
HM511667C Series

1M EDO DRAM (64-kword $\times$ 16-bit)
256 refresh

HITACHI

ADE-203-625A (Z)
Rev. 1.0
Dec. 20, 1997

Description

The Hitachi HM511667C Series is a CMOS dynamic RAM organized 65,536-word $\times$ 16-bit. HM511667C Series has realized higher density, higher performance and various functions by employing 0.8 μ m CMOS process technology and some new CMOS circuit design technologies. The HM511667C Series offers Extended Data Out (EDO) Page Mode as a high speed access mode. Multiplexed address input permits the HM511667C to be packaged in standard 400-mil 40-pin plastic SOJ and standard 400-mil 44-pin plastic TSOPII.

Features

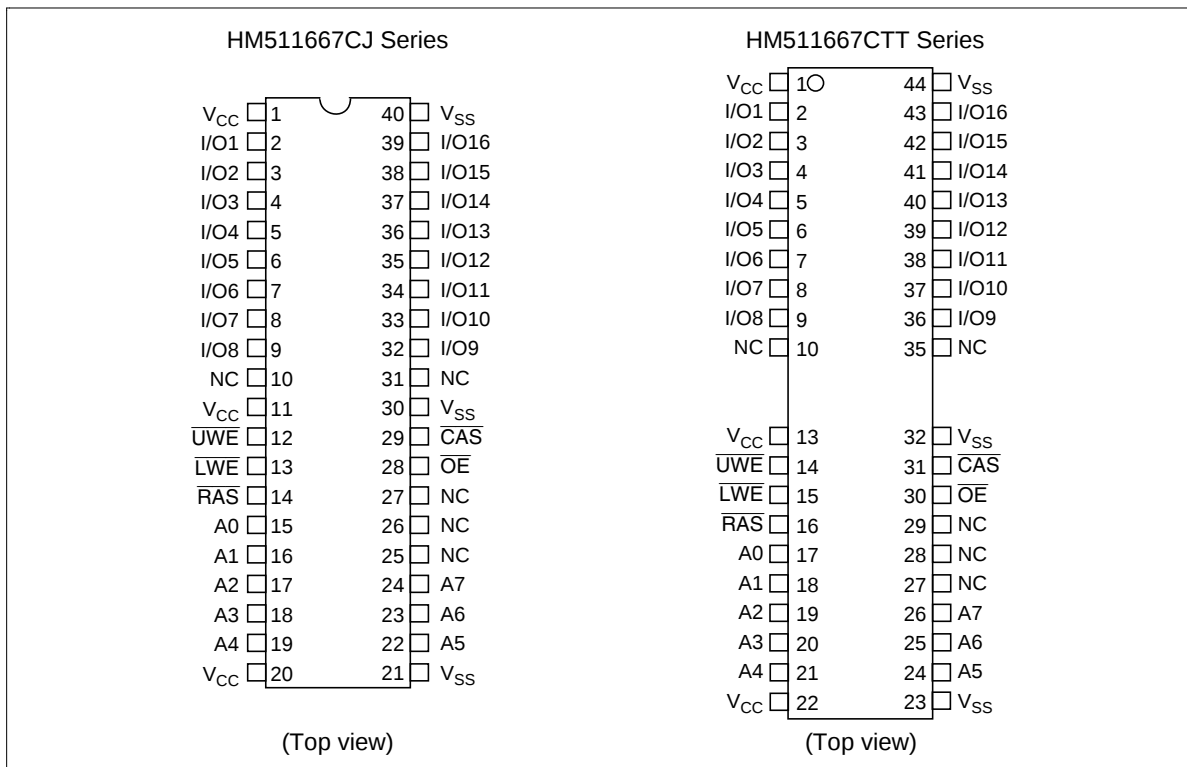
- Single 5 V supply: 5 V $\pm$ 10%
- Access time: 60/70/80 ns (max)
- Power dissipation
 - Active mode: 660/633/495 mW (max)
 - Standby mode: 11 mW (max)
- EDO page mode capability
- Refresh cycles
 - 256 refresh cycles : 4 ms
- 2 variations of refresh
 - $\overline{\text{RAS}}$ -only refresh
 - $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$ refresh
- $2\overline{\text{WE}}$ -byte control

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Ordering Information

Type No.	Access time	Package
HM511667CJ-6	60 ns	400-mil 40-pin plastic SOJ (CP-40D)
HM511667CJ-7	70 ns	
HM511667CJ-8	80 ns	
HM511667CTT-6	60 ns	400-mil 44-pin plastic TSOPII (TTP-44/40DA)
HM511667CTT-7	70 ns	
HM511667CTT-8	80 ns	

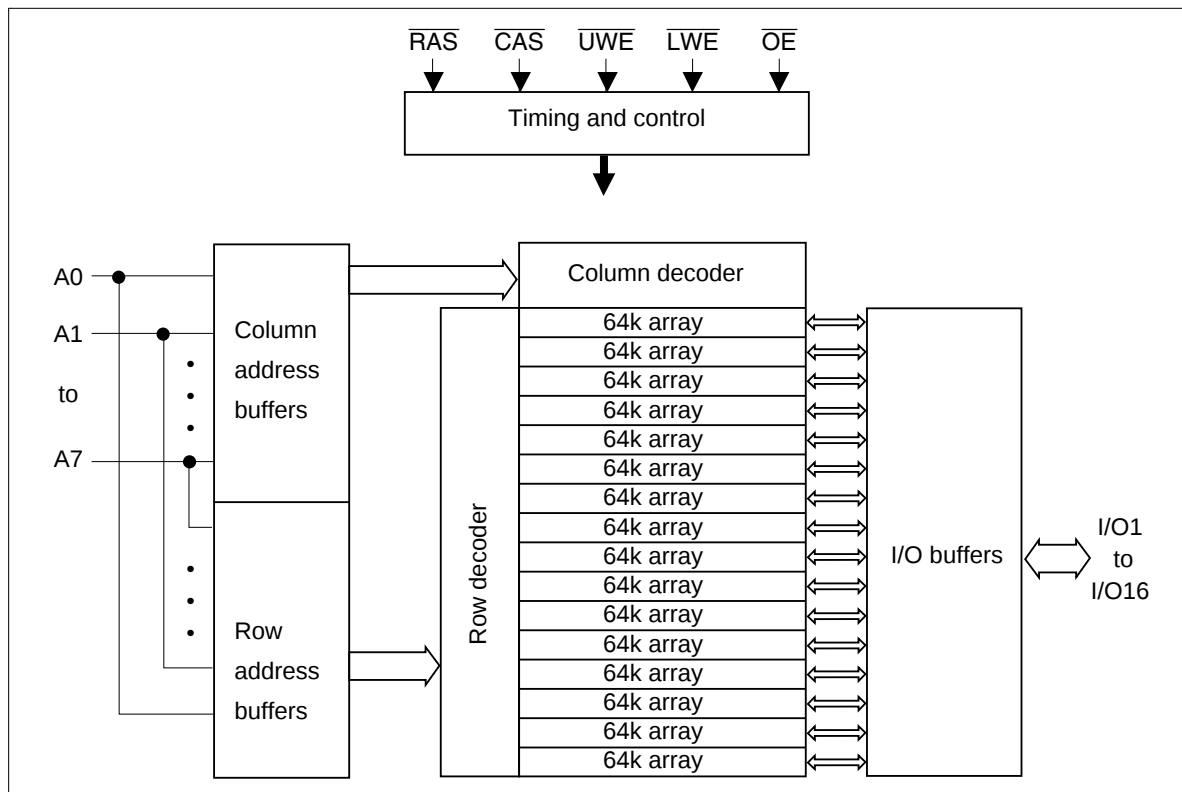
Pin Arrangement



Pin Description

Pin name	Function
A0 to A7	Address input • Row address A0 to A7 • Refresh address A0 to A7 • Column address A0 to A7
I/O1 to I/O16	Data-in/data-out
$\overline{\text{RAS}}$	Row address strobe
$\overline{\text{CAS}}$	Column address strobe
$\overline{\text{UWE}}, \overline{\text{LWE}}$	Read/write enable
$\overline{\text{OE}}$	Output enable
V_{CC}	Power supply
V_{SS}	Ground
NC	No connection

Block Diagram



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Operation Table

The HM511667C series has the following 10 operation modes.

