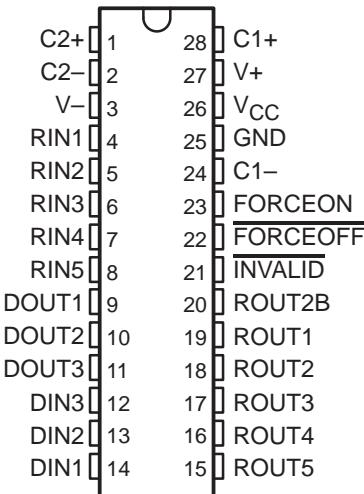


- Single-Chip and Single-Supply Interface for IBM™ PC/AT™ Serial Port
- Meets or Exceeds the Requirements of TIA/EIA-232-F and ITU v.28 Standards
- Operates With 3-V to 5.5-V  $V_{CC}$  Supply
- Always-Active Noninverting Receiver Output (ROUT2B)
- Designed to Transmit at a Data Rate of 250 kbit/s
- Low Standby Current . . . 1  $\mu$ A Typical
- External Capacitors . . .  $4 \times 0.1 \mu$ F
- Accepts 5-V Logic Input With 3.3-V Supply
- Designed to Be Interchangeable With Maxim MAX3243
- Serial-Mouse Driveability
- RS-232 Bus-Pin ESD Protection Exceeds  $\pm 15$ -kV Using Human-Body Model (HBM)†
- Applications
  - Battery-Powered Systems, PDAs, Notebooks, Laptops, Palmtop PCs, and Hand-Held Equipment
- Package Options Include Plastic Small-Outline (DW), Shrink Small-Outline (DB), and Thin Shrink Small-Outline (PW) Packages

DB, DW, OR PW PACKAGE  
(TOP VIEW)



†Manual human-body model ESD testing performed on bus pins exceeds  $\pm 15$  kV. Current human-body model ESD testing capabilities per JESD 22, A114-A, is  $\pm 8$  kV. RS-232 bus pins on this device pass  $\pm 8$  kV.

## description

The MAX3243 device consists of three line drivers, five line receivers, and a dual charge-pump circuit with  $\pm 15$ -kV ESD protection pin to pin (serial-port connection pins, including GND). The device meets the requirements of TIA/EIA-232-F and provides the electrical interface between an asynchronous communication controller and the serial-port connector. This combination of drivers and receivers matches that needed for the typical serial port used in an IBM PC/AT, or compatible. The charge pump and four small external capacitors allow operation from a single 3-V to 5.5-V supply. In addition, the device includes an always-active noninverting output (ROUT2B), which allows applications using the ring indicator to transmit data while the device is powered down. The device operates at data signaling rates up to 250 kbit/s and a maximum of 30-V/ $\mu$ s driver output slew rate.

Flexible control options for power management are available when the serial port is inactive. The auto-powerdown feature functions when FORCEON is low and FORCEOFF is high. During this mode of operation, if the device does not sense a valid RS-232 signal, the driver outputs are disabled. If FORCEOFF is set low, both drivers and receivers (except ROUT2B) are shut off, and the supply current is reduced to 1  $\mu$ A. Disconnecting the serial port or turning off the peripheral drivers causes the auto-powerdown condition to occur.



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# MAX3243

## 3-V TO 5.5-V MULTICHANNEL RS-232 LINE DRIVER/RECEIVER

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### description (continued)

Auto-powerdown can be disabled when FORCEON and FORCEOFF are high, and should be done when driving a serial mouse. With auto-powerdown enabled, the device is activated automatically when a valid signal is applied to any receiver input. The INVALID output is used to notify the user if an RS-232 signal is present at any receiver input. INVALID is high (valid data) if any receiver input voltage is greater than 2.7 V or less than –2.7 V or has been between –0.3 V and 0.3 V for less than 30  $\mu$ s. INVALID is low (invalid data) if all receiver input voltages are between –0.3 V and 0.3 V for more than 30  $\mu$ s. Refer to Figure 5 for receiver input levels.

The MAX3243C is characterized for operation from 0°C to 70°C.

#### AVAILABLE OPTIONS

TA	PACKAGED DEVICES		
	SHRINK SMALL OUTLINE (DB)	SMALL OUTLINE (DW)	THIN SHRINK SMALL OUTLINE (PW)
0°C to 70°C	MAX3243CDB	MAX3243CDW	MAX3243CPW

The DB, DW, and PW packages are available taped and reeled. Add the suffix R to device type (e.g., MAX3243CDBR).

