS}	0.1	1	3	MHZ
Clock capacitance	C_{f1L}, C_{f2L}	---	15	---	pF
	C_{f1}	---	700	---	pF
	C_{f2}	---	600	---	pF
Shift gate capacitance	C_{SH}	---	15	---	pF
S/H gate capacitance	C_{SPL}	---	15	---	pF
Reset gate capacitance	C_{RS}	---	15	---	pF



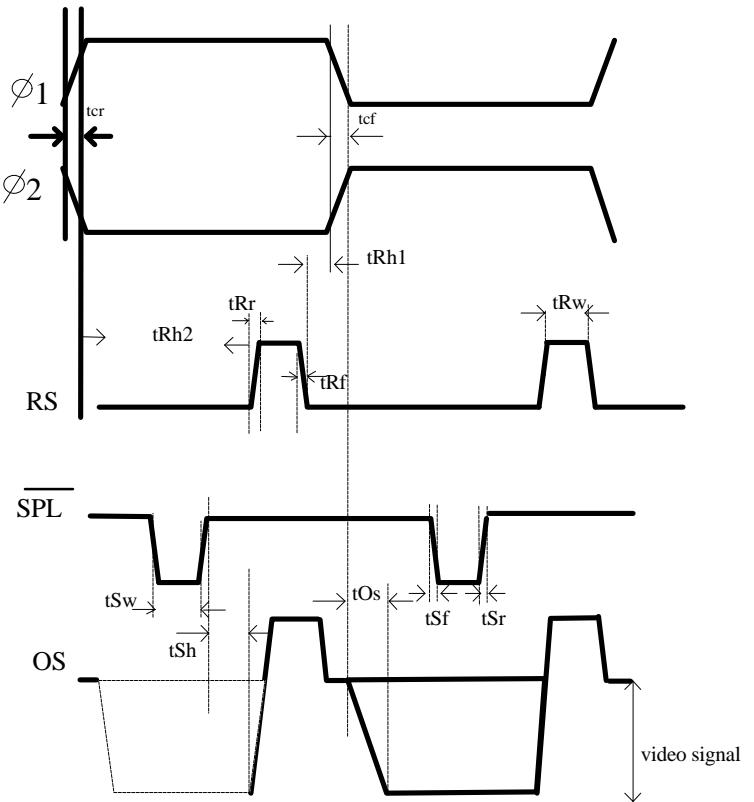
HML3530

L5363 ELEMENTS LINEAR IMAGE SENSOR

Pulse Timing of SH and ϕ_1



Pulse timing of ϕ_1 , ϕ_2 , RS, \overline{SPL} and V_o



TIMING REQUIREMENT

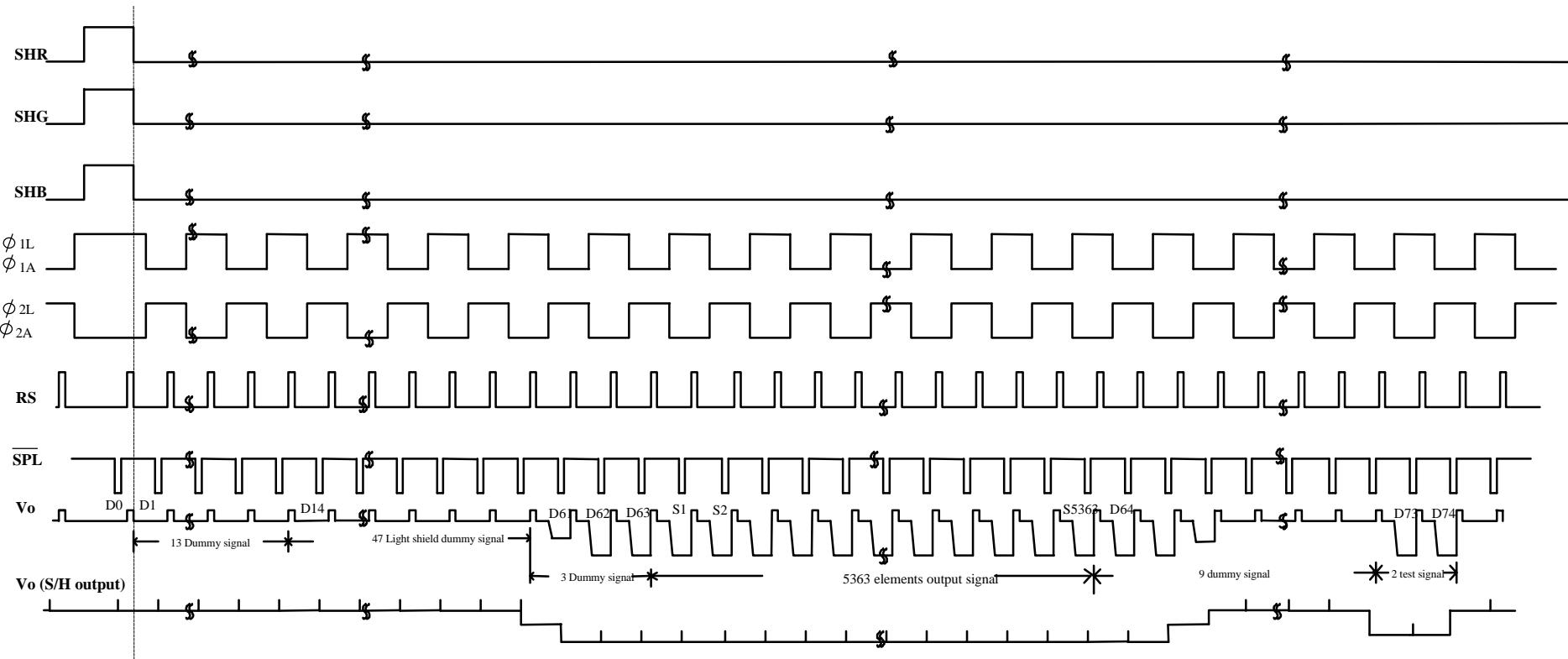
CHARACTERISTIC	SYMBOL	MIN.	TYP.	MAX.	UNIT
Pulse timing of SH and ϕ_1	t_{SH1s} , t_{SH2s}	25	100	---	ns
SH pulse rise time, fall time	t_{SHr} , t_{SHf}	0	25	---	ns
SH pulse width	t_{SHw}	1.0	2.0	20.0	μs
ϕ_1 , ϕ_2 pulse rise and fall time	t_{cr} , t_{cf}	0	50	250	ns
RS, \overline{SPL} pulse rise and fall time	t_{Rr} , t_{Rf} , t_{Sr} , t_{Sf}	0	20	---	ns
RS pulse width	t_{Rw}	60	250	---	ns
\overline{SPL} pulse width	t_{Sw}	125	250	---	ns
Pulse time of ϕ_1 , ϕ_2 , RS	t_{Rh1}	25	100	---	ns
Pulse time of ϕ_1 , ϕ_2 , RS	t_{Rh2}	250	500	---	ns
Pulse time of RS and \overline{SPL}	t_{Sh}	25	100	---	ns
Video data delay time	t_{Os}	---	50	250	ns

