CAT5113

100-Tap Digitally Programmable Potentiometer (DPP™)

FEATURES

- 100-position linear taper potentiometer
- Non-volatile EEPROM wiper storage
- 10nA ultra-low standby current
- Single supply operation: 2.5V-6.0V
- Increment Up/Down serial interface
- Resistance values: 10kΩ , 50kΩ and 100kΩ
- Available in PDIP, SOIC, TSSOP and MSOP packages

APPLICATIONS

- Automated product calibration
- Remote control adjustments
- Offset, gain and zero control
- Tamper-proof calibrations
- Contrast, brightness and volume controls
- Motor controls and feedback systems
- Programmable analog functions

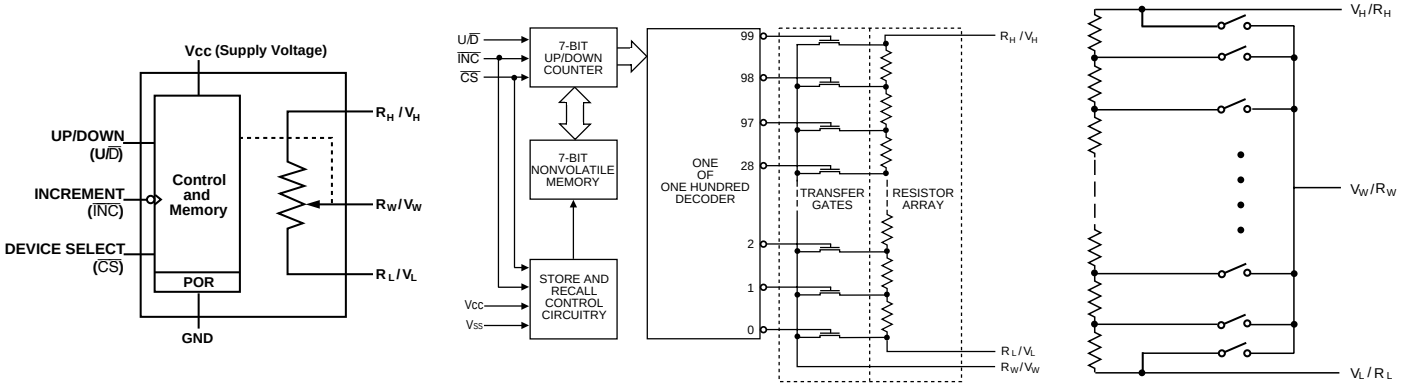
DESCRIPTION

The CAT5113 is a single digitally programmable potentiometer (DPP™) designed as a electronic replacement for mechanical potentiometers and trim pots. Ideal for automated adjustments on high volume production lines, they are also well suited for applications where equipment requiring periodic adjustment is either difficult to access or located in a hazardous or remote environment.

The CAT5113 contains a 100-tap series resistor array connected between two terminals R_H and R_L. An up/down counter and decoder that are controlled by three input pins, determines which tap is connected to the wiper, R_W. The wiper setting, stored in nonvolatile memory, is not lost when the device is powered down and is automatically reinstated when power is returned. The wiper can be adjusted to test new system values without effecting the stored setting. Wiper-control of the CAT5113 is accomplished with three input control pins, $\overline{CS}$, U/$\overline{D}$, and $\overline{INC}$. The $\overline{INC}$ input increments the wiper in the direction which is determined by the logic state of the U/$\overline{D}$ input. The $\overline{CS}$ input is used to select the device and also store the wiper position prior to power down.

The digitally programmable potentiometer can be used as a three-terminal resistive divider or as a two-terminal variable resistor. DPPs bring variability and programmability to a wide variety of applications including control, parameter adjustments, and signal processing.