### Function Tables

#### EACH DRIVER

DIN	INPUTS			VALID RIN RS-232 LEVEL	OUTPUT DOUT	DRIVER STATUS
	FORCEON	FORCEOFF				
X	X	L		X	Z	Powered off
L	H	H		X	H	Normal operation with auto-powerdown disabled
H	H	H		X	L	
L	L	H		Yes	H	Normal operation with auto-powerdown enabled
H	L	H		Yes	L	
L	L	H		No	Z	Powered off by auto-powerdown feature
H	L	H		No	Z	

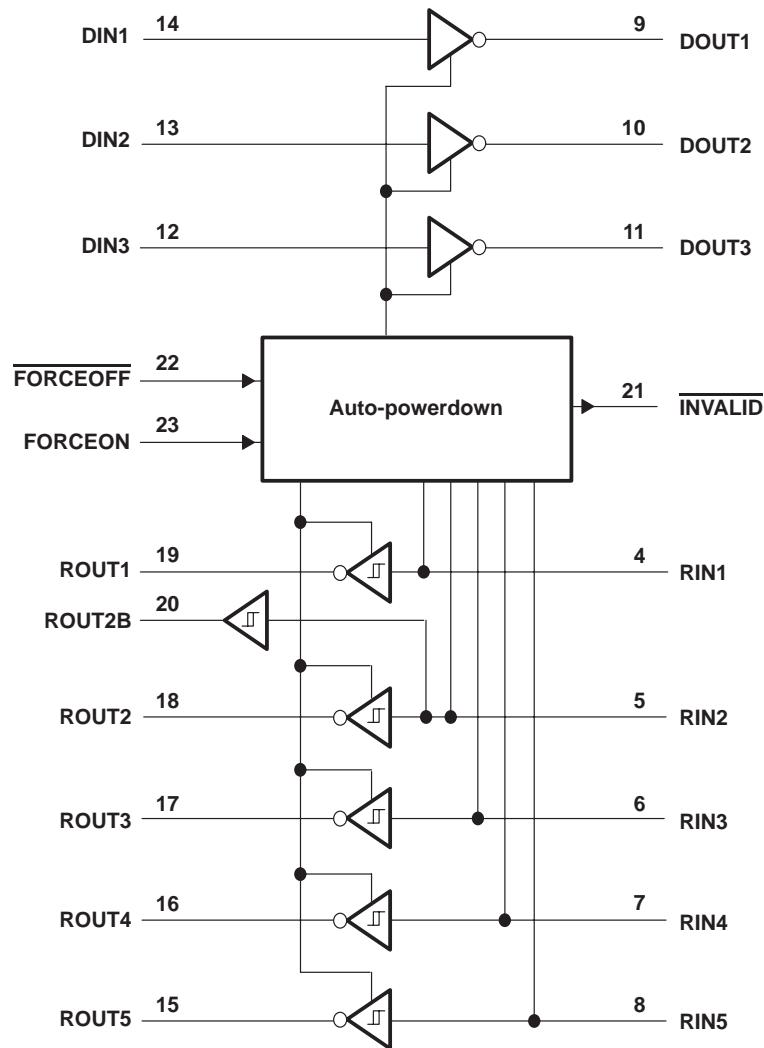
H = high level, L = low level, X = irrelevant, Z = high impedance

#### EACH RECEIVER

RIN2	INPUTS			OUTPUTS		RECEIVER STATUS
	RIN1, RIN3-RIN5	FORCEOFF	VALID RIN RS-232 LEVEL	ROUT2B	ROUT	
L	X	L	X	L	Z	Powered off while ROUT2B is active
H	X	L	X	H	Z	
L	L	H	Yes	L	H	
L	H	H	Yes	L	L	
H	L	H	Yes	H	H	Normal operation with auto-powerdown disabled/enabled
H	H	H	Yes	H	L	
Open	Open	H	No	L	H	

H = high level, L = low level, X = irrelevant, Z = high impedance (off), Open = input disconnected or connected driver off

**logic diagram (positive logic)**



# MAX3243 3-V TO 5.5-V MULTICHANNEL RS-232 LINE DRIVER/RECEIVER

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**absolute maximum ratings over operating free-air temperature range (unless otherwise noted)**

† Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTES: 1. All voltages are with respect to network GND.