HMC

HML3530

L5363 ELEMENTS LINEAR IMAGE SENSOR

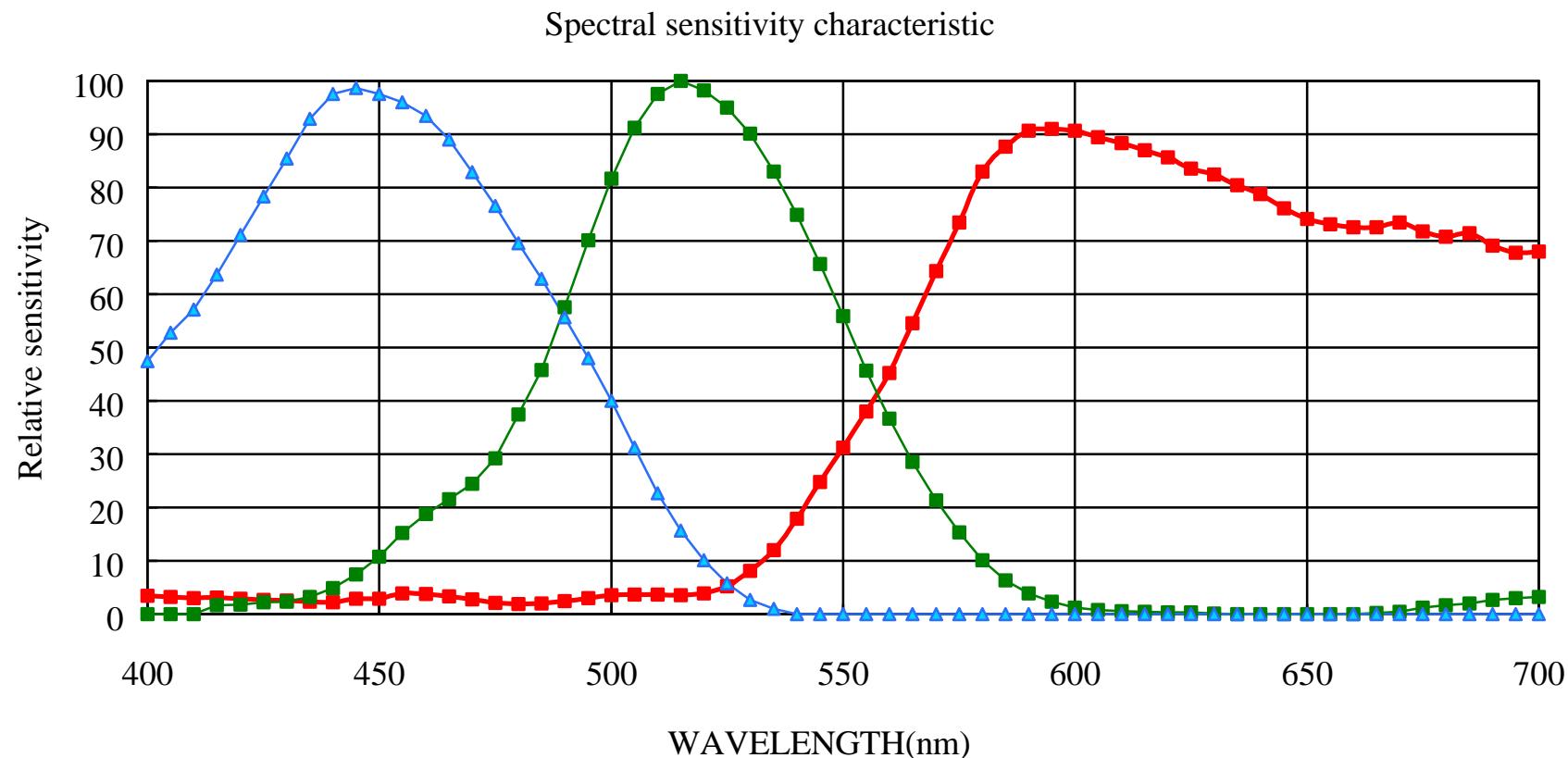
TIMING CHART





HML3530

L5363 ELEMENTS LINEAR IMAGE SENSOR

