

Eureka Microelectronics, Inc.



Data Sheet

EK7004

160 Output Segment/
Common LCD Driver



160 Output Segment/Common LCD Driver

Description

The EK7004 is a 160 output segment/common LCD driver adaptable to drive a large scale dot matrix panel. It uses the Tape Carrier Package(TCP) to greatly reduce the size of the LCD module. EK7004 consumes very little power. Large LCD panels can be assembled by cascading EK7004s. In Segment Mode, the input data can be either 4-bit parallel or 8-bit parallel, selected by the Mode Select pin (MD).

Features

- CMOS process
- Logic power supply : 2.5V to 5.5V
- Low power consumption
- 160 LCD display output
- Supply voltage for LCD driver :15 to 40V
- Package : TCP, COG available

Features in Segment mode

- Shift clock frequency : 14MHz max. at $V_{DD}=5V$
- 4bit/8bit parallel input
- Automatic transfer of enable signal
- Automatic counting in the chip select mode. The internal clock stopped by automatically counting 160 of input data.

Features in Common mode

- Shift clock frequency : 4MHz max. at $V_{DD}=5V$
- Built-in 160-bit bidirectional shift register
- Single mode (160-bit shift register) or Dual Mode (two 80-bit shift registers) with these options:
 1. Y1 $\rightarrow$ Y160 Single mode
 2. Y160 $\rightarrow$ Y1 Single mode
 3. Y1 $\rightarrow$ Y80, Y81 $\rightarrow$ Y160 Dual mode
 4. Y160 $\rightarrow$ Y81, Y80 $\rightarrow$ Y1 Dual mode

Block Diagram

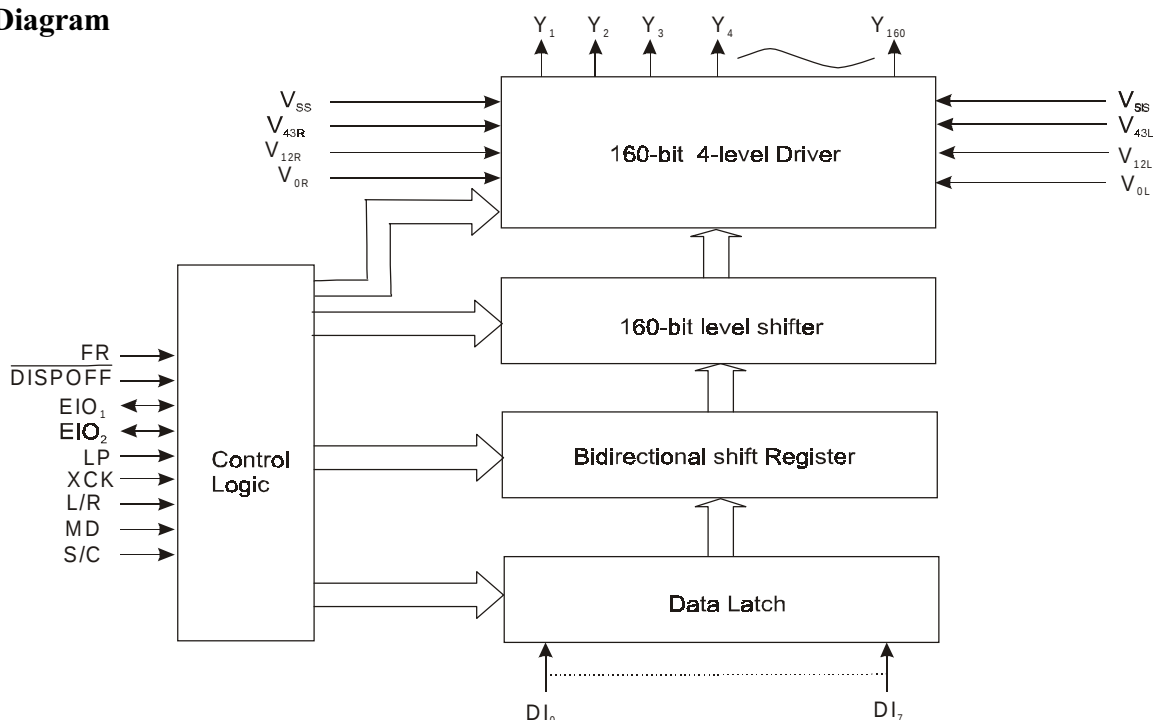


Fig.1
1

Pin Configuration

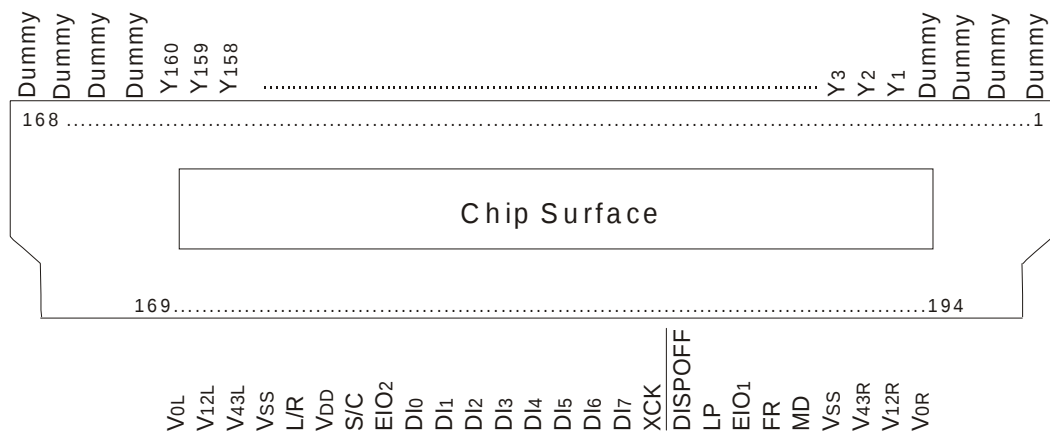


Fig.2

Pin Designations

Pin No.	Symbol	I/O	Designation
5 to 164	Y1-Y160	O	LCD output
169, 194	V0L, V0R	-	Power supply for LCD driver level
170, 193	V12L, V12R	-	Power supply for LCD driver level
171, 192	V43L, V43R	-	Power supply for LCD driver level
173	L/R	I	Display data shift direction selection
174	VDD	-	Power supply for logic circuit(+2.5 to +5.5V)
175	S/C	I	Segment mode/common mode selection
176	EIO ₂	I/O	Input/output for chip select or data of shift register
177 to 183	DI ₀ -DI ₆	I	Input of display data in segment mode
184	DI ₇	I	Input of display data in Segment mode, or Dual mode data input in common mode
185	XCK	I	Display data shift clock input in segment mode
186	$\overline{\text{DISPOFF}}$	I	Control pin input to deselect output level
187	LP	I	Latch pulse input in segment mode Shift clock input for shift register in common mode
188	EIO ₁	I/O	Input/output for chip select or data of shift register
189	FR	I	AC-converting signal input for LCD driver waveform
190	MD	I	Mode selection
172, 191	VSS	-	Ground
1~ 4, 165~168	Dummy	-	Dummy PADS

Tab.1

Input/Output Circuit

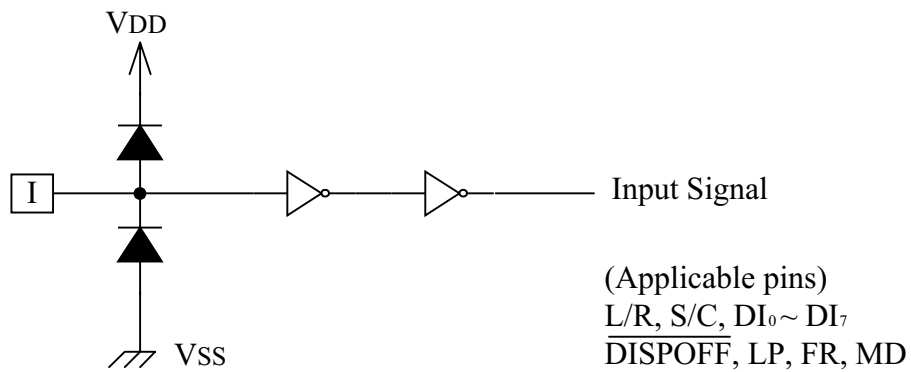


Fig.3 Input Circuit(1)