2. The package thermal impedance is calculated in accordance with JESD 51.

recommended operating conditions (see Note 3 and Figure 6)

			MIN	NOM	MAX	UNIT
Supply voltage			$V_{CC} = 3.3\text{ V}$	3	3.3	3.6
			$V_{CC} = 5\text{ V}$	4.5	5	5.5
$V_{IH}$	Driver and control high-level input voltage	DIN, <u>FORCEOFF</u> , <u>FORCEON</u>	$V_{CC} = 3.3\text{ V}$	2		V
			$V_{CC} = 5\text{ V}$	2.4		
$V_{IL}$	Driver and control low-level input voltage	DIN, <u>FORCEOFF</u> , <u>FORCEON</u>			0.8	V
$V_I$	Driver and control input voltage	DIN, <u>FORCEOFF</u> , <u>FORCEON</u>		0	5.5	V
$V_I$	Receiver input voltage			-25	25	V
$T_A$	Operating free-air temperature		MAX3243C	0	70	°C

NOTE 3: Test conditions are C1–C4 = 0.1  $\mu$ F at  $V_{CC} = 3.3$  V  $\pm$  0.3 V; C1 = 0.047  $\mu$ F, C2–C4 = 0.33  $\mu$ F at  $V_{CC} = 5$  V  $\pm$  0.5 V.

electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Note 3 and Figure 6)

PARAMETER		TEST CONDITIONS	MIN	TYP†	MAX	UNIT
I <sub>I</sub>	Input leakage current	FORCEOFF, FORCEON		±0.01	±1	µA
I <sub>CC</sub>	Supply current	Auto-powerdown disabled	No load, FORCEOFF and FORCEON at V <sub>CC</sub>	0.3	1	mA
		Powered off	No load, FORCEOFF at GND	1	10	µA
	Supply current	Auto-powerdown enabled	No load, FORCEOFF at V <sub>CC</sub> , FORCEON at GND, All RIN are open or grounded All DIN are grounded	1	10	

<sup>†</sup> All typical values are at  $V_{CC} = 3.3$  V or  $V_{CC} = 5$  V, and  $T_A = 25^\circ\text{C}$ .

NOTE 3. Test conditions are  $C1-C4 = 0.1 \mu\text{F}$  at  $V_{CC} = 3.3 \text{ V} \pm 0.3 \text{ V}$ ;  $C1 = 0.047 \mu\text{F}$ ,  $C2-C4 = 0.33 \mu\text{F}$  at  $V_{CC} = 5 \text{ V} \pm 0.5 \text{ V}$ .

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## DRIVER SECTION

**electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Note 3 and Figure 6)**

PARAMETER	TEST CONDITIONS	MIN	TYP†	MAX	UNIT
$V_{OH}$	High-level output voltage All DOUT at $R_L = 3\text{ k}\Omega$ to GND	5	5.4		V
$V_{OL}$	Low-level output voltage All DOUT at $R_L = 3\text{ k}\Omega$ to GND	-5	-5.4		V
$V_O$	Output voltage (mouse driveability) DIN1 = DIN2 = GND, DIN3 = $V_{CC}$ , 3- $\text{k}\Omega$ to GND at DOUT3, DOUT1 = DOUT2 = 2.5 mA		±5		V
$I_{IH}$	High-level input current $V_I = V_{CC}$		±0.01	±1	$\mu\text{A}$
$I_{IL}$	Low-level input current $V_I$ at GND		±0.01	±1	$\mu\text{A}$
$I_{OS}$	Short-circuit output current‡ $V_{CC} = 3.6\text{ V}$ , $V_O = 0\text{ V}$ $V_{CC} = 5.5\text{ V}$ , $V_O = 0\text{ V}$		±35	±60	mA
$r_O$	$V_{CC}$ , $V_+$ , and $V_- = 0\text{ V}$ , $V_O = \pm 2\text{ V}$	300	10M		$\Omega$
$I_{off}$	FORCEOFF = GND, $V_O = \pm 12\text{ V}$ , $V_{CC} = 0$ to $5.5\text{ V}$			±25	$\mu\text{A}$

† All typical values are at  $V_{CC} = 3.3\text{ V}$  or  $V_{CC} = 5\text{ V}$ , and  $T_A = 25^\circ\text{C}$ .

‡ Short-circuit durations should be controlled to prevent exceeding the device absolute power dissipation ratings, and not more than one output should be shorted at a time.

NOTE 3. Test conditions are  $C1\text{--}C4 = 0.1\text{ }\mu\text{F}$  at  $V_{CC} = 3.3\text{ V} \pm 0.3\text{ V}$ ;  $C1 = 0.047\text{ }\mu\text{F}$ ,  $C2\text{--}C4 = 0.33\text{ }\mu\text{F}$  at  $V_{CC} = 5\text{ V} \pm 0.5\text{ V}$ .