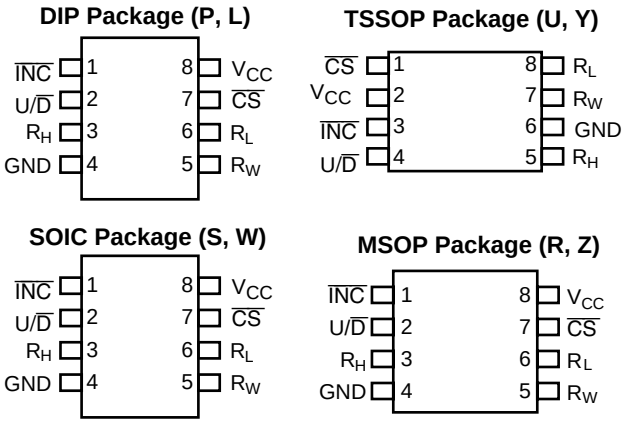
FUNCTIONAL DIAGRAM



GENERAL DETAILED ELECTRONIC POTENTIOMETER IMPLEMENTATION

Doc. No. 2009, Rev. N

PIN CONFIGURATION



PIN FUNCTIONS

Pin Name	Function
$\overline{INC}$	Increment Control
U/$\overline{D}$	Up/Down Control
R_H	Potentiometer High Terminal
GND	Ground
R_W	Potentiometer Wiper Terminal
R_L	Potentiometer Low Terminal
$\overline{CS}$	Chip Select
V_{CC}	Supply Voltage

PIN DESCRIPTIONS

$\overline{INC}$: Increment Control Input

The $\overline{INC}$ input moves the wiper in the up or down direction determined by the condition of the U/$\overline{D}$ input.

U/$\overline{D}$: Up/Down Control Input

The U/$\overline{D}$ input controls the direction of the wiper movement. When in a high state and $\overline{CS}$ is low, any high-to-low transition on $\overline{INC}$ will cause the wiper to move one increment toward the R_H terminal. When in a low state and $\overline{CS}$ is low, any high-to-low transition on $\overline{INC}$ will cause the wiper to move one increment towards the R_L terminal.

R_H: High End Potentiometer Terminal

R_H is the high end terminal of the potentiometer. It is not required that this terminal be connected to a potential greater than the R_L terminal. Voltage applied to the R_H terminal cannot exceed the supply voltage, V_{CC} or go below ground, GND.

R_W: Wiper Potentiometer Terminal

R_W is the wiper terminal of the potentiometer. Its position on the resistor array is controlled by the control inputs, $\overline{INC}$, U/$\overline{D}$ and $\overline{CS}$. Voltage applied to the R_W terminal cannot exceed the supply voltage, V_{CC} or go below ground, GND.

R_L: Low End Potentiometer Terminal

R_L is the low end terminal of the potentiometer. It is not required that this terminal be connected to a potential less than the R_H terminal. Voltage applied to the R_L terminal cannot exceed the supply voltage, V_{CC} or go below ground, GND. R_L and R_H are electrically interchangeable.

$\overline{CS}$: Chip Select

The chip select input is used to activate the control input of the CAT5113 and is active low. When in a high state, activity on the $\overline{INC}$ and U/$\overline{D}$ inputs will not affect or change the position of the wiper.

DEVICE OPERATION

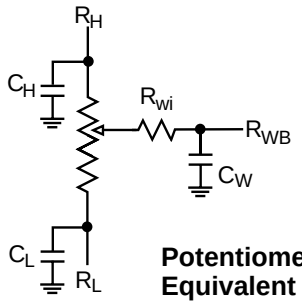
The CAT5113 operates like a digitally controlled potentiometer with R_H and R_L equivalent to the high and low terminals and R_W equivalent to the mechanical potentiometer's wiper. There are 100 available tap positions including the resistor end points, R_H and R_L. There are 99 resistor elements connected in series between the R_H and R_L terminals. The wiper terminal is connected to one of the 100 taps and controlled by three inputs, $\overline{INC}$, U/$\overline{D}$ and $\overline{CS}$. These inputs control a seven-bit up/down counter whose output is decoded to select the wiper position. The selected wiper position can be stored in nonvolatile memory using the $\overline{INC}$ and $\overline{CS}$ inputs.

With $\overline{CS}$ set LOW the CAT5113 is selected and will respond to the U/$\overline{D}$ and $\overline{INC}$ inputs. HIGH to LOW transitions on $\overline{INC}$ wil increment or decrement the wiper (depending on the state of the U/$\overline{D}$ input and seven-bit counter). The wiper, when at either fixed terminal, acts like its mechanical equivalent and does not move beyond the last position. The value of the counter is stored in nonvolatile memory whenever $\overline{CS}$ transitions HIGH while the $\overline{INC}$ input is also HIGH. When the CAT5113 is powered-down, the last stored wiper counter position is maintained in the nonvolatile memory. When power is restored, the contents of the memory are recalled and the counter is set to the value stored.