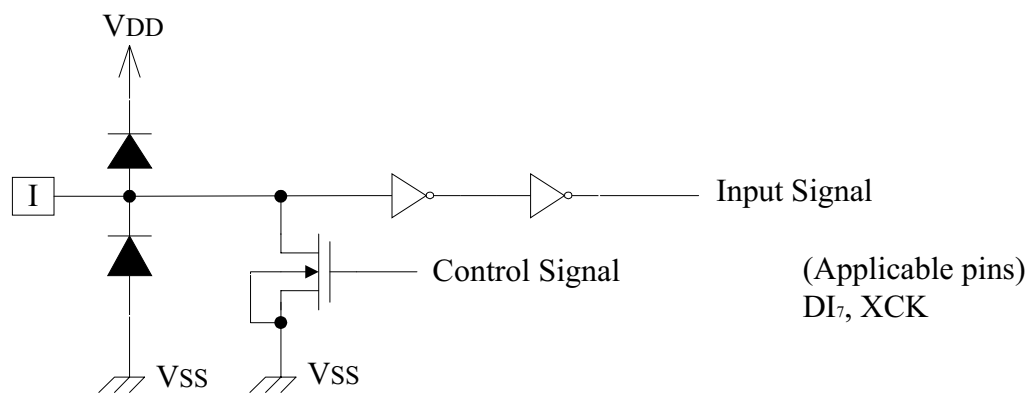


Fig.4 Input Circuit(2)

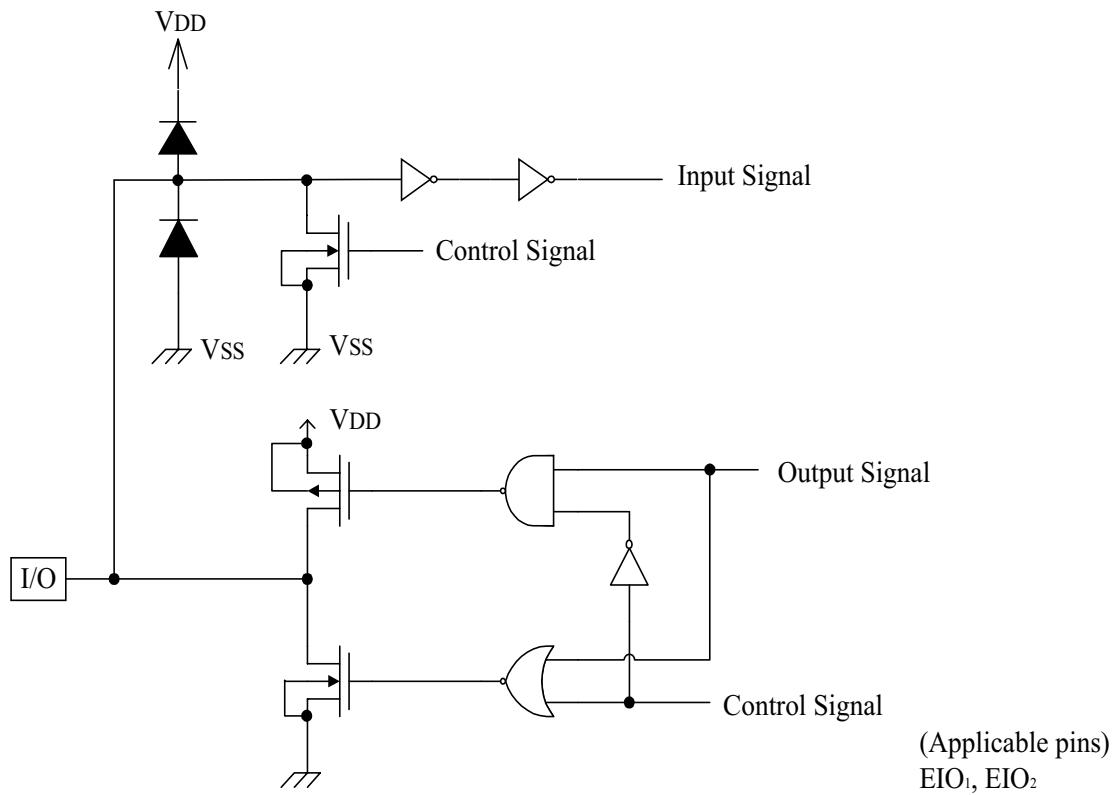


Fig.5 Input/Output Circuit

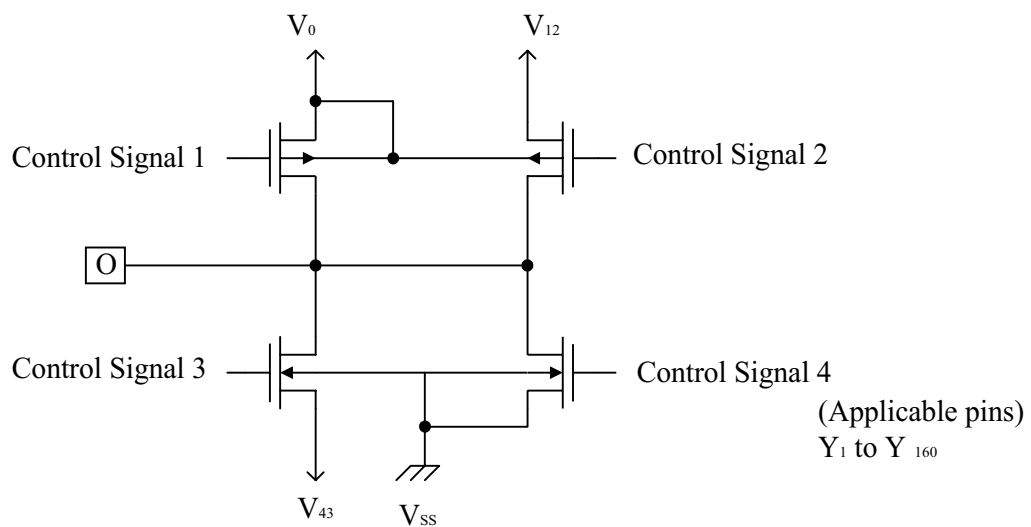


Fig.6 LCD Driver Output Circuit

Pin Functions (Segment mode)

Symbol	Function
V_{DD}	Logic circuit power supply +2.5 to +5.5 V
V_{SS}	Ground pin
V_{0R}, V_{0L} V_{12R}, V_{12L} V_{43R}, V_{43L}	Power supply for LCD driver voltage level ● Normally, the bias voltage used is set by a resistor divider. ● Ensure that voltages are set such that $V_{SS} < V_{43} < V_{12} < V_0$. ● V_{iR} and V_{iL} ($i=0, 12, 43$) should be externally connected to reduce the difference between the waveforms of the output pins $Y_1 \sim Y_{160}$.
$DI_0 \sim DI_7$	Input for display data ● In 4-bit parallel input mode, input data into the 4 pins $DI_0 \sim DI_3$. Connect $DI_4 \sim DI_7$ to V_{SS} or V_{DD}. ● In 8-bit parallel input mode, input data into the 8 pins $DI_0 \sim DI_7$.
XCK	Input clock pin for displaying data ● Data is read on the falling edge of the clock pulse.
LP	Latch pulse input for displaying data ● Data is latched on the falling edge of the clock pulse.
L/R	Direction selection for reading display data ● When set to V_{SS}, data is read sequentially from Y_{160} to Y_1. ● When set to V_{DD}, data is read sequentially from Y_1 to Y_{160}.
$\overline{DISPOFF}$	Control input to deselect output level ● The input signal is level-shifted from logic voltage level to LCD drive voltage level, and controls LCD drive circuit. ● When set to V_{SS} level "L", the LCD driver output pins ($Y_1 \sim Y_{160}$) are set to level V_{SS}. ● While set to "L", the contents of the line latch are cleared, but read the display data in the data latch regardless of condition of $\overline{DISPOFF}$. When the $\overline{DISPOFF}$ function is cancelled, the driver outputs deselect level (V_{12} or V_{43}), then outputs the contents of the data latch on the next falling edge of the LP. At that time, if $\overline{DISPOFF}$ removal time does not meet the conditions shown in Tab.15, it can not output the reading data correctly.
FR	AC signal for LCD driver output level ● The input signal is level-shifted from logic voltage level to LCD drive voltage level, and controls LCD drive circuit. ● Normally, inputs a frame inversion signal. ● The LCD driver output voltage level of output pin can be setted using the line latch output signal and the FR signal. ● Truth table is shown on Tab.6 & Tab.7.

Tab.2

Pin Functions

(Segment mode)

Symbol	Function
MD	Mode selection ● When set to V_{SS} level "L", 4-bit parallel input mode is selected. ● When set to V_{DD} level "H", 8-bit parallel input mode is selected. ● The relationship between the display data and driver output pins is shown on Tab.8 & Tab.9.
S/C	Segment mode/common mode selection pin ● When set to V_{DD} , segment input mode is set.
EIO1 EIO2	Input/Output for chip selection ● When L/R input is at V_{SS} level "L", EIO1 is set for output, and EIO2 is set for input. ● When L/R input is at V_{DD} level "H", EIO1 is set for input, and EIO2 is set for output. ● During output, set to "H" while LP*XCK is "H" and after 160-bit data have been read, set to "L" for one cycle (from falling edge of XCK to next falling edge of XCK), after which it returns to "H". ● During input, after the LP signal is input, the chip is selected while EI is set to "L". After 160-bits of data have been read, the chip is deselected.
Y1-Y160	LCD driver output ● Corresponding directly to each bit of the data latch, one level(V_0 , V_{12} , V_{43} , or V_{SS}) is selected for output. ● Truth table values is shown on Tab.6 & Tab.7.