**switching characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Note 3 and Figure 6)**

PARAMETER	TEST CONDITIONS	MIN	TYP†	MAX	UNIT
Maximum data rate	$C_L = 1000\text{ pF}$ , One DOUT switching, See Figure 1		250		kbit/s
$t_{sk(p)}$	Pulse skew§ $C_L = 150\text{ pF}$ to $2500\text{ pF}$	$R_L = 3\text{ k}\Omega$ to $7\text{ k}\Omega$ , See Figure 2	100		ns
$SR(tr)$ (see Figure 1)	$V_{CC} = 3.3\text{ V}$ , $R_L = 3\text{ k}\Omega$ to $7\text{ k}\Omega$	$C_L = 150\text{ pF}$ to $1000\text{ pF}$	6	30	$\text{V}/\mu\text{s}$
		$C_L = 150\text{ pF}$ to $2500\text{ pF}$	4	30	

† All typical values are at  $V_{CC} = 3.3\text{ V}$  or  $V_{CC} = 5\text{ V}$ , and  $T_A = 25^\circ\text{C}$ .

§ Pulse skew is defined as  $|t_{PLH} - t_{PHL}|$  of each channel of the same device.

NOTE 3. Test conditions are  $C1\text{--}C4 = 0.1\text{ }\mu\text{F}$  at  $V_{CC} = 3.3\text{ V} \pm 0.3\text{ V}$ ;  $C1 = 0.047\text{ }\mu\text{F}$ ,  $C2\text{--}C4 = 0.33\text{ }\mu\text{F}$  at  $V_{CC} = 5\text{ V} \pm 0.5\text{ V}$ .

# MAX3243

## 3-V TO 5.5-V MULTICHANNEL RS-232 LINE DRIVER/RECEIVER

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### RECEIVER SECTION

**electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Note 3 and Figure 6)**

PARAMETER	TEST CONDITIONS	MIN	TYP†	MAX	UNIT
$V_{OH}$	High-level output voltage $I_{OH} = -1 \text{ mA}$	$V_{CC} - 0.6 \text{ V}$	$V_{CC} - 0.1 \text{ V}$		V
$V_{OL}$	Low-level output voltage $I_{OL} = 1.6 \text{ mA}$			0.4	V
$V_{IT+}$	Positive-going input threshold voltage $V_{CC} = 3.3 \text{ V}$		1.6	2.4	V
	$V_{CC} = 5 \text{ V}$		1.9	2.4	
$V_{IT-}$	Negative-going input threshold voltage $V_{CC} = 3.3 \text{ V}$	0.6	1.1		V
	$V_{CC} = 5 \text{ V}$	0.8	1.4		
$V_{hys}$	Input hysteresis ( $V_{IT+} - V_{IT-}$ )		0.5		V
$I_{off}$	Output leakage current (except ROUT2B) $\text{FORCEOFF} = 0 \text{ V}$		$\pm 0.05$	$\pm 10$	$\mu\text{A}$
$r_i$	Input resistance $V_I = \pm 3 \text{ V} \text{ to } \pm 25 \text{ V}$	3	5	7	$\text{k}\Omega$

† All typical values are at  $V_{CC} = 3.3 \text{ V}$  or  $V_{CC} = 5 \text{ V}$ , and  $T_A = 25^\circ\text{C}$ .

NOTE 3. Test conditions are  $C1-C4 = 0.1 \mu\text{F}$  at  $V_{CC} = 3.3 \text{ V} \pm 0.3 \text{ V}$ ;  $C1 = 0.047 \mu\text{F}$ ,  $C2-C4 = 0.33 \mu\text{F}$  at  $V_{CC} = 5 \text{ V} \pm 0.5 \text{ V}$ .

**switching characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Note 3)**

PARAMETER	TEST CONDITIONS	MIN	TYP†	MAX	UNIT
$t_{PLH}$	Propagation delay time, low- to high-level output $C_L = 150 \text{ pF}$ , See Figure 3		150		ns
$t_{PHL}$	Propagation delay time, high- to low-level output		150		ns
$t_{en}$	Output enable time $C_L = 150 \text{ pF}$ , $R_L = 3 \text{ k}\Omega$ , See Figure 4		200		ns
$t_{dis}$	Output disable time		200		ns
$t_{sk(p)}$	Pulse skew‡ See Figure 3		50		ns

† All typical values are at  $V_{CC} = 3.3 \text{ V}$  or  $V_{CC} = 5 \text{ V}$ , and  $T_A = 25^\circ\text{C}$ .