1. Read cycle
2. Early write cycle
3. Delayed write cycle
4. Read-modify-write cycle
5. $\overline{\text{RAS}}$ -only refresh cycle
6. $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$ refresh cycle
7. EDO page mode read cycle
8. EDO page mode early write cycle
9. EDO page mode delayed write cycle
10. EDO page mode read-modify-write cycle

Inputs

$\overline{\text{RAS}}$	$\overline{\text{CAS}}$	$\overline{\text{UWE}}$	$\overline{\text{LWE}}$	Output	Operation
H	H	D	D	Open	Standby
H	L	H	H	Valid	Standby
L	L	H	H	Valid	Read cycle
L	L	L ^{*2}	L ^{*2}	Open	Early write cycle
L	L	L ^{*2}	L ^{*2}	Undefined	Delayed write cycle
L	L	H to L	H to L	Valid	Read-modify-write cycle
L	H	D	D	Open	$\overline{\text{RAS}}$ -only refresh cycle
H to L	L	D	D	Open	$\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$ refresh cycle
L	H to L	H	H	Valid	EDO page mode read cycle
L	H to L	L ^{*2}	L ^{*2}	Open	EDO page mode early write cycle
L	H to L	L ^{*2}	L ^{*2}	Undefined	EDO page mode delayed write cycle
L	H to L	H to L	H to L	Valid	EDO page mode read modify-write cycle

Notes: 1. H: High (inactive) L: Low (active) D: H or L

2. $t_{\text{WCS}} \geq 0 \text{ ns}$ Early write cycle

$t_{\text{WCS}} < 0 \text{ ns}$ Delayed write cycle

3. Mode is determined by the OR function of the $\overline{\text{UWE}}$ and $\overline{\text{LWE}}$. (Mode is set by the earliest of $\overline{\text{UWE}}$ and $\overline{\text{LWE}}$ active edge and reset by the latest of $\overline{\text{UWE}}$ and $\overline{\text{LWE}}$ inactive edge.) However write OPERATION and output High-Z control are done independently by each $\overline{\text{UWE}}$, $\overline{\text{LWE}}$.

Absolute Maximum Ratings

Parameter	Symbol	Value	Unit
Voltage on any pin relative to V_{SS}	V_T	–1.0 to +7.0	V
Supply voltage relative to V_{SS}	V_{CC}	–1.0 to +7.0	V
Short circuit output current	I_{out}	50	mA
Power dissipation	P_T	1.0	W
Operating temperature	T_{opr}	0 to +70	°C
Storage temperature	T_{stg}	–55 to +125	°C

Recommended DC Operating Conditions ($T_a = 0$ to +70°C)

Parameter	Symbol	Min	Typ	Max	Unit	Notes
Supply voltage	V_{SS}	0	0	0	V	2
	V_{CC}	4.5	5.0	5.5	V	1, 2
Input high voltage	V_{IH}	2.4	—	6.5	V	1
Input low voltage (I/O pin)	V_{IL}	–0.5	—	0.8	V	1
(Others)	V_{IL}	–1.0	—	0.8	V	1

Notes: 1. All voltage referred to V_{SS} .
 2. The supply voltage with all V_{CC} pins must be on the same level.
 The supply voltage with all V_{SS} pins must be on the same level.

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DC Characteristics (Ta = 0 to +70°C, V_{CC} = 5 V ±10%, V_{SS} = 0 V) *4

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Parameter	Symbol	Min	Max	Min	Max	Min	Max	Unit	Test conditions
Operating current*1, *2	I _{CC1}	—	120	—	115	—	90	mA	$\overline{\text{RAS}}$ cycling $\overline{\text{CAS}}$ cycling, t _{RC} = min
Standby current	I _{CC2}	—	2	—	2	—	2	mA	TTL interface $\overline{\text{RAS}}, \overline{\text{CAS}} = V_{\text{IH}}$ Dout = High-Z
		—	1	—	1	—	1	mA	CMOS interface $\overline{\text{RAS}}, \overline{\text{CAS}}, \overline{\text{UWE}}, \overline{\text{LWE}},$ $\overline{\text{OE}} \geq V_{\text{CC}} - 0.2 \text{ V}$ Dout = High-Z
$\overline{\text{RAS}}$ -only refresh current*2	I _{CC3}	—	120	—	115	—	90	mA	t _{RC} = min
Standby current*1	I _{CC5}	—	5	—	5	—	5	mA	$\overline{\text{RAS}} = V_{\text{IH}}, \overline{\text{CAS}} = V_{\text{IL}},$ Dout = enable
$\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$ refresh current*2	I _{CC6}	—	120	—	115	—	90	mA	t _{RC} = min
EDO page mode current*1, *3	I _{CC4}	—	150	—	120	—	115	mA	t _{HPC} = min
Input leakage current	I _{LI}	−10	10	−10	10	−10	10	μA	0 V ≤ Vin ≤ 6.5 V
Output leakage current	I _{LO}	−10	10	−10	10	−10	10	μA	0 V ≤ Vout ≤ 6.5 V Dout = disable
Output high voltage	V _{OH}	2.4	V _{CC}	2.4	V _{CC}	2.4	V _{CC}	V	High Iout = −2 mA
Output low voltage	V _{OL}	0	0.4	0	0.4	0	0.4	V	Low Iout = 2 mA

Notes: 1. I_{CC} depends on output load condition when the device is selected. I_{CC} max is specified at the output open condition.

2. Address can be changed twice or less while $\overline{\text{RAS}} = V_{\text{IL}}$.

3. Address can be changed once or less within one EDO page cycle.

4. All the V_{CC} pins should be supplied with the same voltage. And all the V_{SS} pins should be supplied with the same voltage.

Capacitance ($T_a = +25^{\circ}\text{C}$, $V_{CC} = 5\text{ V} \pm 10\%$)

Parameter	Symbol	Typ	Max	Unit	Notes
Input capacitance (Address)	C_{I1}	—	5	pF	1
Input capacitance (Clocks)	C_{I2}	—	7	pF	1
Output capacitance (Data-in, Data-out)	$C_{I/O}$	—	10	pF	1, 2

Notes: 1. Capacitance measured with Boonton Meter or effective capacitance measuring method.
 2. $\overline{\text{RAS}}, \overline{\text{CAS}} = V_{IH}$ to disable Dout.

AC Characteristics ($T_a = 0$ to $+70^{\circ}\text{C}$, $V_{CC} = 5\text{ V} \pm 10\%$, $V_{SS} = 0\text{ V}$)*1, *14, *15, *17, *18

Test Conditions

- Input rise and fall time : 2 ns
- Input levels: $V_{IL} = 0\text{ V}$, $V_{IH} = 3.0\text{ V}$
- Input timing reference levels : 0.8 V, 2.4 V
- Output timing reference levels : 0.8 V, 2.0 V
- Output load : 1 TTL gate + C_L (50 pF) (Including scope and jig)

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Read, Write, Read-Modify-Write and Refresh Cycles (Common parameters)

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		-6		-7		-8			
Parameter	Symbol	Min	Max	Min	Max	Min	Max	Unit	Notes
Random read or write cycle time	t _{RC}	105	—	125	—	145	—	ns	
$\overline{\text{RAS}}$ precharge time	t _{RP}	40	—	50	—	60	—	ns	
$\overline{\text{RAS}}$ pulse width	t _{RAS}	60	10000	70	10000	80	10000	ns	26
$\overline{\text{CAS}}$ pulse width	t _{CAS}	10	10000	13	10000	15	10000	ns	27
Row address setup time	t _{ASR}	0	—	0	—	0	—	ns	
Row address hold time	t _{RAH}	10	—	10	—	10	—	ns	
Column address setup time	t _{ASC}	0	—	0	—	0	—	ns	
Column address hold time	t _{CAH}	10	—	13	—	15	—	ns	
$\overline{\text{RAS}}$ to $\overline{\text{CAS}}$ delay time	t _{RCD}	20	45	20	50	20	60	ns	8
$\overline{\text{RAS}}$ to column address delay time	t _{RAD}	15	30	15	35	15	40	ns	9
$\overline{\text{RAS}}$ hold time	t _{RSH}	20	—	20	—	20	—	ns	
$\overline{\text{CAS}}$ hold time	t _{CSH}	48	—	58	—	68	—	ns	28
$\overline{\text{CAS}}$ to $\overline{\text{RAS}}$ precharge time	t _{CRP}	10	—	10	—	10	—	ns	
$\overline{\text{OE}}$ to Din delay time	t _{ODD}	15	—	15	—	15	—	ns	
$\overline{\text{OE}}$ delay time from Din	t _{DZO}	0	—	0	—	0	—	ns	
$\overline{\text{CAS}}$ setup time from Din	t _{DZC}	0	—	0	—	0	—	ns	
Transition time (rise and fall)	t _T	2	50	2	50	2	50	ns	7
Refresh period	t _{REF}	—	4	—	4	—	4	ms	

