Features

- Operating voltage: +5.0V
- · Programming voltage
 - $-V_{PP}=12.5V\pm0.2V$
 - V_{CC} =6.0V±0.2V
- High-reliability CMOS technology
- Latch-up immunity to 100mA from -1.0V to $V_{\rm CC}$ +1.0V
- CMOS and TTL compatible I/O
- Low power consumption
 - Active: 30mA max.
 - Standby: 1µA typ.

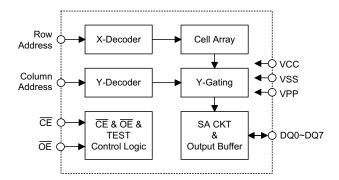
- 512K×8-bit organization
- Fast read access time: -70ns, -90ns and -120ns
- Fast programming algorithm
- Programming time 75µs typ.
- Two line controls (OE and CE)
- Standard product identification code
- Commercial temperature range (0°C to +70°C)
- 32-pin DIP package

General Description

The HT27C040 chip family is a low-power, 4096K (4,194,304) bit, +5V electrically one-time programmable (OTP) read-only memories (EPROM). Organized into 512K words with 8 bits per word, it features a fast single address location programming, typically at 75 μ s per byte. Any byte can be accessed in less than

70ns/90ns/120ns with respect to Spec. This eliminates the need for WAIT states in high-performance microprocessor systems. The HT27C040 has separate Output Enable (\overline{OE}) and Chip Enable (\overline{CE}) controls which eliminate bus contention issues.

Block Diagram





Pin Assignment

	$\overline{}$, ,	1
VPP □	1	32	□ vcc
A16 🗆	2	31	□ A18
A15 🗆	3	30	□ A17
A12 🗆	4	29	☐ A14
A7 🗆	5	28	□ A13
A6 🗆	6	27	□ A8
A5 🗆	7	26	□ A9
A4 🗆	8	25	□ A11
A3 🗆	9	24	
A2 🗆	10	23	□ A10
A1 🗆	11	22	□ CE
A0 [12	21	DQ7
DQ0	13	20	□ DQ6
DQ1	14	19	DQ5
DQ2	15	18	DQ4
VSS [16	17	□ DQ3
	HT270 - 32	C040 DIP	I

Pin Description

Pin No.	Pin Name	I/O/C/P	Description
1	VPP	P	Program voltage supply
12~5, 27, 26, 23, 25, 4, 28, 29, 3, 2, 30, 31	A0~A18	I	Address inputs
13~15, 17~21	DQ0~DQ7	I/O	Data inputs/outputs
16	VSS	_	Negative power supply, ground
22	$\overline{ ext{CE}}$	C	Chip enable
24	ŌĒ	C	Output enable
32	VCC	_	Positive power supply



Absolute Maximum Rating

Operation Temperature Commercial	0°C to +70°C
Storage Temperature	65°C to 125°C
Applied VCC Voltage with Respect to VSS	0.6V to 7.0V
Applied Voltage on Input Pin with Respect to VSS	0.6V to 7.0V
Applied Voltage on Output Pin with Respect to VSS	. $-0.6\mathrm{V}$ to V_{CC} + $0.5\mathrm{V}$
Applied Voltage on A9 Pin with Respect to VSS	0.6V to 13.5V
Applied VPP Voltage with Respect to VSS	0.6V to 13.5V
Applied READ Voltage (Functionality is guaranteed between these limits)	+4.5V to +5.5V

Note: These are stress ratings only. Stresses exceeding the range specified under "Absolute Maximum Ratings" may cause substantial damage to the device. Functional operation of this device at other conditions beyond those listed in the specification is not implied and prolonged exposure to extreme conditions may affect device reliability.

D.C. Characteristics

Read operation

Sb al	Domomoton		Test Conditions	ъл:	Т	M	TT *4
Symbol	Parameter	$\mathbf{v}_{\mathbf{c}\mathbf{c}}$	Conditions	wiin.	Тур.	Max.	Unit
V_{OH}	Output High Level	5V	I_{OH} =-0.4mA	2.4	_	_	V
V_{OL}	Output Low Level	5V	I _{OL} =2.1mA		_	0.45	V
V_{IH}	Input High Level	5V		2.0	_	$V_{\rm CC}$ +0.5	V
V_{IL}	Input Low Level	5V	_	-0.3	_	0.8	V
I_{LI}	Input Leakage Current	5V	$V_{\rm IN}$ =0 to 5.5V	-5	_	5	μΑ
I_{LO}	Output Leakage Current	5V	V_{OUT} =0 to 5.5V	-10	_	10	μΑ
I_{CC}	VCC Active Current	5V	$\overline{\text{CE}}$ =V _{IL} , f=5MHz, I _{OUT} =0mA	_	_	30	mA
I_{SB1}	Standby Current (CMOS)	5V	$\overline{\text{CE}} = V_{\text{CC}} \pm 0.3V$	_	1.0	10	μΑ
I_{SB2}	Standby Current (TTL)	5V	$\overline{\text{CE}}$ = V_{IH}			1.0	mA
I_{PP}	VPP Read/Standby Current	5V	$\overline{\text{CE}} = \overline{\text{OE}} = V_{\text{IL}}, V_{\text{PP}} = V_{\text{CC}}$			100	μΑ



