

**RADIATION TOLERANT FULL BRIDGE
POWER DRIVER HYBRID
FOR 3-PHASE BRUSHLESS DC MOTORS**

Mii

**MICROCIRCUITS PRODUCTS
DIVISION**

Features:

- Designed for 100 krad(Si) Total Dose
- Hermetically Sealed Package
- 2A Peak Output Current
- Built-in High-Side Gate Drive Circuit
- N- and P-channel MOSFETs for Ease of Drive
- Electrically Isolated Package
- Interface Directly with UC1625 Motor Controller

Applications:

- 3-Phase BLDC Motor Control
- Fin Actuator Control
- Antenna Deployment Control
- Mirror Position Control
- X-Y Table Control
- Gimbal Stabilization Platform
- Guidance System

DESCRIPTION

The 42144 Full Bridge Power Driver Hybrid is designed for high reliability applications in harsh environment. This compact design offers a full-bridge power driver stage for three-phase brushless DC motor applications. The circuit is electrically isolated from the metal case for ease of mounting in the system. The hybrid package provides two mounting ears for ease of assembly and low thermal resistance path. Each phase contains a high-side gate drive circuit for the P-channel power MOSFET, a series gate resistor for the low-side N-channel power MOSFET, and three Schottky diodes. The high-side gate drive circuit accepts an open-collector signal of the application controller circuit and generates required gate voltage to operate the high-side MOSFET. The low-side gate resistor will prevent any oscillations and minimize ringing. As an option, a Schottky diode in series with the low-side MOSFET insures that braking current will not flow backward through the N-channel MOSFET. Sources of the low-side MOSFETs are terminated individually allowing user to configure the desired current sensing option.

Micropac 42144 Full Bridge Power Driver Hybrid employed selected components that are capable to perform in radiation environment with minimum degradation. The hybrid will perform over the full military temperature range of -55°C to $+125^{\circ}\text{C}$. It is fabricated using DSCC certified manufacturing processes that are fully in compliance with MIL-PRF-38534. This device is available in a variety of quality levels from COTS to Class K including any custom screening requirements. The basic data sheet part is environmentally screened to H level in accordance with Table C-IX of MIL-PRF-38534.

ABSOLUTE MAXIMUM RATINGS

Supply Voltage, V_M	60 VDC
Peak Pulsed Output Current (< 1% duty cycle)	5 A
Dielectric Withstanding Voltage	500 VDC
Storage Temperature Range	-65°C to $+150^{\circ}\text{C}$
Operating Junction Temperature	-55°C to $+150^{\circ}\text{C}$
Lead Solder Temperature for 10 seconds	300°C
Junction-to case thermal resistance, θ_{JC}	TBD $^{\circ}\text{C/W}$
Case Temperature	125°C

WEIGHT: TBD grams (typical)

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RECOMMENDED OPERATING CONDITIONS:

Parameter	Symbol	Min.	Max.	Units
Motor Supply Voltage	V_M		50	VDC
Continuous Output Current	$I_{O(ON)}$		2	A
Input Voltage (off)	$V_{F(OFF)}$	0	1	VDC
Operating Case Temperature	T_C	-55	125	°C

ELECTRICAL SPECIFICATIONS

$T_C = 25^\circ\text{C}$ unless otherwise specified

Switching Characteristics (N-Channel, lower switches)

CHARACTERISTICS	SYM.	MIN.	TYP.	MAX.	UNIT	TEST CONDITIONS
Turn-On Delay Time	$t_{d(ON)}$			25	ns	$V_M = 24\text{VDC}$, $I_M = 2\text{A}$,
Rise Time	t_r			55	ns	$V_M = 24\text{VDC}$, $I_M = 2\text{A}$
Turn-Off Delay Time	$t_{d(OFF)}$			55	ns	$V_M = 24\text{VDC}$, $I_M = 2\text{A}$
Fall Time	t_f			45	ns	$V_M = 24\text{VDC}$, $I_M = 2\text{A}$
On-State Resistance	$R_{DS(ON)}$			0.20	ohms	$V_M = 24\text{VDC}$, $I_M = 2\text{A}$

Switching Characteristics (P-Channel, upper switches)