With $\overline{INC}$ set low, the CAT5113 may be de-selected and powered down without storing the current wiper position in nonvolatile memory. This allows the system to always power up to a preset value stored in nonvolatile memory.

OPERATION MODES

$\overline{INC}$	$\overline{CS}$	U/$\overline{D}$	Operation
High to Low	Low	High	Wiper toward H
High to Low	Low	Low	Wiper toward L
High	Low to High	X	Store Wiper Position
Low	Low to High	X	No Store, Return to Standby
X	High	X	Standby



Potentiometer Equivalent Circuit

ABSOLUTE MAXIMUM RATINGS

Supply Voltage
- V_{CC} to GND ..... –0.5V to +7V

Inputs
- $\overline{CS}$ to GND ..... –0.5V to V_{CC} +0.5V
- $\overline{INC}$ to GND ..... –0.5V to V_{CC} +0.5V
- U/$\overline{D}$ to GND ..... –0.5V to V_{CC} +0.5V
- H to GND ..... –0.5V to V_{CC} +0.5V
- L to GND ..... –0.5V to V_{CC} +0.5V
- W to GND ..... –0.5V to V_{CC} +0.5V

Operating Ambient Temperature
- Commercial ('C' or Blank suffix) ..... 0°C to +70°C
- Industrial ('I' suffix) ..... – 40°C to +85°C

Junction Temperature ..... +150°C
Storage Temperature ..... –65°C to +150°C
Lead Soldering (10 sec max) ..... +300°C

* Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. Absolute Maximum Ratings are limited values applied individually while other parameters are within specified operating conditions, and functional operation at any of these conditions is NOT implied. Device performance and reliability may be impaired by exposure to absolute rating conditions for extended periods of time.

RELIABILITY CHARACTERISTICS

Symbol	Parameter	Test Method	Min	Typ	Max	Units
V_{ZAP}(1)	ESD Susceptibility	MIL-STD-883, Test Method 3015	2000			Volts
I_{LTH}(1)(2)	Latch-Up	JEDEC Standard 17	100			mA
T_{DR}	Data Retention	MIL-STD-883, Test Method 1008	100			Years
N_{END}	Endurance	MIL-STD-883, Test Method 1003	1,000,000			Stores

DC Electrical Characteristics: V_{CC} = +2.5V to +6.0V unless otherwise specified

Power Supply

Symbol	Parameter	Conditions	Min	Typ	Max	Units
V_{CC}	Operating Voltage Range		2.5		6.0	V
I_{CC1}	Supply Current (Increment)	V_{CC} = 6V, f = 1MHz, I_W=0 V_{CC} = 6V, f = 250kHz, I_W=0			100 50	µA
I_{CC2}	Supply Current (Write)	Programming, V_{CC} = 6V V_{CC} = 3V			1 500	mA µA
ISB_1 (2)	Supply Current (Standby)	CS=V_{CC}-0.3V U/D, INC=V_{CC}-0.3V or GND		0.01	1	µA

Logic Inputs

Symbol	Parameter	Conditions	Min	Typ	Max	Units
I_{IH}	Input Leakage Current	V_{IN} = V_{CC}			10	µA
I_{IL}	Input Leakage Current	V_{IN} = 0V			–10	µA
V_{IH1}	TTL High Level Input Voltage	4.5V ≤ V_{CC} ≤ 5.5V	2		V_{CC}	V
V_{IL1}	TTL Low Level Input Voltage		0		0.8	V
V_{IH2}	CMOS High Level Input Voltage	2.5V ≤ V_{CC} ≤ 6V	V_{CC} x 0.7		V_{CC} + 0.3	V
V_{IL2}	CMOS Low Level Input Voltage		-0.3		V_{CC} x 0.2	V

NOTES: (1) This parameter is tested initially and after a design or process change that affects the parameter.
(2) Latch-up protection is provided for stresses up to 100mA on address and data pins from –1V to V_{CC} + 1V
(3) I_W=source or sink
(4) These parameters are periodically sampled and are not 100% tested.