Tab.3

Pin Functions (Common mode)

Symbol	Function
V_{DD}	Logic circuit power supply pin connects to +2.5 to +5.5 V.
V_{SS}	Ground pin .
V_{0R}, V_{0L} V_{12R}, V_{12L} V_{43R}, V_{43L}	Power supply pin for LCD driver voltage bias ● Normally, the bias voltage used is set by a resistor divider. ● Ensure that voltages are set such that $V_{SS} < V_{43} < V_{12} < V_0$. ● V_{iR} and V_{iL} ($i=0, 12, 43$) should be externally connected to reduce the difference between the waveforms of the output pins $Y_1 \sim Y_{160}$.
EIO_1	Bidirectional shift register input/output. ● Output when L/R is set at V_{SS} level "L", input when L/R is at V_{DD} level "H". ● When EIO_1 is used as input pin, it will be pull-down. ● When EIO_1 is used as output pin, it will not be pull-down.
EIO_2	Bidirectional shift register input/output. ● Input when L/R is set at V_{SS} level "L", output when L/R is at V_{DD} level "H". ● When EIO_2 is used as input, it will be pull-down.. ● When EIO_2 is used as output, it will not be pull-down.
LP	Bidirectional shift register clock pulse input ● Data is shifted on the falling edge of the clock pulse.
L/R	Bidirectional shift register shift direction selection ● When set to V_{SS}, data is shifted from Y_{160} to Y_1. ● When set to V_{DD}, data is shifted from Y_1 to Y_{160}.
$\overline{DISPOFF}$	Control input pin to deselect output level ● The input signal is level-shifted from logic voltage level to LCD drive voltage level, and controls LCD drive circuit. ● When set to "L", the LCD driver output pins ($Y_1 \sim Y_{160}$) are set to level V_{SS}. ● While set to "L", the contents of the shift register are cleared. When the $\overline{DISPOFF}$ function is cancelled, the driver outputs deselect level (V_{12} or V_{43}). and the shift data is read on the falling edge of the LP. At that time, if the $\overline{DISPOFF}$ removal time does not meet the conditions shown in Fig.15, then the shift data is not read correctly.
FR	AC signal input for LCD driver output level ● The input signal is level-shifted from logic voltage level to LCD drive voltage level, and controls LCD drive circuit. ● The LCD driver output voltage level can be set by using the shift register output signal and the FR signal. ● Truth table is shown on Tab6 & Tab7.

Tab.4

Pin Functions (Common mode)

Symbol	Function
MD	Mode selection ● When set to V_{SS} level "L", Single Mode operation is selected, when set to V_{DD} level "H", Dual Mode operation is selected.
DI_7	Dual Mode data input ● According to the data shift direction of the data shift register, data can be input starting from the 81th bit. ● When the chip is used as Dual Mode, DI_7 will be pull-down. ● When the chip is used as Single Mode, DI_7 will not be pull-down.
S/C	Segment mode/common mode selection ● When set to V_{SS} level "L", Common Mode is setted.
$DI_0 \sim DI_6$	Not used ● Connect $DI_0 \sim DI_6$ to V_{SS} or V_{DD} . Avoiding floating.
XCK	Not used ● XCK is pull-down in common mode, so connect them to V_{SS} or open.
$Y_1 \sim Y_{160}$	LCD driver output ● Corresponding directly to each bit of the shift register, one level (V_0 , V_{12} , V_{43} , or V_{SS}) is selected. ● Truth table is shown on Tab.6 & Tab.7.

Tab.5

Functional Operations

Truth Table

(Segment Mode)

FR	Latch Data	$\overline{\text{DISPOFF}}$	Driver Output Voltage Level(Y_1 - Y_{160})
L	L	H	V_{43}
L	H	H	V_{SS}
H	L	H	V_{12}
H	H	H	V_0
X	X	L	V_{SS}

Here, $V_{SS} < V_{43} < V_{12} < V_0$, H: V_{DD} (+2.5 to +5.5V), L: V_{SS} (0 V)

X:Don't care

Tab.6

(Common Mode)

FR	Latch Data	$\overline{\text{DISPOFF}}$	Driver Output Voltage Level(Y_1 - Y_{160})
L	L	H	V_{43}
L	H	H	V_0
H	L	H	V_{12}
H	H	H	V_{SS}
X	X	L	V_{SS}

Here, $V_{SS} < V_{43} < V_{12} < V_0$, H: V_{DD} (+2.5 to +5.5V), L: V_{SS} (0 V)

X:Don't care

Tab.7

Note:There have two kinds of power supply (logic level voltage, LCD drive voltage) for LCD driver.

Supply proper voltage according to each power pin specification.

“Don't care” means that should be connected to “H” or “L”. Do not leave them open.

Relationship between the Display Data and Driver Output pins

(Segment Mode)

(a)4-bit Parallel Mode

MD	L/R	EIO ₁	EIO ₂	Data Input	Figure of Clock						
					40 clock	39 clock	38 clock		3 clock	2 clock	1 clock
L	L	Output	Input	DI ₀	Y ₁	Y ₅	Y ₉		Y ₁₄₉	Y ₁₅₃	Y ₁₅₇
				DI ₁	Y ₂	Y ₆	Y ₁₀		Y ₁₅₀	Y ₁₅₄	Y ₁₅₈
				DI ₂	Y ₃	Y ₇	Y ₁₁		Y ₁₅₁	Y ₁₅₅	Y ₁₅₉
				DI ₃	Y ₄	Y ₈	Y ₁₂		Y ₁₅₂	Y ₁₅₆	Y ₁₆₀
L	H	Input	Output	DI ₀	Y ₁₆₀	Y ₁₅₆	Y ₁₅₂		Y ₁₂	Y ₈	Y ₄
				DI ₁	Y ₁₅₉	Y ₁₅₅	Y ₁₅₁		Y ₁₁	Y ₇	Y ₃
				DI ₂	Y ₁₅₈	Y ₁₅₄	Y ₁₅₀		Y ₁₀	Y ₆	Y ₂
				DI ₃	Y ₁₅₇	Y ₁₅₃	Y ₁₄₉		Y ₉	Y ₅	Y ₁

Tab.8

(b)8-bit Parallel Mode

MD	L/R	EIO1	EIO2	Data Input	Figure of Clock						
					20 clock	19 clock	18 clock		3 clock	2 clock	1 clock
H	L	Output	Input	DI0	Y1	Y9	Y17		Y137	Y145	Y153
				DI1	Y2	Y10	Y18		Y138	Y146	Y154
				DI2	Y3	Y11	Y19		Y139	Y147	Y155
				DI3	Y4	Y12	Y20		Y140	Y148	Y156
				DI4	Y5	Y13	Y21		Y141	Y149	Y157
				DI5	Y6	Y14	Y22		Y142	Y150	Y158
				DI6	Y7	Y15	Y23		Y143	Y151	Y159
				DI7	Y8	Y16	Y24		Y144	Y152	Y160
H	H	Input	Output	DI0	Y160	Y152	Y144		Y24	Y16	Y8
				DI1	Y159	Y151	Y143		Y23	Y15	Y7
				DI2	Y158	Y150	Y142		Y22	Y14	Y6
				DI3	Y157	Y149	Y141		Y21	Y13	Y5
				DI4	Y156	Y148	Y140		Y20	Y12	Y4
				DI5	Y155	Y147	Y139		Y19	Y11	Y3
				DI6	Y154	Y146	Y138		Y18	Y10	Y2
				DI7	Y153	Y145	Y137		Y17	Y9	Y1

Tab.9

(Common Mode)

MD	L/R	Data Transfer Direction	EIO1	EIO2	DI7
L (Single)	L(shift to left)	$Y_{160} \rightarrow Y_1$	Output	Input	X
	H(shift to right)	$Y_1 \rightarrow Y_{160}$	Input	Output	X
H (Dual)	L(shift to left)	$Y_{160} \rightarrow Y_{81}$ $Y_{80} \rightarrow Y_1$	Output	Input	Input
	H(shift to right)	$Y_1 \rightarrow Y_{80}$ $Y_{81} \rightarrow Y_{160}$	Input	Output	Input

Tab.10

L: V_{SS} (0 V), H: V_{DD} (+2.5V to +5.5V), X: Don't Care

Note: "Don't care" means that should be connected to "H" or "L". Do not leave them open.

