

PRELIMINARY W986416DH



1M × 4 BANKS × 16 BITS SDRAM

GENERAL DESCRIPTION

W986416DH is a high-speed synchronous dynamic random access memory (SDRAM), organized as 1M words × 4 banks × 16 bits. Using pipelined architecture and 0.175 μm process technology, W986416DH delivers a data bandwidth of up to 400M bytes per second (5). For different application, W986416DH is sorted into four speed grades: -5, -5.5, -6, -7, -8.

Accesses to the SDRAM are burst oriented. Consecutive memory location in one page can be accessed at a burst length of 1, 2, 4, 8 or full page when a bank and row is selected by an ACTIVE command. Column addresses are automatically generated by the SDRAM internal counter in burst operation. Random column read is also possible by providing its address at each clock cycle. The multiple bank nature enables interleaving among internal banks to hide the precharging time.

By having a programmable Mode Register, the system can change burst length, latency cycle, interleave or sequential burst to maximize its performance. W986416DH is ideal for main memory in high performance applications.

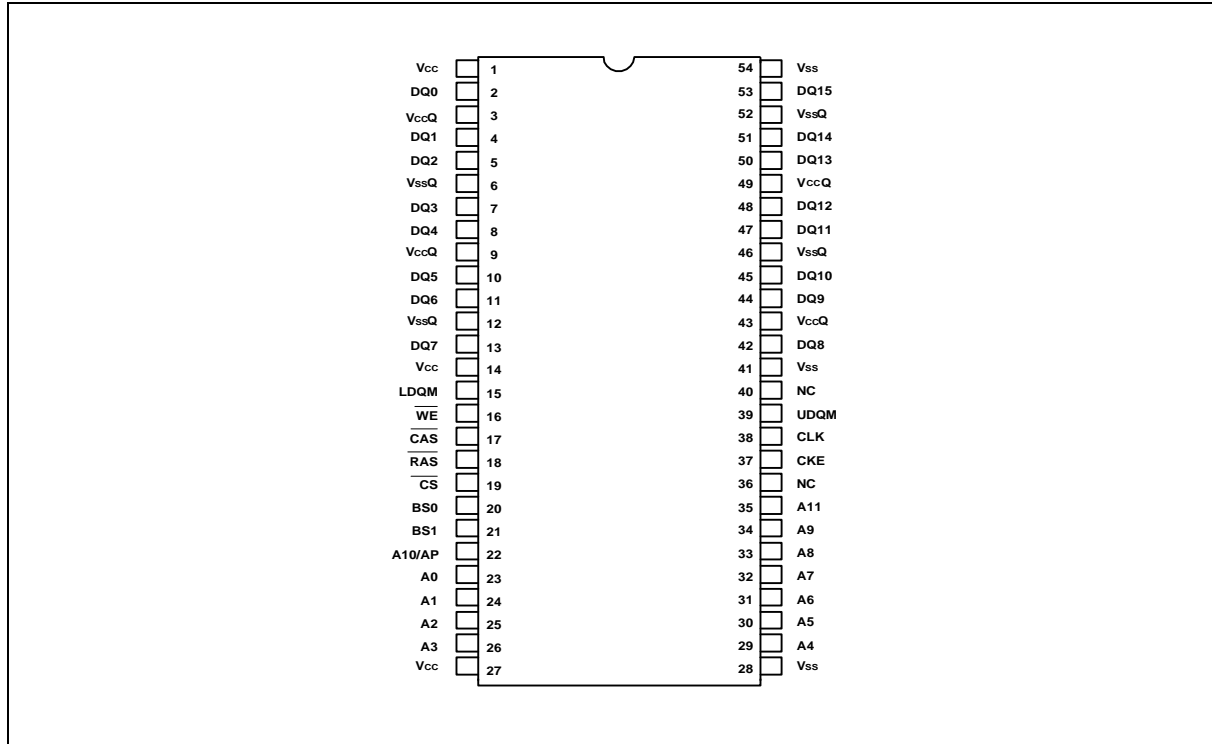
FEATURES

- 3.3V ±0.3V power supply
- 1048576 words × 4 banks × 16 bits organization
- Auto Refresh and Self Refresh
- CAS latency: 2 and 3
- Burst Length: 1, 2, 4, 8, and full page
- Sequential and Interleave burst
- Burst read, single write operation
- Byte data controlled by DQM
- Power-down Mode
- Auto-precharge and controlled precharge
- 4K refresh cycles/64 mS
- Interface: LVTTTL
- Packaged in 86-pin TSOP II, 400 mil - 0.50

KEY PARAMETERS

Symbol	Description	min/max	-5	-5.5	-6	-7	-8
tCK	Clock Cycle Time	min	5ns	5.5ns	6ns	7ns	8ns
tAC	Access Time from CLK	max	4.5ns	5ns	5ns	5ns	6ns
tRP	Precharge to Active Command	min	14ns	15ns	18ns	20ns	20ns
tRCD	Active to Read/Write Command	min	14ns	15ns	18ns	20ns	20ns
ICC1	Operation Current (Single bank)	max	110mA	100mA	90mA	80mA	70mA
ICC4	Burst Operation Current	max	190mA	185mA	165mA	145mA	130mA
ICC6	Self-Refresh Current	max	1mA	1mA	1mA	1mA	1mA

PIN CONFIGURATION

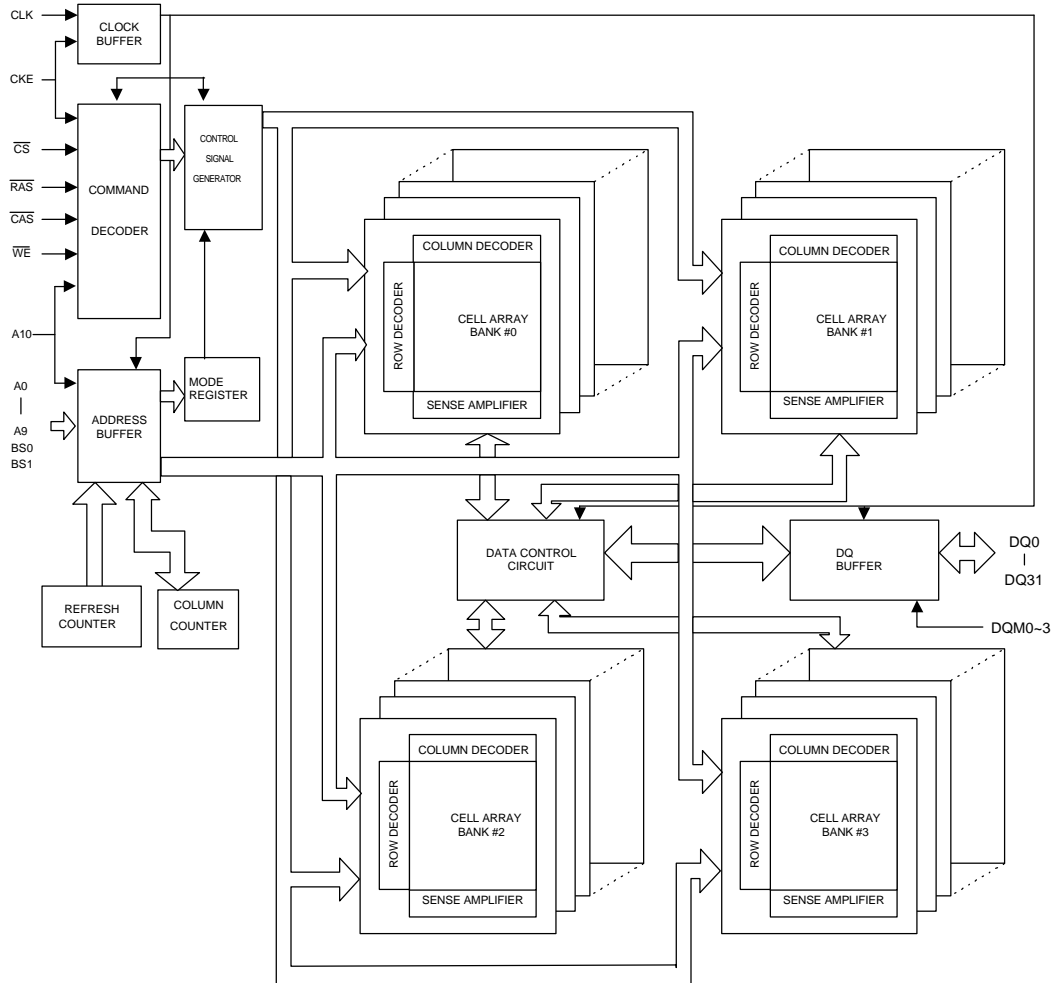


PIN DESCRIPTION

PIN NAME	FUNCTION	DESCRIPTION
A0–A10	Address	Multiplexed pins for row and column address. Row address: A0–A10. Column address: A0–A7. A10 is sampled during a precharge command to determine if all banks are to be precharged or bank selected by BS0, BS1.
BS0, BS1	Bank Select	Select bank to activate during row address latch time, or bank to read/write during address latch time.
DQ0–DQ31	Data Input/Output	Multiplexed pins for data output and input.
$\overline{\text{CS}}$	Chip Select	Disable or enable the command decoder. When command decoder is disabled, new command is ignored and previous operation continues.
$\overline{\text{RAS}}$	Row Address Strobe	Command input. When sampled at the rising edge of the clock $\overline{\text{RAS}}$, $\overline{\text{CAS}}$ and $\overline{\text{WE}}$ define the operation to be executed.
$\overline{\text{CAS}}$	Column Address Strobe	Referred to $\overline{\text{RAS}}$

WE	Write Enable	Referred to RAS
DQM0– DQM3	Input/output mask	The output buffer is placed at Hi-Z (with latency of 2) when DQM is sampled high in read cycle. In write cycle, sampling DQM high will block the write operation with zero latency.
CLK	Clock Inputs	System clock used to sample inputs on the rising edge of clock.
CKE	Clock Enable	CKE controls the clock activation and deactivation. When CKE is low, Power Down mode, Suspend mode, or Self Refresh mode is entered.
Vcc	Power (+3.3V)	Power for input buffers and logic circuit inside DRAM.
Vss	Ground	Ground for input buffers and logic circuit inside DRAM.
Vccq	Power (+3.3V) for I/O buffer	Separated power from Vcc, to improve DQ noise immunity.
Vssq	Ground for I/O buffer	Separated ground from Vss, to improve DQ noise immunity.
NC	No Connection	No connection

BLOCK DIAGRAM



NOTE:
The cell array configuration is 2048 * 256 * 32

FUNCTIONAL DESCRIPTION

Power Up and Initialization

The default power up state of the mode register is unspecified. The following power up and initialization sequence need to be followed to guarantee the device being preconditioned to each user specific needs.

During power up, all VCC and VCCQ pins must be ramp up simultaneously to the specified voltage when the input signals are held in the "NOP" state. The power up voltage must not exceed VCC +0.3V on any of the input pins or VCC supplies. After power up, an initial pause of 200 μ S is required followed by a precharge of all banks using the precharge command. To prevent data contention on the DQ bus during power up, it is required that the DQM and CKE pins be held high during the initial pause period. Once all banks have been precharged, the Mode Register Set Command must be issued to initialize the Mode Register. An additional eight Auto Refresh cycles (CBR) are also required before or after programming the Mode Register to ensure proper subsequent operation.

Programming Mode Register

After initial power up, the Mode Register Set Command must be issued for proper device operation. All banks must be in a precharged state and CKE must be high at least one cycle before the Mode Register Set Command can be issued. The Mode Register Set Command is activated by the low signals of $\overline{\text{RAS}}$, $\overline{\text{CAS}}$, $\overline{\text{CS}}$ and $\overline{\text{WE}}$ at the positive edge of the clock. The address input data during this cycle defines the parameters to be set as shown in the Mode Register Operation table. A new command may be issued following the mode register set command once a delay equal to t_{RSC} has elapsed. Please refer to the next page for Mode Register Set Cycle and Operation Table.

Bank Activate Command

The Bank Activate command must be applied before any Read or Write operation can be executed. The operation is similar to RAS activate in EDO DRAM. The delay from when the Bank Activate command is applied to when the first read or write operation can begin must not be less than the RAS to CAS delay time (t_{RCD}). Once a bank has been activated it must be precharged before another Bank Activate command can be issued to the same bank. The minimum time interval between successive Bank Activate commands to the same bank is determined by the RAS cycle time of the device (t_{RC}). The minimum time interval between interleaved Bank Activate commands (Bank A to Bank B and vice versa) is the Bank to Bank delay time (t_{RRD}). The maximum time that each bank can be held active is specified as T_{RAS} (max.).

Read and Write Access Modes

After a bank has been activated, a read or write cycle can be followed. This is accomplished by setting $\overline{\text{RAS}}$ high and $\overline{\text{CAS}}$ low at the clock rising edge after minimum of t_{RCD} delay. $\overline{\text{WE}}$ pin voltage level defines whether the access cycle is a read operation ($\overline{\text{WE}}$ high), or a write operation ($\overline{\text{WE}}$ low). The address inputs determine the starting column address. Reading or writing to a different row within an activated bank requires the bank be precharged and a new Bank Activate command be issued. When more than one bank is activated, interleaved bank Read or Write operations are possible. By using the programmed burst length and alternating the access and precharge operations between multiple banks, seamless data access operation among many different pages can be realized. Read or Write Commands can also be issued to the same bank or between active banks on every clock cycle.



Burst Read Command

The Burst Read command is initiated by applying logic low level to $\overline{\text{CS}}$ and $\overline{\text{CAS}}$ while holding $\overline{\text{RAS}}$ and $\overline{\text{WE}}$ high at the rising edge of the clock. The address inputs determine the starting column address for the burst. The Mode Register sets type of burst (sequential or interleave) and the burst length (1, 2, 4, 8, full page) during the Mode Register Set Up cycle. Table 2 and 3 in the next page explain the address sequence of interleave mode and sequence mode.

Burst Command

The Burst Write command is initiated by applying logic low level to $\overline{\text{CS}}$, $\overline{\text{CAS}}$ and $\overline{\text{WE}}$ while holding $\overline{\text{RAS}}$ high at the rising edge of the clock. The address inputs determine the starting column address. Data for the first burst write cycle must be applied on the DQ pins on the same clock cycle that the Write Command is issued. The remaining data inputs must be supplied on each subsequent rising clock edge until the burst length is completed. Data supplied to the DQ pins after burst finishes will be ignored.

Read Interrupted by a Read

A Burst Read may be interrupted by another Read Command. When the previous burst is interrupted, the remaining addresses are overridden by the new read address with the full burst length. The data from the first Read Command continues to appear on the outputs until the CAS latency from the interrupting Read Command is satisfied.

Read Interrupted by a Write

To interrupt a burst read with a Write Command, DQM may be needed to place the DQs (output drivers) in a high impedance state to avoid data contention on the DQ bus. If a Read Command will issue data on the first and second clocks cycles of the write operation, DQM is needed to insure the DQs are tri-stated. After that point the Write Command will have control of the DQ bus and DQM masking is no longer needed.

Write Interrupted by a Write

A burst write may be interrupted before completion of the burst by another Write Command. When the previous burst is interrupted, the remaining addresses are overridden by the new address and data will be written into the device until the programmed burst length is satisfied.

Write Interrupted by a Read

A Read Command will interrupt a burst write operation on the same clock cycle that the Read Command is activated. The DQs must be in the high impedance state at least one cycle before the new read data appears on the outputs to avoid data contention. When the Read Command is activated, any residual data from the burst write cycle will be ignored.

Burst Stop Command

A Burst Stop Command may be used to terminate the existing burst operation but leave the bank open for future Read or Write Commands to the same page of the active bank, if the burst length is full page. Use of the Burst Stop Command during other burst length operations is illegal. The Burst Stop Command is defined by having $\overline{\text{RAS}}$ and $\overline{\text{CAS}}$ high with $\overline{\text{CS}}$ and $\overline{\text{WE}}$ low at the rising edge of the clock. The data DQs go to a high impedance state after a delay, which is equal to the CAS Latency in a burst read cycle, interrupted by Burst Stop. If a Burst Stop Command is issued during a full page burst write operation, then any residual data from the burst write cycle will be ignored.

Addressing Sequence of Sequential Mode

A column access is performed by increasing the address from the column address which is input to the device. The disturb address is varied by the Burst Length as shown in Table 2.

Table 2 Address Sequence of Sequential Mode

DATA	ACCESS ADDRESS	BURST LENGTH
Data 0	n	BL = 2 (disturb address is A0) No address carry from A0 to A1
Data 1	n + 1	
Data 2	n + 2	BL = 4 (disturb addresses are A0 and A1) No address carry from A1 to A2
Data 3	n + 3	
Data 4	n + 4	BL = 8 (disturb addresses are A0, A1 and A2) No address carry from A2 to A3
Data 5	n + 5	
Data 6	n + 6	
Data 7	n + 7	

Addressing Sequence of Interleave Mode

A column access is started in the input column address and is performed by inverting the address bit in the sequence shown in Table 3.

Table 3 Address Sequence of Interleave Mode

DATA	ACCESS ADDRESS	BURST LENGTH
Data 0	A8 A7 A6 A5 A4 A3 A2 A1 A0	BL = 2
Data 1	A8 A7 A6 A5 A4 A3 A2 A1 $\overline{A0}$	
Data 2	A8 A7 A6 A5 A4 A3 A2 $\overline{A1}$ A0	BL = 4
Data 3	A8 A7 A6 A5 A4 A3 A2 $\overline{A1}$ $\overline{A0}$	
Data 4	A8 A7 A6 A5 A4 A3 $\overline{A2}$ A1 A0	BL = 8
Data 5	A8 A7 A6 A5 A4 A3 $\overline{A2}$ A1 $\overline{A0}$	
Data 6	A8 A7 A6 A5 A4 A3 $\overline{A2}$ $\overline{A1}$ A0	
Data 7	A8 A7 A6 A5 A4 A3 $\overline{A2}$ $\overline{A1}$ $\overline{A0}$	



Auto-precharge Command

If A10 is set to high when the Read or Write Command is issued, then the auto-precharge function is entered. During auto-precharge, a Read Command will execute as normal with the exception that the active bank will begin to precharge automatically before all burst read cycles have been completed. Regardless of burst length, it will begin a certain number of clocks prior to the end of the scheduled burst cycle. The number of clocks is determined by CAS latency.