Programming operation

Symbol Parameter		Т	est Conditions	Min.	Т	Max.	Unit
Symbol	Parameter	$\mathbf{v}_{\mathbf{c}\mathbf{c}}$	Conditions	Wiin.	Тур.	max.	Unit
V_{OH}	Output High Level	6V	I _{OH} =-0.4mA	2.4	_		V
V_{OL}	Output Low Level	6V	I _{OL} =2.1mA		_	0.45	V
V_{IH}	Input High Level	6V	_	$0.7V_{\mathrm{CC}}$	_	$V_{\rm CC}$ +0.5	V
$ m V_{IL}$	Input Low Level	6V		-0.5		0.8	V
I_{LI}	Input Load Current	6V	$V_{\rm IN}=V_{\rm IL},V_{\rm IH}$		_	5.0	μА
V_{H}	A9 Product ID Voltage	6V	_	11.5	_	12.5	V
I_{CC}	VCC Supply Current	6V	_		_	40	mA
I_{PP}	VPP Supply Current	6V	$\overline{\mathrm{CE}}$ = V_{IL}			10	mA

Capacitance

Cb - 1	Domonoston	Т	est Conditions	М:	Т	Man	T7
Symbol	Parameter	$\mathbf{v_{cc}}$	Conditions	wiin.	1yp.	Max.	Unit
C_{IN}	Input Capacitance	5V	V _{IN} =0V	_	8	12	pF
C_{OUT}	Output Capacitance	5V	V _{OUT} =0V	_	8	12	pF
C_{VPP}	VPP Capacitance	5V	V _{PP} =0V		18	25	pF

A.C. Characteristics

Read operation

Ch al	Parameter	Test	Conditions	-70		-90		-120		Unit
Symbol	Parameter	$\mathbf{v}_{\mathbf{c}\mathbf{c}}$	Conditions	Min.	Max.	Min.	Max.	Min.	Max.	Unit
$t_{ m ACC}$	Address to Output Delay	5V	$\overline{\text{CE}} = \overline{\text{OE}} = V_{\text{IL}}$	_	70	_	90	_	120	ns
$t_{ m CE}$	Chip Enable to Output Delay	5V	$\overline{\mathrm{OE}}$ = $\mathrm{V_{IL}}$	_	70	_	90	_	120	ns
t_{OE}	Output Enable to Output Delay	5V	$\overline{\text{CE}}$ = V_{IL}	_	30	_	35	_	40	ns
$t_{ m DF}$	CE or OE High to Output Float, Whichever Occurred First	5V	_	_	25	_	25	_	30	ns
$t_{ m OH}$	Output Hold from Address, $\overline{\text{CE}}$ or $\overline{\text{OE}}$, Whichever Occurred First	5V	_	0		0		0	_	ns



Programming operation

Ta=+	-25°	$^{\circ}C\pm5$	$^{\circ}C$
1a-7	740	-	•

G 1 1	D 4	Te	st Conditions	Min.	Tum	ъл	TT *4	
Symbol	Parameter	$\mathbf{v}_{\mathbf{c}\mathbf{c}}$	Conditions	Min.	Тур.	Max.	Unit	
t_{AS}	Address Setup Time	6V	_	2	_	_	μs	
t_{OES}	OE Setup Time	6V	_	2	_	_	μs	
${ m t_{DS}}$	Data Setup Time	6V	_	2	_	_	μs	
$t_{ m AH}$	Address Hold Time	6V	_	0	_	_	μs	
${ m t_{DH}}$	Data Hold Time	6V	_	2	_	_	μs	
${ m t_{DFP}}$	Output Enable to Output Float Delay	6V	_	0	_	130	ns	
$t_{ m VPS}$	VPP Setup Time	6V	_	2	_	_	μs	
$\mathrm{t_{PW}}$	PGM Program Pulse Width	6V	_	30	75	105	μs	
$t_{ m VCS}$	VCC Setup Time	6V		2	_	_	μs	
$t_{\rm CES}$	CE Setup Time	6V	_	2	_	_	ns	
t_{OE}	Data Valid from $\overline{\text{OE}}$	6V	_	_	_	150	μs	
t_{PRT}	VPP Pulse Rise Time During Programming	6V	_	2	_	_	μs	

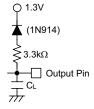
Test waveforms and measurements

For -70, -90, -120 devices



 $t_R,\,t_F\!\!<20ns~(10\%$ to 90%)

Output test load



Note: C_L =100pF including jig capacitance, except for the -45 devices, where C_L =30pF.