Connection Examples of Plural Segment Drives

(a) Case of L/R="L"

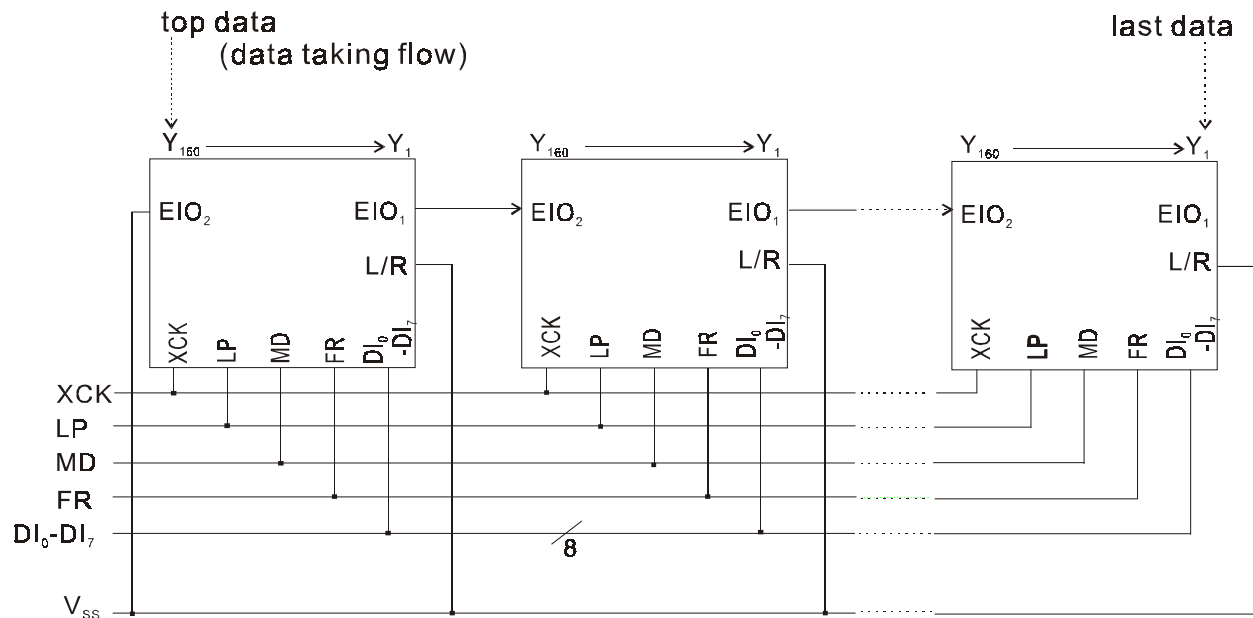


Fig.7

(b) Case of L/R="H"