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Read Cycle

		HM511667C							
		-6		-7		-8			
Parameter	Symbol	Min	Max	Min	Max	Min	Max	Unit	Notes
Access time from $\overline{\text{RAS}}$	t_{RAC}	—	60	—	70	—	80	ns	2, 3
Access time from $\overline{\text{CAS}}$	t_{CAC}	—	15	—	20	—	20	ns	3, 4, 13
Access time from address	t_{AA}	—	30	—	35	—	40	ns	3, 5, 13
Access time from $\overline{\text{OE}}$	t_{OAC}	—	15	—	20	—	20	ns	22
Read command setup time	t_{RCS}	0	—	0	—	0	—	ns	20
Read command hold time to $\overline{\text{CAS}}$	t_{RCH}	0	—	0	—	0	—	ns	16, 19
Read command hold time to $\overline{\text{RAS}}$	t_{RRH}	0	—	0	—	0	—	ns	16, 19
Column address to $\overline{\text{RAS}}$ lead time	t_{RAL}	30	—	35	—	40	—	ns	
Column address to $\overline{\text{CAS}}$ lead time	t_{CAL}	18	—	23	—	28	—	ns	
Output buffer turn-off time	t_{OFF1}	0	15	0	15	0	15	ns	6, 24
Output buffer turn-off time to $\overline{\text{OE}}$	t_{OFF2}	0	15	0	15	0	15	ns	6
$\overline{\text{CAS}}$ to Din delay time	t_{CDD}	15	—	18	—	20	—	ns	
$\overline{\text{RAS}}$ to Din delay time	t_{RDD}	15	—	18	—	20	—	ns	
$\overline{\text{WE}}$ to Din delay time	t_{WDD}	15	—	18	—	20	—	ns	
$\overline{\text{OE}}$ pulse width	t_{OEP}	15	—	20	—	20	—	ns	22
Turn-off to $\overline{\text{RAS}}$	t_{OFR}	0	15	0	15	0	15	ns	6, 24
Turn-off to $\overline{\text{WE}}$	t_{WEZ}	0	15	0	15	0	15	ns	6
Output data hold time	t_{OH}	5	—	5	—	5	—	ns	24
Output data hold time from $\overline{\text{RAS}}$	t_{OHR}	5	—	5	—	5	—	ns	24
Read command hold time from $\overline{\text{RAS}}$	t_{RCHR}	60	—	70	—	80	—	ns	
Read command hold time from $\overline{\text{CAS}}$	t_{RCHC}	15	—	18	—	20	—	ns	
Read command hold time from column address	t_{RCHA}	30	—	35	—	40	—	ns	

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Write Cycle

		HM511667C							
		-6		-7		-8			
Parameter	Symbol	Min	Max	Min	Max	Min	Max	Unit	Notes
Write command setup time	t_{WCS}	0	—	0	—	0	—	ns	10, 19
Write command hold time	t_{WCH}	10	—	13	—	15	—	ns	20
Write command pulse width	t_{WP}	10	—	13	—	15	—	ns	21
Write command to $\overline{RAS}$ lead time	t_{RWL}	10	—	13	—	15	—	ns	21
Write command to $\overline{CAS}$ lead time	t_{CWL}	10	—	13	—	15	—	ns	21
Data-in setup time	t_{DS}	0	—	0	—	0	—	ns	11, 21
Data-in hold time	t_{DH}	10	—	13	—	15	—	ns	11, 21

Read-Modify-Write Cycle

		HM511667C							
		-6		-7		-8			
Parameter	Symbol	Min	Max	Min	Max	Min	Max	Unit	Notes
Read-modify-write cycle time	t_{RWC}	135	—	165	—	185	—	ns	
$\overline{RAS}$ to $\overline{WE}$ delay time	t_{RWD}	77	—	90	—	102	—	ns	10, 19
$\overline{CAS}$ to $\overline{WE}$ delay time	t_{CWD}	32	—	38	—	42	—	ns	10, 19
Column address to $\overline{WE}$ delay time	t_{AWD}	47	—	55	—	62	—	ns	10, 19
$\overline{OE}$ hold time from $\overline{WE}$	t_{OEh}	15	—	18	—	20	—	ns	21

Refresh Cycle

		HM511667C							
		-6		-7		-8			
Parameter	Symbol	Min	Max	Min	Max	Min	Max	Unit	Notes
$\overline{CAS}$ setup time (CBR refresh cycle)	t_{CSR}	10	—	10	—	10	—	ns	
$\overline{CAS}$ hold time (CBR refresh cycle)	t_{CHR}	10	—	10	—	10	—	ns	
$\overline{RAS}$ precharge to $\overline{CAS}$ hold time	t_{RPC}	10	—	10	—	10	—	ns	
$\overline{CAS}$ precharge time in normal mode	t_{CPN}	10	—	10	—	10	—	ns	

EDO Page Mode Cycle

		HM511667C							
		-6		-7		-8			
Parameter	Symbol	Min	Max	Min	Max	Min	Max	Unit	Notes
EDO page mode cycle time	t_{HPC}	25	—	30	—	35	—	ns	23
EDO page mode $\overline{CAS}$ precharge time	t_{CP}	10	—	13	—	15	—	ns	
EDO page mode $\overline{RAS}$ pulse width	t_{RASC}	60	100000	70	100000	80	100000	ns	12
Access time from $\overline{CAS}$ precharge	t_{ACP}	—	35	—	40	—	45	ns	3, 13
$\overline{RAS}$ hold time from $\overline{CAS}$ precharge	t_{RHCP}	35	—	40	—	45	—	ns	
Output data hold time from $\overline{CAS}$ low	t_{DOH}	5	—	5	—	5	—	ns	25
$\overline{CAS}$ hold time referred $\overline{OE}$	t_{COL}	10	—	13	—	20	—	ns	
$\overline{CAS}$ to $\overline{OE}$ setup time	t_{COP}	5	—	5	—	5	—	ns	
Read command hold time from $\overline{CAS}$ precharge	t_{RCHP}	35	—	40	—	45	—	ns	

EDO Page Mode Read-Modify-Write Cycle

		HM511667C							
		-6		-7		-8			
Parameter	Symbol	Min	Max	Min	Max	Min	Max	Unit	Notes
EDO page mode read-modify-write cycle time	t_{HPCM}	66	—	77	—	86	—	ns	
EDO page mode read-modify-write cycle $\overline{CAS}$ precharge to $\overline{WE}$ delay time	t_{CPW}	52	—	60	—	67	—	ns	10, 21

- Notes:
1. AC measurements assume $t_f = 2$ ns.
 2. Assumes that $t_{RCD} \leq t_{RCD}(\text{max})$ and $t_{RAD} \leq t_{RAD}(\text{max})$. If t_{RCD} or t_{RAD} is greater than the maximum recommended value shown in this table, t_{RAC} exceeds the value shown.
 3. Measured with a load circuit equivalent to 1 TTL loads and 50 pF.
 4. Assumes that $t_{RCD} \geq t_{RCD}(\text{max})$ and $t_{RAD} \leq t_{RAD}(\text{max})$.
 5. Assumes that $t_{RCD} \leq t_{RCD}(\text{max})$ and $t_{RAD} \geq t_{RAD}(\text{max})$.
 6. $t_{OFF1}(\text{max})$, $t_{OFF2}(\text{max})$, $t_{OFR}(\text{max})$ and $t_{WEZ}(\text{max})$ define the time at which the output achieves the open circuit condition and is not referred to output voltage levels.
 7. $V_{IH}(\text{min})$ and $V_{IL}(\text{max})$ are reference levels for measuring timing of input signals. Also, transition times are measured between V_{IH} and V_{IL} .
 8. Operation with the $t_{RCD}(\text{max})$ limit insures that $t_{RAC}(\text{max})$ can be met, $t_{RCD}(\text{max})$ is specified as a reference point only, if t_{RCD} is greater than the specified $t_{RCD}(\text{max})$ limit, then access time is controlled exclusively by t_{CAC} .