A Read or Write Command with auto-precharge cannot be interrupted before the entire burst operation is completed for the same bank. Therefore, use of a Read, Write, or Precharge Command is prohibited during a read or write cycle with auto-precharge. Once the precharge operation has started, the bank cannot be reactivated until the Precharge time (t_{RP}) has been satisfied. Issue of Auto-Precharge command is illegal if the burst is set to full page length. If A10 is high when a Write Command is issued, the Write with Auto-Precharge function is initiated. The SDRAM automatically enters the precharge operation one clock delay from the last burst write cycle. This delay is referred to as write t_{DPL} . The bank undergoing auto-precharge cannot be reactivated until t_{DPL} and t_{RP} are satisfied. This is referred to as t_{DAL} , Data-in to Active delay ($t_{DAL} = t_{DPL} + t_{RP}$). When using the Auto-precharge Command, the interval between the Bank Activate Command and the beginning of the internal precharge operation must satisfy $t_{RAS}(\text{min})$.

Precharge Command

The Precharge Command is used to precharge or close a bank that has been activated. The Precharge Command is entered when \overline{CS} , \overline{RAS} and \overline{WE} are low and \overline{CAS} is high at the rising edge of the clock. The Precharge Command can be used to precharge each bank separately or all banks simultaneously. Three address bits, A10, BS0, and BS1 are used to define which bank(s) is to be precharged when the command is issued. After the Precharge Command is issued, the precharged bank must be reactivated before a new read or write access can be executed. The delay between the Precharge Command and the Activate Command must be greater than or equal to the Precharge time (t_{RP}).

Self Refresh Command

The Self Refresh Command is defined by having \overline{CS} , \overline{RAS} , \overline{CAS} and CKE held low with \overline{WE} high at the rising edge of the clock. All banks must be idle prior to issuing the Self Refresh Command. Once the command is registered, CKE must be held low to keep the device in Self Refresh mode. When the SDRAM has entered Self Refresh mode all of the external control signals, except CKE, are disabled. The clock is internally disabled during Self Refresh Operation to save power. The device will exit Self Refresh operation after CKE is returned high. A minimum delay time is required when the device exits Self Refresh Operation and before the next command can be issued. This delay is equal to the t_{AC} cycle time plus the Self Refresh exit time.

If, during normal operation, AUTO REFRESH cycles are issued in bursts (as opposed to being evenly distributed), a burst of 4,096 AUTO REFRESH cycles should be completed just prior to entering and just after exiting the self refresh mode.

Power Down Mode

The Power Down mode is initiated by holding CKE low. All of the receiver circuits except CKE are gated off to reduce the power. The Power Down mode does not perform any refresh operations, therefore the device can not remain in Power Down mode longer than the Refresh period (t_{REF}) of the device.

The Power Down mode is exited by bringing CKE high. When CKE goes high, a No Operation Command is required on the next rising clock edge, depending on t_{CK}. The input buffers need to be enabled with CKE held high for a period equal to t_{CES} (min.) + t_{CK} (min.).

No Operation Command

The No Operation Command should be used in cases when the SDRAM is in a idle or a wait state to prevent the SDRAM from registering any unwanted commands between operations. A No Operation Command is registered when \overline{CS} is low with \overline{RAS} , \overline{CAS} , and \overline{WE} held high at the rising edge of the clock. A No Operation Command will not terminate a previous operation that is still executing, such as a burst read or write cycle.

Deselect Command

The Deselect Command performs the same function as a No Operation Command. Deselect Command occurs when \overline{CS} is brought high, the \overline{RAS} , \overline{CAS} , and \overline{WE} signals become don't cares.

Clock Suspend Mode

During normal access mode, CKE must be held high enabling the clock. When CKE is registered low while at least one of the banks is active, Clock Suspend Mode is entered. The Clock Suspend mode deactivates the internal clock and suspends any clocked operation that was currently being executed. There is a one clock delay between the registration of CKE low and the time at which the SDRAM operation suspends. While in Clock Suspend mode, the SDRAM ignores any new commands that are issued. The Clock Suspend mode is exited by bringing CKE high. There is a one clock cycle delay from when CKE returns high to when Clock Suspend mode is exited.

TABLE OF OPERATING MODES

Fully synchronous operations are performed to latch the commands at the positive edges of CLK. Table 1 shows the truth table for the operation commands.

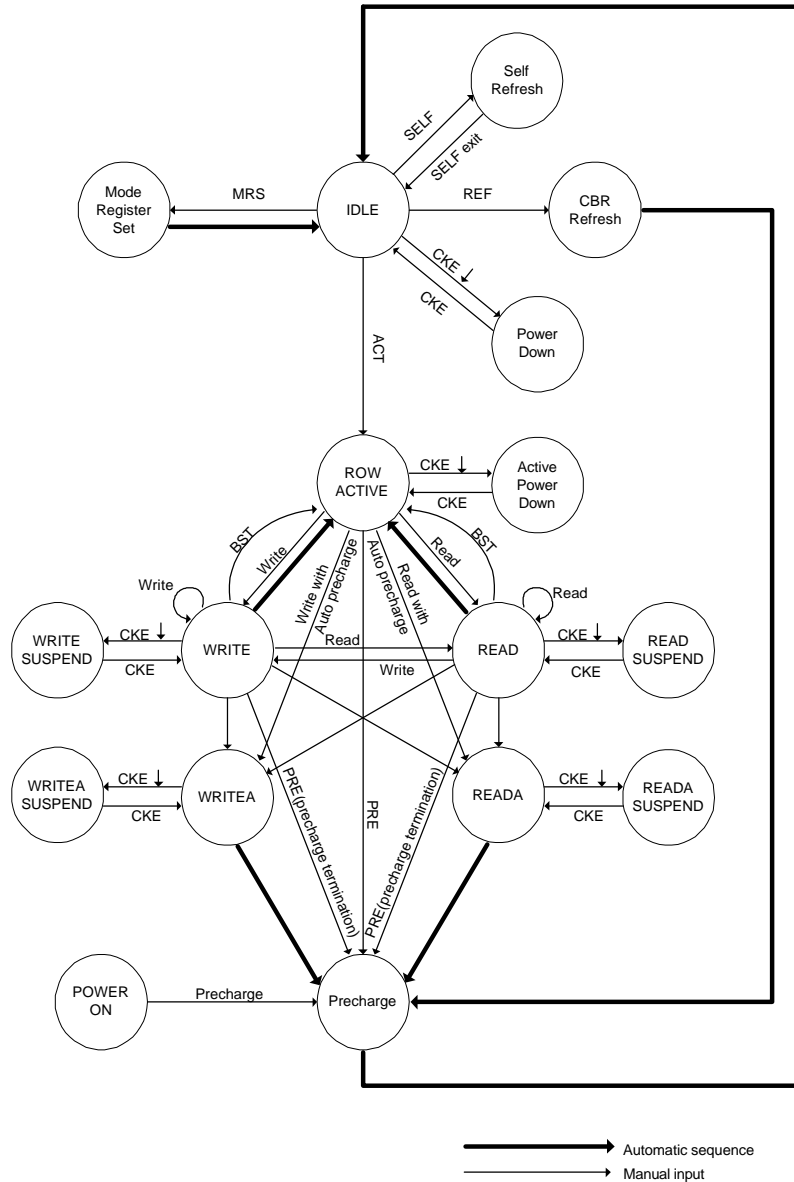
TABLE 1 TRUTH TABLE (NOTE (1), (2))

Command	Device state	CKEn-1	CKEn	DQM	BS0, 1	A10	A0-A9	\overline{CS}	\overline{RAS}	CAS	\overline{WE}
Bank Active	Idle	H	x	x	v	v	V	L	L	H	H
Bank Precharge	Any	H	x	x	v	L	x	L	L	H	L
Precharge All	Any	H	x	x	x	H	x	L	L	H	L
Write	Active (3)	H	x	x	v	L	v	L	H	L	L
Write with Autoprecharge	Active (3)	H	x	x	v	H	v	L	H	L	L
Read	Active (3)	H	x	x	v	L	v	L	H	L	H
Read with Autoprecharge	Active (3)	H	x	x	v	H	v	L	H	L	H
Mode Register Set	Idle	H	x	x	v	v	v	L	L	L	L
No-Operation	Any	H	x	x	x	x	x	L	H	H	H
Burst Stop	Active (4)	H	x	x	x	x	x	L	H	H	L
Device Deselect	Any	H	x	x	x	x	x	H	x	x	x
Auto-Refresh	Idle	H	H	x	x	x	x	L	L	L	H
Self-Refresh Entry	Idle	H	L	x	x	x	x	L	L	L	H
Self Refresh Exit	idle	L	H	x	x	x	x	H	x	x	x
	(S.R)	L	H	x	x	x	x	L	H	H	x
Clock suspend Mode Entry	Active	H	L	x	x	x	x	x	x	x	x
Power Down Mode Entry	Idle	H	L	x	x	x	x	H	x	x	X
	Active (5)	H	L	x	x	x	x	L	H	H	H
Clock Suspend Mode Exit	Active	L	H	x	x	x	x	x	x	x	X
Power Down Mode Exit	Any	L	H	x	x	x	x	H	x	x	X
	(power down)	L	H	x	x	x	x	L	H	H	H
Data write/Output Enable	Active	H	x	L	x	x	x	x	x	x	x
Data Write/Output Disable	Active	H	x	H	x	x	x	x	x	x	x

Notes:

- (1) v = valid, x = Don't care, L = Low Level, H = High Level
- (2) CKEn signal is input level when commands are provided.
- (3) These are state of bank designated by BS0, BS1 signals.
- (4) Device state is full page burst operation.
- (5) Power Down Mode can not be entered in the burst cycle.
When this command asserts in the burst cycle, device state is clock suspend mode.

SIMPLIFIED STATE DIAGRAM



MRS = Mode Register Set
REF = Refresh
ACT = Active
PRE = Precharge
WRITEA = Write with Auto precharge
READA = Read with Auto precharge

DC CHARACTERISTICS

Absolute Maximum Rating

PARAMETER	SYM.	RATING	UNIT	NOTES
Input, Column Output Voltage	V _{IN} , V _{OUT}	-0.3 – V _{CC} +0.3	V	1
Power Supply Voltage	V _{CC} , V _{CCQ}	-0.3 – 4.6	V	1
Operating Temperature	T _{OPR}	0 – 70	°C	1
Storage Temperature	T _{STG}	-55 – 150	°C	1
Soldering Temperature (10s)	T _{SOLDER}	260	°C	1
Power Dissipation	P _D	1	W	1
Short Circuit Output Current	I _{OUT}	50	mA	1

Note: Exposure to conditions beyond those listed under Absolute Maximum Ratings may adversely affect the life and reliability of the device.

RECOMMENDED DC OPERATING CONDITIONS

(T_A = 0 to 70°C)

PARAMETER	SYM.	MIN.	TYP.	MAX.	UNIT	NOTES
Power Supply Voltage	V _{CC}	3.0	3.3	3.6	V	2
Power Supply Voltage (for I/O Buffer)	V _{CCQ}	3.0	3.3	3.6	V	2
Input High Voltage	V _{IH}	2.0	-	V _{CC} +0.3	V	2
Input Low Voltage	V _{IL}	-0.3	-	0.8	V	2

Note: V_{IH} (max.) = V_{CC}/V_{CCQ}+1.2V for pulse width ≤ 5 nS

V_{IL} (min.) = V_{SS}/V_{SSQ}-1.2V for pulse width ≤ 5 nS

CAPACITANCE

(V_{DD} = 3.3V, T_A = 25 °C, f = 1 MHz)

PARAMETER	SYM.	MIN.	MAX.	UNIT
Input Capacitance (A0 to A11, BS0, BS1, $\overline{\text{CS}}$, $\overline{\text{RAS}}$, $\overline{\text{CAS}}$, $\overline{\text{WE}}$, DQM, CKE)	C _i	2.5	4	pf
Input Capacitance (CLK)	C _{CLK}	2.5	4	pf
Input/Output capacitance (DQ0–DQ31)	C _o	4	6.5	pf

Note: These parameters are periodically sampled and not 100% tested

DC CHARACTERISTICS

(VCC = 3.3V ±0.3V, TA = 0°~70°C)

PARAMETER		SYM.	-5	-55	-6	-7	-8	UNIT	NOTES
			MAX.	MAX.	MAX.	MAX.	MAX.		
Operating Current tCK = min., tRC = min. Active precharge command cycling without burst operation	1 bank operation	ICC1	110	100	90	80	70		3
Standby Current tCK = min., CS = VIH VIH/L = VIH (min.)/VIL (max.) Bank: inactive state	CKE = VIH	ICC2	45	40	35	30	25		3
	CKE = VIL (Power Down mode)	ICC2P	1	1	1	1	1		3
Standby Current CLK = VIL, CS = VIH VIH/L = VIH (min.)/VIL (max.) BANK: inactive state	CKE = VIH	ICC2S	8	8	8	8	8		
	CKE = VIL (Power Down mode)	ICC2PS	1	1	1	1	1	MA	
No Operating Current tCK = min., CS = VIH (min.) BANK: active state (4 banks)	CKE = VIH	ICC3	70	65	60	55	50		
	CKE = VIL (Power Down mode)	ICC3P	3	3	3	3	3		
Burst Operating Current Read/Write command cycling	(tCK = min.)	ICC4	190	185	165	145	130		3, 4
Auto Refresh Current Auto refresh command cycling	(tCK = min.)	ICC5	125	125	120	110	100		3
Self Refresh Current Self refresh mode	(CKE = 0.2V)	ICC6	1	1	1	1	1		

PARAMETER	SYMBOL	MIN.	MAX.	UNIT	NOTES
Input Leakage Current (0V ≤ VIN ≤ VCC, all other pins not under test = 0V)	II(L)	-5	5	μA	
Output Leakage Current 7(Output disable, 0V ≤ VOUT ≤ VCCQ)	VO(L)	-5	5	μA	
LVTTL Output "H" Level Voltage (IOUT = -2 mA)	VOH	2.4	-	V	
LVTTL Output "L" Level Voltage (IOUT = 2 mA)	VOL	-	0.4	V	

AC CHARACTERISTICS

($V_{CC} = 3.3V \pm 0.3V$, $V_{SS} = 0V$, $T_a = 0$ to $70^\circ C$) (Notes: 5, 6.)

PARAMETER	Symbol	-5		-55		-6		UNIT	NOTE
		MIN	MAX	MIN	MAX	MIN	MAX		
Ref/Active to Ref/Active Command Period	tRC	54		55		60		ns	
Active to precharge Command Period	tRAS	40	100000	40	100000	42	100000		
Active to Read/Write Command Delay Time	tRCD	14		15		18			
Read/Write(a) to Read/Write(b) Command Period	tCCD	1		1		1		Cycle	
Precharge to Active(b) Command Period	tRP	14		15		18		ns	
Active(a) to Active(b) Command Period	tRRD	10		10.8		12			
Write Recovery Time	CL* = 2 CL* = 3	7		7.5		7.5			
		5		5.4		6			
CLK Cycle Time	CL* = 2 CL* = 3	7	1000	7.5	1000	7.5	1000		
		5	1000	5.4	1000	6	1000		
CLK High Level	tCH	2		2		2			
CLK Low Level	tCL	2		2		2			
Access Time from CLK	CL* = 2 CL* = 3		4.5		5.5		5.5		
			4.5		5		5		
Output Data Hold Time	tOH	2.75		2.75		2.75			
Output Data High Impedance Time	tHZ	2.75	5	2.75	5.4	2.75	6		
Output Data Low Impedance Time	tLZ	0		0		0			
Power Down Mode Entry Time	tSB	0	5	0	5.4	0	6		
Transition Time of CLK (Rise and Fall)	tT	0.5	10	0.5	10	0.5	10		
Data-in-Set-up Time	tDS	1		1.5		1.5			
Data-in Hold Time	tDH	0.5		1		1			
Address Set-up Time	tAS	1.3		1.5		1.5			
Address Hold Time	tAH	0.8		1		1			
CKE Set-up Time	tCKS	1.3		1.5		1.5			
CKE Hold Time	tCKH	0.8		1		1			
Command Set-up Time	tCMS	1		1.5		1.5			
Command Hold Time	tCMH	0.5		1		1			
Refresh Time	tREF		64		64		64	ms	
Mode Register Set Cycle Time	tRSC	10		10.8		12		ns	

AC CHARACTERISTICS

($V_{CC} = 3.3V \pm 0.3V$, $V_{SS} = 0V$, $T_a = 0$ to $70^\circ C$) (Notes: 5, 6.)