Potentiometer Parameters

Symbol	Parameter	Conditions	Min	Typ	Max	Units
R_{POT}	Potentiometer Resistance	-10 Device		10		kΩ
		-50 Device		50		
		-00 Device		100		
	Pot Resistance Tolerance				±20	%
V_{RH}	Voltage on R_H pin		0		V_{CC}	V
V_{RL}	Voltage on R_L pin		0		V_{CC}	V
	Resolution			1%		%
INL	Integral Linearity Error	$I_W \le 2\mu A$		0.5	1	LSB
DNL	Differential Linearity Error	$I_W \le 2\mu A$		0.25	0.5	LSB
R_{Wi}	Wiper Resistance	V_{CC} = 5V, I_W = 1mA			400	Ω
		V_{CC} = 2.5V, I_W = 1mA			1	kΩ
I_W	Wiper Current				1	mA
TC_{RPOT}	TC of Pot Resistance			300		ppm/°C
TC_{RATIO}	Ratiometric TC				20	ppm/°C
R_{ISO}	Isolation Resistance			TBD		Ω
V_N	Noise	100kHz / 1kHz		8/24		$nV/\sqrt{Hz}$
$C_H/C_L/C_W$	Potentiometer Capacitances			8/8/25		pF
fc	Frequency Response	Passive Attenuator, 10kΩ		1.7		MHz

AC CONDITIONS OF TEST

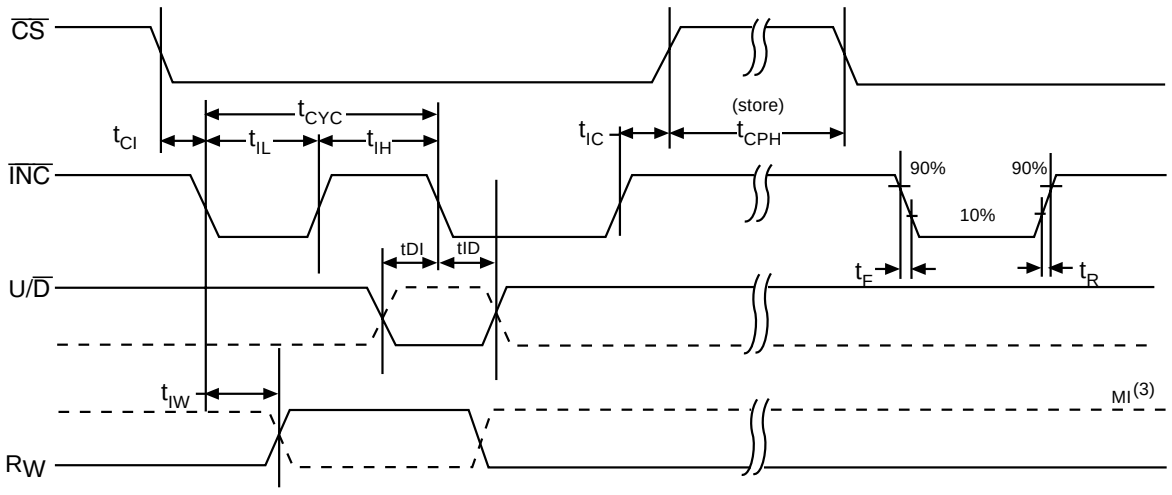
V_{CC} Range	$2.5V \le V_{CC} \le 6V$
Input Pulse Levels	$0.2V_{CC}$ to $0.7V_{CC}$
Input Rise and Fall Times	10ns
Input Reference Levels	$0.5V_{CC}$

AC OPERATING CHARACTERISTICS:

V_{CC} = +2.5V to +6.0V, $V_H = V_{CC}$, V_L = 0V, unless otherwise specified

Symbol	Parameter	Min	Typ(1)	Max	Units
t_{CI}	$\overline{CS}$ to INC Setup	100	—	—	ns
t_{DI}	U/$\overline{D}$ to $\overline{INC}$ Setup	50	—	—	ns
t_{ID}	U/$\overline{D}$ to $\overline{INC}$ Hold	100	—	—	ns
t_{IL}	$\overline{INC}$ LOW Period	250	—	—	ns
t_{IH}	$\overline{INC}$ HIGH Period	250	—	—	ns
t_{IC}	$\overline{INC}$ Inactive to $\overline{CS}$ Inactive	1	—	—	µs
t_{CPH}	$\overline{CS}$ Deselect Time (NO STORE)	100	—	—	ns
t_{CPH}	$\overline{CS}$ Deselect Time (STORE)	10	—	—	ms
t_{IW}	$\overline{INC}$ to V_{OUT} Change	—	1	5	µs
t_{CYC}	$\overline{INC}$ Cycle Time	1	—	—	µs
t_R, t_F(2)	$\overline{INC}$ Input Rise and Fall Time	—	—	500	µs
t_{PU}(2)	Power-up to Wiper Stable	—	—	1	msec
t_{WR}	Store Cycle	—	5	10	ms

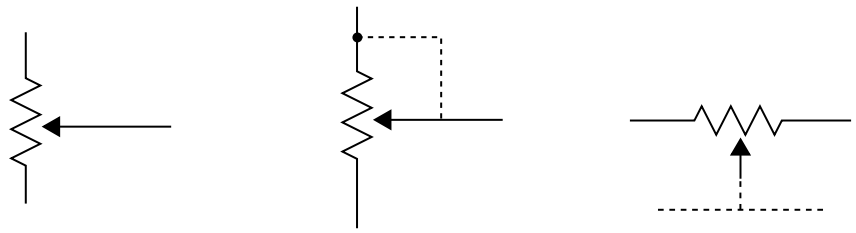
A. C. TIMING



(1) Typical values are for T_A=25˚C and nominal supply voltage.
(2) This parameter is periodically sampled and not 100% tested.
(3) MI in the A.C. Timing diagram refers to the minimum incremental change in the W output due to a change in the wiper position.