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9. Operation with the t_{RAD} (max) limit insures that t_{RAC} (max) can be met, t_{RAD} (max) is specified as a reference point only, if t_{RAD} is greater than the specified t_{RAD} (max) limit, then access time is controlled exclusively by t_{AA} .
10. t_{WCS} , t_{RWD} , t_{CWD} and t_{AWD} are not restrictive operating parameters. They are included in the data sheet as electrical characteristics only: if $t_{WCS} \geq t_{WCS}(\text{min})$, the cycle is an early write cycle and the data out pin will remain open circuit (high impedance) throughout the entire cycle; if $t_{RWD} \geq t_{RWD}(\text{min})$, $t_{CWD} \geq t_{CWD}(\text{min})$, $t_{AWD} \geq t_{AWD}(\text{min})$ and $t_{CPW} \geq t_{CPW}(\text{min})$, the cycle is a read-modify-write and the data output will contain data read from the selected cell; if neither of the above sets of conditions is satisfied, the condition of the data out (at access time) is indeterminate.
11. These parameters are referred to $\overline{CAS}$ leading edge in an early write cycle and to $\overline{WE}$ leading edge in a delayed write or a read-modify-write cycle.
12. t_{RASC} defines $\overline{RAS}$ pulse width in EDO page mode cycles.
13. Access time is determined by the longest among t_{AA} , t_{CAC} and t_{ACP} .
14. An initial pause of 100 μs is required after power up followed by a minimum of eight initialization cycles ($\overline{RAS}$ -only refresh cycle or $\overline{CAS}$ -before- $\overline{RAS}$ refresh cycle). If the internal refresh counter is used, a minimum of eight $\overline{CAS}$ -before- $\overline{RAS}$ refresh cycles is required.
15. In delayed write or read-modify-write cycles, $\overline{OE}$ must disable output buffer prior to applying data to the device.
16. Either t_{RCH} or t_{RRH} must be satisfied for a read cycle.
17. When both $\overline{UWE}$ and $\overline{LWE}$ go low at the same time, all 16-bits data are written into the device. $\overline{UWE}$ and $\overline{LWE}$ cannot be staggered within the same write/read cycles.
18. All the V_{CC} and V_{SS} pins shall be supplied with the same voltages.
19. t_{RCH} , t_{RRH} , t_{WCS} , t_{RWD} , t_{CWD} and t_{AWD} are determined by the earlier falling edge of $\overline{UWE}$ and $\overline{LWE}$.
20. t_{WCH} and t_{RCS} are determined by the later rising edge of $\overline{UWE}$ or $\overline{LWE}$.
21. t_{WP} , t_{RWL} , t_{CWL} , t_{OEHL} , t_{DS} , t_{DH} and t_{CPW} should be satisfied by both $\overline{UWE}$ and $\overline{LWE}$.
22. When output buffers are enabled once, sustain the low impedance state until valid data is obtained. When output buffer is turned on and off within a very short time, generally it causes large V_{CC}/V_{SS} line noise, which causes to degrade $V_{IH\text{ min}}/V_{IL\text{ max}}$ level.
23. $t_{HPC}(\text{min})$ can be achieved during a series of EDO page mode early write cycles or EDO page mode read cycles. If both write and read operation are mixed in a EDO page mode $\overline{RAS}$ cycle (EDO page mode mix cycle (1), (2)), minimum value of $\overline{CAS}$ cycle t_{HPC} ($t_{CAS} + t_{CP} + 2t_T$) becomes greater than the specified $t_{HPC}(\text{min})$ value.
24. Data output turns off and becomes high impedance from later rising edge of $\overline{RAS}$ and $\overline{CAS}$. Hold time and turn off time are specified by the timing specifications of later rising edge of $\overline{RAS}$ and $\overline{CAS}$ between t_{OHR} and t_{OH} , and between t_{OFF} and t_{OFF} .
25. t_{DOH} defines the time at which the output level satisfied the output timing reference levels. Measured with the test conditions.
26. $t_{RAS}(\text{min}) = t_{RWD}(\text{min}) + t_{RWL}(\text{min}) + t_T$ in read-modify-write cycle.
27. $t_{CAS}(\text{min}) = t_{CWD}(\text{min}) + t_{CWL}(\text{min}) + t_T$ in read-modify-write cycle.
28. $t_{CSH}(\text{min})$ can be achieved when $t_{RCD} \leq t_{CSH}(\text{min}) - t_{CAS}(\text{min})$.
29. XXX: H or L (H: $V_{IH}(\text{min}) \leq V_{IN} \leq V_{IH}(\text{max})$, L: $V_{IL}(\text{min}) \leq V_{IN} \leq V_{IL}(\text{max})$)

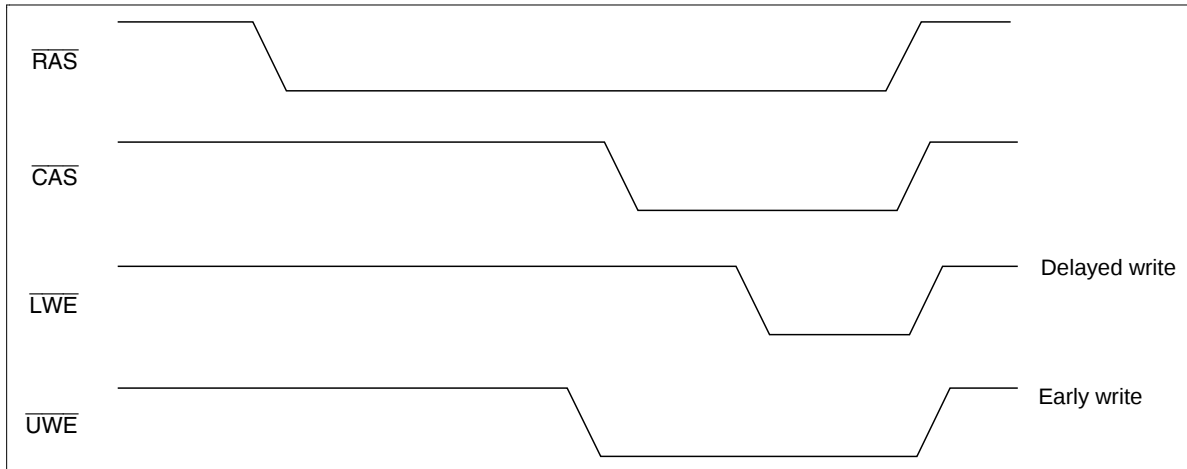
//////: Invalid Dout

When the address, clock and input pins are not described on timing waveforms, their pins must be applied V_{IH} or V_{IL} .

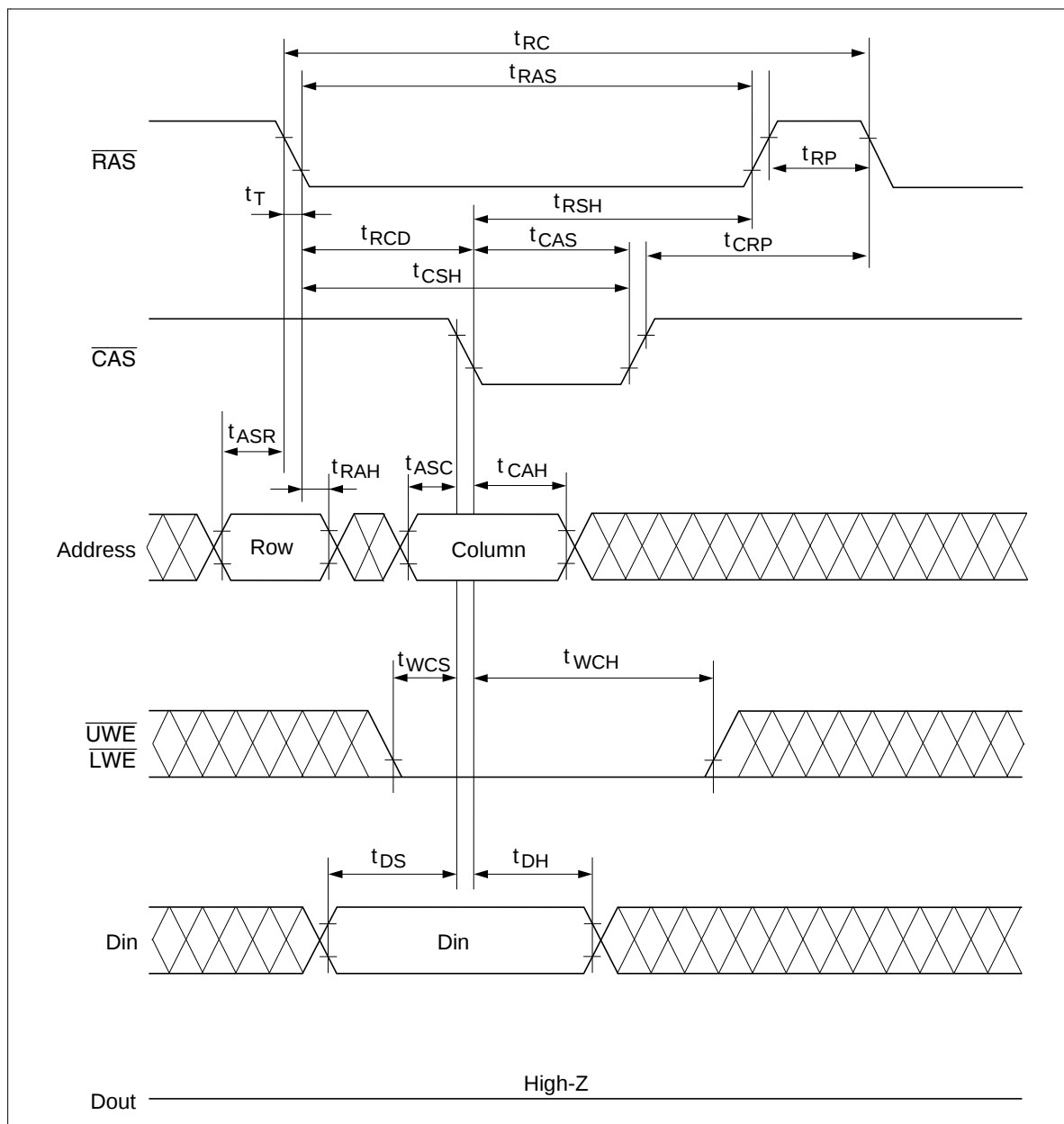
Notes concerning $\overline{2WE}$ control