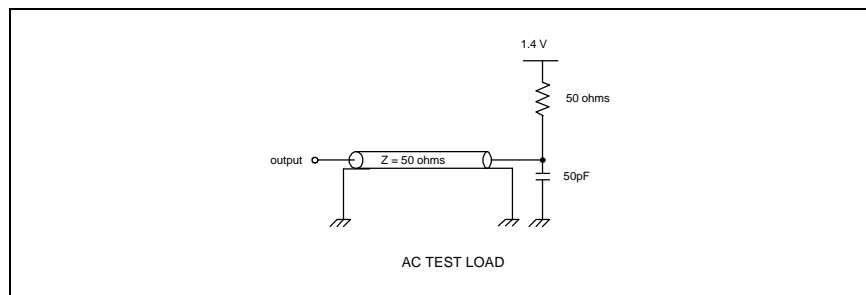
PARAMETER	Symbol	-7		-8				UNIT	NOTE
		MIN	MAX	MIN	MAX	MIN	MAX		
Ref/Active to Ref/Active Command Period	tRC	65		68				ns	
Active to precharge Command Period	tRAS	45	100000	48	100000				
Active to Read/Write Command Delay Time	tRCD	20		20					
Read/Write(a) to Read/Write(b) Command Period	tCCD	1		1				Cycle	
Precharge to Active(b) Command Period	tRP	20		20				ns	
Active(a) to Active(b) Command Period	tRRD	14		20					
Write Recovery Time	CL* = 2 CL* = 3	tWR		10					
			7	8					
CLK Cycle Time	CL* = 2 CL* = 3	tCK		10					
			7	8					
CLK High Level	tCH	2		3					
CLK Low Level	tCL	2		3					
Access Time from CLK	CL* = 2 CL* = 3	tAC		5.5	6				
				5	6				
Output Data Hold Time	tOH	3		3					
Output Data High Impedance Time	tHZ	3	7	3	8				
Output Data Low Impedance Time	tLZ	0		0					
Power Down Mode Entry Time	tSB	0	7	0	8				
Transition Time of CLK (Rise and Fall)	tT	0.5	10	0.5	10				
Data-in-Set-up Time	tDS	1.5		2					
Data-in Hold Time	tDH	1		1					
Address Set-up Time	tAS	1.5		2					
Address Hold Time	tAH	1		1					
CKE Set-up Time	tCKS	1.5		2					
CKE Hold Time	tCKH	1		1					
Command Set-up Time	tCMS	1.5		2					
Command Hold Time	tCMH	1		1					
Refresh Time	tREF		64		64			ms	
Mode Register Set Cycle Time	tRSC	14		16				ns	

Notes:

1. Operation exceeds "ABSOLUTE MAXIMUM RATING" may cause permanent damage to the devices.
2. All voltages are referenced to Vss
3. These parameters depend on the cycle rate and listed values are measured at a cycle rate with the minimum values of tCK and tRC.
4. These parameters depend on the output loading conditions. Specified values are obtained with output open.
5. Power up Sequence
 - (1) Power up must be performed in the following sequence.
 - (2) Power must be applied to Vcc and VccQ (simultaneously) while all input signals are held in the "NOP" state. The CLK signals must be started at the same time.
 - (3) After power-up a pause of at least 200 μ seconds is required. It is required that DQM and CKE signals then be held 'high' (Vcc levels) to ensure that the DQ output is impedance.
 - (4) All banks must be precharged.
 - (5) The Mode Register Set command must be asserted to initialize the Mode Register.
 - (6) A minimum of eight Auto Refresh dummy cycles is required to stabilize the internal circuitry of the device.

6. AC Testing Conditions

PARAMETER	CONDITIONS
Output Reference Level	1.4V
Output Load	See diagram below
Input Signal Levels (V _{IH} /V _{IL})	2.4V/0.4V
Transition Time (Rise and Fall) of Input Signal	1 nS
Input Reference Level	1.4V



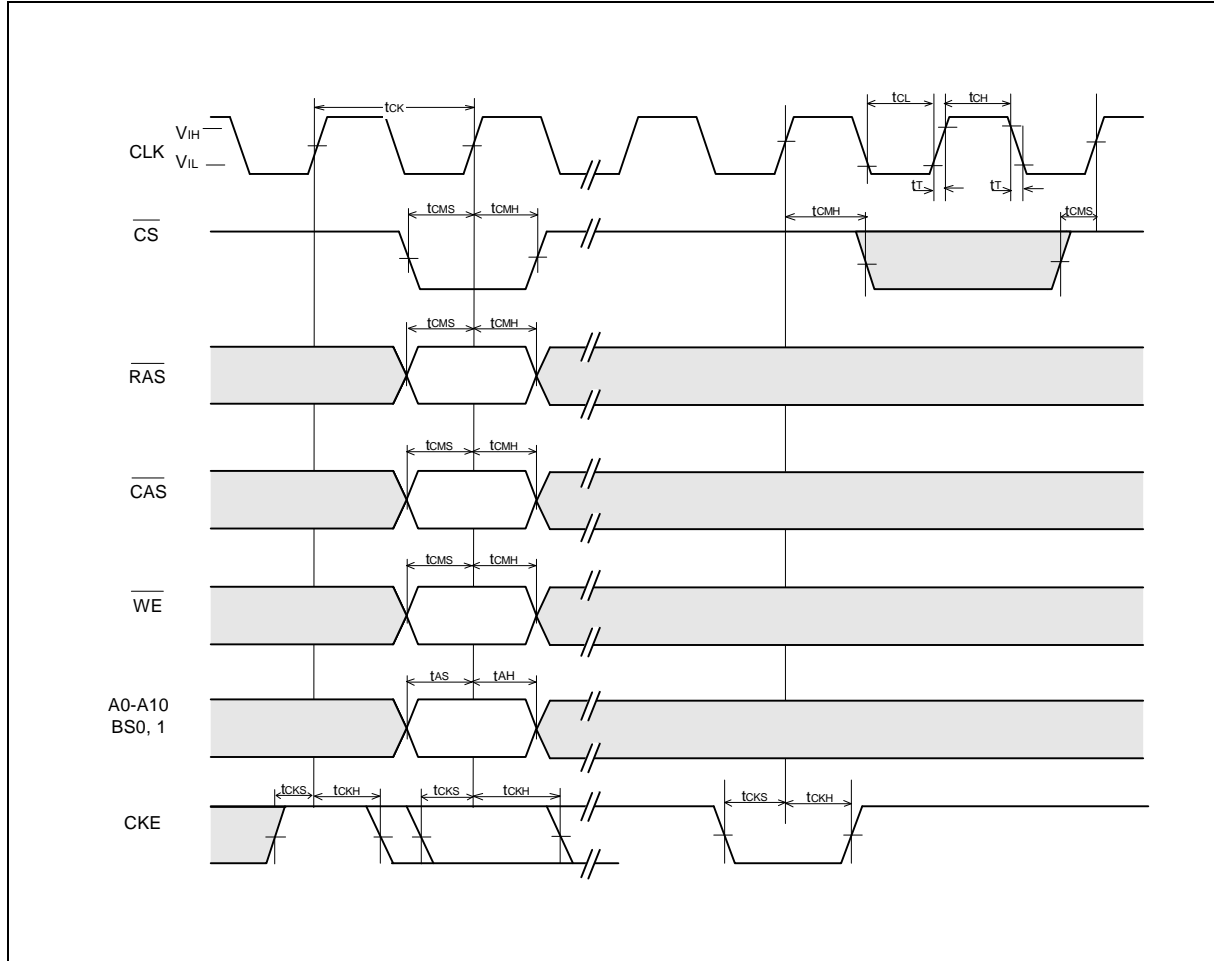
1. Transition times are measured between V_{IH} and V_{IL}.
2. t_{HZ} defines the time at which the outputs achieve the open circuit condition and is not referenced to output level.
3. These parameters account for the number of clock cycles and depend on the operating frequency of the clock, as follows the number of clock cycles = specified value of timing/ clock period (count fractions as whole number)
 - (1) t_{CH} is the pulse width of CLK measured from the positive edge to the negative edge referenced to V_{IH} (min.).
 - t_{CL} is the pulse width of CLK measured from the negative edge to the positive edge referenced to V_{IL} (max.).

(2) A.C Latency Characteristics

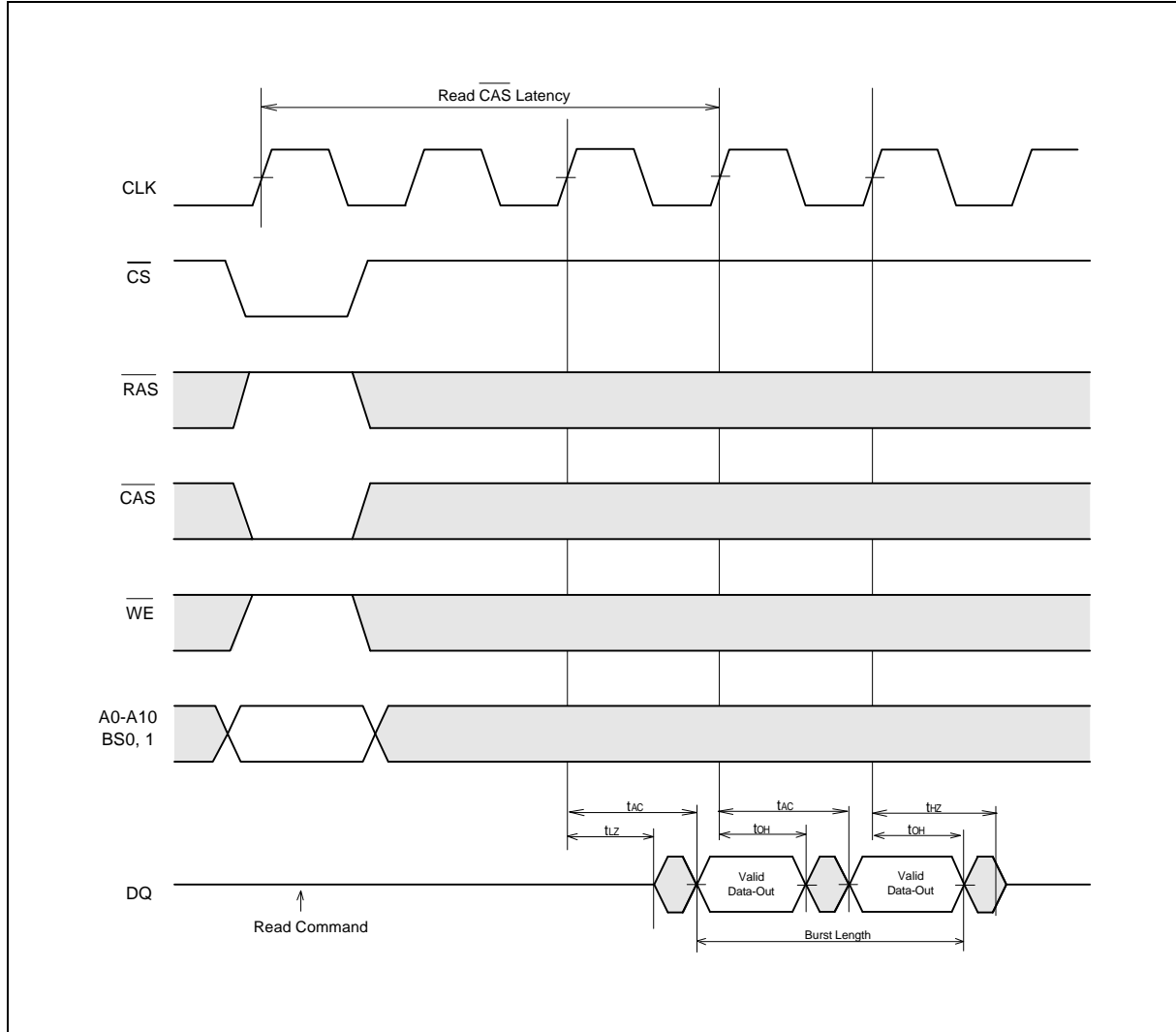
CKE to clock disable (CKE Latency)		1	Cycle
DQM to output to HI-Z (Read DQM Latency)		2	
DQM to output to HI-Z (Write DQM Latency)		0	
Write command to input data (Write Data Latency)		0	
\overline{CS} to Command input (\overline{CS} Latency)		0	
Precharge to DQ Hi-Z Lead time	CL = 2	2	
	CL = 3	3	
Precharge to Last Valid data out	CL = 2	1	
	CL = 3	2	
Bust Stop Command to DQ Hi-Z Lead time	CL = 2	2	
	CL = 3	3	
Bust Stop Command to Last Valid Data out	CL = 2	1	
	CL = 3	2	
Read with Auto-precharge Command to Active/Ref Command	CL = 2	BL + t _{RP}	Cycle + nS
	CL = 3	BL + t _{RP}	
Write with Auto-precharge Command to Active/Ref Command	CL = 2	BL + t _{RP}	
	CL = 3	BL + t _{RP}	