CHARACTERISTICS	SYM.	MIN.	TYP.	MAX.	UNIT	TEST CONDITIONS
Turn-On Delay Time	$t_{d(ON)}$			30	ns	$V_M = 24\text{VDC}$, $I_M = 2\text{A}$
Rise Time	t_r			50	ns	$V_M = 24\text{VDC}$, $I_M = 2\text{A}$
Turn-Off Delay Time	$t_{d(OFF)}$			70	ns	$V_M = 24\text{VDC}$, $I_M = 2\text{A}$
Fall Time	t_f			70	ns	$V_M = 24\text{VDC}$, $I_M = 2\text{A}$
On-State Resistance	$R_{DS(ON)}$			0.35	ohms	$V_M = 24\text{VDC}$, $I_M = 2\text{A}$

Diode Characteristics

CHARACTERISTICS	SYM.	MIN.	TYP.	MAX.	UNIT	TEST CONDITIONS
Forward Voltage	V_F			0.6	VDC	$V_M = 24\text{VDC}$, $I_M = 2\text{A}$
Forward Time	t_r			TBD	ns	$V_M = 24\text{VDC}$, $I_M = 2\text{A}$
Reverse Recovery Time	t_{rr}			TBD	ns	$V_M = 24\text{VDC}$, $I_M = 2\text{A}$

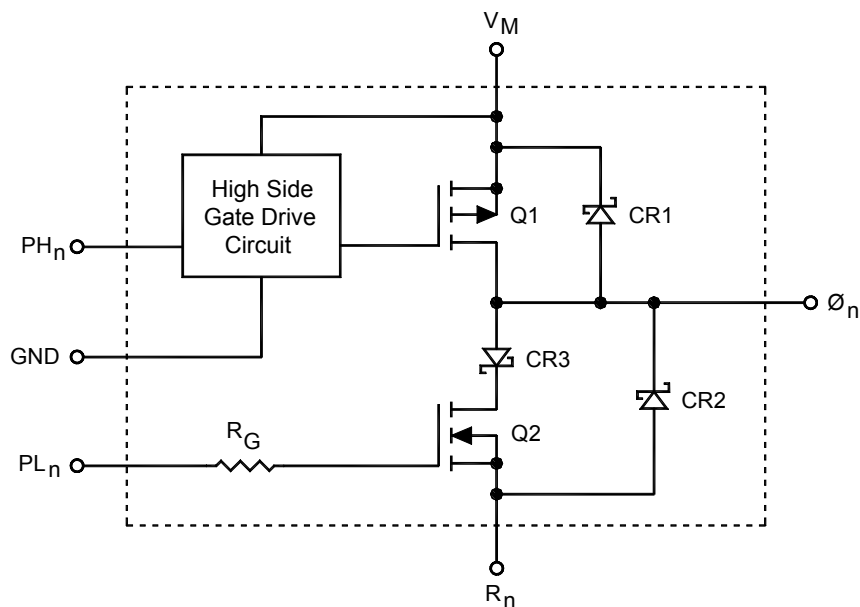
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High Side Input Specifications (Open Collector)

PARAMETERS	MIN	MAX	UNIT	TEST CONDITIONS
$V_{CE(OFF)}$	TBD	TBD	VDC	
$V_{CE(SAT)}$	TBD	TBD	VDC	@ $I_M = 2A$
Rise Time	TBD	TBD	ns	
Fall Time	TBD	TBD	ns	

Low Side Input Specifications

PARAMETERS	MIN	MAX	UNIT	TEST CONDITIONS
$V_{in} (Hi)$		15	VDC	
$V_{in} (Lo)$	0	0.5	VDC	
$I_{in} (Hi)$		300	mA	
$I_{in} (Lo)$		-300	mA	
Rise Time		TBD	ns	
Fall Time		TBD	ns	



EQUIVALENT SCHEMATIC PER PHASE

Figure 1. Block Diagram

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Pin*	Symbol	Function
1	V _M	Motor Bus Voltage
2	GND	GROUND
3	Ø _A	OUTPUT, Phase A
4	Ø _B	OUTPUT, Phase B
5	Ø _C	OUTPUT, Phase C
6	PH _A	INPUT, High Side, Phase A
7	PH _B	INPUT, High Side, Phase B
8	PH _C	INPUT, High Side, Phase C
9	PL _A	INPUT, Low Side, Phase A
10	PL _B	INPUT, Low Side, Phase B
11	PL _C	INPUT, Low Side, Phase C
12	R _A	Current Sense, Phase A
13	R _B	Current Sense, Phase B
14	R _C	Current Sense, Phase C
15	NC	Not Used
16	NC	Not Used
17	NC	Not Used
18	NC	Not Used

*Tentative Pin assignment.