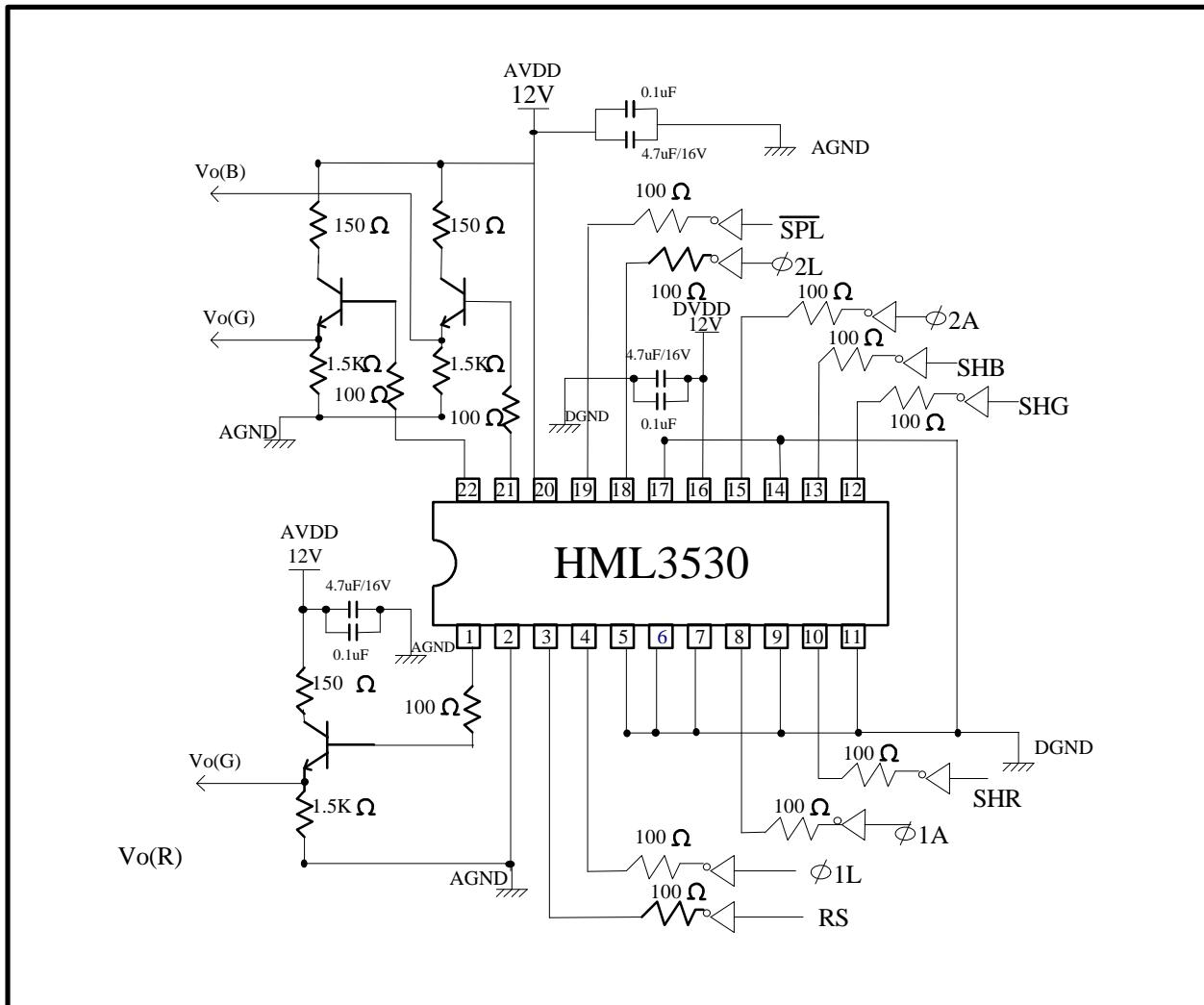


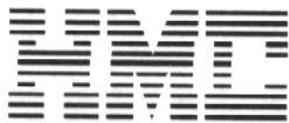


HML3530

L3530 ELEMENTS LINEAR IMAGE SENSOR

APPLICATION CIRCUIT

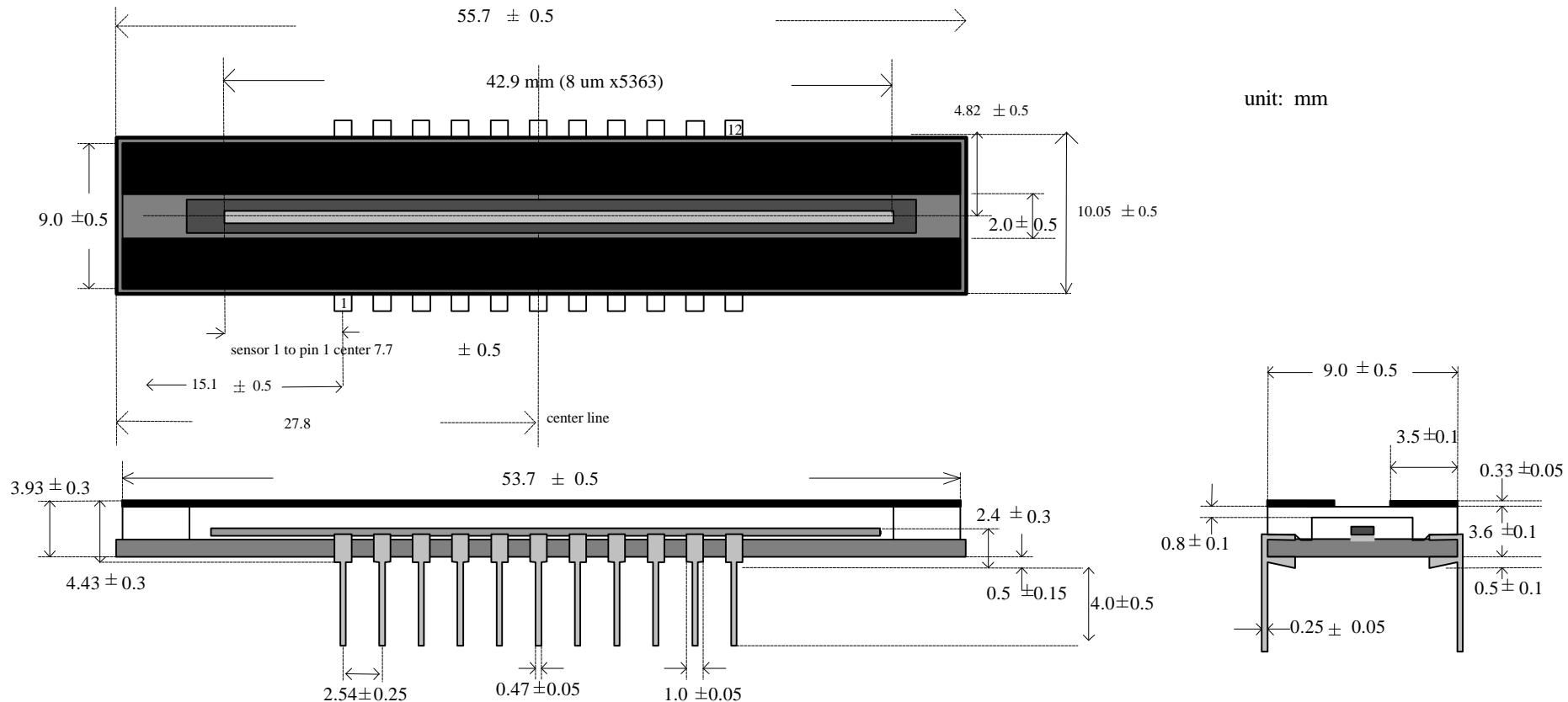




HML3530

L5363 ELEMENTS LINEAR IMAGE SENSOR

PACKAGE OUTLINE



package structure

package material	plastic
lead material	alloy
glass refractive index	1.51