TIMING WAVEFORMS

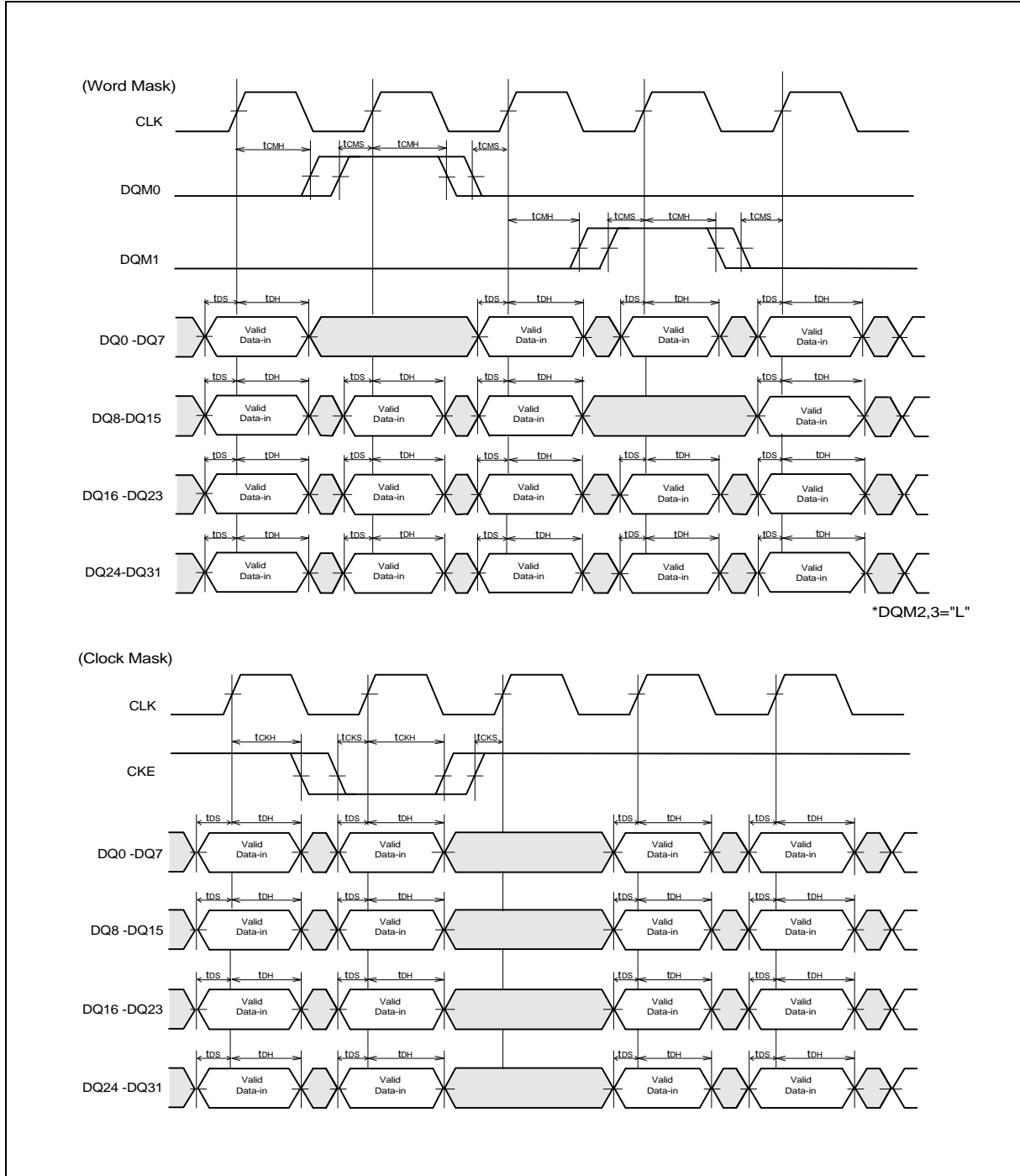
Command Input Timing



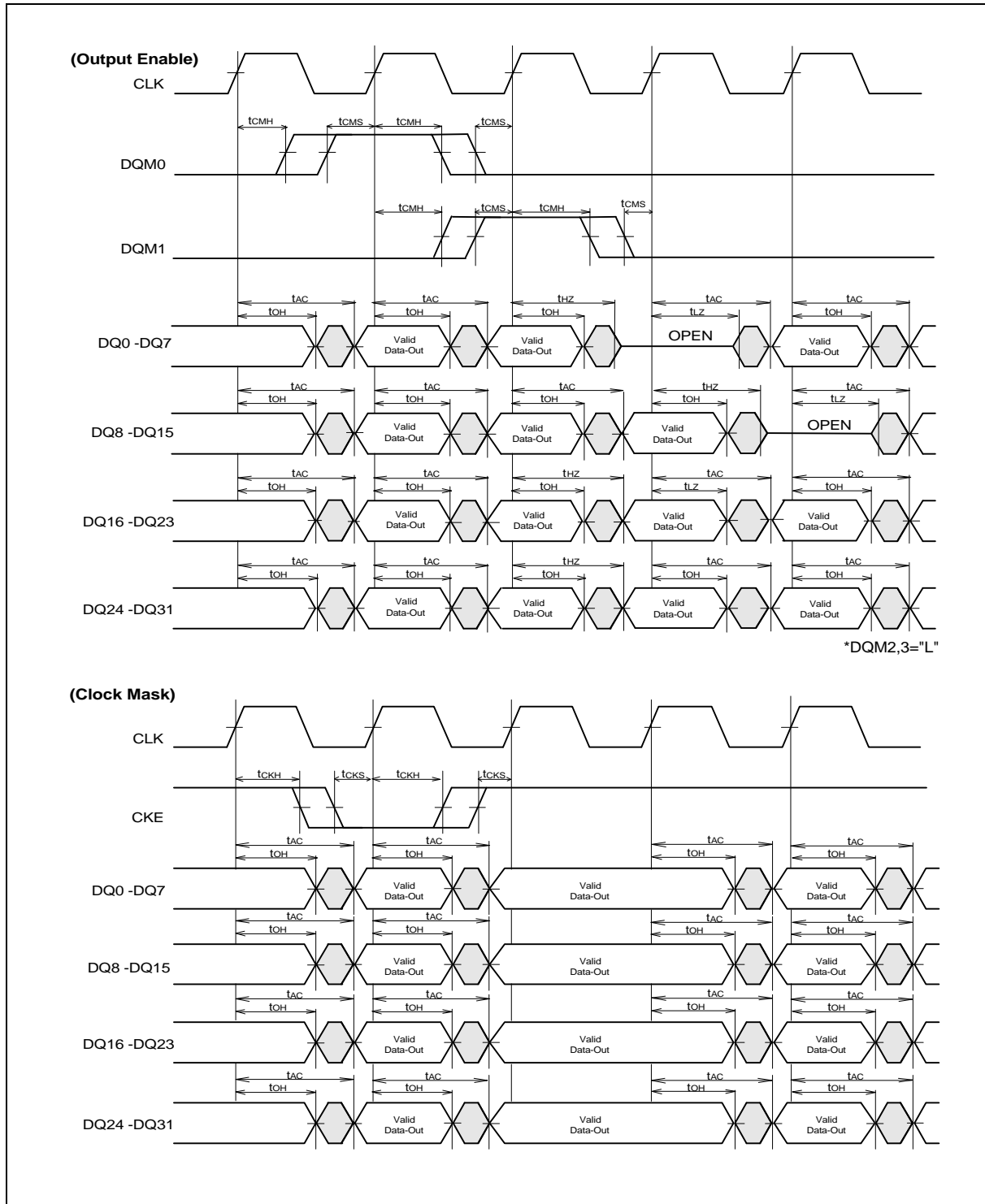
Read Timing



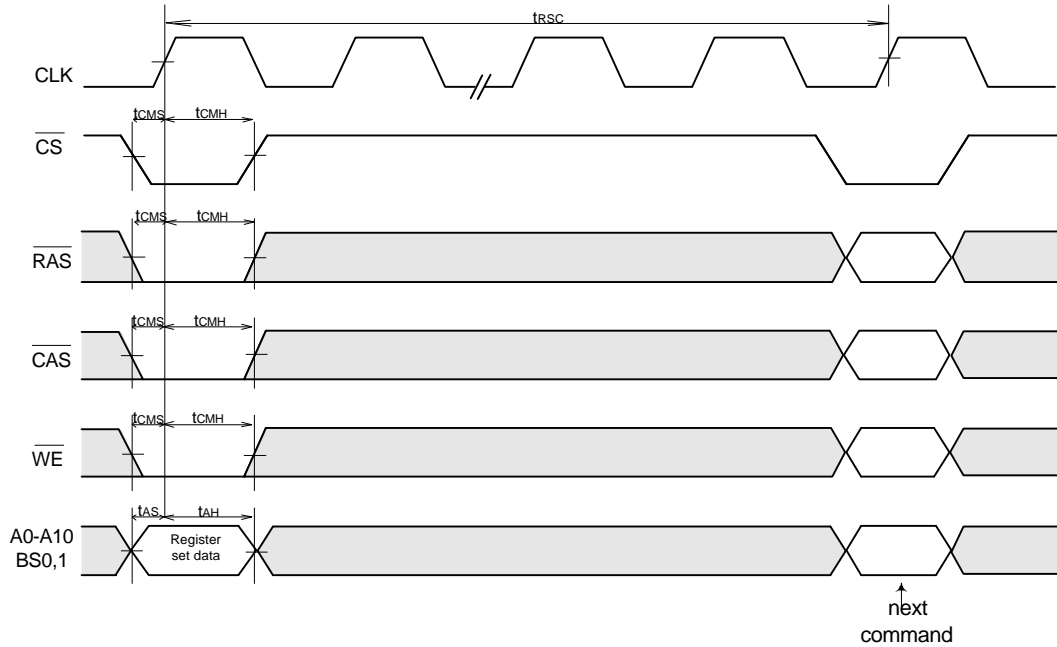
Control Timing of Input Data



Control Timing of Output Data



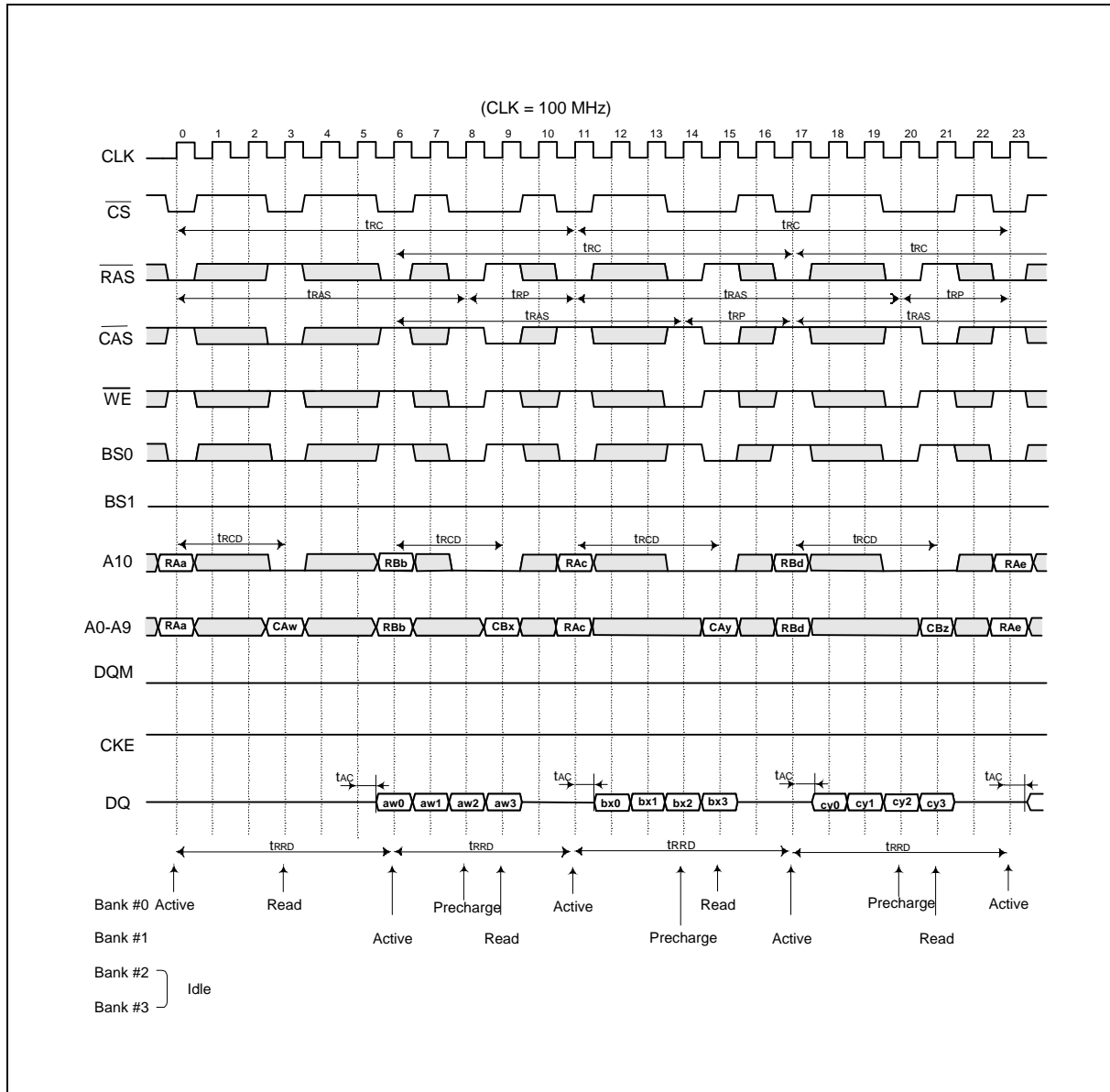
Mode Register Set Cycle



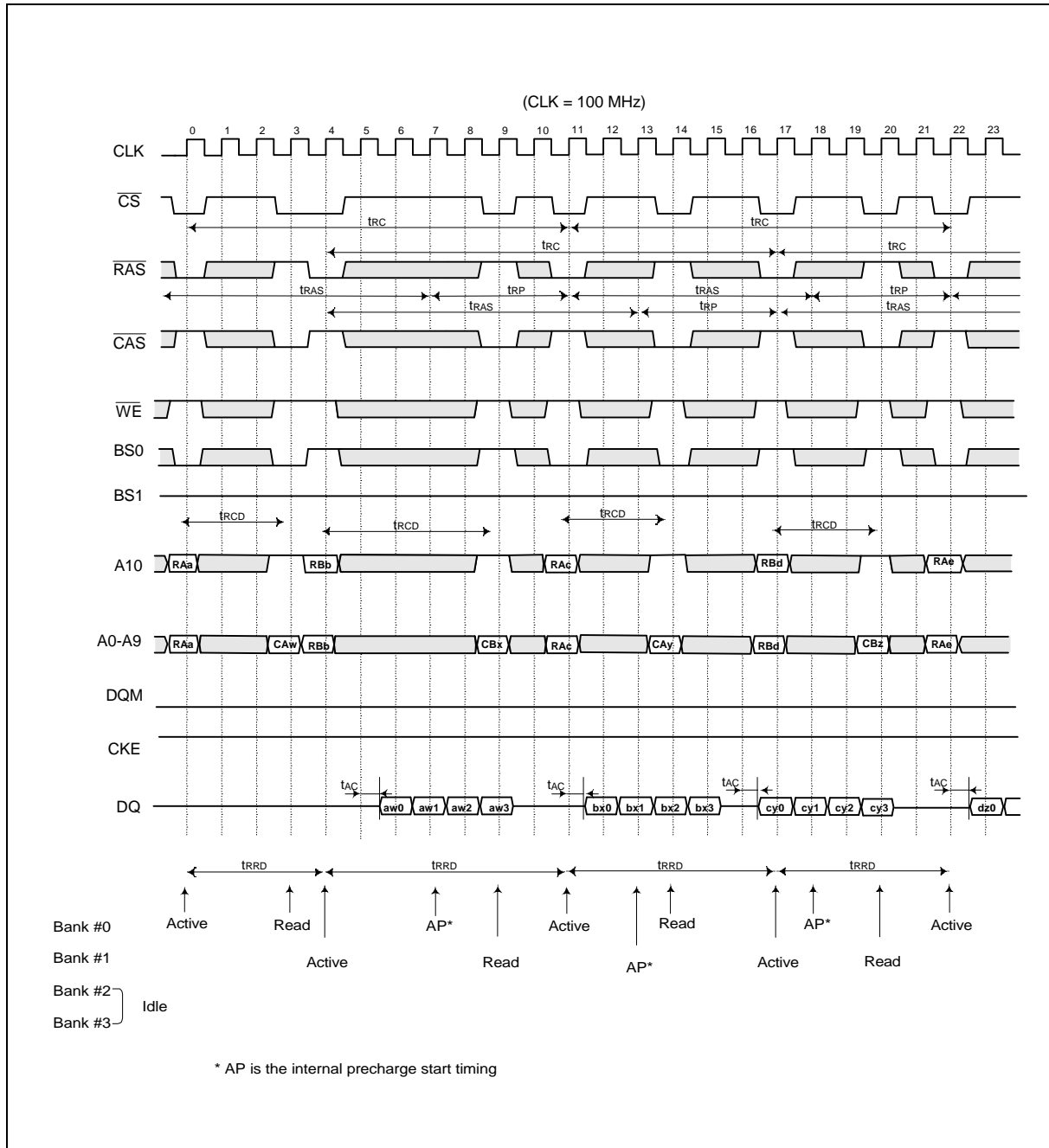
A0	Burst Length					Burst Length		
A1			A2	A0	Sequential	Interleave		
A2			0	0	0	1	1	
A3	Addressing Mode		0	0	1	2	2	
0			1	0	4	4		
0			1	1	8	8		
A4	CAS Latency		1	0	0	Reserved	Reserved	
A5			1	0	1			
A6			1	1	0			
A7			1	1	1	Full Page		
A8	"0"	(Test Mode)	A3			Addressing Mode		
A9	"0"	Reserved	0			Sequential		
A10	Write Mode		1			Interleave		
A11			A6			A5	A4	CAS Latency
BS0			0			0	0	Reserved
BS1			0			0	1	Reserved
	Reserved		0			1	0	2
			0			1	1	3
			1			0	0	Reserved
			A9			Single Write Mode		
			0			Burst read and Burst write		
			1			Burst read and single write		

OPERATING TIMING EXAMPLE

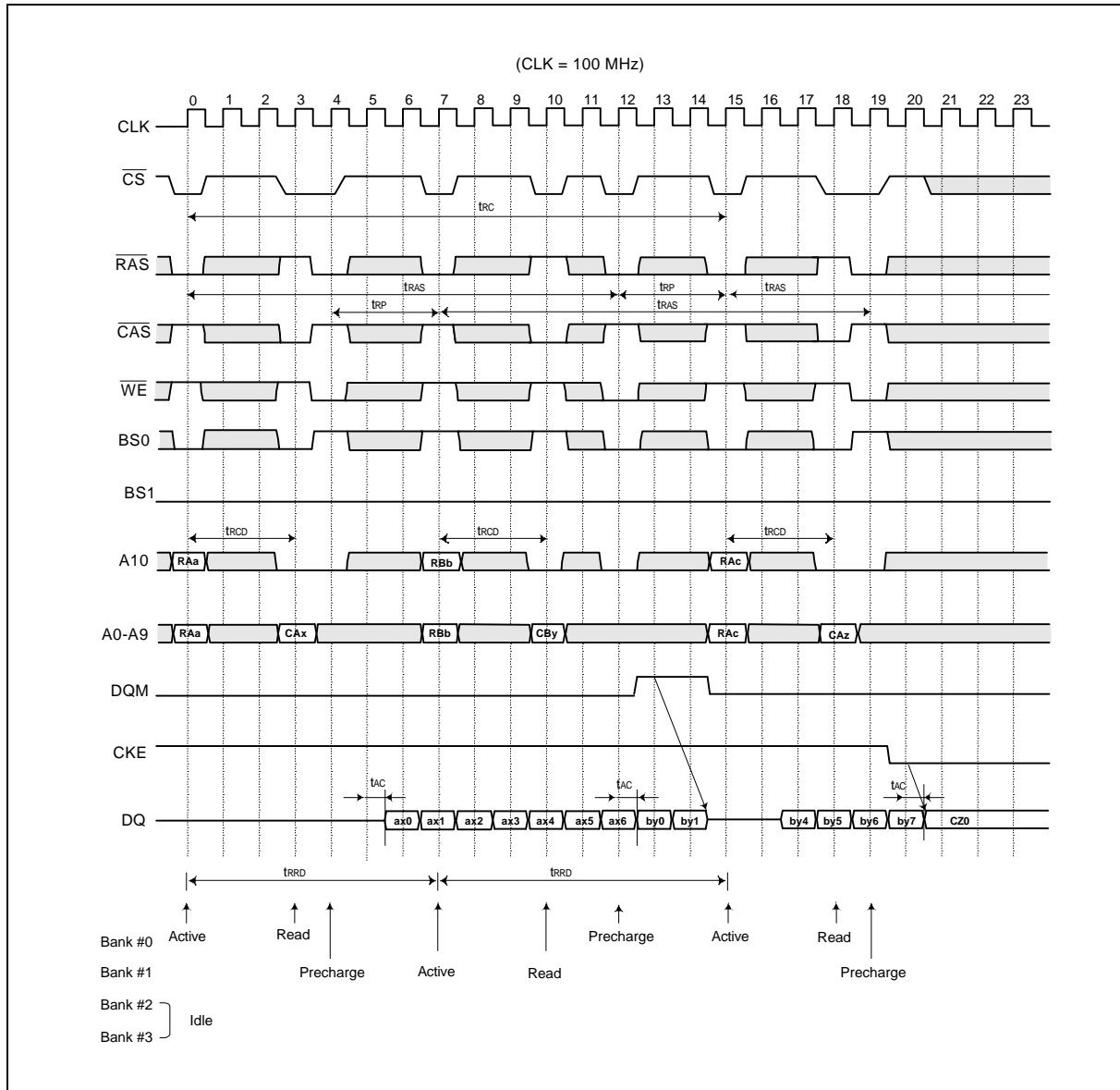
Interleaved Bank Read (Burst Length = 4, CAS Latency = 3)



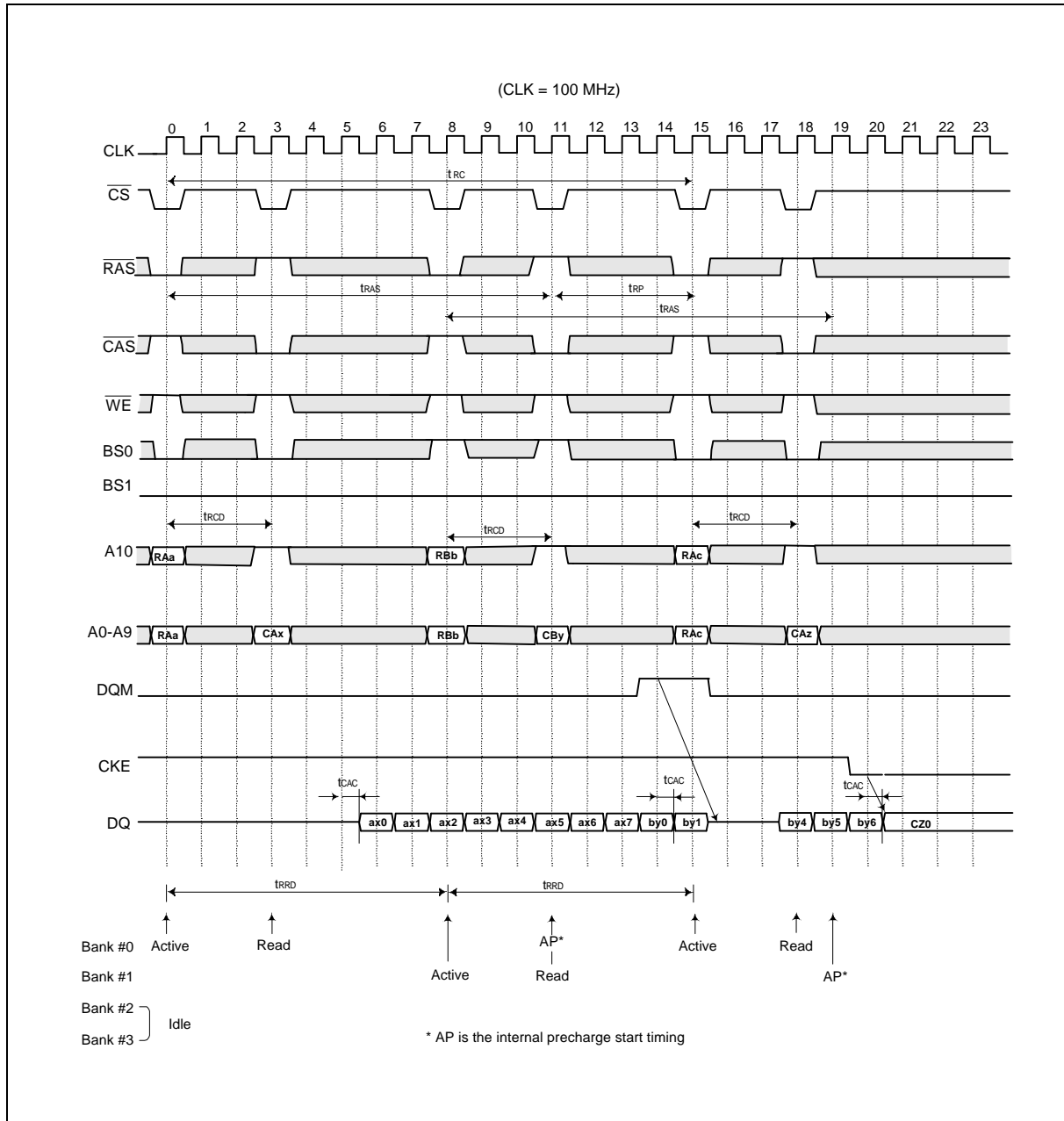
Interleaved Bank Read (Burst Length = 4, CAS Latency = 3, Autoprecharge)