Please do not separate the $\overline{UWE}/\overline{LWE}$ operation timing intentionally. However skew between $\overline{UWE}/\overline{LWE}$ are allowed under the following conditions.

- (1) Each of the $\overline{UWE}/\overline{LWE}$ should satisfy the timing specifications individually.
- (2) Different operation mode for upper/lower byte is not allowed; such as following.

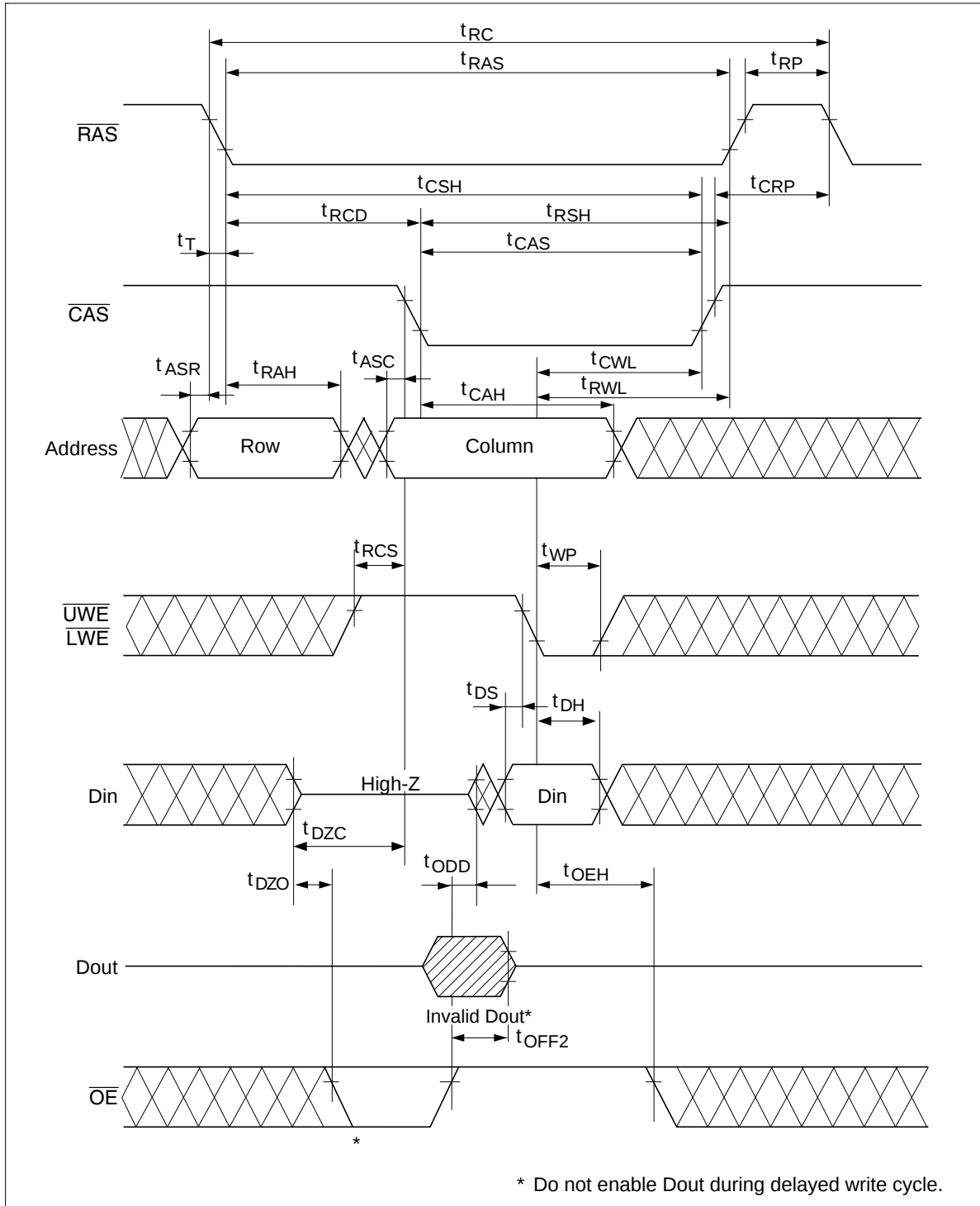


Early Write Cycle



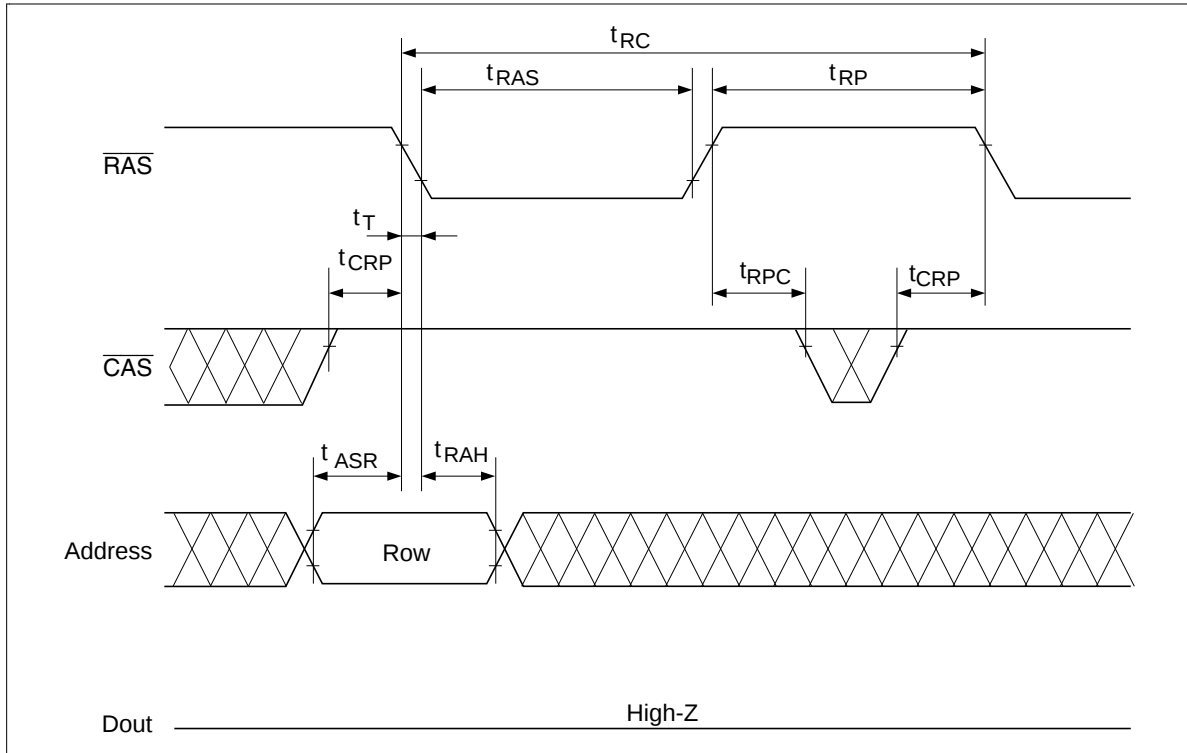
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Delayed Write Cycle

