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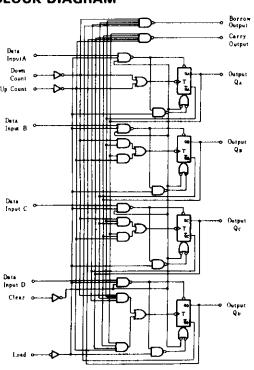
Synchronous operation is provided by having all flip-flops clocked simultaneously so that the outputs change coincidently with each other when so instructed by the steering logic. This mode of operation eliminates the output counting spikes which are normally associated with asynchronous (ripple-clock) counters. The outputs of the four master-slave flip-flops are triggered by a low-to-high-level transition of either count (clock) input. The direction of counting is determined by which count input is pulsed while the other count input is high. This counter is fully programmable; That is, each output may be preset to either level by entering the desired data at the data inputs while the load input is low. The output will change to agree with the data inputs independently of the count pulses. This feature allows the counters to be used as modulo-N dividers by simply modifying the count length with the preset inputs. A clear input has been

provided which forces all outputs to the low level when a high level is applied. The clear function is independent of the count and load inputs. The clear, count, and load inputs are buffered to lower the drive requirements. This reduces the number of clock drivers, etc., required for long words. This counter was designed to be cascaded without the need for external circuitry. Both borrow and carry outputs are available to cascade both the up-and down-counting functions.

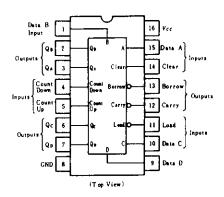
The borrow output produces a pulse equal in width to the count-down input when the counter underflows. Similarly, the carry output produces a pulse equal in width to the count-up input when an overflow condition exists.

The counters can then be easily cascaded by feeding the borrow and carry outputs to the count-down and count-up inputs respectively of the succeeding counter.

#### **■BLOCK DIAGRAM**



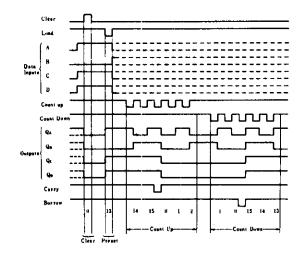
#### **MPIN ARRANGEMENT**



#### **TRECOMMENDED OPERATING CONDITIONS**

l tem	Symbol	min	typ	max	Unit
Clock frequency	felock	0	_	25	MHz
Pulse width	tur	20	_	-	ns
Setup time (Clear)	faulclear)	40	_	_	ns
Setup time	lou	20	_	-	ns
Hold time	ts	3	_	-	ns

#### **COUNT SEQUENCES**



#### Illustrated below is the following sequence:

- 1. Clear outputs to zero.
- 2. Load (preset) to binary thirteen.
- 3. Count up to fourteen, fifteen, carry, zero, one, and two.
- Count down to one, zero, borrow, fifteen, fourteen, and thirteen.

#### **ELECTRICAL CHARACTERISTICS** ( $Ta = -20 \sim +75^{\circ}C$ )

Item	Symbol	Test Conditions	min	typ*	max	Unit	
Innut makes a	Vin			2.0	_	_	v
Input voltage	VIL			_		0.8	v
	Von	$V_{CC} = 4.75 \text{V}, V_{IH} = 2 \text{V}, V_{IL} = 0.8 \text{V}, I$	2.7	_	_	v	
Output voltage	Vol	V 4 7517 W 631 W 637	IoL = 4mA	_	_	0.4	٠,,
		$V_{CC} = 4.75 \text{V}, V_{IH} = 2 \text{V}, V_{IL} = 0.8 \text{V}$	IoL = 8mA	_	_	0.5	v
Input current	Iн	$V_{CC} = 5.25$ V, $V_I = 2.7$ V	_	_	20	μA	
	IIL	$V_{CC} = 5.25 \text{V}, V_I = 0.4 \text{V}$		_	_	-0.4	mА
	- Iı	$V_{CC} = 5.25 \text{V}, V_I = 7 \text{V}$		_		0.1	mА
Short-circuit output current	los	$V_{CC} = 5.25 \text{V}$	-20		- 100	mA	
Supply current**	<b>I</b> cc	$V_{CC} = 5.25 \text{V}$		19	34	mA	
Input clamp voltage	VIK	$V_{CC} = 4.75 \text{V}, I_{IN} = -18 \text{mA}$	_	<del>-</del>	-1.5	V	

<sup>\*</sup> VCC=5V, Ta=25°C

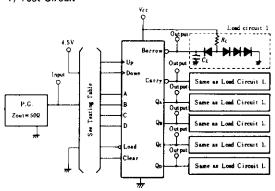
### **ESWITCHING CHARACTERISTICS** ( $V_{CC} = 5V$ , $T_a = 25^{\circ}C$ )

Item	Symbol	Inputs	Outputs	Test Conditions	min	typ	max	Unit
Maximum clock frequency	fmex				25	32	<u> </u>	MHz
Propagation delay time	<b>t</b> PLH	Count-up	C	$C_L = 15 \text{pF}$ $R_L = 2 \text{k}\Omega$	_	17	26	ns
	lpнi,	Count-up	Саггу			18	24	ns
	<b>t</b> PLH	Count-down	Borrow			16	24	ns
	teni,				-	15	24	ns
	tplH	Either Count	Q			27	38	ns
	tPHL	Eliner Count			_	30	47	ns
	tpl.H				_	24	40	ns
	IPHL	Load	Q		-	25	40	ns
	tphi.	Clear	Q		_	23	35	ns

<sup>\*\*</sup> ICC is measured with all outputs open, clear and load inputs grounded, and all other inputs at 4.5V.