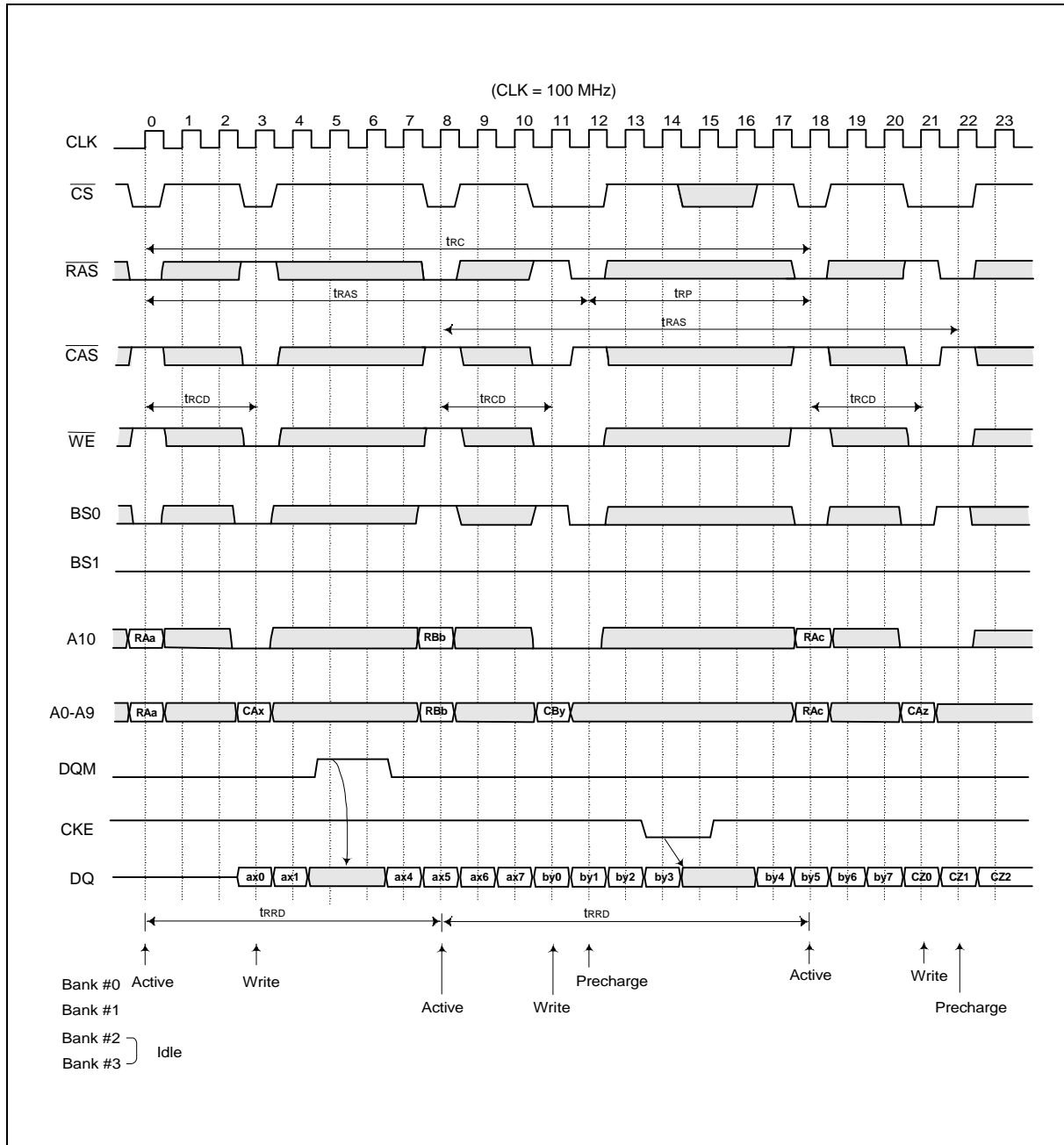
Interleaved Bank Read (Burst Length = 8, CAS Latency = 3)



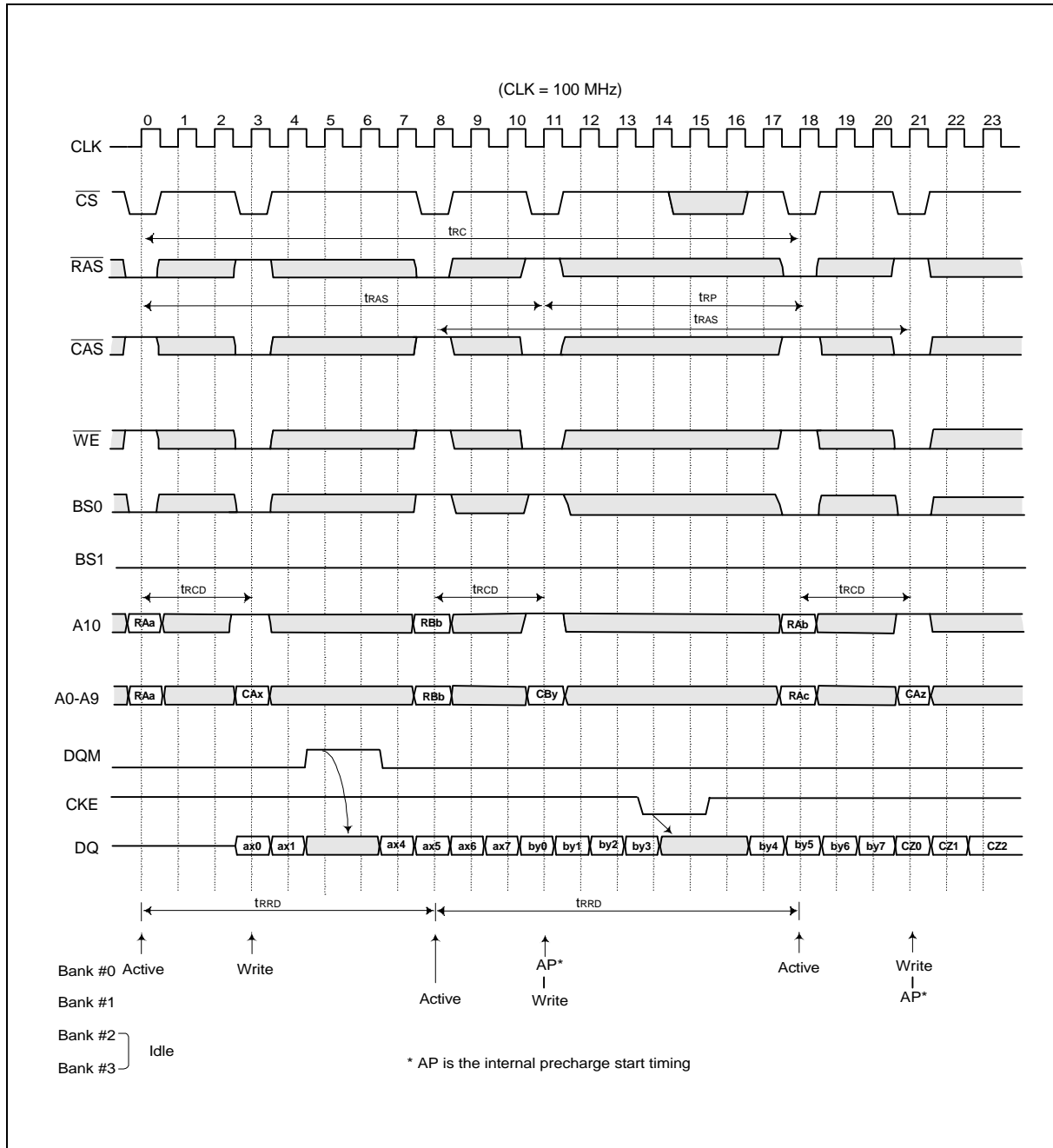
Interleaved Bank Read (Burst Length = 8, CAS Latency = 3, Autoprecharge)



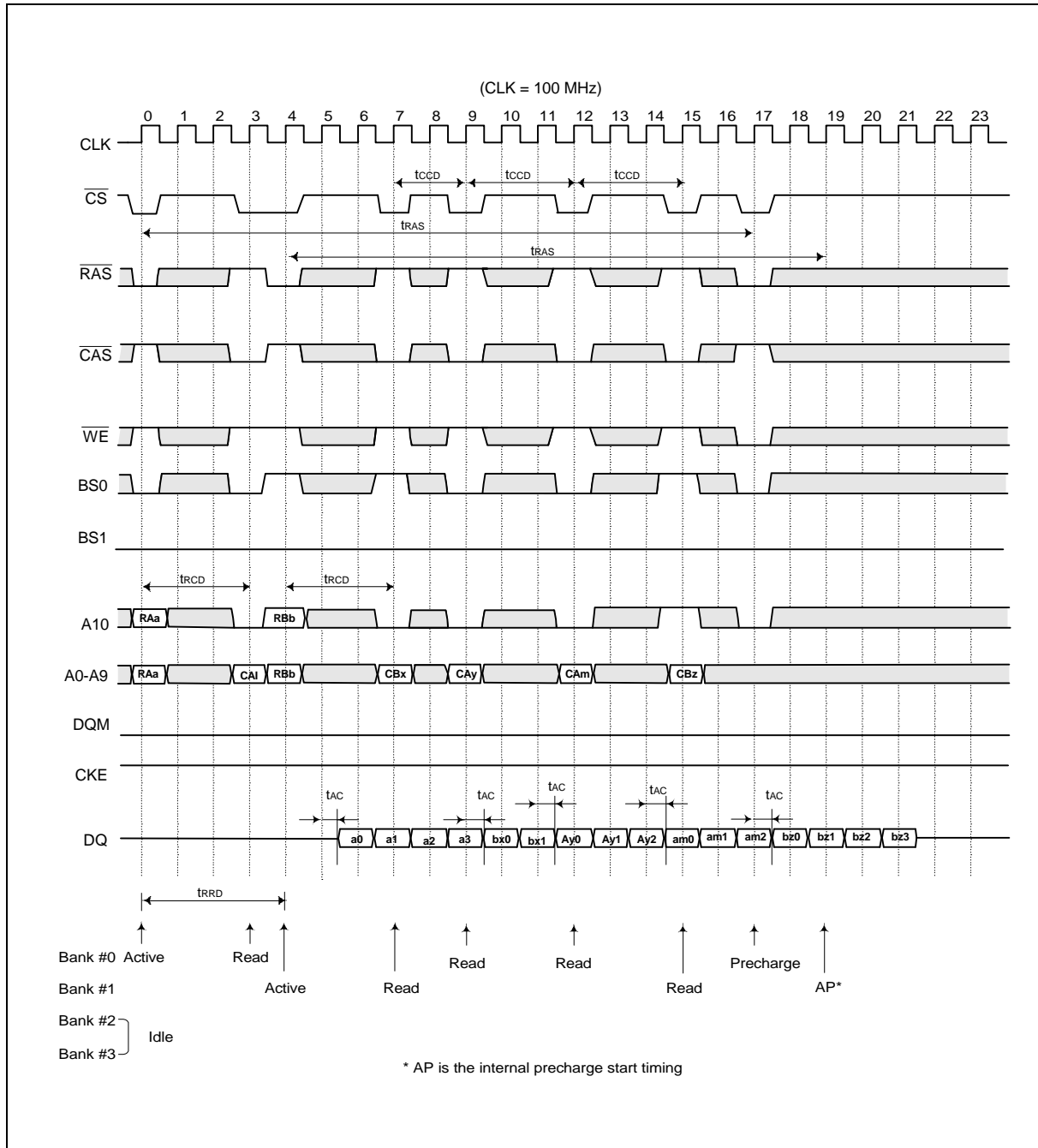
Interleaved Bank Write (Burst Length = 8)



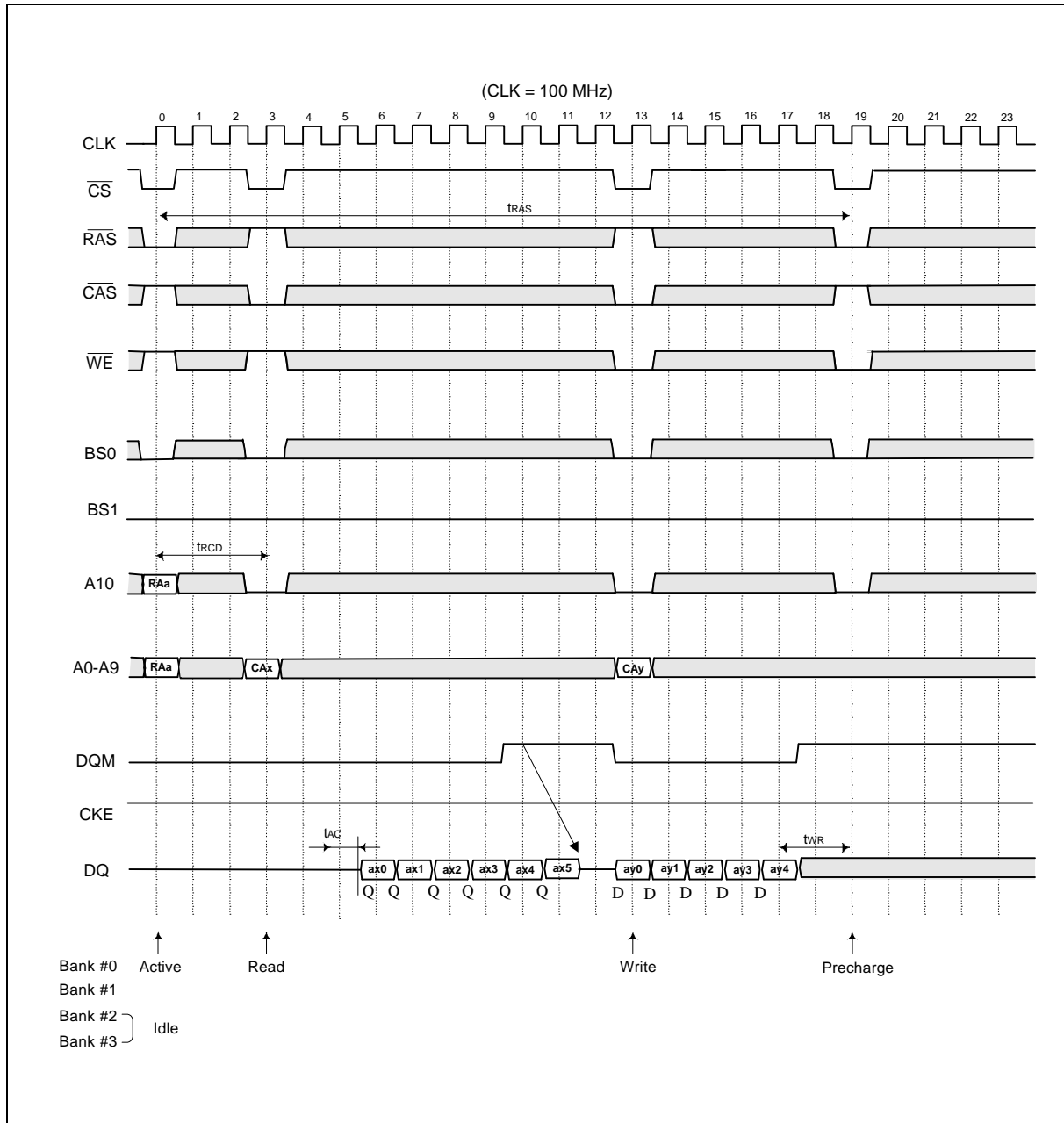
Interleaved Bank Write (Burst Length = 8, Autoprecharge)