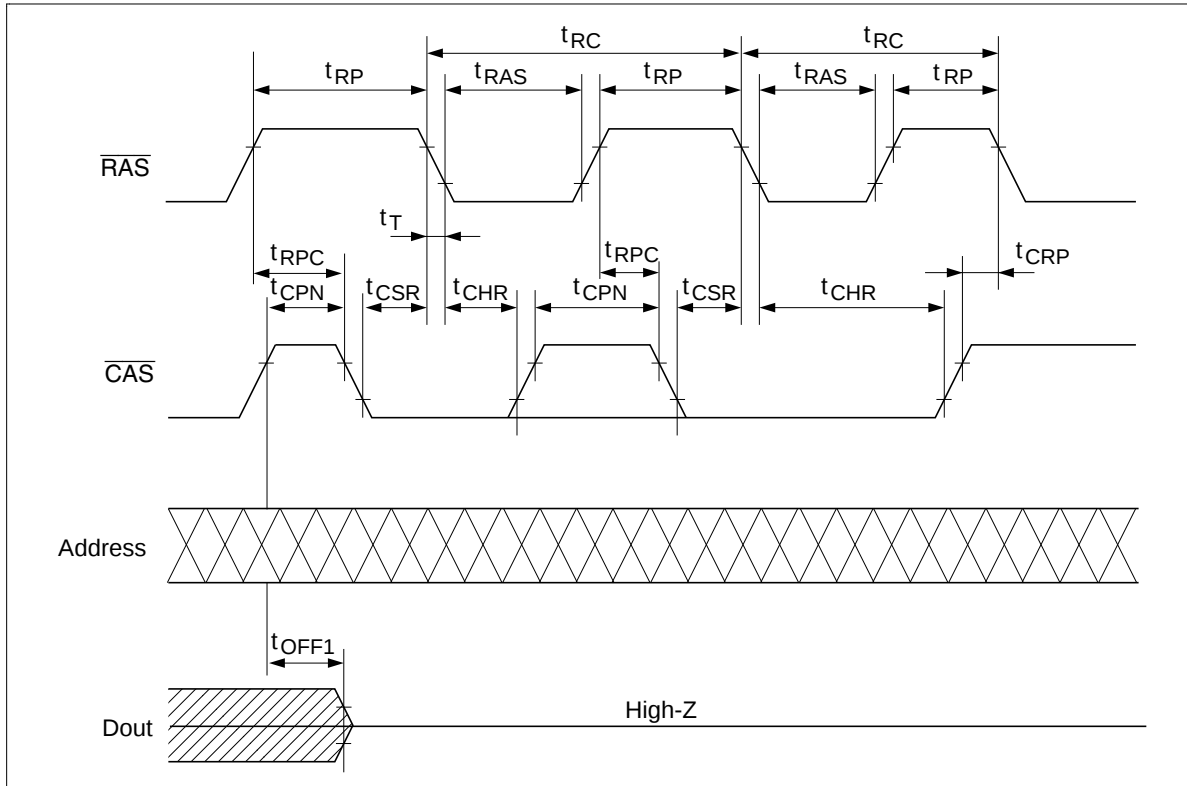


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$\overline{\text{RAS}}$ -Only Refresh Cycle



$\overline{\text{CAS}}$ -Before- $\overline{\text{RAS}}$ Refresh Cycle

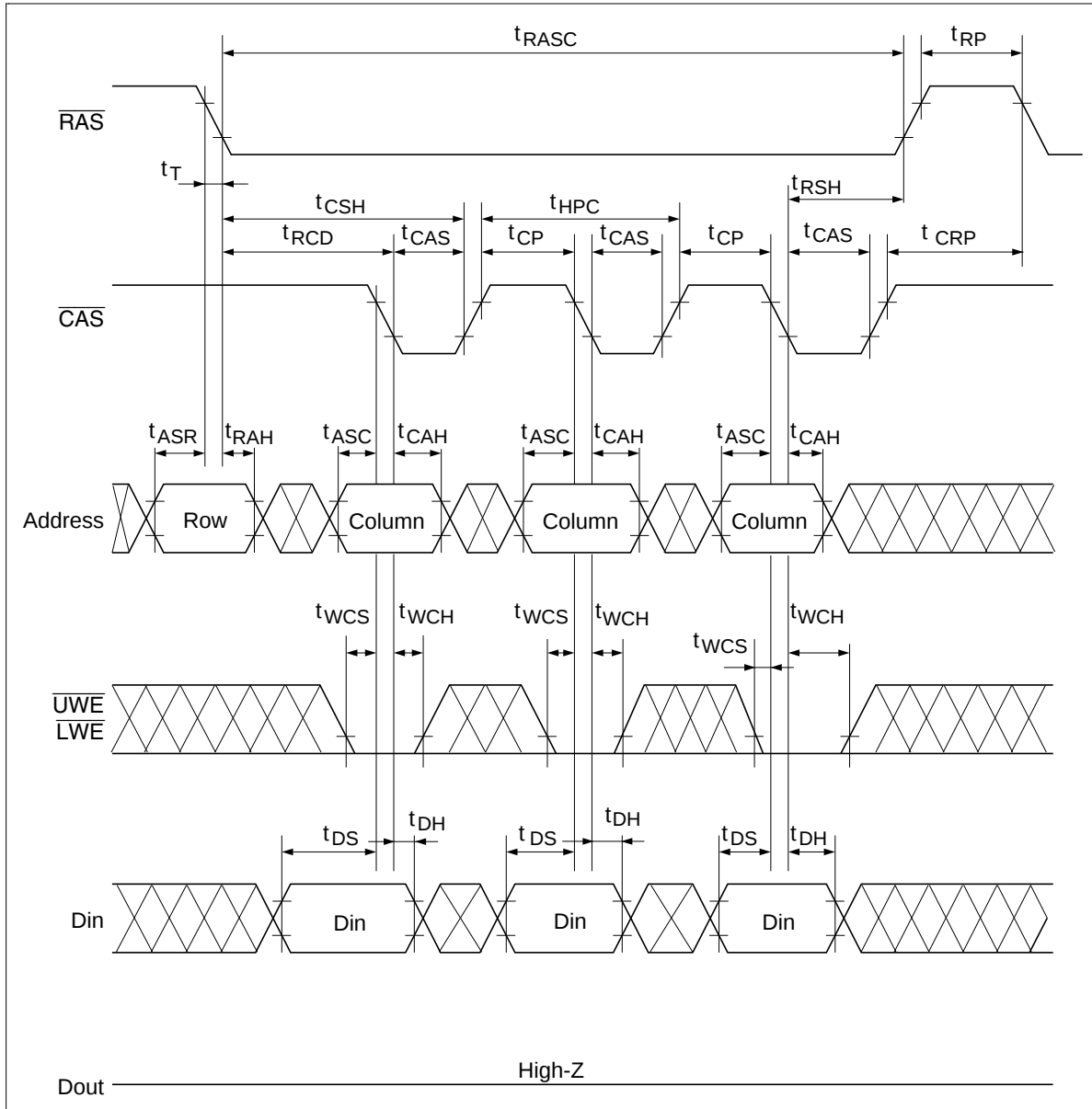


EDO Page Mode Read Cycle (t_{HPC} minimum cycle operation)