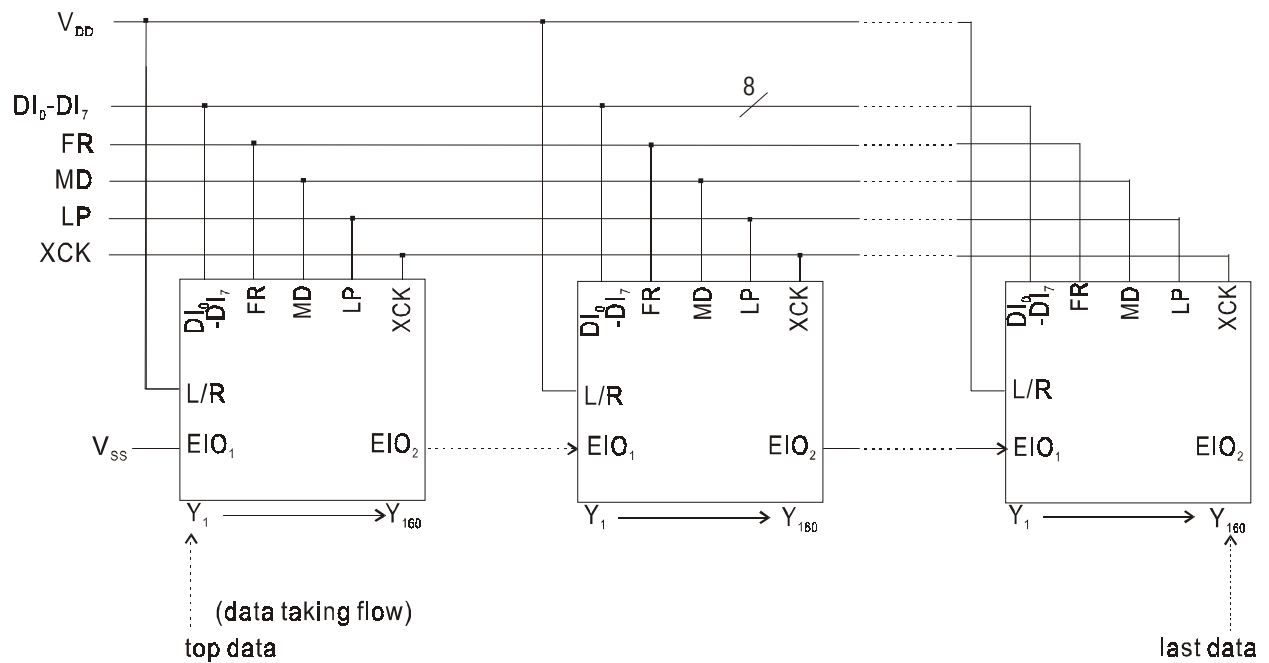


Fig.8

Timing Chart of 4-Device cascade Connection of Segment Drivers

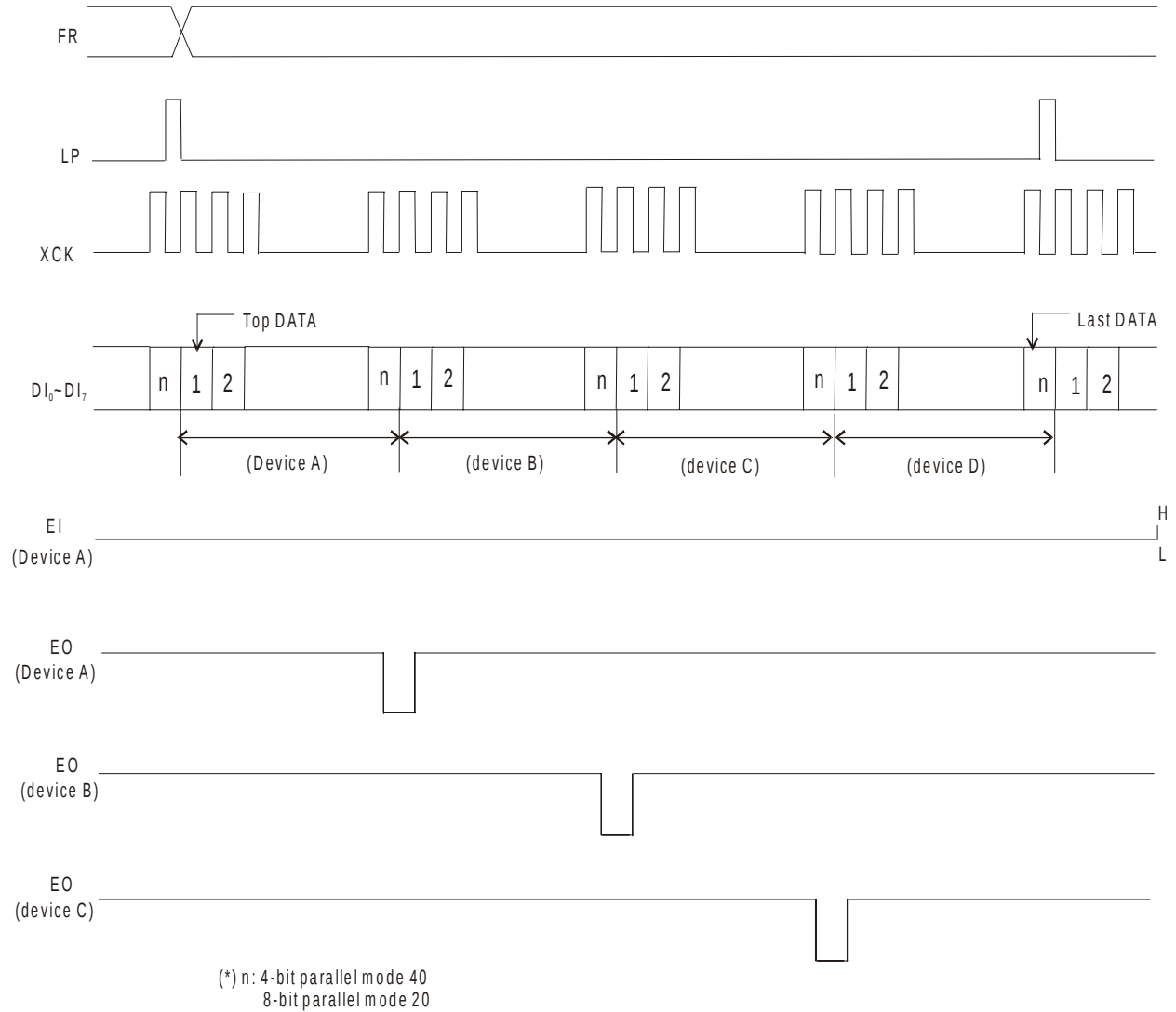


Fig.9

Connection Examples for Plural Common Drivers

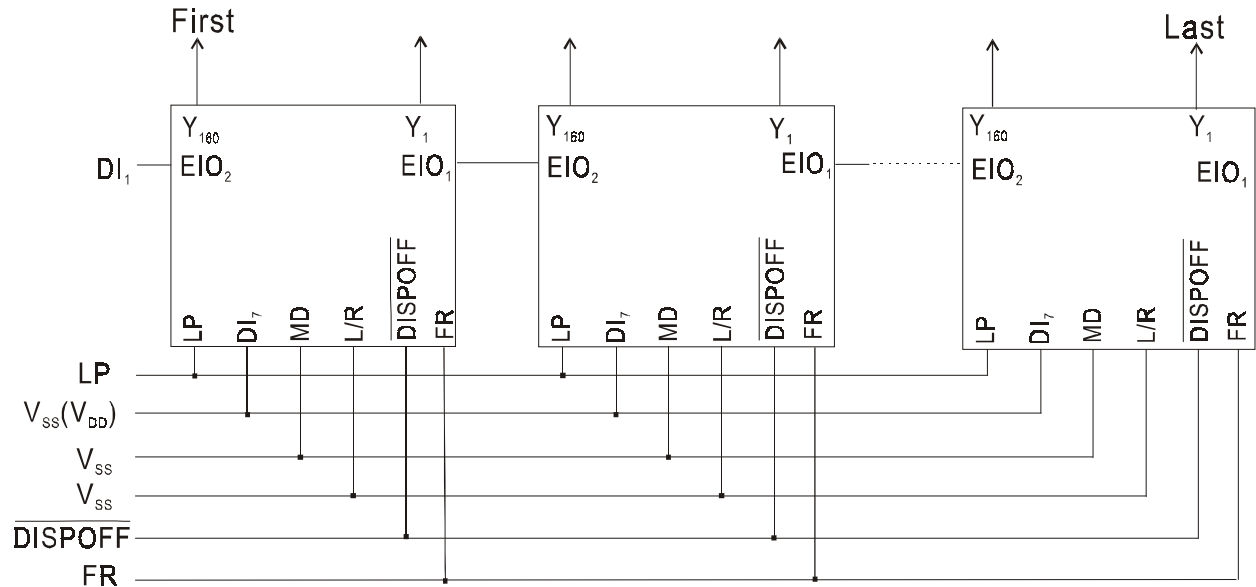


Fig.10 Single Mode (Shifting toward left)

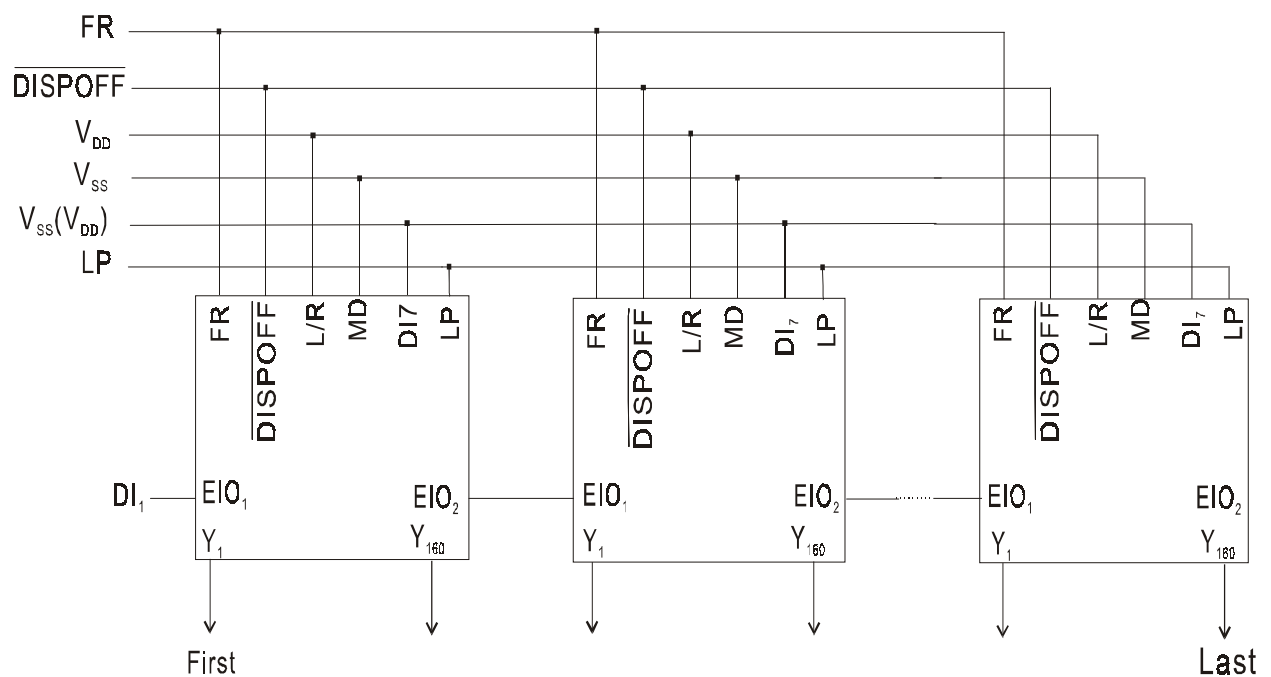


Fig.11 Single Mode (Shifting toward right)

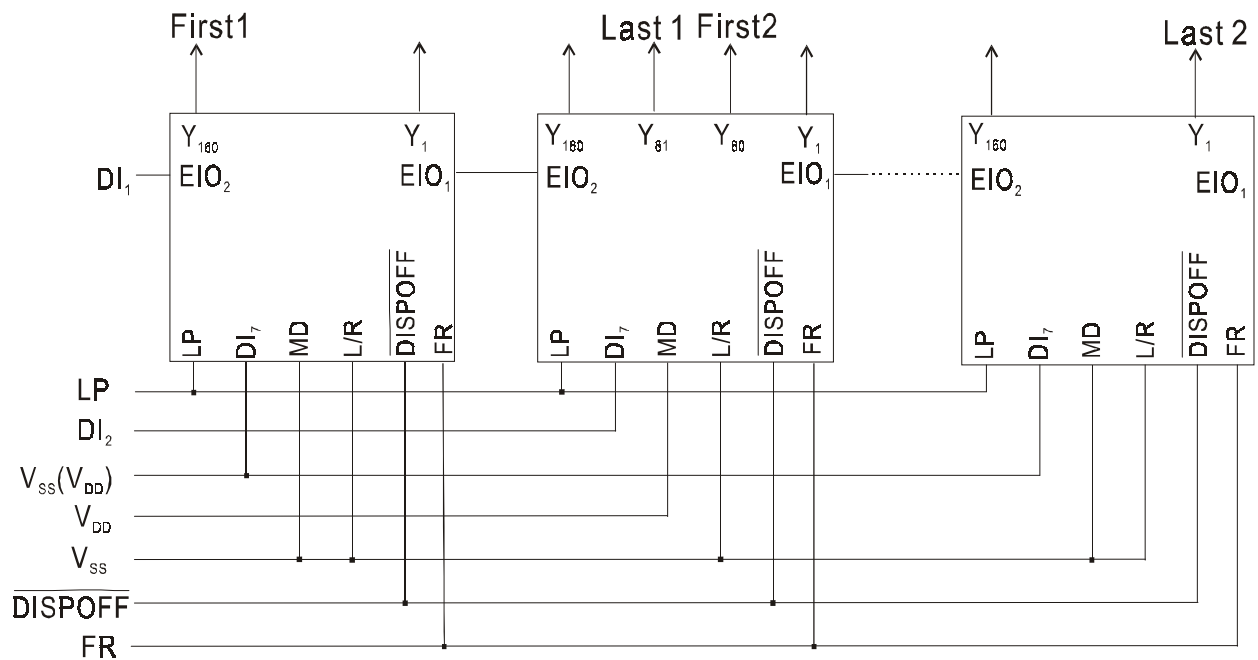


Fig.12 Dual Mode (Shifting toward left)