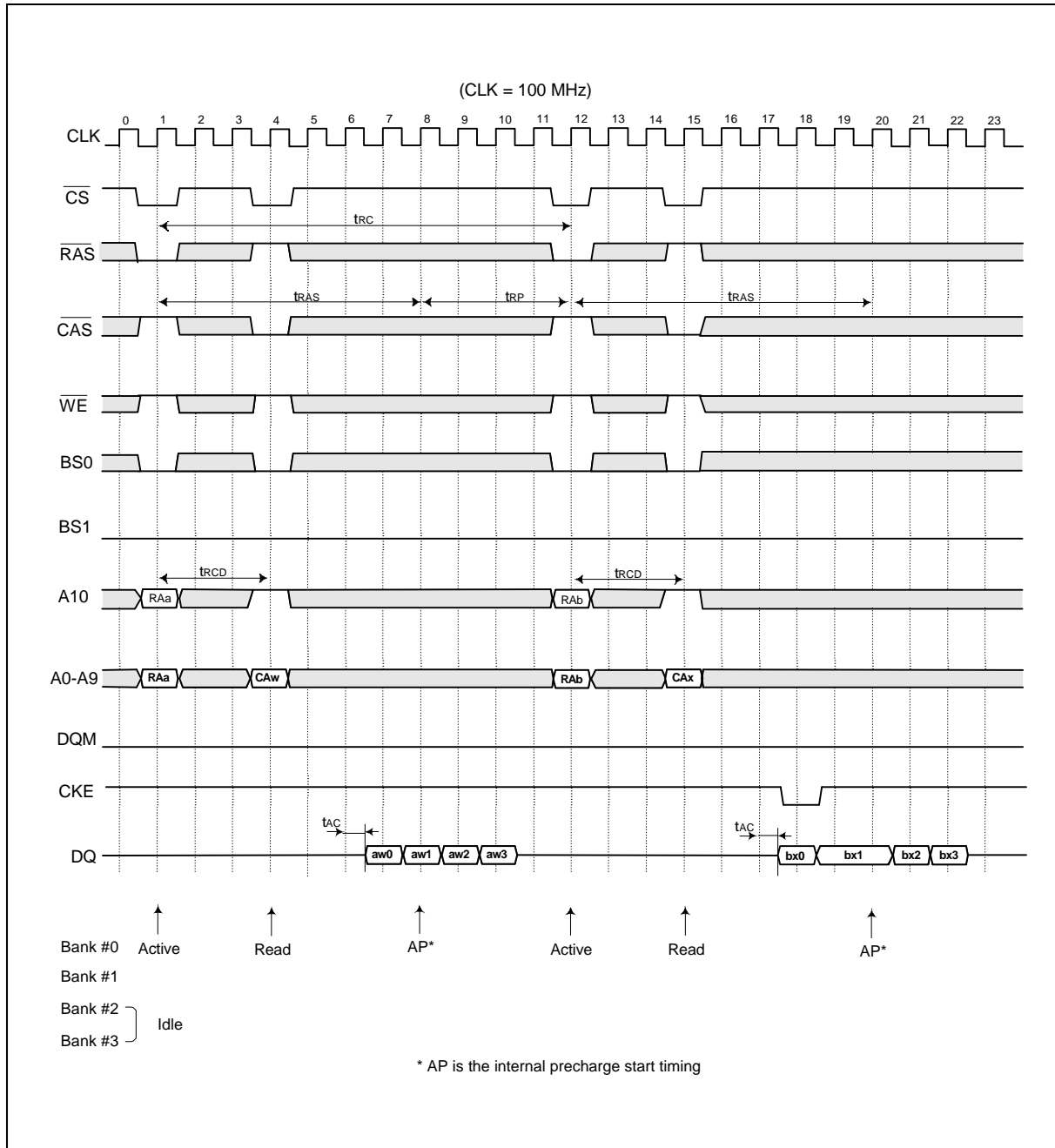
Page Mode Read (Burst Length = 4, CAS Latency = 3)



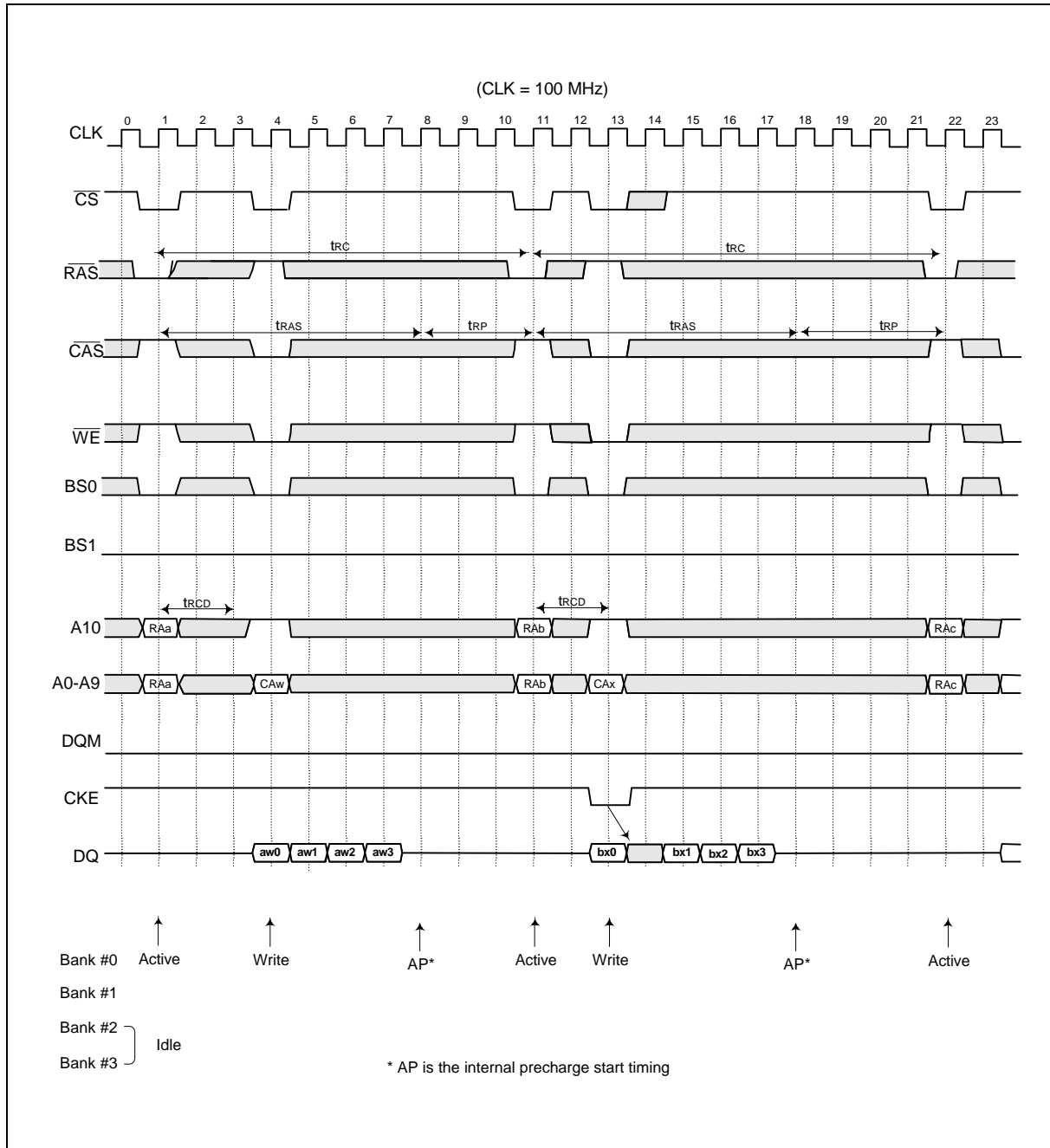
Page Mode Read/Write (Burst Length = 8, CAS Latency = 3)



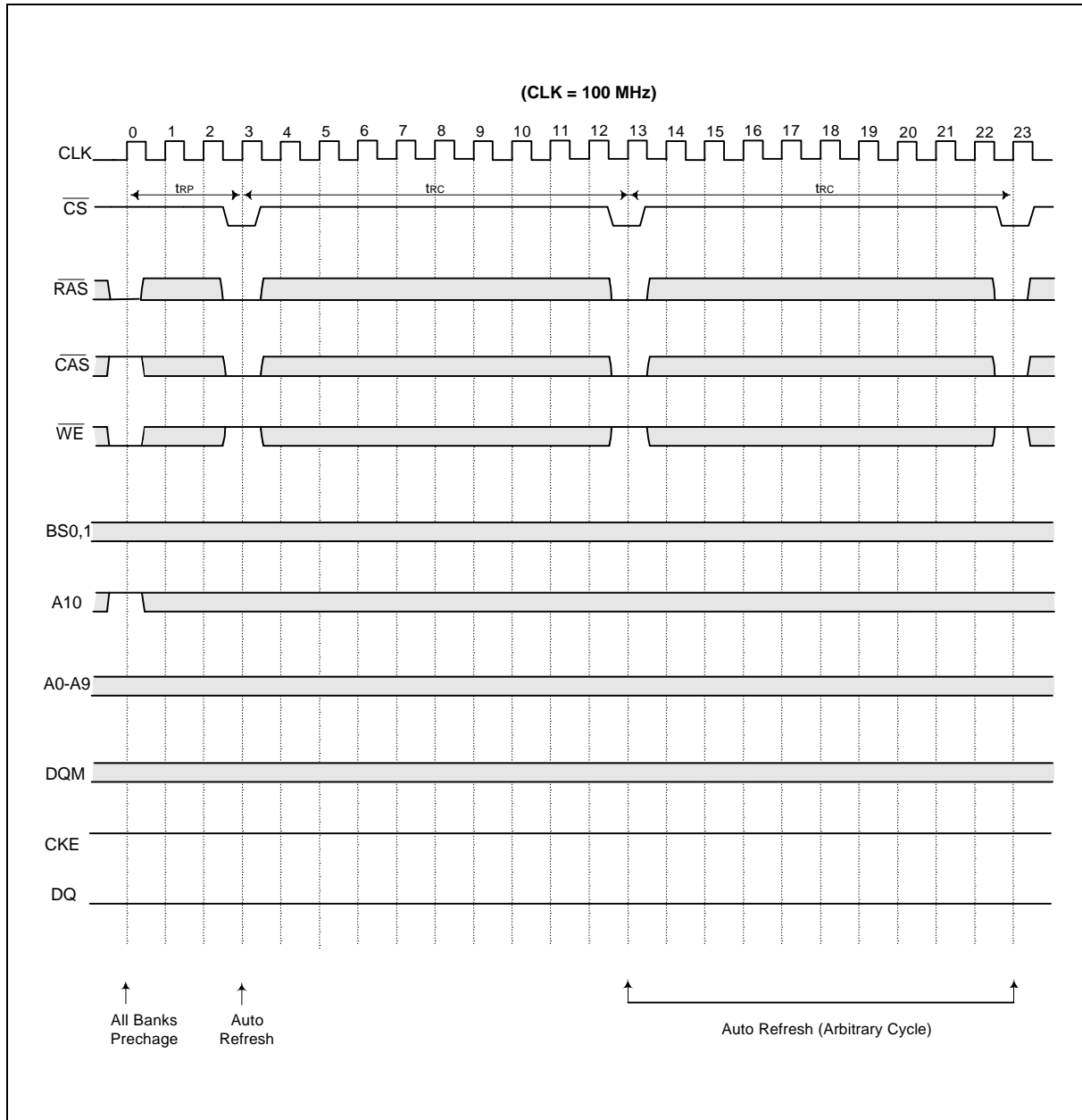
Autoprecharge Read (Burst Length = 4, CAS Latency = 3)



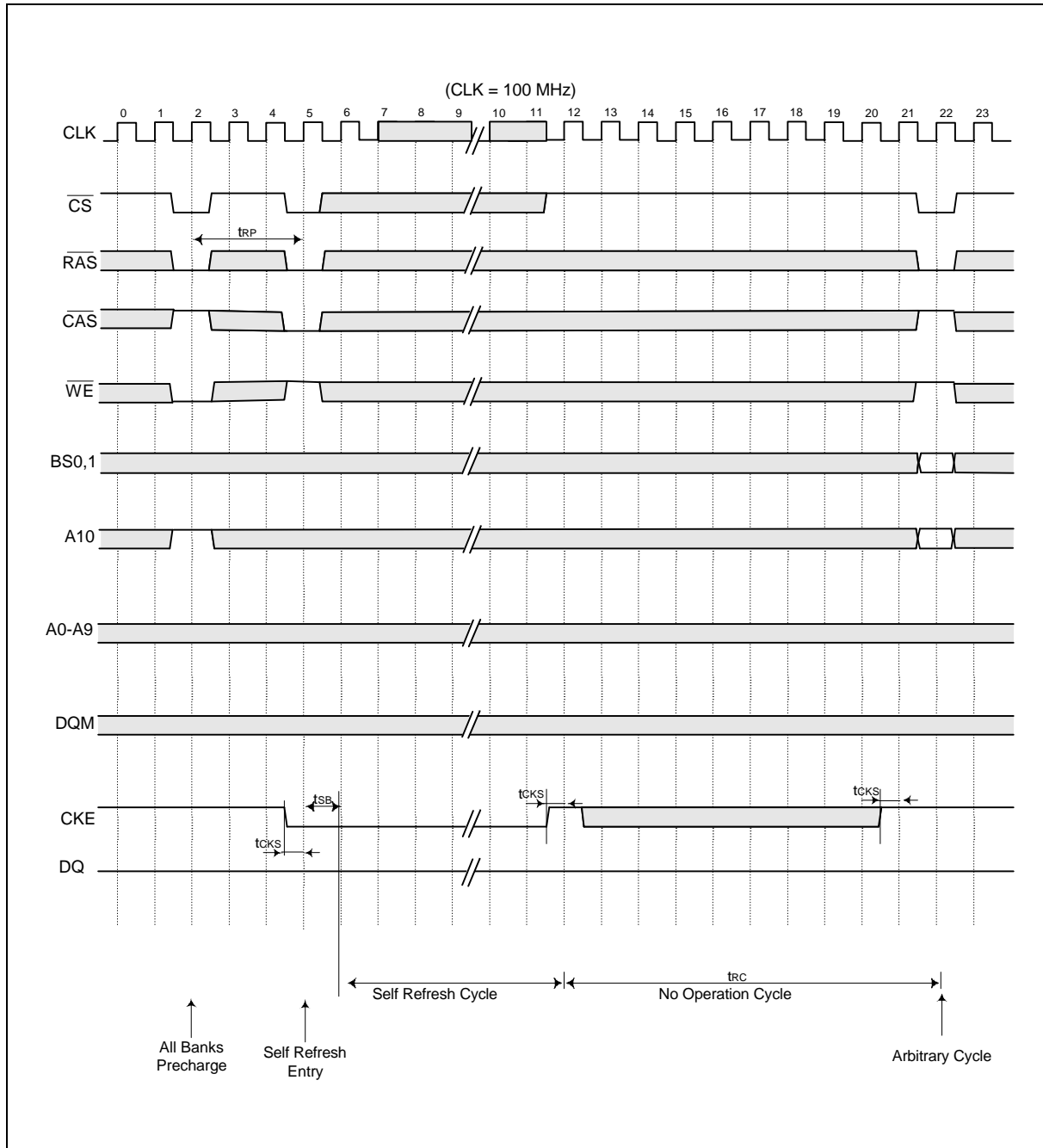
Autoprecharge Write (Burst Length = 4)