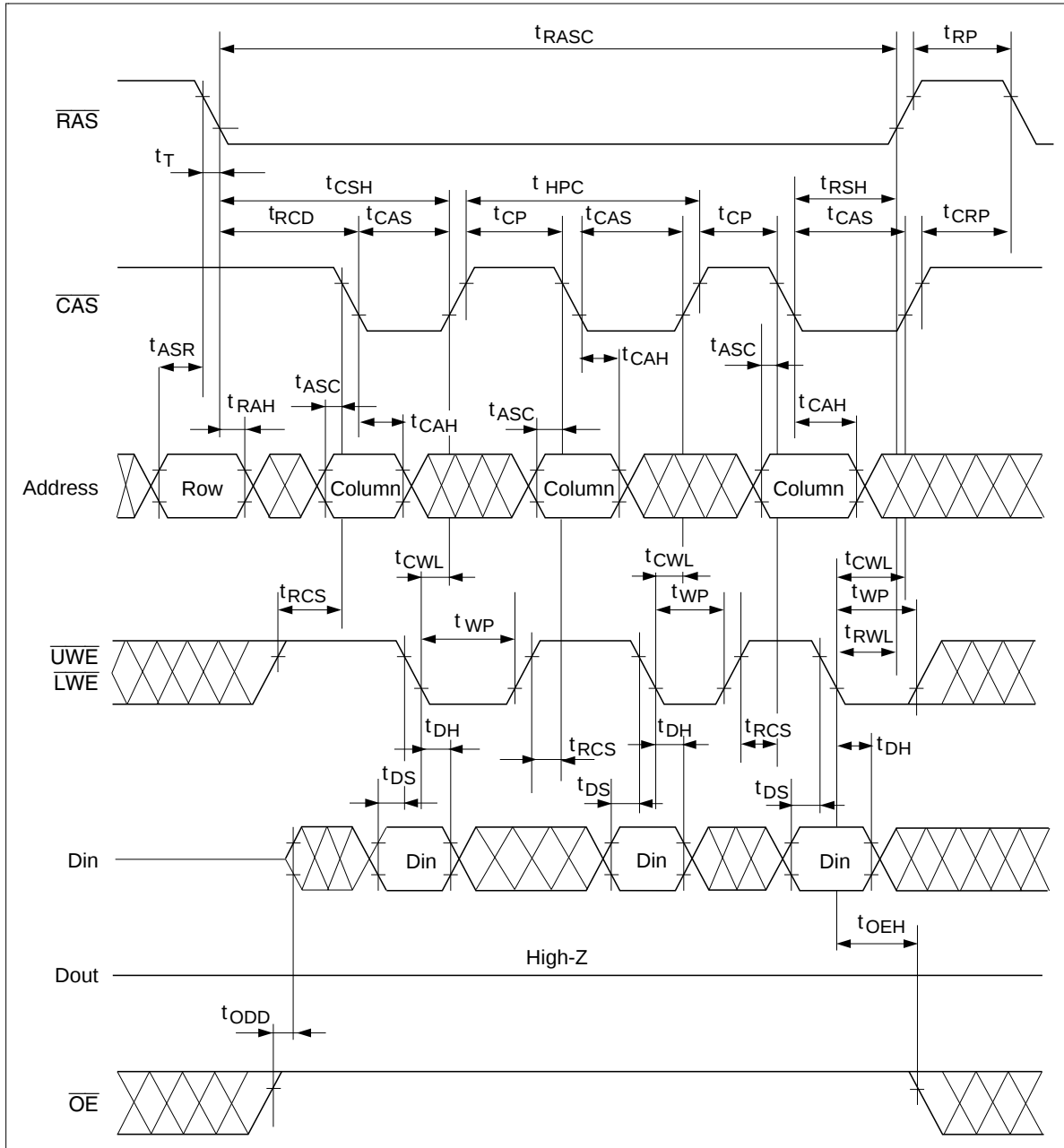


HM511667C Series

EDO Page Mode Early Write Cycle (t_{HPC} minimum cycle operation)