‡ Pulse skew is defined as  $|t_{PLH} - t_{PHL}|$  of each channel of the same device.

NOTE 3. Test conditions are  $C1-C4 = 0.1 \mu\text{F}$  at  $V_{CC} = 3.3 \text{ V} \pm 0.3 \text{ V}$ ;  $C1 = 0.047 \mu\text{F}$ ,  $C2-C4 = 0.33 \mu\text{F}$  at  $V_{CC} = 5 \text{ V} \pm 0.5 \text{ V}$ .

### AUTO-POWERDOWN SECTION

**electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Figure 5)**

PARAMETER	TEST CONDITIONS	MIN	TYP†	MAX	UNIT
$V_{T+}(\text{valid})$	Receiver input threshold for <u>INVALID</u> high-level output voltage FORCEON = GND, FORCEOFF = $V_{CC}$			2.7	V
$V_{T-}(\text{valid})$	Receiver input threshold for <u>INVALID</u> high-level output voltage FORCEON = GND, FORCEOFF = $V_{CC}$		-2.7		V
$V_{T}(\text{invalid})$	Receiver input threshold for <u>INVALID</u> low-level output voltage FORCEON = GND, FORCEOFF = $V_{CC}$		-0.3	0.3	V
$V_{OH}$	<u>INVALID</u> high-level output voltage $I_{OH} = -1 \text{ mA}$ , FORCEON = GND, FORCEOFF = $V_{CC}$		$V_{CC} - 0.6$		V
$V_{OL}$	<u>INVALID</u> low-level output voltage $I_{OL} = 1.6 \text{ mA}$ , FORCEON = GND, FORCEOFF = $V_{CC}$			0.4	V

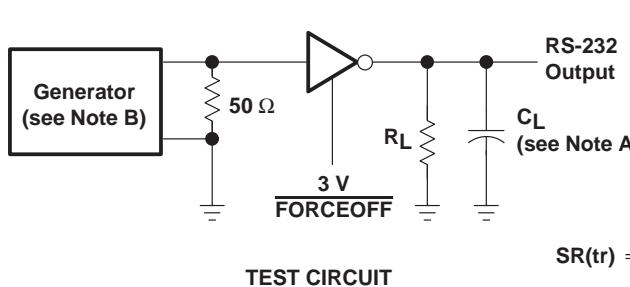
† All typical values are at  $V_{CC} = 3.3 \text{ V}$  or  $V_{CC} = 5 \text{ V}$ , and  $T_A = 25^\circ\text{C}$ .

**switching characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted) (see Figure 5)**

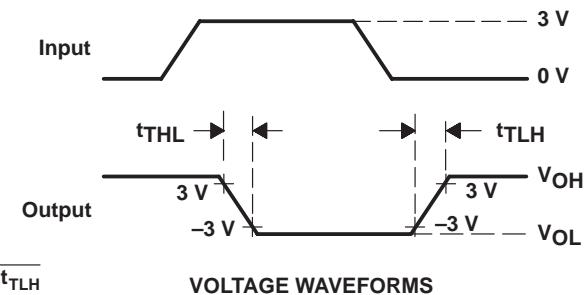
PARAMETER	MIN	TYP†	MAX	UNIT
$t_{\text{valid}}$	Propagation delay time, low- to high-level output		1	$\mu\text{s}$
$t_{\text{invalid}}$	Propagation delay time, high- to low-level output		30	$\mu\text{s}$
$t_{\text{en}}$	Supply enable time		100	$\mu\text{s}$

† All typical values are at  $V_{CC} = 3.3 \text{ V}$  or  $V_{CC} = 5 \text{ V}$ , and  $T_A = 25^\circ\text{C}$ .

### PARAMETER MEASUREMENT INFORMATION



$$SR(tr) = \frac{6 \text{ V}}{t_{\text{THL}} \text{ or } t_{\text{TLH}}}$$



NOTES: A.  $C_L$  includes probe and jig capacitance.

B. The pulse generator has the following characteristics: PRR = 250 kbit/s,  $Z_O = 50 \Omega$ , 50% duty cycle,  $t_r \leq 10 \text{ ns}$ ,  $t_f \leq 10 \text{ ns}$ .