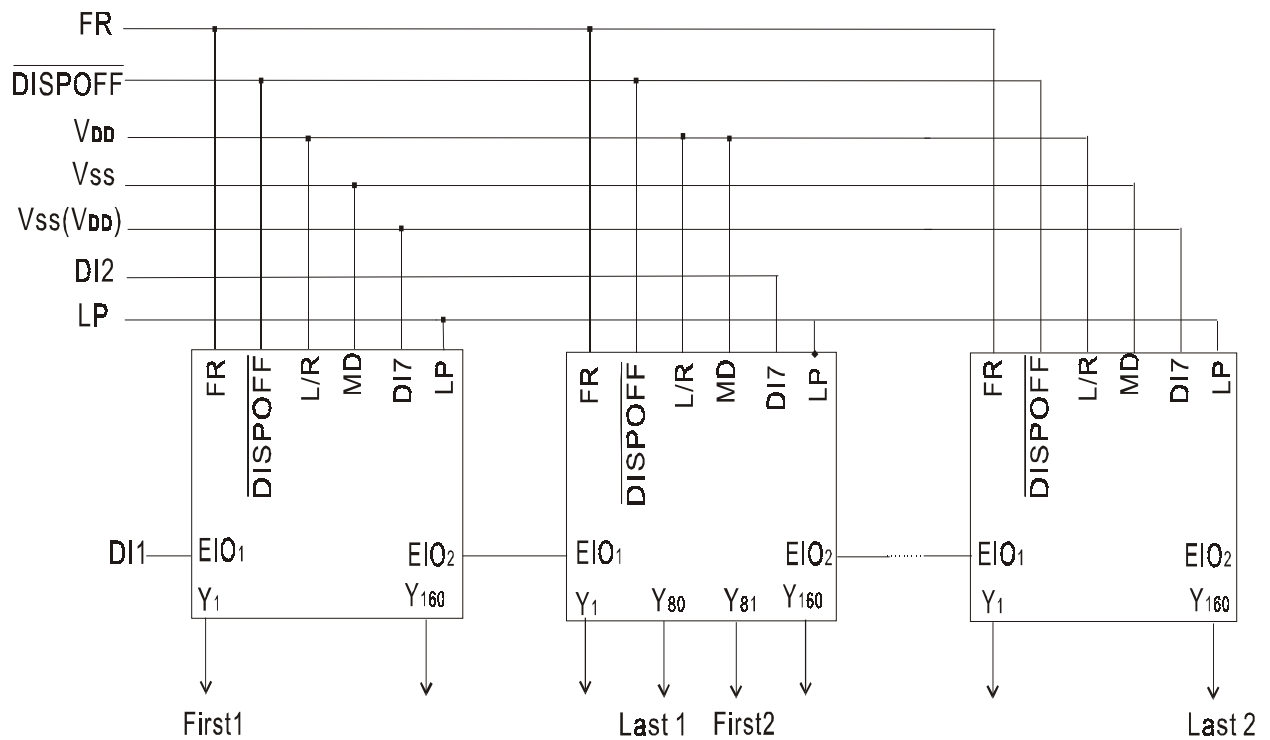


Fig.13 Dual Mode (Shifting toward right)

Absolute Maximum Ratings

Parameter	Symbol	Conditions	Applicable Pins	Ratings	Unit
Supply voltage(1)	V_{DD}	Ta=25°C Referenced to V_{SS} (0 V)	V_{DD}	-0.3 to +7.0	V
Supply voltage(2)	V_0		V_{0L}, V_{0R}	-0.3 to +45.0	V
	V_{12}		V_{12L}, V_{12R}	-0.3 to $V_0+0.3$	V
	V_{43}		V_{43L}, V_{43R}	-0.3 to $V_0+0.3$	V
Input voltage	V_I		DI ₀₋₇ , XCK, LP, L/R, FR, MD, S/C, EIO ₁ , EIO ₂ , $\overline{\text{DISPOFF}}$	-0.3 to $V_{DD}+0.3$	V
Storage temperature	Tstg			-45 to +125	°C

Tab.11

Recommended Operating Conditions

Parameter	Symbol	Conditions	Applicable pins	Min.	Typ.	Max.	Unit
Supply voltage(1)	V_{DD}	Referenced to V_{SS} (0 V)	V_{DD}	+2.5		+5.5	V
Supply voltage(2)	V_0		V_{0L}, V_{0R}	+15.0		+40	V
Storage temperature	T_{opr}			-20		+85	°C

Tab.12

Note: Ensure that voltages are set such that $V_{SS} < V_{43} < V_{12} < V_0$

Electrical Characteristics

DC Characteristics

(Segment Mode)

($V_{SS}=0$ V, $V_{DD}=+2.5$ V to $+5.5$ V, $V_0=+15.0$ to $+40$ V, $T_a=-20$ to $+85$ °C)

Parameter	Symbol	Conditions		Applicable pins	Min.	Typ.	Max.	Unit
Input voltage	V _{IH}			DI _{0~7} , XCK, LP, L/R, FR, MD, S/C, EIO ₁ , EIO ₂ , <u>DISPOFF</u>	0.8V _{DD}			V
	V _{IL}						0.2V _{DD}	V
Output voltage	V _{OH}	I _{OH} =-0.4mA		EIO ₁ ,EIO ₂	V _{DD} -0.4			V
	V _{OL}	I _{OL} =+0.4mA					+0.4	V
Input leakage current	I _{LIH}	V _I =V _{DD}		DI _{0~7} , XCK, LP, L/R, FR, MD, S/C, EIO ₁ , EIO ₂ , <u>DISPOFF</u>			+10.0	μA
	I _{LIL}	V _I =V _{SS}					-10.0	μA
Output resistance	R _{ON}	ΔV _{ON} =0.5V	V ₀ =+40.0V	Y ₁ -Y ₁₆₀		0.7	1.0	KΩ
			V ₀ =+30.0V			1.0	1.5	
			V ₀ =+20.0V			1.5	2.0	
Stand-by current	I _{STB}	*1		V _{SS}			50.0	μA
Consumed current(1) (Deselection)	I _{DD1}	*2		V _{DD}			2.0	mA
Consumed current(2) (Selection)	I _{DD2}	*3		V _{DD}			8.0	mA
Consoumed current	I ₀	*4		V ₀			1.0	mA

Tab.13

Note:

*1 $V_{DD}=+5.0$ V, $V_0=+40$ V, $V_I=V_{SS}$

*2 $V_{DD}=+5.0$ V, $V_0=+40$ V, $f_{XCK}=14$ MHz, No-load, $EI=V_{DD}$

The input data is turned over by data taking clock (4-bit parallel input mode)

*3 $V_{DD}=+5.0$ V, $V_0=+40$ V, $f_{XCK}=14$ MHz, No-load, $EI=V_{SS}$

The input data is turned over by data taking clock (4-bit parallel input mode)

*4 $V_{DD}=+5.0$ V, $V_0=+40$ V, $f_{XCK}=14$ MHz, $f_{LP}=41.6$ KHz, $f_{FR}=80$ Hz, No-load

The input data is turned over by data taking clock (4-bit parallel input mode)

(Common Mode)

($V_{SS}=0\text{ V}$, $V_{DD}=+2.5\text{V to }+5.5\text{V}$, $V_0=+15.0\text{ to }+40\text{ V}$, $T_a=-20\text{ to }+85\text{ }^\circ\text{C}$)

Parameter	Symbol	Conditions	Applicable pins	Min.	Typ.	Max.	Unit
Input voltage	V_{IH}		DI_{0-7} , XCK, LP, L/R, FR, MD, S/C, EIO_1 , EIO_2 , DISPOFF	$0.8V_{DD}$			V
	V_{IL}					$0.2V_{DD}$	V
Output voltage	V_{OH}	$I_{OH}=-0.4\text{mA}$	EIO_1 , EIO_2	$V_{DD}-0.4$			V
	V_{OL}	$I_{OL}=+0.4\text{mA}$				+0.4	V
Input leakage current	I_{LIH}	$V_i=V_{DD}$	DI_{0-6} , LP, L/R, FR, MD, S/C, DISPOFF			+10.0	μA
	I_{LIL}	$V_i=V_{SS}$	DI_{0-7} , XCK, LP, L/R, FR, MD, S/C, EIO_1 , EIO_2 , DISPOFF			-10.0	μA
Input pull-down current	I_{PD}	$V_i=V_{DD}$	XCK, EIO_1 , EIO_2 , DI_7			100.0	μA
Output resistance	R_{ON}	$ \Delta V_{ON} =0.5\text{V}$	$V_0=+40.0\text{V}$ $V_0=+30.0\text{V}$ $V_0=+20.0\text{V}$	$Y_1 \sim Y_{160}$		0.7	1.0
						1.0	1.5
						1.5	2.0
Stand-by current	I_{STB}	*1	V_{SS}			50.0	μA
Consumed current(1)	I_{DD}	*2	V_{DD}			80.0	μA
Consumed current(2)	I_O	*2	V_0			160.0	μA