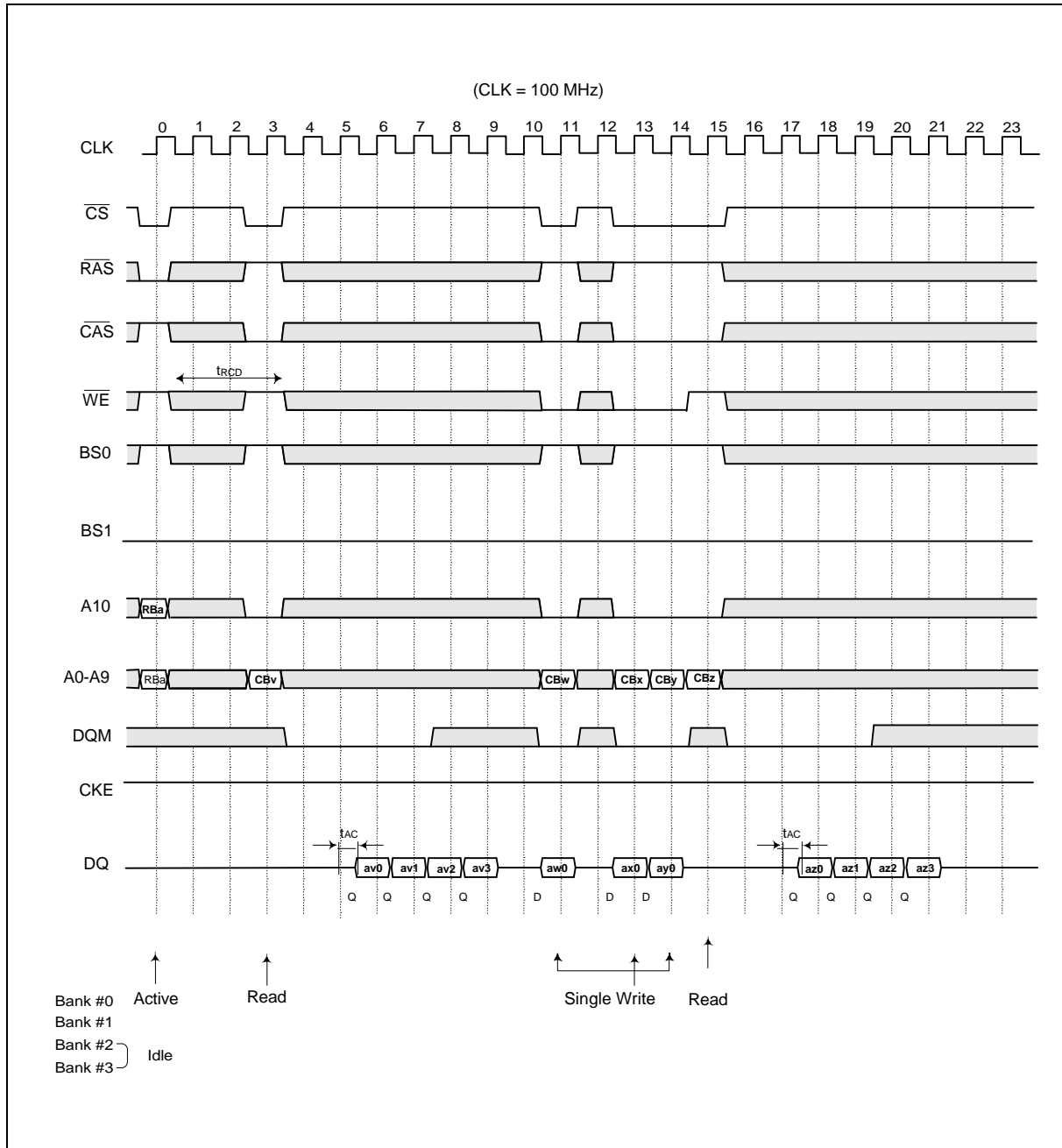
Autorefresh Cycle



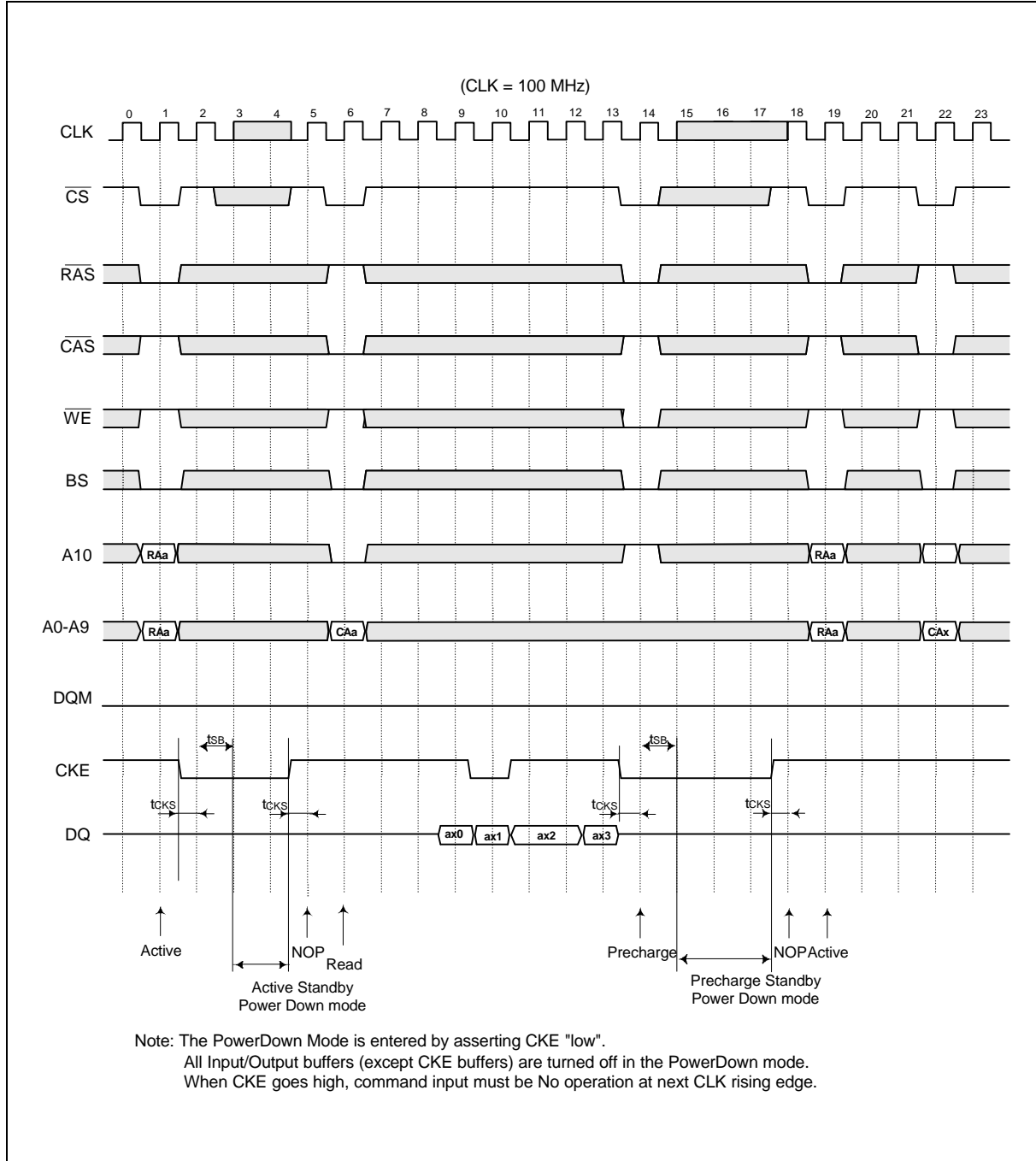
Self-refresh Cycle



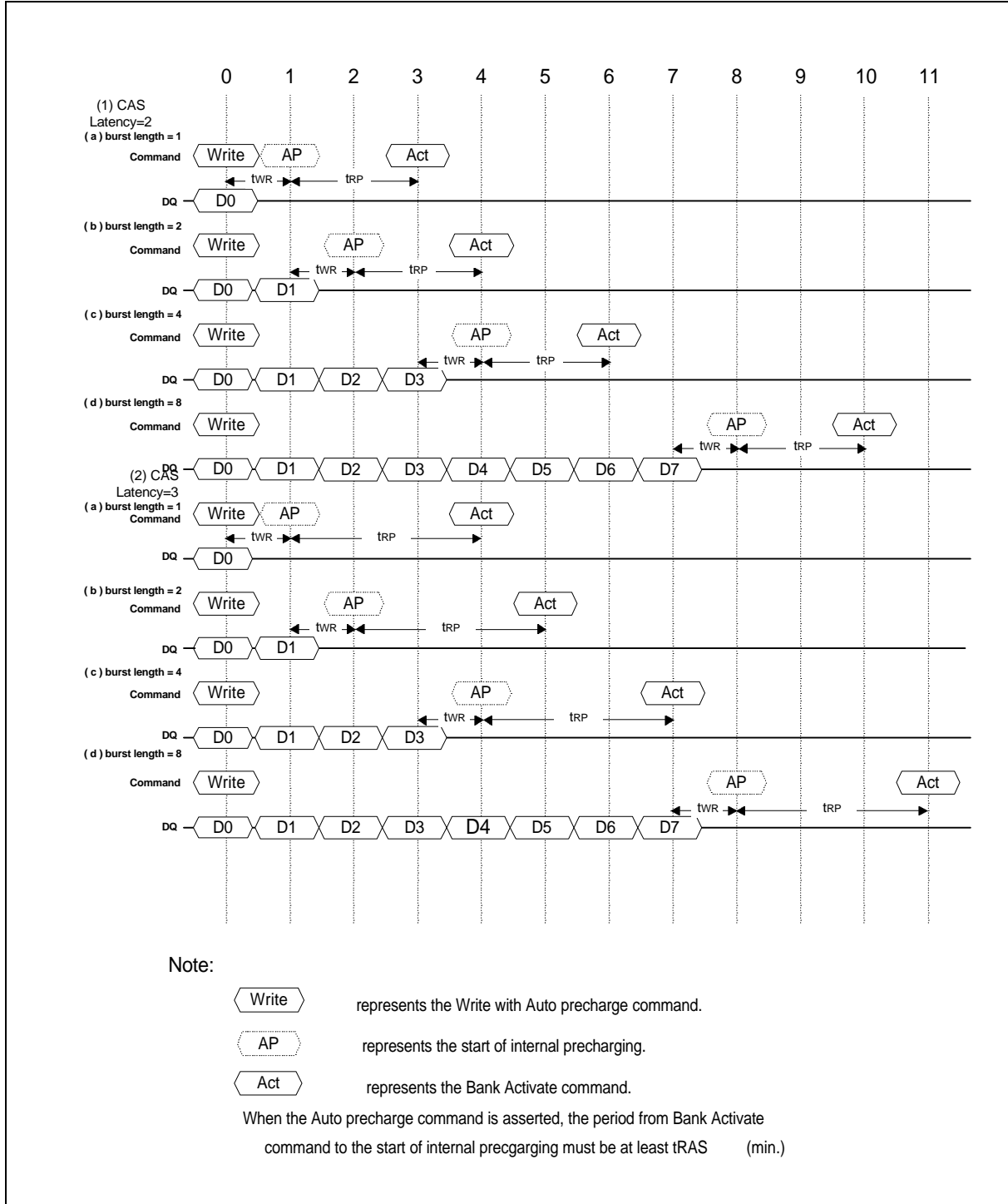
Burst Read and Single Write (Burst Length = 4, CAS Latency = 3)



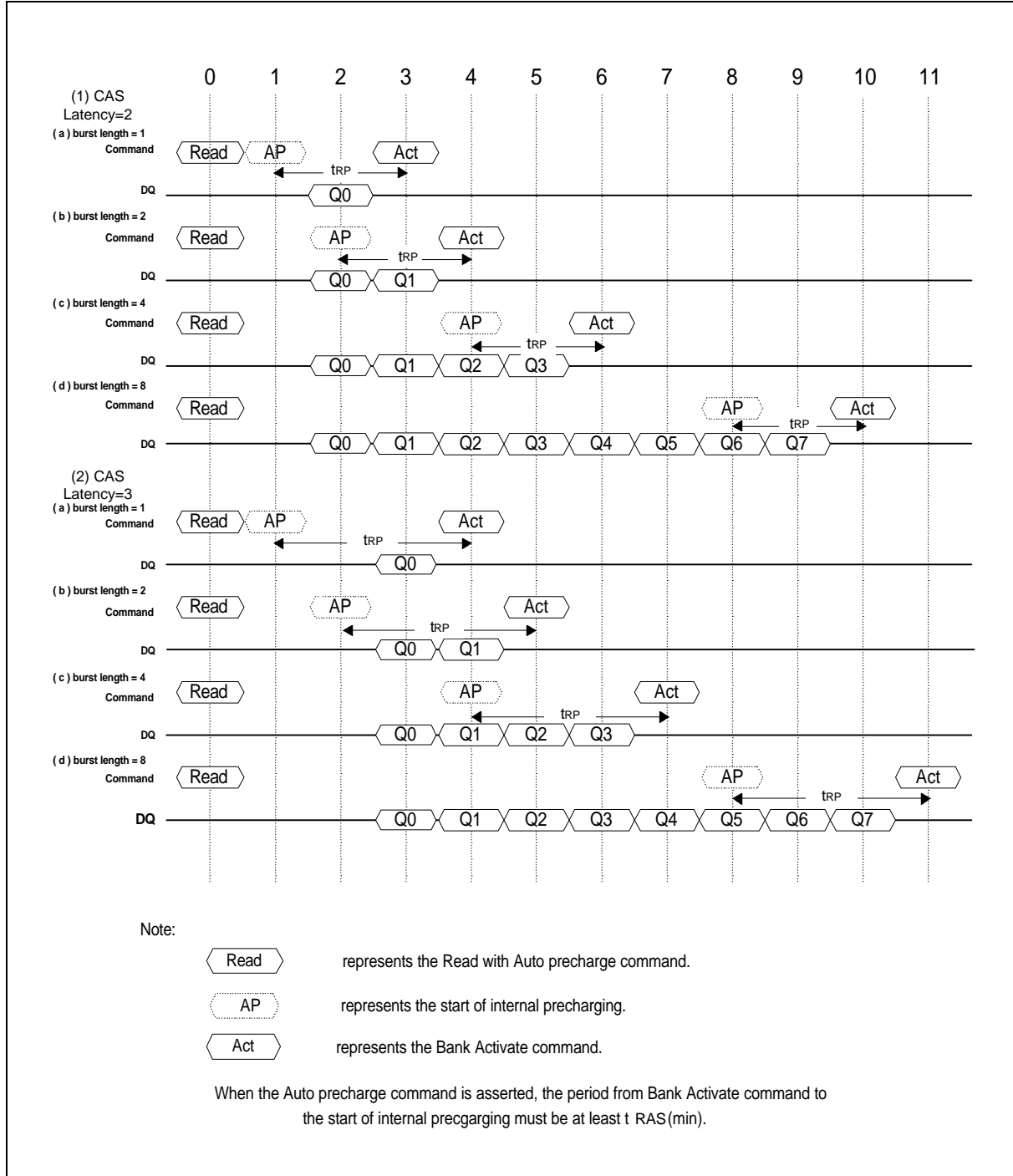
Power-down Mode



Auto-precharge Timing (Write Cycle)

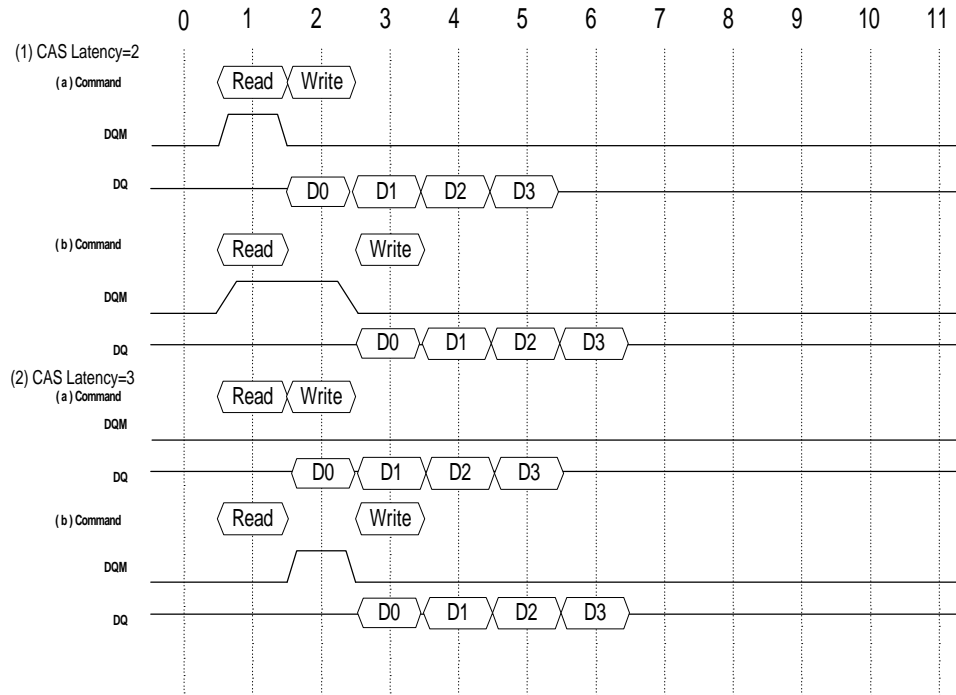


Auto-precharge Timing (Read Cycle)



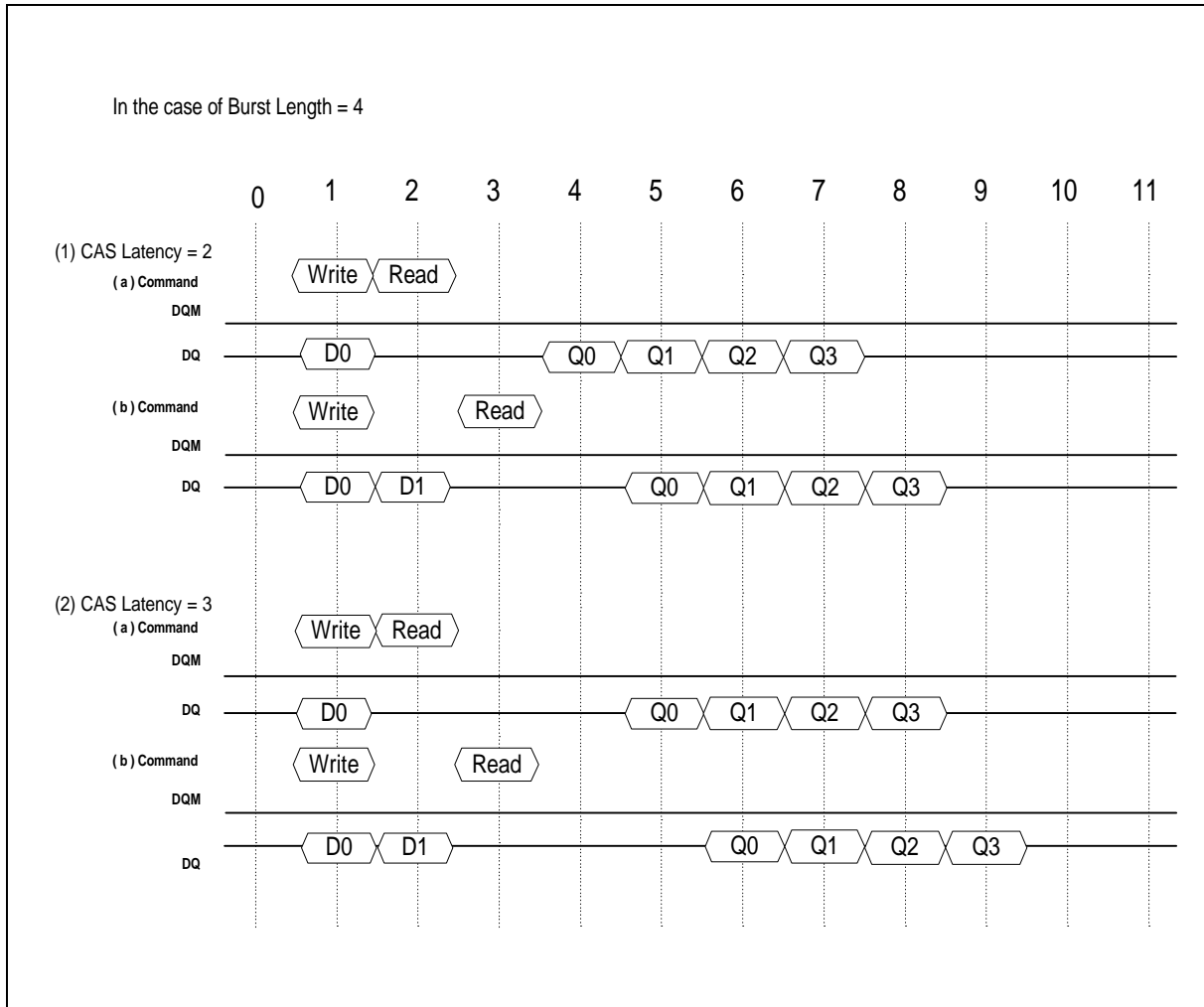
Timing Chart of Read to Write Cycle

In the case of Burst Length = 4

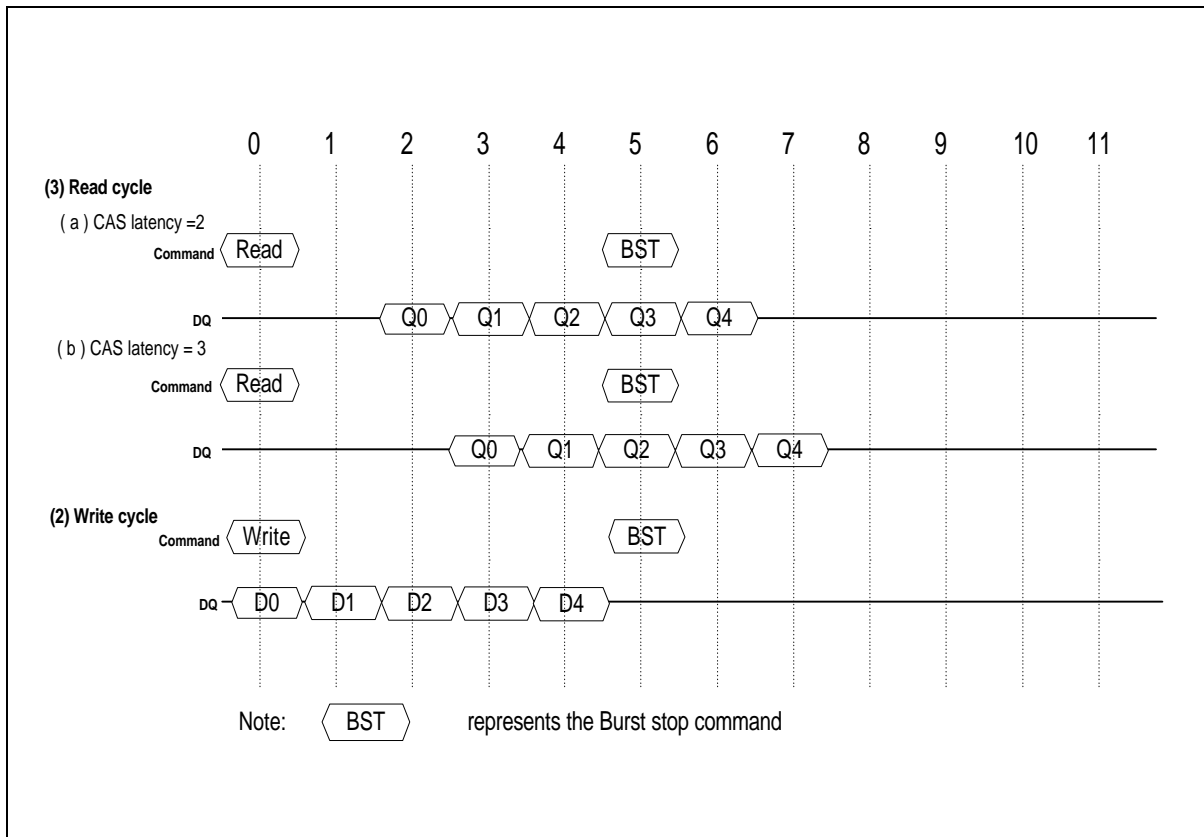


Note: The Output data must be masked by DQM to avoid I/O conflict.