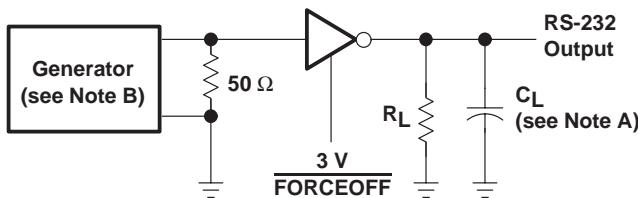
**Figure 1. Driver Slew Rate**

# MAX3243

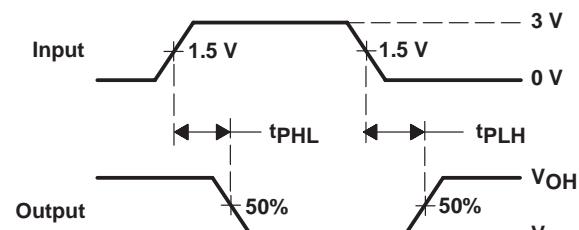
## 3-V TO 5.5-V MULTICHANNEL RS-232 LINE DRIVER/RECEIVER

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### PARAMETER MEASUREMENT INFORMATION



TEST CIRCUIT

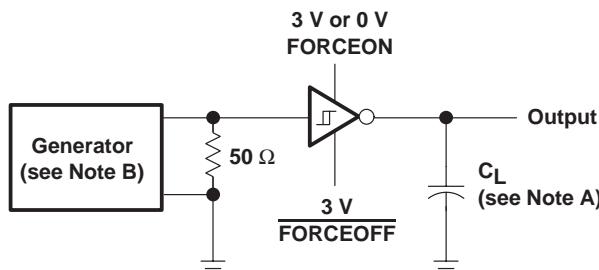


VOLTAGE WAVEFORMS

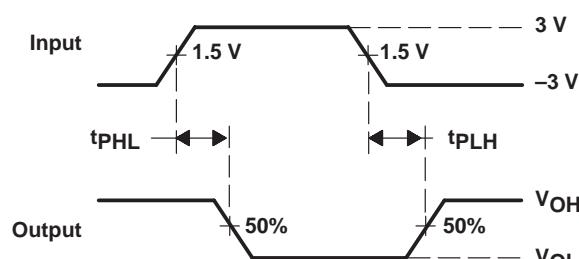
NOTES: A.  $C_L$  includes probe and jig capacitance.

B. The pulse generator has the following characteristics: PRR = 250 kbit/s,  $Z_O = 50 \Omega$ , 50% duty cycle,  $t_r \leq 10 \text{ ns}$ ,  $t_f \leq 10 \text{ ns}$ .

Figure 2. Driver Pulse Skew



TEST CIRCUIT

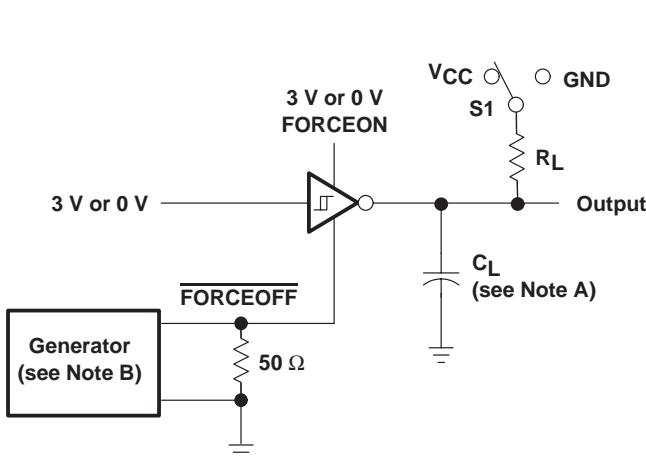


VOLTAGE WAVEFORMS

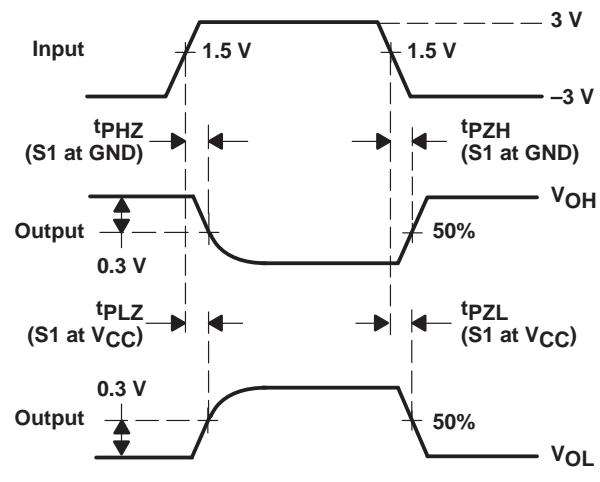
NOTES: A.  $C_L$  includes probe and jig capacitance.