Tab.14

*1 $V_{DD}=+5.0\text{V}$, $V_0=+40\text{V}$, $V_i=V_{SS}$

*2 $V_{DD}=+5.0\text{V}$, $V_0=+40\text{V}$, $f_{LP}=41.6\text{KHz}$, $f_{FR}=80\text{Hz}$, case of 1/480 duty operation, No-load

AC Characteristics

(Segment Mode 1)

(V_{SS}=0 V, V_{DD}=+4.5V to +5.5V, V₀=+15.0 to +40 V, Ta=-20 to +85 °C)

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit
Shift clock period *1	t _{WCK}	t _r , t _f ≤ 10 ns	71			ns
Shift clock "H" pulse width	t _{WCKH}		23			ns
Shift clock "L" pulse width	t _{WCKL}		23			ns
Data setup time	t _{DS}		10			ns
Data Hold time	t _{DH}		20			ns
Latch pulse"H"pulse width	t _{WLPH}		23			ns
Shift clock rise to Latch pulse rise time	t _{LD}		0			ns
Shift clock fall to Latch pulse fall time	t _{SL}		25			ns
Latch pulse rise to Shift clock rise time	t _{LS}		25			ns
Latch pulse fall to Shift clock fall time	t _{LH}		25			ns
Input signal rise time*2	t _r				50	ns
Input signal fall time*2	t _f				50	ns
Enable setup time	t _s		21			ns
$\overline{\text{DISPOFF}}$ removal time	t _{SD}		100			ns
$\overline{\text{DISPOFF}}$ " L " pulse width	t _{WDL}		1.2			μs
Output delay time(1)	t _D	C _L =15pF			40	ns
Output delay time(2)	t _{pd1} , t _{pd2}	C _L =15pF			1.2	μs
Output delay time(3)	t _{pd3}	C _L =15pF			1.2	μs

Tab.15

Note:

*1 Take the cascade connection into consideration

*2 (t_{CK}-t_{WCKH}-t_{WCKL}) /2 is maximum in the case of high speed operation

(Segment Mode 2)

(V_{SS}=0 V, V_{DD}=+2.5V to +4.5V, V₀=+15.0 to +40 V, Ta=-20 to +85 °C)

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit
Shift clock period *1	t _{WCK}	t _r , t _f ≤ 11 ns	125			ns
Shift clock "H" pulse width	t _{WCKH}		51			ns
Shift clock "L" pulse width	t _{WCKL}		51			ns
Data setup time	t _{DS}		30			ns
Data Hold time	t _{DH}		40			ns
Latch pulse"H"pulse width	t _{WLPH}		51			ns
Shift clock rise to Latch pulse rise time	t _{LD}		0			ns
Shift clock fall to Latch pulse fall time	t _{SL}		51			ns
Latch pulse rise to Shift clock rise time	t _{LS}		51			ns
Latch pulse fall to Shift clock fall time	t _{LH}		51			ns
Input signal rise time*2	t _r				50	ns
Input signal fall time*2	t _f				50	ns
Enable setup time	t _s		36			ns
$\overline{\text{DISPOFF}}$ removal time	t _{SD}		100			ns
$\overline{\text{DISPOFF}}$ " L" pulse width	t _{WDL}		1.2			μs
Output delay time(1)	t _D	C _L =15pF			78	ns
Output delay time(2)	t _{pd1} , t _{pd2}	C _L =15pF			1.2	μs
Output delay time(3)	t _{pd3}	C _L =15pF			1.2	μs

Tab.16

Note:

*1 Take the cascade connection into consideration

*2 (t_{CK}-t_{WCKH}-t_{WCKL}) /2 is maximum in the case of high speed operation

(Timing Characteristics of Segment Mode)

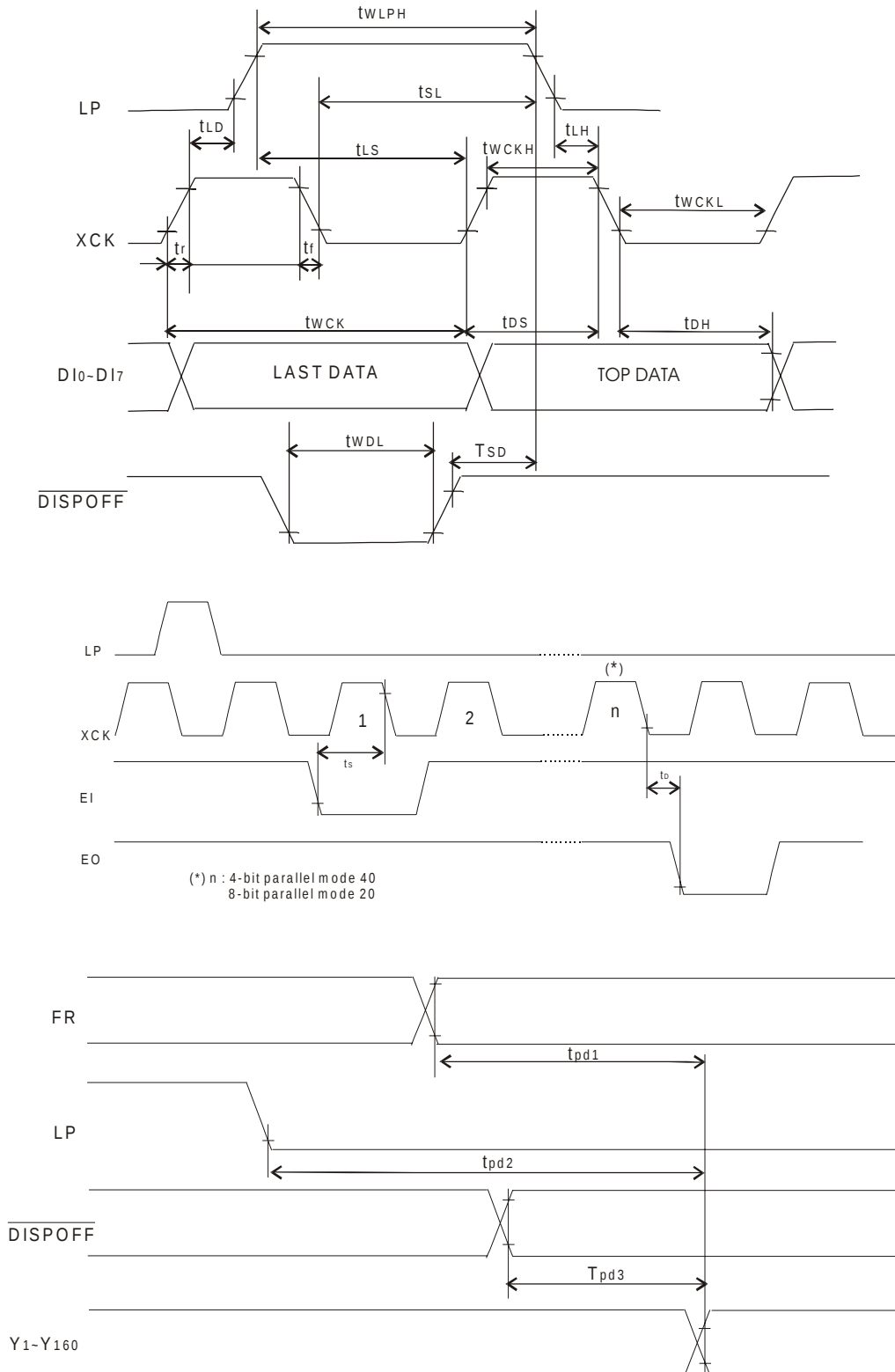


Fig.14

(Common Mode)

(V_{SS}=0 V, V_{DD}=+2.5V to +5.5V, V₀=+15.0 to +40 V, Ta=-20 to +85 °C)

Parameter	Symbol	Condition	Min.	Typ.	Max.	Unit
Shift clock period	t _{WLP}	t _r , t _f 20 ns	250			ns
Shift clock "H" pulse width	t _{WLPH}	V _{DD} =+5.0 V±10%	15			ns
		V _{DD} =+2.5V~ +4.5V	30			ns
Data setup time	t _{SU}		30			ns
Data Hold time	t _H		50			ns
Input signal rise time	t _r				50	ns
Input signal fall time	t _f				50	ns
$\overline{\text{DISPOFF}}$ removal time	t _{SD}		100			ns
$\overline{\text{DISPOFF}}$ " L" pulse width	t _{WDL}		1.2			μs
Output delay time(1)	t _{DL}	C _L =15pF			200	ns
Output delay time(2)	t _{pd1} , t _{pd2}	C _L =15pF			1.2	μs
Output delay time(3)	t _{pd3}	C _L =15pF			1.2	μs

Tab.17

(Timing Characteristics of Common Mode)