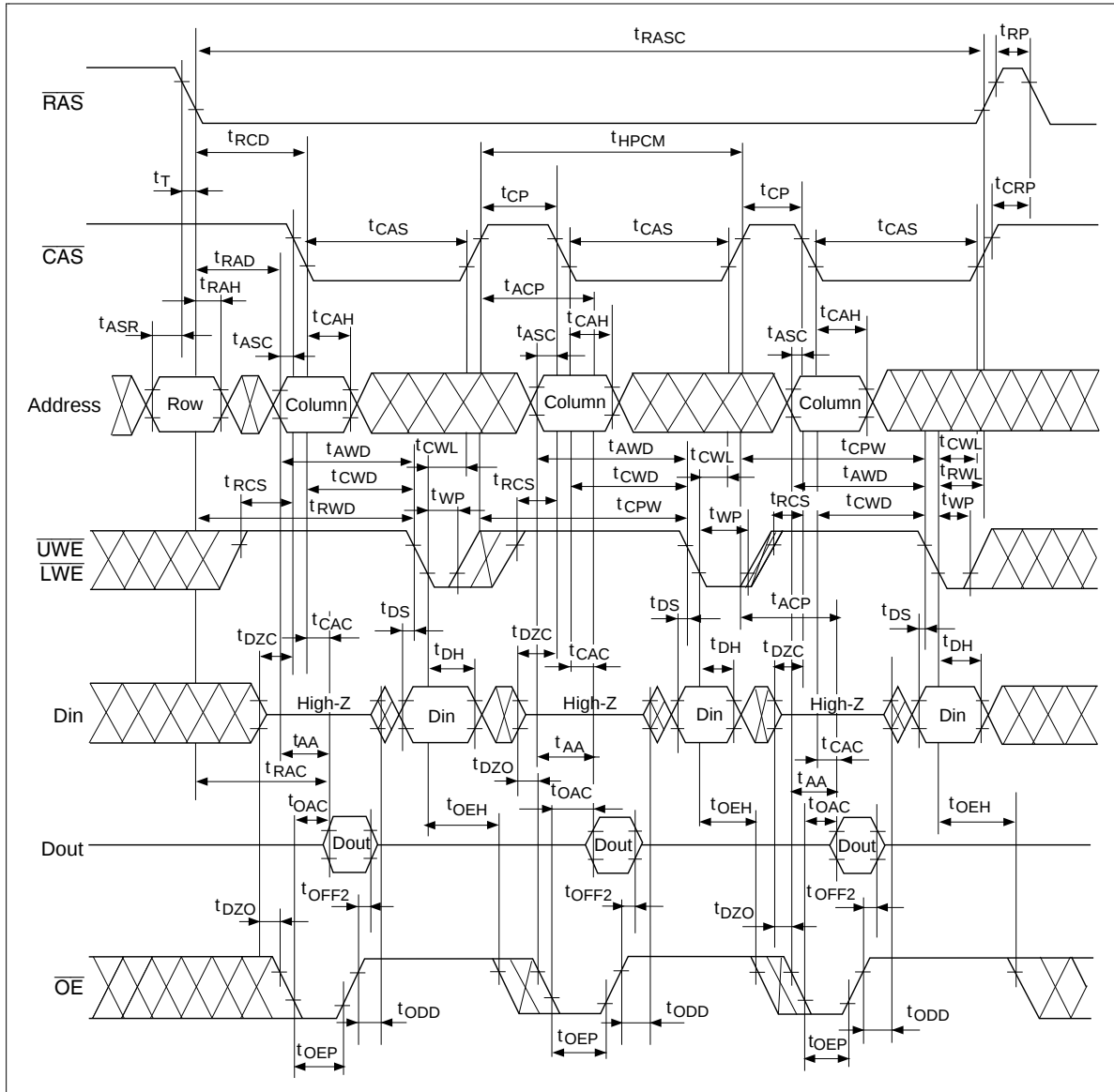


EDO Page Mode Delayed Write Cycle



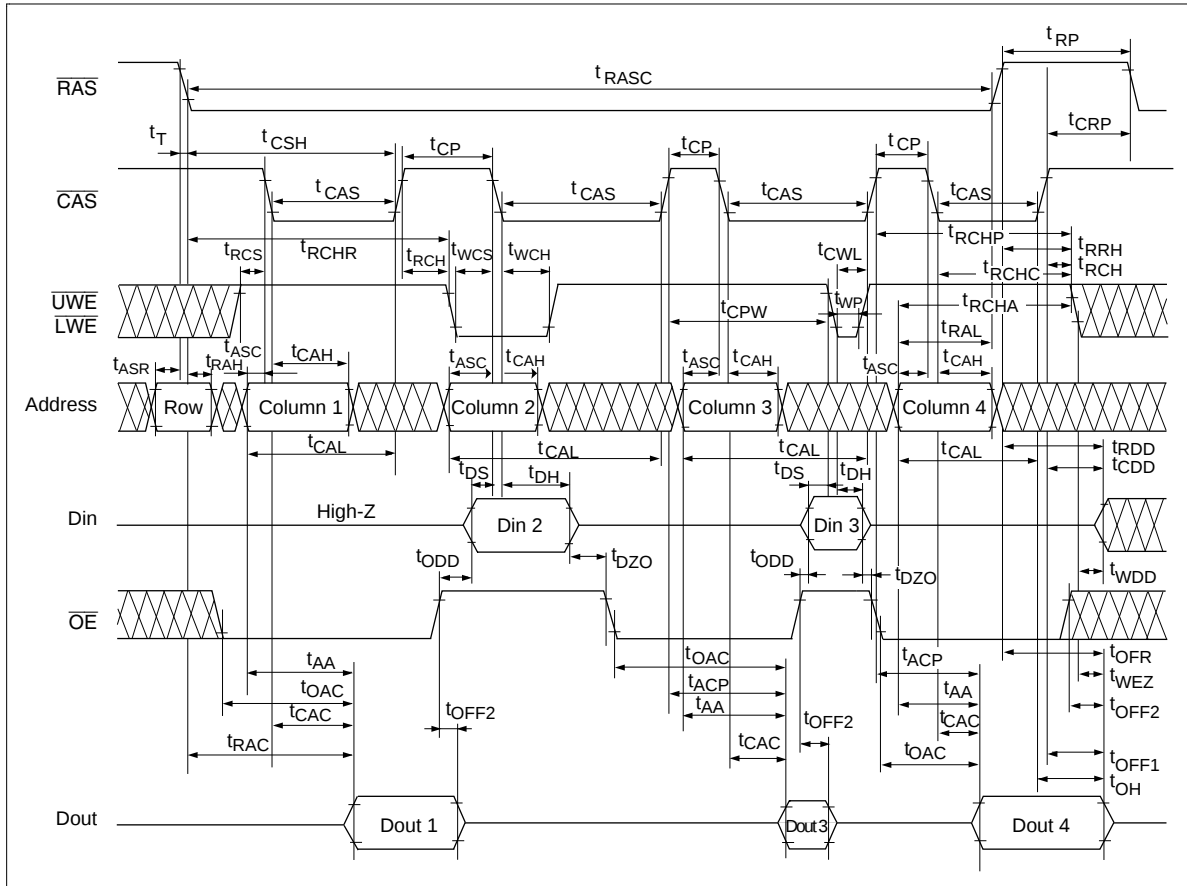
HM511667C Series

EDO Page Mode Read-Modify-Write Cycle



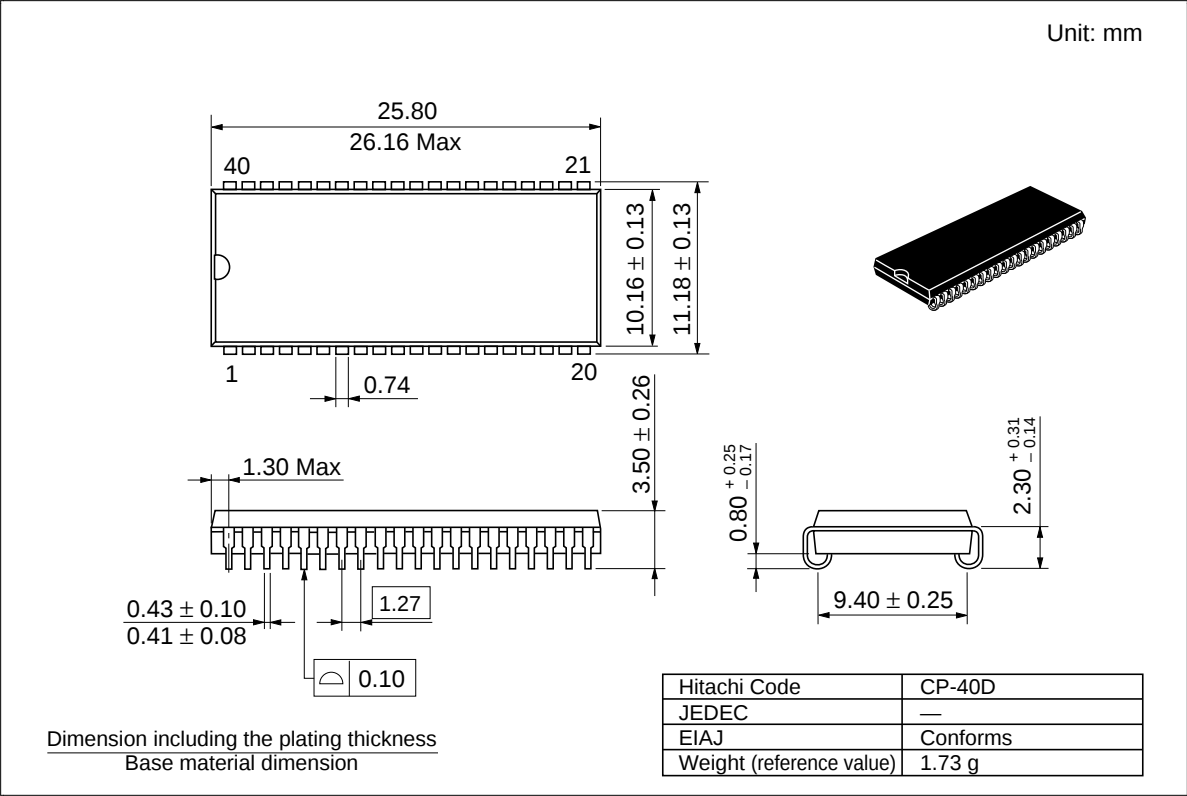
HM511667C Series

EDO Page Mode Mix Cycle (2)*23



Package Dimension

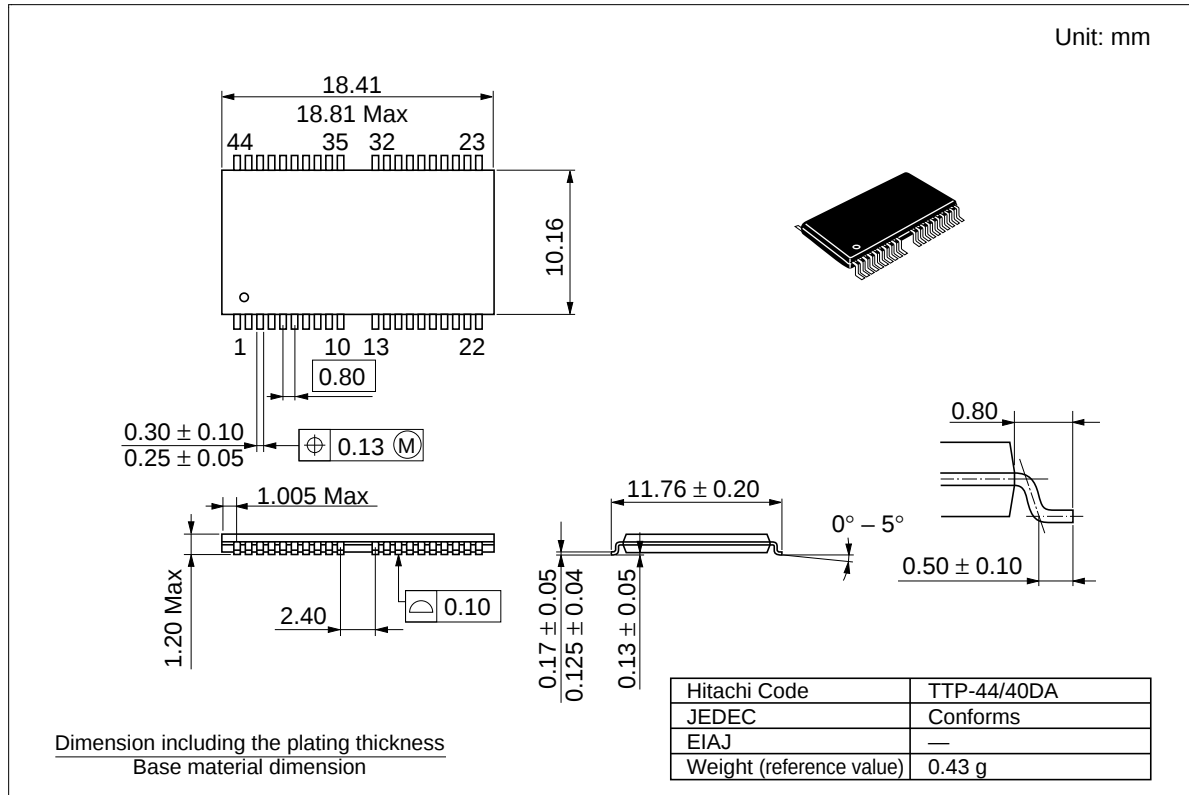
HM511667CJ Series (CP-40D)



HM511667C Series

Package Dimension (cont.)

HM511667CTT Series (TTP-44/40DA)



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HM511667C Series

Revision Record

Rev.	Date	Contents of Modification	Drawn by	Approved by
0.0	Aug. 30, 1996	Initial issue	I. Ogiwara	S. Suzuki
1.0	Dec. 20, 1997	Change of Subtitle		