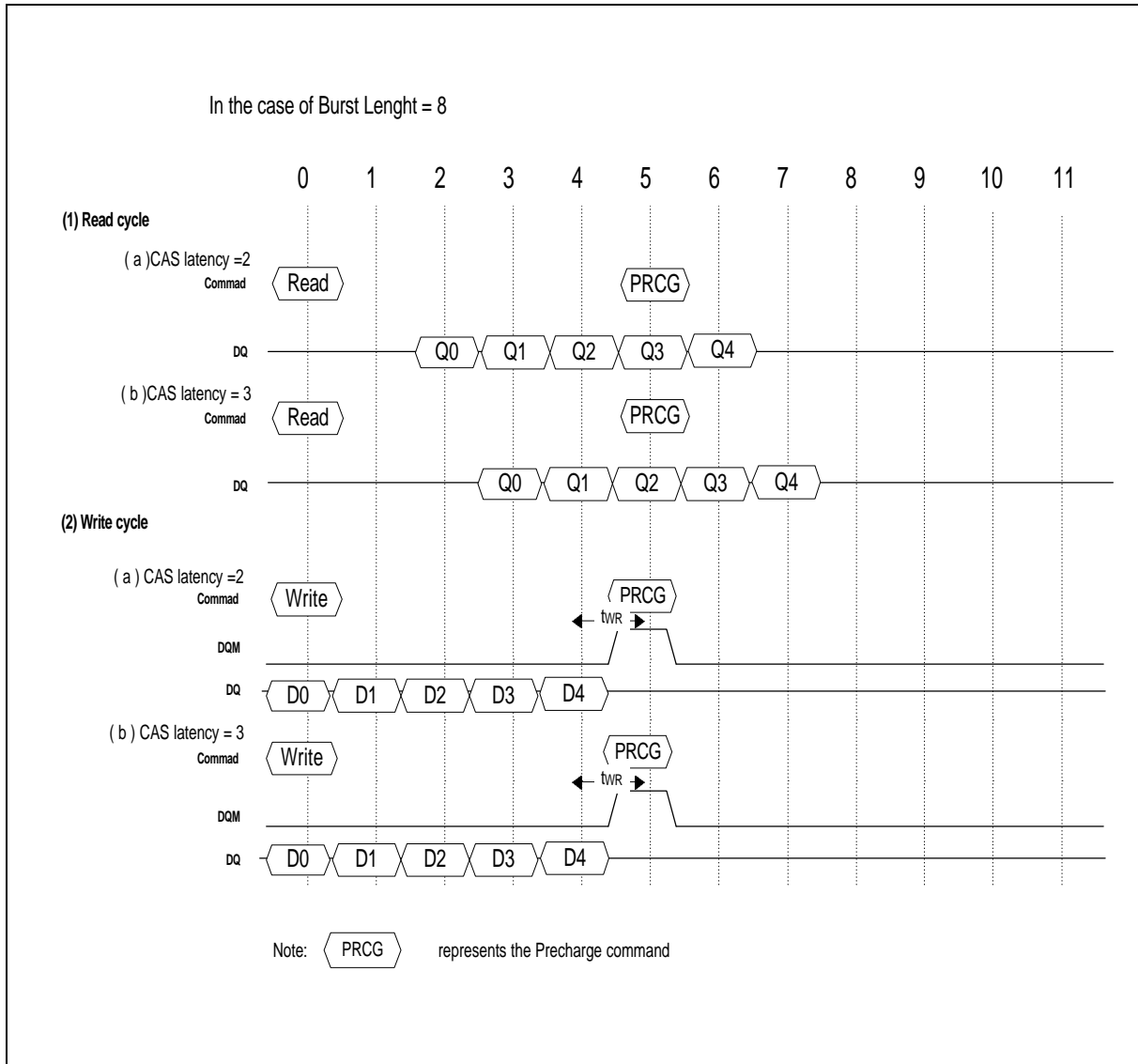
Timing Chart of Write to Read Cycle



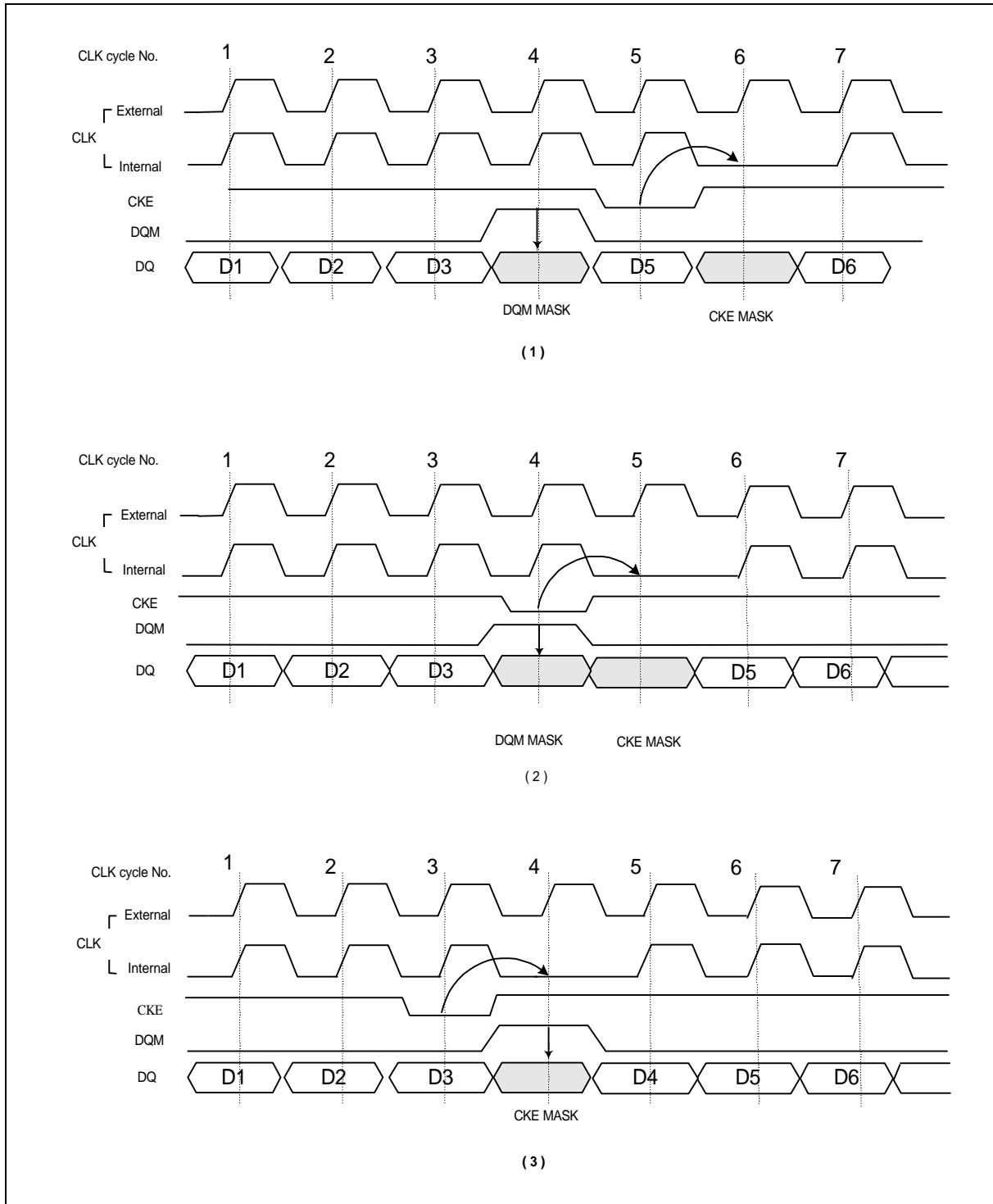
Timing Chart of Burst Stop Cycle (Burst Stop Command)



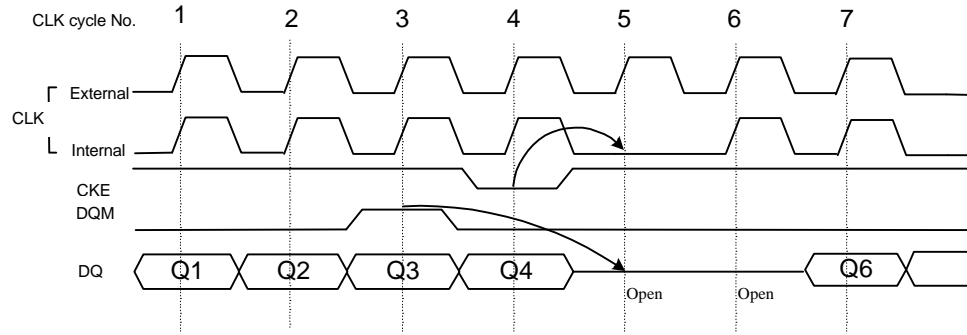
Timing Chart of Burst Stop Cycle (Precharge Command)



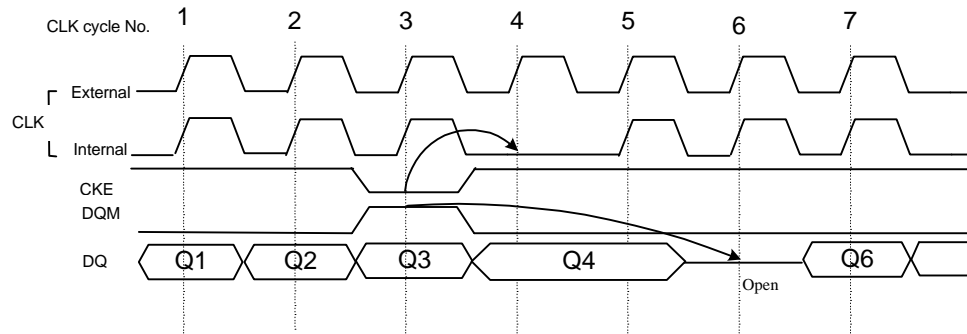
CKE/DQM Input Timing (Write Cycle)



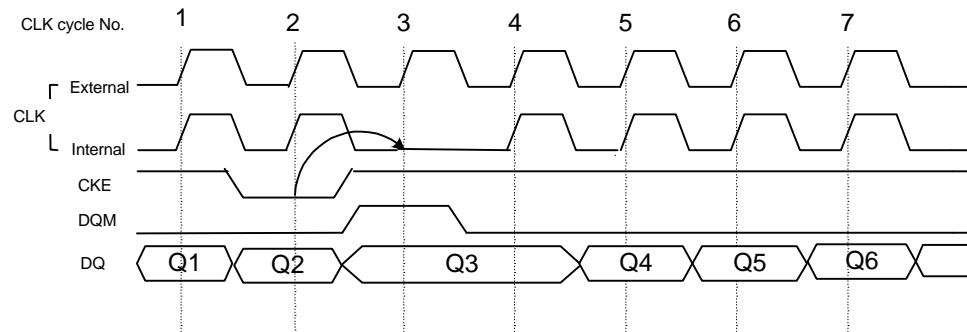
CKE/DQM Input Timing (Read Cycle)



(1)



(2)



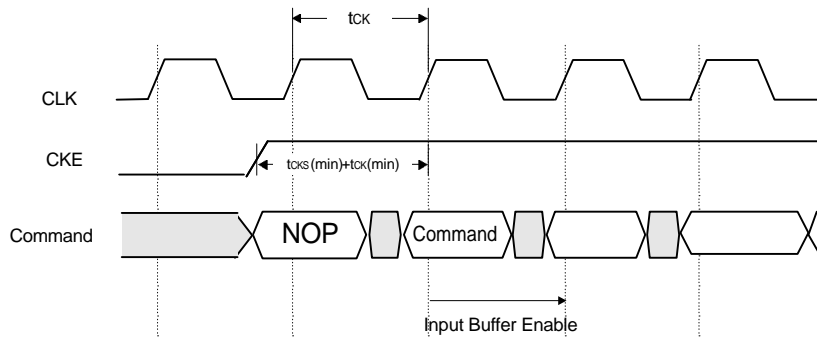
(3)

Self Refresh/Power Down Mode Exit Timing

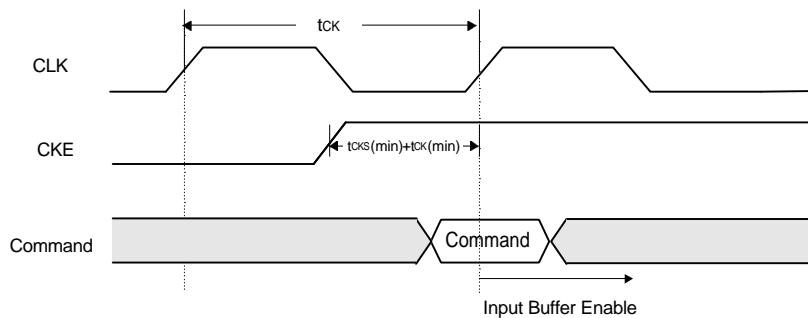
Asynchronous Control

Input Buffer turn on time (Power down mode exit time) is specified by $t_{CKS}(\text{min.}) + t_{CK}(\text{min.})$

A) $t_{CK} < t_{CKS}(\text{min.}) + t_{CK}(\text{min.})$


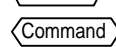


B) $t_{CK} \geq t_{CKS}(\text{min.}) + t_{CK}(\text{min.})$



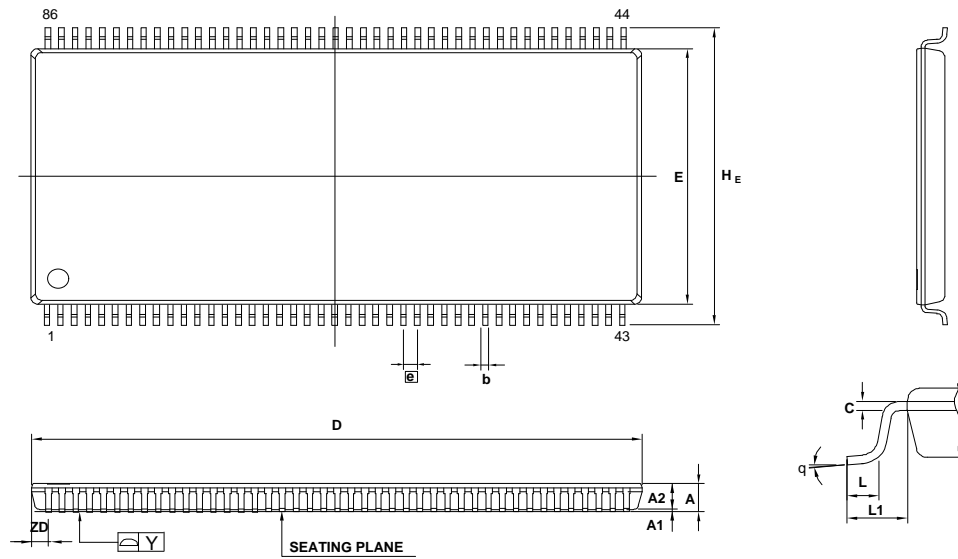
Note:

All Input Buffer (Include CLK Buffer) are turned off in the Power Down mode and Self Refresh mode

-  Represents the No-Operation command
-  Represents one command

PACKAGE DIMENSIONS

86L TSOP (II)-400 mil



Controlling Dimension: Millimeters

SYM.	DIMENSION (MM)			DIMENSION (INCH)		
	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.
A	—	—	1.20	—	—	0.047
A1	0.05	—	0.15	0.002	—	0.006
A2	—	1.00	—	—	0.039	—
b	0.17	—	0.27	0.007	—	0.011
c	0.12	—	0.21	0.005	—	0.008
D	22.12	22.22	22.62	0.871	0.875	0.905
E	10.06	10.16	10.26	0.396	0.400	0.404
H_E	11.56	11.76	11.96	0.455	0.463	0.471
a	—	0.50	—	—	0.020	—
L	0.40	0.50	0.60	0.016	0.020	0.024
L1	—	0.80	—	—	0.032	—
Y	—	—	0.10	—	—	0.004
ZD	—	0.61	—	—	0.024	—

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Note: All data and specifications are subject to change without notice.