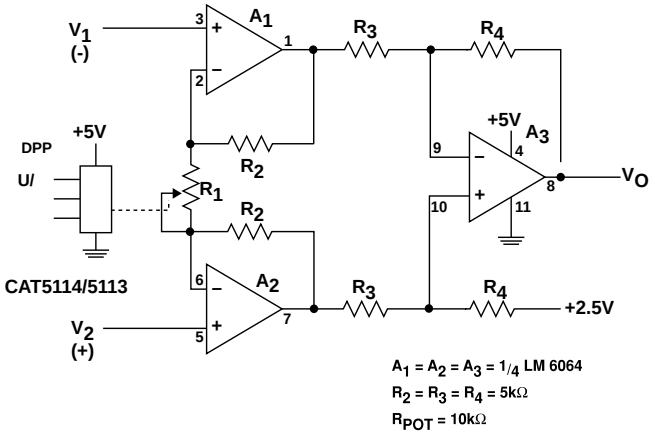
APPLICATIONS INFORMATION

Potentiometer Configurations

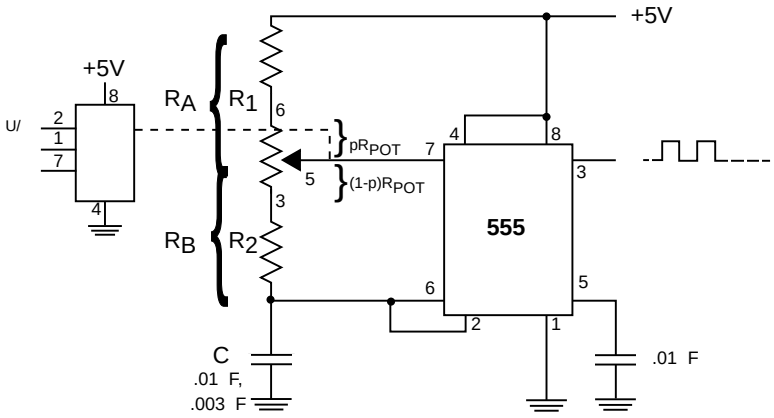


(a) resistive divider (b) variable resistance (c) two-port

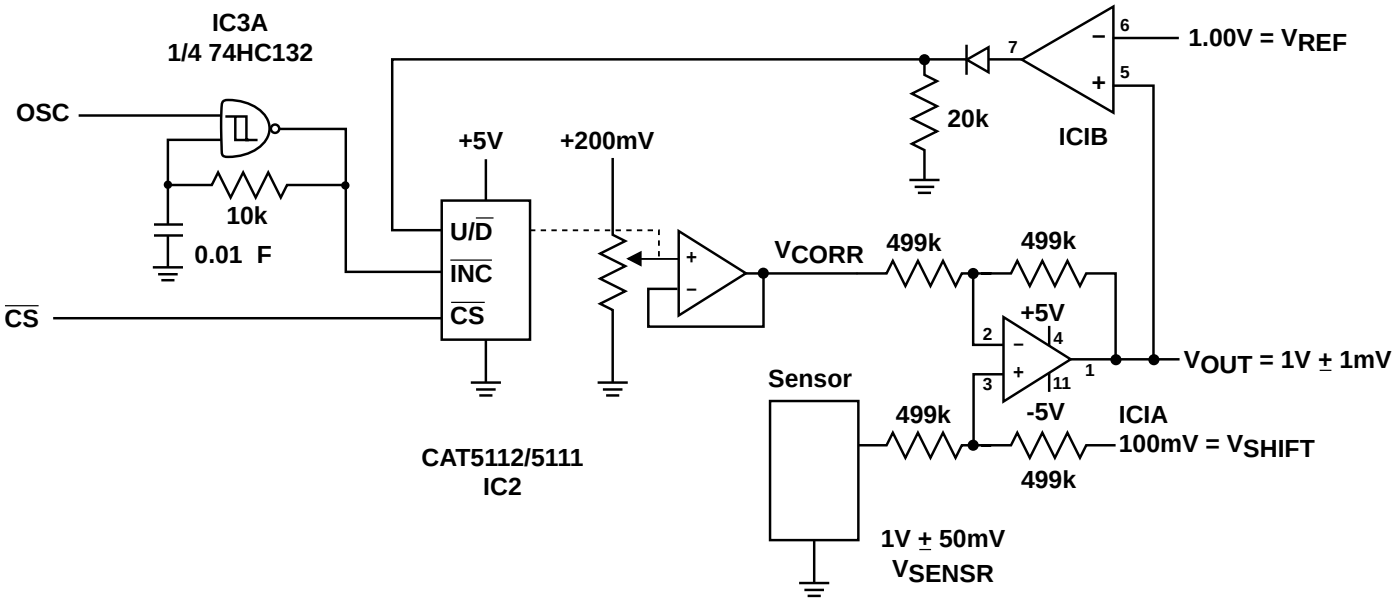
Applications



Programmable Instrumentation Amplifier

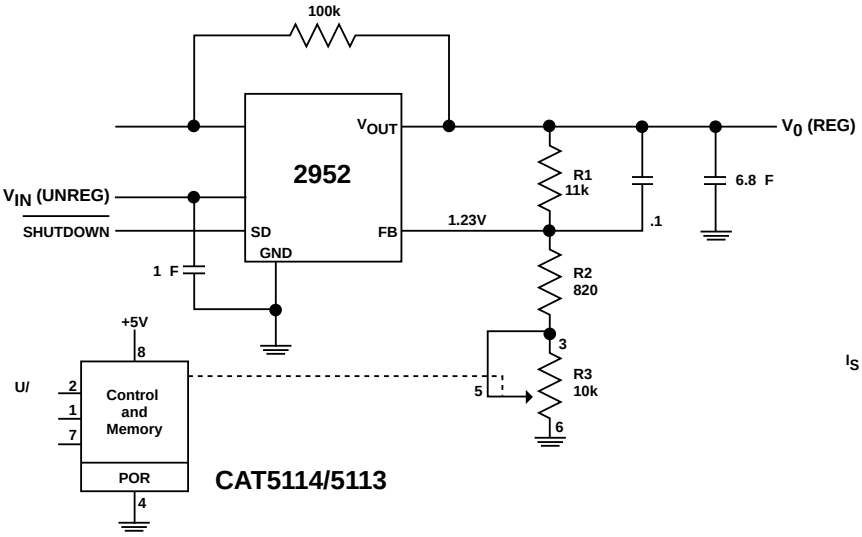


Programmable Sq. Wave Oscillator (555)