#### **ETESTING METHOD**

#### 1) Test Circuit

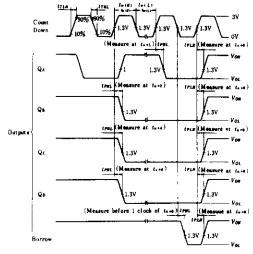


Notes) 1.  $C_L$  includes probe and jig capacitance. 2. All diodes are 1\$2074 P

Input pulse:  $t_{TLH}, t_{THL} \le 7$ ns Duty Cycle  $\le 50\%$ , PRR = 500kHz (Data input)

PRR=1MHz (except data input)

#### Waveform-2 fmax, tPLH, tPHL (Count Down)



Notes) 1. Input pulse:  $t_{TLH} \le 7 \text{ns}$ ,  $t_{THL} \le 7 \text{ns}$ , PRR = 1 MHz, duty cycle 50%

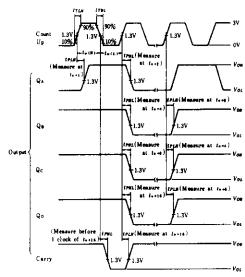
- 2. for  $f_{max}$ ,  $t_{TLH}$ ,  $t_{THL} \le 2.5$ ns
- 3.  $t_n$  is reference bit time when all outputs are high.

#### 2) Testing Table

•	From input	Inputs							Outputs						
Item	to output	CLR	Load	Up	Down	A	В	C	D	Q۸	Qв	Qc	QD	Carry	Воггом
	Up Count	GND	4.5V	IN	4.5V	GND	GND	GND	GND	OUT	OUT	OUT	OUT	OUT	_
fmax	Down Count	GND	4.5V	4.5V	IN	GND	GND	GND	GND	OUT	OUT	OUT	OUT	-	OUT
	Up Count	GND	4.5V	IN	4.5V	GND	GND	GND	GND	OUT	OUT	OUT	OUT	OUT	
<b>t</b> PLH	Down Count	GND	4.5V	4.5V	IN	GND	GND	GND	GND	OUT	OUT	OUT	OUT	-	OUT
	Load→Q	GND	IN	GND	GND	IN	IN	IN	IN	OUT	OUT	OUT	OUT		
tphi,	Clear→Q	IN	IN.	GND	GND	4.5V	4.5V	4.5V	4.5V	OUT	OUT	OUT	OUT		

<sup>•</sup> for initialized

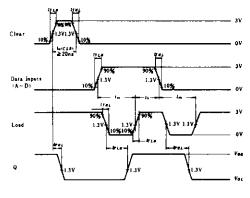
#### fmax, tPLH, tPHL (Count Up) Waveform-1



Notes) 1. for  $f_{max}$ ,  $t_{TLH} = t_{THL} \le 2.5$ ns.

2.  $t_n$  is reference bit time when all outputs are low.

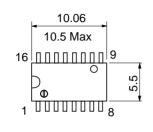
#### Waveform-3 tPLH, tPHL (Load, Clear→Q)

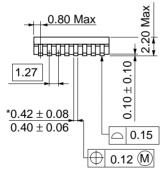


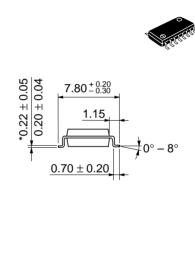
Input pulse:  $t_{TLH} \le 7$ ns,  $t_{THL} \le 7$ ns

Unit: mm 19.20 20.00 Max 16 7.40 Max 6.30 1.3 1.11 Max 7.62 5.06 Max 2.54 Min 0.51 Min  $0.25^{+0.13}_{-0.05}$  $0.48 \pm 0.10$  $2.54\pm0.25$  $0^{\circ} - 15^{\circ}$ Hitachi Code DP-16 **JEDEC** Conforms EIAJ Conforms Weight (reference value) 1.07 g

Unit: mm







\*Dimension including the plating thickness
Base material dimension

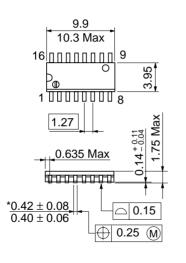
EIAJ Conforms
Weight (reference value) 0.24 g

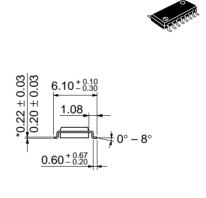
FP-16DA

Hitachi Code

**JEDEC** 

Unit: mm





\*Dimension including the plating thickness
Base material dimension

Hitachi Code	FP-16DN
JEDEC	Conforms
EIAJ	Conforms
Weight (reference value)	0.15 g

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