Functional Description

Programming of the HT27C040

When the HT27C040 is delivered, the chip has all 4096K bits in the "ONE", or HIGH state. "ZEROs" are loaded into the HT27C040 through programming.

The programming mode is entered when $12.5\pm0.2V$ is applied to the VPP pin, \overline{OE} is at V_{IH} , and \overline{CE} is V_{IL} . For programming, the data to be programmed is applied with 8 bits in parallel to the data pins.

The programming flowchart in Figure 3 shows the fast interactive programming algorithm. The interactive algorithm reduces programming time by using 30 µs to 105 µs programming pulses and giving each address only as many pulses as is necessary in order to reliably program the data. After each pulse is applied to a given address, the data in that address is verified. If the data is not verified, additional pulses are given until it is verified or until the maximum number of pulses is reached while sequencing through each address of the HT27C040. This process is repeated while sequencing through each address of the HT27C040. This part of the programming algorithm is done at V_{CC} =6.0V to assure that each EPROM bit is programmed to a sufficiently high threshold voltage. This ensures that all bits have sufficient margin. After the final address is completed, the entire EPROM memory is read at V_{CC} = V_{PP} =5.25 \pm 0.25V to verify the entire memory.

Program inhibit mode

Programming of multiple HT27C040 in parallel with different data is also easily accomplished by using the Program Inhibit Mode. Except for $\overline{\text{CE}}$, all like inputs of the parallel HT27C040 may be common. A TTL low-level program pulse applied to an HT27C040 $\overline{\text{CE}}$ input with Vpp=12.5±0.2V, and $\overline{\text{OE}}$ HIGH will program that HT27C040. A high-level $\overline{\text{CE}}$ input inhibits the HT27C040 from being programmed.

Program verify mode

Verification should be performed on the programmed bits to determine whether they were correctly programmed. The verification should be performed with \overline{OE} at V_{IL} , and \overline{CE} at V_{IH} , and VPP at its programming voltage.

Auto product identification

The Auto Product Identification mode allows the reading out of a binary code from an EPROM that will identify its manufacturer and the type. This mode is intended for programming to automatically match the device to be programmed with its corresponding programming algorithm. This mode is functional in the $25^{\circ}\text{C}\pm5^{\circ}\text{C}$ ambient temperature range that is required when programming the HT27C040.

To activate this mode, the programming equipment must force $12.0\pm0.5V$ on the address line A9 of the HT27C040. Two identifier bytes may then be sequenced from the device outputs by toggling address line A0 from V_{IL} to V_{IH} , when A1=V_{IH}. All other address lines must be held at V_{IH} during Auto Product Identification mode.

Byte 0 (A0=V $_{\rm IL}$) represents the manufacturer code, and byte 1 (A0=V $_{\rm IH}$), the device code. For HT27C040, these two identifier bytes are given in the Operation mode truth table. All identifiers for the manufacturer and device codes will possess odd parity, with the MSB (DQ7) defined as the parity bit. When A1=V $_{\rm IL}$, the HT27C040 will read out the binary code of 7F, continuation code, to signify the unavailability of manufacturer ID codes.

Read mode

The HT27C040 has two control functions, both of which must be logically satisfied in order to obtain data at outputs. Chip Enable (\overline{CE}) is the power control and should be used for device selection. Output Enable (\overline{OE}) is the output control and should be used to gate data to the output pins, independent of device selection. Assuming that addresses are stable, address access time (t_{ACC}) is equal to the delay from \overline{CE}



to output $(t_{CE}).$ Data is available at the outputs $(\underline{t_{OE}})$ after the falling edge of $\overline{OE},$ assuming the \overline{CE} has been LOW and addresses have been stable for at least $t_{ACC}\text{-}t_{OE}.$

Standby mode

The HT27C040 has CMOS standby mode which reduces the maximum VCC current to $10\mu A.$ It is placed in CMOS standby when \overline{CE} is at $V_{CC}\pm 0.3V.$ The HT27C040 also has a TTL-standby mode which reduces the maximum VCC current to 1.0mA. It is placed in TTL-standby when \overline{CE} is at $V_{IH}.$ When in standby mode, the outputs are in a high-impedance state, independent of the \overline{OE} input.