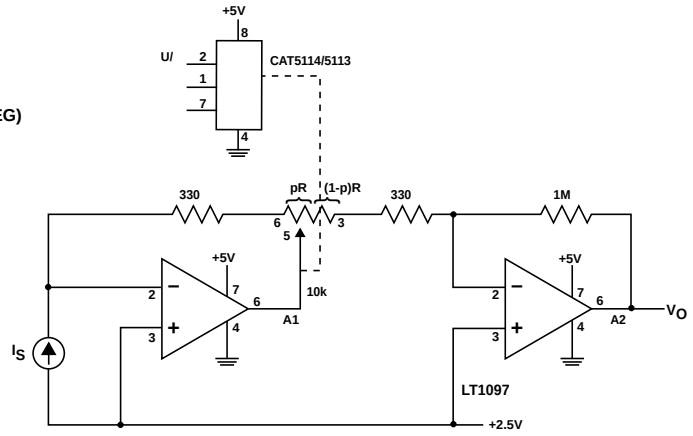


Sensor Auto Referencing Circuit

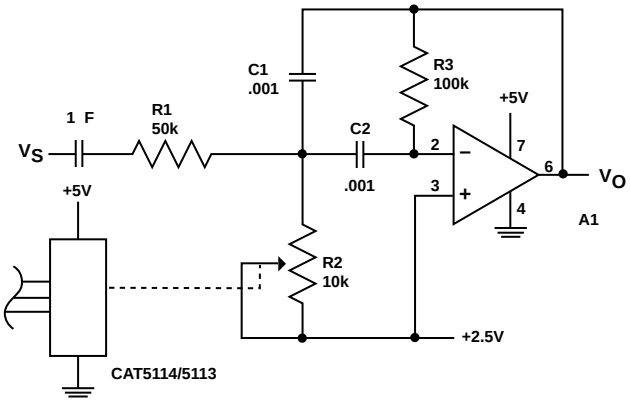
APPLICATIONS INFORMATION



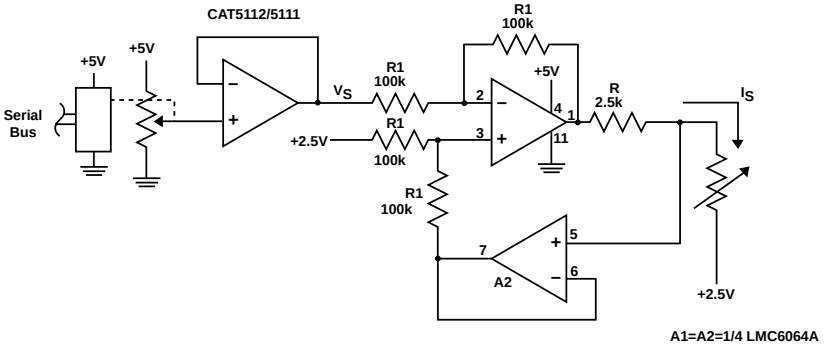
Programmable Voltage Regulator



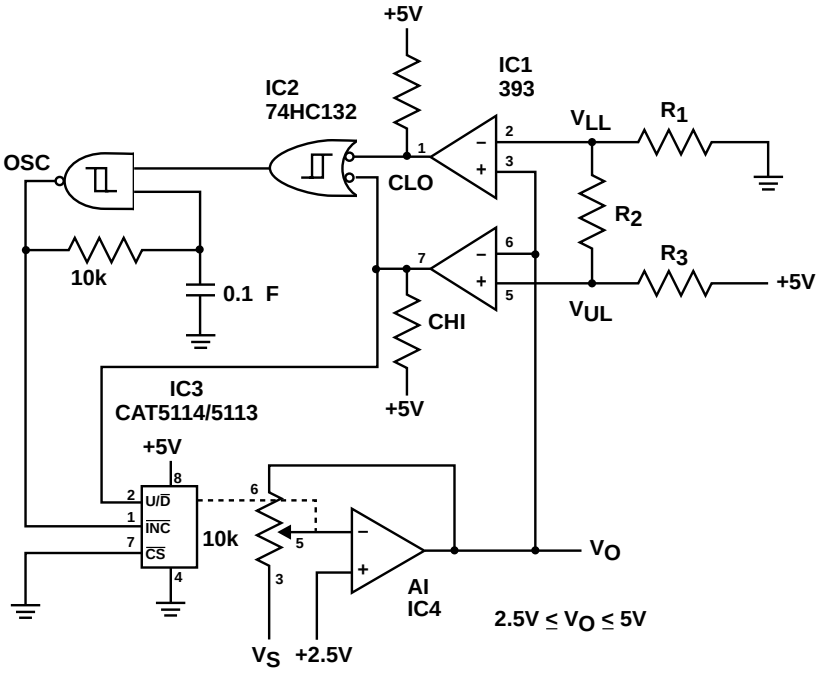
Programmable I to V convertor



Programmable Bandpass Filter

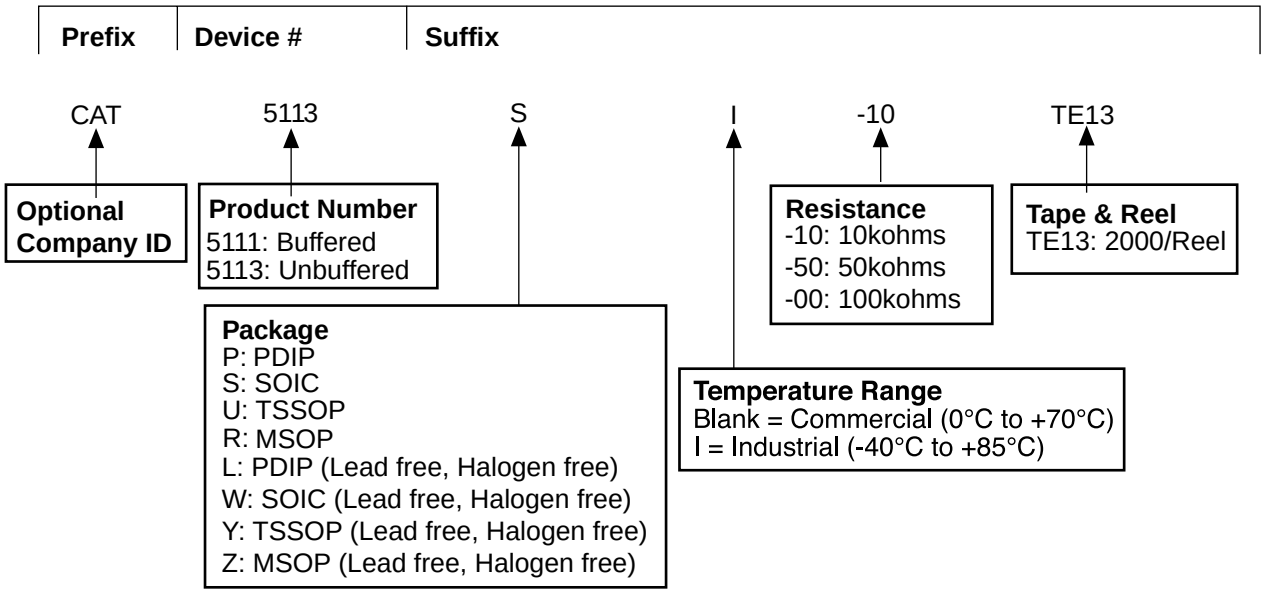


Programmable Current Source/Sink



Automatic Gain Control

ORDERING INFORMATION



Notes:
(1) The device used in the above example is a CAT5113 SI-10TE13 (SOIC, 10K Ohms, Industrial Temperature, Tape & Reel)

REVISION HISTORY

Date	Rev.	Reason
10/9/2003	M	Revised Features Revised DC Electrical Characteristics
3/10/2004	N	Updated Potentiometer Parameters

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Publication #: 2009
Revison: N
Issue date: 3/10/04
Type: Final