B. The pulse generator has the following characteristics:  $Z_O = 50 \Omega$ , 50% duty cycle,  $t_r \leq 10 \text{ ns}$ ,  $t_f \leq 10 \text{ ns}$ .

Figure 3. Receiver Propagation Delay Times



TEST CIRCUIT



VOLTAGE WAVEFORMS

NOTES: A.  $C_L$  includes probe and jig capacitance.

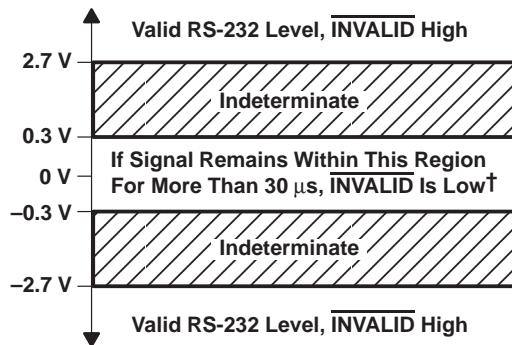
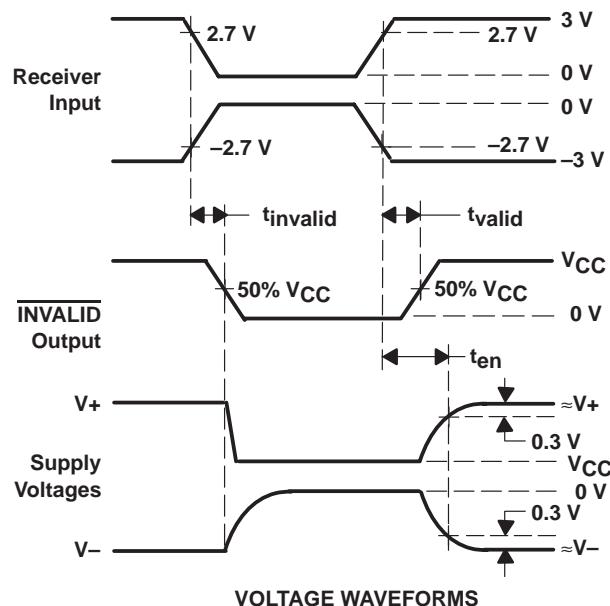
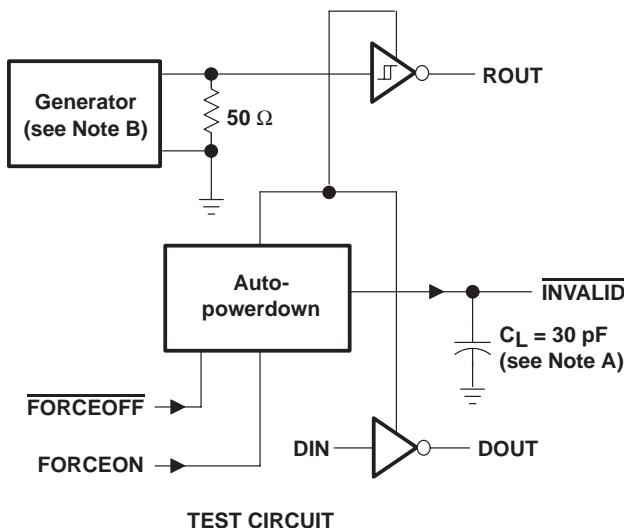
B. The pulse generator has the following characteristics:  $Z_O = 50 \Omega$ , 50% duty cycle,  $t_r \leq 10 \text{ ns}$ ,  $t_f \leq 10 \text{ ns}$ .