Two-line output control function

To accommodate multiple memory connections, a two-line control function is provided to allow for:

- · Low memory power dissipation
- Assurance that output bus contention will not occur

It is recommended that \overline{CE} be decoded and used as the primary device-selection function, while

 $\overline{\text{OE}}$ be made a common connection to the READ line from the system control bus. This assures that all deselected memory devices are in their low-power standby mode and that the output pins are only active when data is desired from a particular memory device.

System considerations

During the switch between active and standby conditions, transient current peaks are produced on the rising and falling edges of Chip Enable. The magnitude of these transient current peaks is dependent on the output capacitance loading of the device. At a minimum, a 0.1µF ceramic capacitor (high frequency, low inherent inductance) should be used on each device between VCC and VPP to minimize transient effects. In addition, to overcome the voltage drop caused by the inductive effects of the printed circuit board traces on EPROM arrays, a 4.7µF bulk electrolytic capacitor should be used between VCC and VPP for each eight devices. The location of the capacitor should be close to where the power supply is connected to the array.

Operation mode truth table

All the operation modes are shown in the table following.

Mode	CE	ŌE	A0	A1	A9	VPP	Output
Read	$ m V_{IL}$	V_{IL}	X	X	X	V_{CC}	Dout
Output Disable	$V_{ m IL}$	V_{IH}	X	X	X	V_{CC}	High Z
Standby (TTL)	V_{IH}	X	X	X	X	V_{CC}	High Z
Standby (CMOS)	$V_{\rm CC} \pm 0.3 V$	X	X	X	X	$V_{\rm CC}$	High Z
Program	V_{IL}	V_{IH}	X	X	X	V_{PP}	$\mathrm{D_{IN}}$
Program Verify	X	V_{IL}	X	X	X	V_{PP}	D_{OUT}
Product Inhibit	V_{IH}	X	X	X	X	V_{PP}	High Z
Manufacturer Code (3)	$V_{ m IL}$	$V_{\rm IL}$	$ m V_{IL}$	V_{IH}	V _H (1)	V_{CC}	1C
Device Type Code (3)	$ m V_{IL}$	V_{IL}	V_{IH}	V_{IH}	V _H (1)	V_{CC}	04

Note: (1) $V_H = 12.0V \pm 0.5V$

- (2) X=Either V_{IH} or V_{IL}
- (3) For Manufacturer Code and Device Code, $A1=V_{IH}$, When $A1=V_{IL}$, both codes will read 7F



Product Identification Code

Code	Pins										Hex
Code	A0	A1	DQ7	DQ6	DQ5	DQ4	DQ3	DQ2	DQ1	DQ0	Data
Manufacturer	0	1	0	0	0	1	1	1	0	0	1C
Device Type	1	1	0	0	0	0	0	0	1	0	04
G 1: 1:	0	0	0	1	1	1	1	1	1	1	7F
Continuation	1	0	0	1	1	1	1	1	1	1	7F

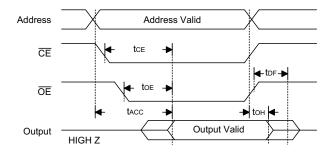


Figure 1. A.C. waveforms for read operation

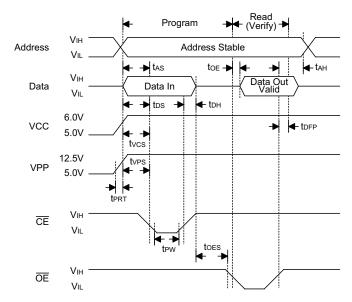
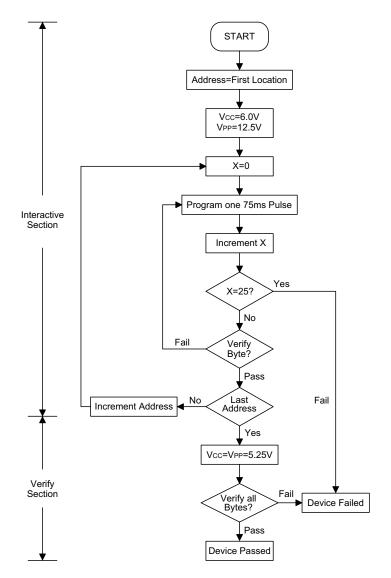


Figure 2. Programming waveforms



Note: Either $105\mu s$ or $30\mu s$ pulse.

Figure 3. Fast programming flowchart



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