Figure 2. Pin Function

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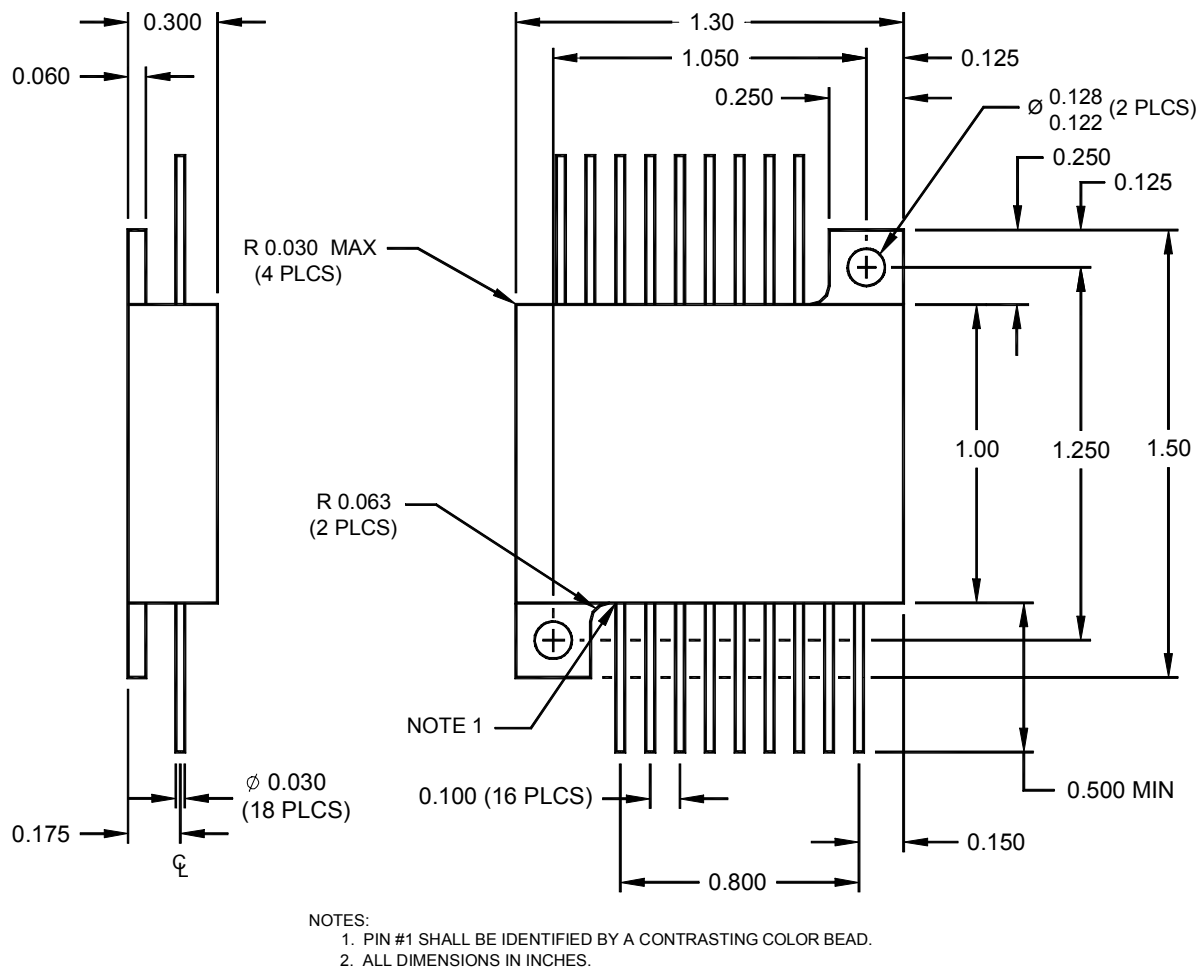


Figure 3. Case Outline

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