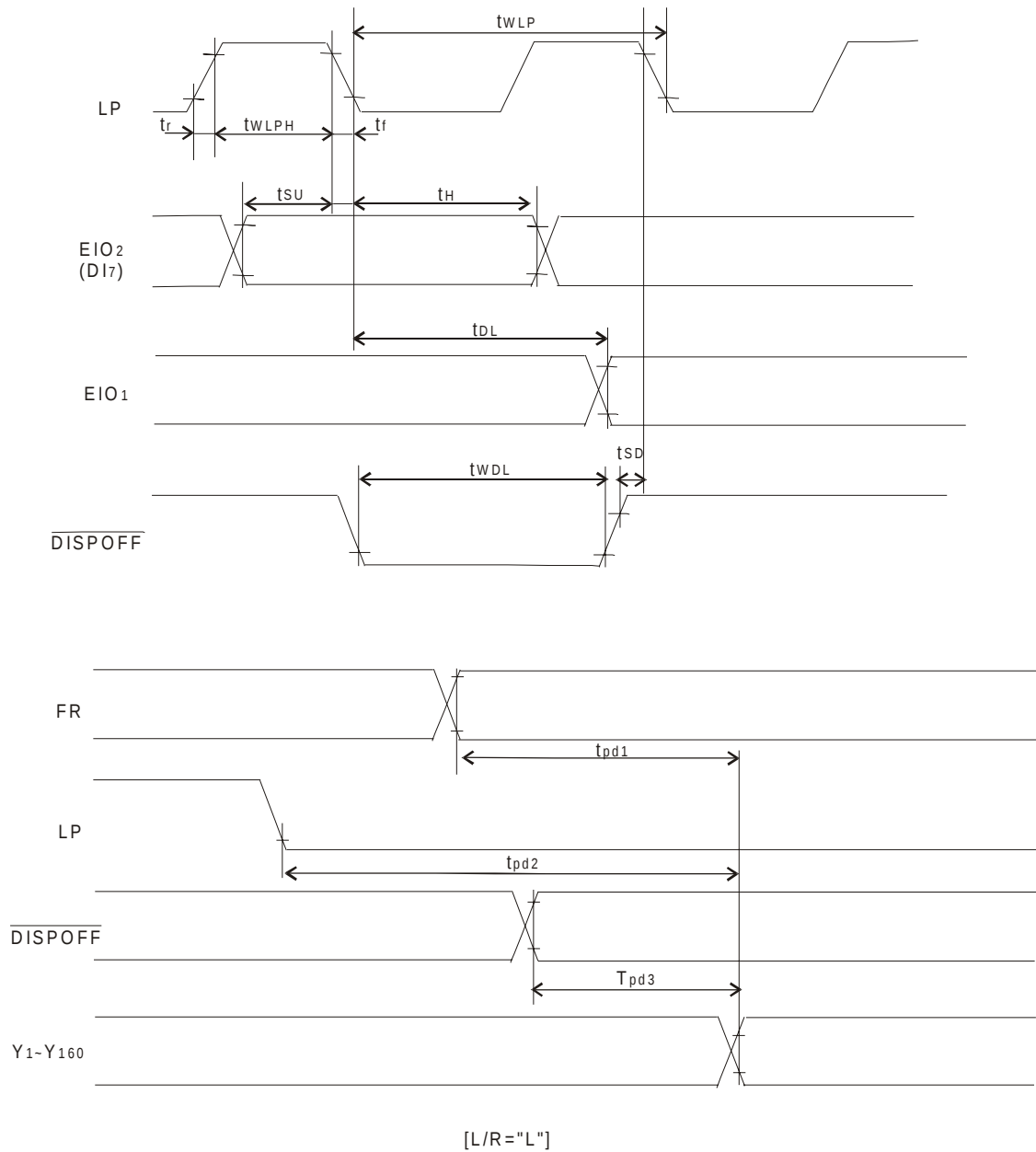


Fig.15

Example of system Configuration

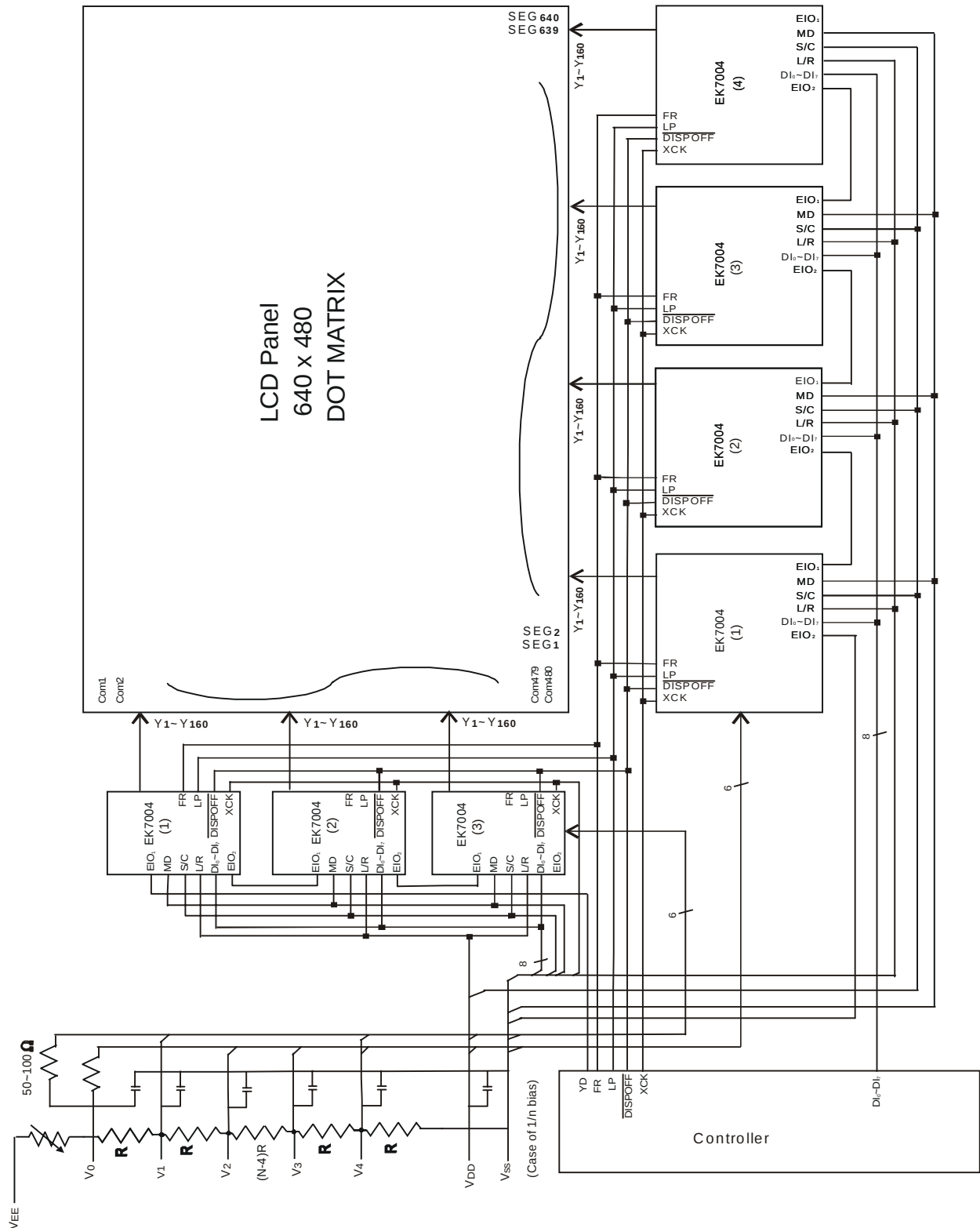


Fig.16

Example of Typical Characteristic

Parameter	Condition	Min.	Typ.	Max.	Unit
Typical Fundamental Rating Propagation Delay Time	Ta=+25°C, Vss=0V, V _{DD} =+5.0V		10		ns

Tab.18

Precaution

- Precaution when connecting or disconnecting the power

This LSI has a high-voltage LCD driver, so it may be permanently damaged by a high current which may flow if a voltage is supplied to the LCD driver power supply while the logic system power supply is floating.

The detail is as follows.

- When connecting the power supply, connect the LCD drive power after connecting the logic system power. Furthermore, when disconnecting the power, disconnect the logic system power after disconnecting the LCD drive power.
- We recommend you connecting the serial resistor(50~100Ω) or fuse to the LCD drive power V_0 of the system as a current limiter. And set up the suitable value of the resistor in consideration of LCD display grade.

And when connecting the logic power supply, the logic condition of this LSI inside is insecurity. Therefore connect the LCD drive power supply after resetting logic condition of this LSI inside on $\overline{\text{DISPOFF}}$ function. After that, cancel the $\overline{\text{DISPOFF}}$ function after the LCD drive power supply has become stable. Furthermore, when disconnecting the power, set the LCD drive output pins to level V_{SS} on $\overline{\text{DISPOFF}}$ function. After that, disconnect the logic system power after disconnecting the LCD drive power. When connecting the power supply, show the following recommend sequence.