C.  $t_{PLZ}$  and  $t_{PHZ}$  are the same as  $t_{dis}$ .

D.  $t_{PZL}$  and  $t_{PZH}$  are the same as  $t_{ten}$ .

Figure 4. Receiver Enable and Disable Times

## PARAMETER MEASUREMENT INFORMATION



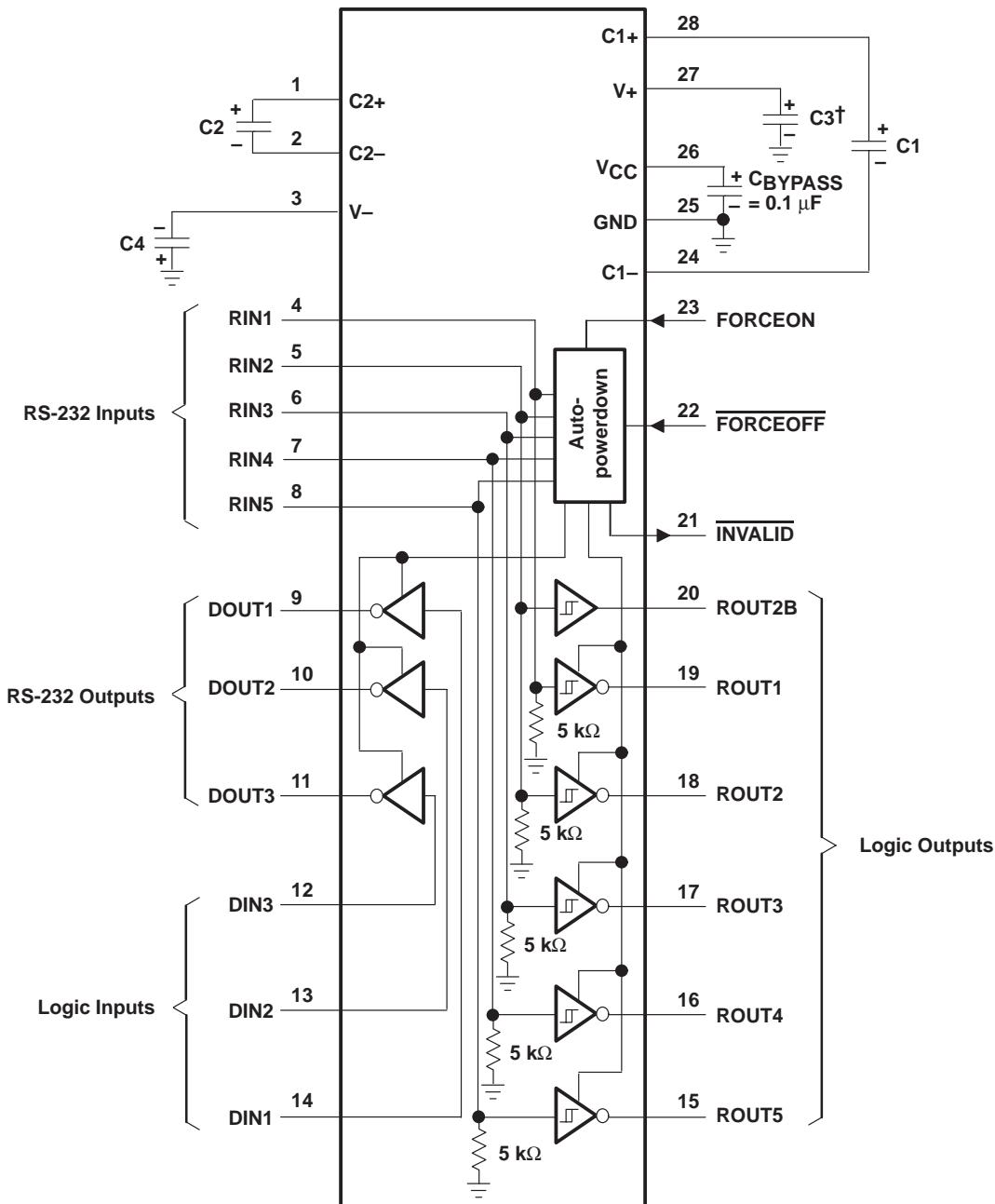
† Auto-powerdown disables drivers and reduces supply current to 1  $\mu$ A.

NOTES: A.  $C_L$  includes probe and jig capacitance.

B. The pulse generator has the following characteristics: PRR = 5 kbit/s,  $Z_O = 50 \Omega$ , 50% duty cycle,  $t_r \leq 10$  ns,  $t_f \leq 10$  ns.

**Figure 5. INVALID Propagation Delay Times and Supply Enabling Time**

## APPLICATION INFORMATION



† C3 can be connected to V<sub>CC</sub> or GND.

NOTE A: Resistor values shown are nominal.

V<sub>CC</sub> vs CAPACITOR VALUES

V <sub>CC</sub>	C1	C2, C3, and C4
3.3 V $\pm$ 0.3 V	0.1 $\mu$ F	0.1 $\mu$ F
5 V $\pm$ 0.5 V	0.047 $\mu$ F	0.33 $\mu$ F
3 V to 5.5 V	0.1 $\mu$ F	0.47 $\mu$ F

Figure 6. Typical Operating Circuit and Capacitor Values

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